

(64) $t = [0, 10, 15, 20, 32, 59, 62, 125]$; $v(t) = [0, 185, 319, 447, 742, 1325, 1445, 4151]$

(a) $v(t) = 0.00146t^3 - 0.11553t^2 + 24.98169t - 21.26872$

(b) $h = \int_0^{125} v(t) dt = 2.064 \cdot 10^5 \text{ [feet]}$

5.5 SUBSTITUTION RULE

$$\int 2x \sqrt{1+x^2} dx = \left| \begin{array}{l} u = 1+x^2 \\ du = 2x dx \end{array} \right| = \int \sqrt{u} du = \frac{2}{3} u^{3/2} = \frac{2}{3} \sqrt{(1+x^2)^3} + C$$

$$\frac{2}{3} \frac{d}{dx} (1+x^2)^{3/2} = \frac{2}{3} \cdot \frac{3}{2} (1+x^2)^{3/2-1} \cdot 2x = 2x \sqrt{1+x^2}$$

$\int f(g(x)) g'(x) dx$ Use this approach whenever you meet such form of integral

If $F' = f$ then:

$$\int F'(g(x)) g'(x) dx = \int F'(g(x)) d(g(x)) = F(g(x)) + C \quad \ominus$$

$$\frac{d}{dx} F(g(x)) = F'(g(x)) g'(x), \quad u = g(x) \quad \text{gggg}$$

$$\int F'(g(x)) g'(x) dx = F(g(x)) + C = \int F'(u) du = F(u) + C$$

$$F' = f; \quad \int f(g(x)) g'(x) dx = \int f(u) du$$

• Substitution rule: If $u = g(x)$ differentiable function in interval I and f is continuous on I then:

$$\int f(g(x)) g'(x) dx = \int f(u) du$$

EXAMPLE 1:

$$I = \int x^3 \cos(x^4+2) dx = \left| \begin{array}{l} x^4+2 = u \\ 4x^3 dx = du \end{array} \right| = \int \cos(u) \frac{du}{4} = \frac{1}{4} \sin(u) + C$$

$$I = \frac{1}{4} \sin(x^4+2) + C$$

EXAMPLE 2: $I = \int \sqrt{2x+1} dx = \left| \begin{array}{l} u = 2x+1 \\ du = 2 dx \end{array} \right| = \int \sqrt{u} \frac{du}{2} =$

$$= \frac{1}{2} \int \sqrt{u} du = \frac{1}{2} \cdot \frac{2}{3} u^{3/2} = \frac{1}{3} (2x+1)^{3/2} + C$$

$$\frac{d}{dx} (I) = \frac{1}{3} \cdot \frac{3}{2} (2x+1)^{1/2} \cdot 2 = \sqrt{2x+1}$$

• SOLUTION 2: $u = \sqrt{2x+1} \quad u^2 = 2x+1 \quad 2u du = 2 dx$
 $dx = u du$

$$I = \int u \cdot u du = \int u^2 du = \frac{1}{3} u^3 = \frac{1}{3} \sqrt{(2x+1)^3} = \frac{1}{3} (2x+1)^{3/2}$$

EXAMPLE 3 $I = \int \frac{x}{\sqrt{1-4x^2}} dx = \left| \begin{array}{l} u = 1-4x^2 \\ du = -8x dx \\ x dx = -\frac{du}{8} \end{array} \right| = \int -\frac{du}{8\sqrt{u}} =$

$$= -\frac{1}{8} \frac{u^{-\frac{1}{2}+1}}{-\frac{1}{2}+1} = -\frac{1}{8} \frac{\sqrt{u}}{\frac{1}{2}} = -\frac{1}{4} \sqrt{u} + C = -\frac{1}{4} \sqrt{1-4x^2} + C$$

$f(x) = \frac{x}{\sqrt{1-4x^2}}$; $g(x) = \frac{1}{4} \sqrt{1-4x^2}$; $g'(x) = f(x)$

ex 4 $\int e^{5x} dx = \left| \begin{array}{l} u = 5x \\ du = 5 dx \end{array} \right| = \int \frac{e^u du}{5} = \frac{1}{5} e^u = \frac{1}{5} e^{5x} + C$

ex 5 $I = \int \sqrt{1+x^2} \cdot x^5 dx = \left| \int u dv = u \cdot v - \int v du \right|$

$I = \int \underbrace{\sqrt{1+x^2}}_u \cdot \underbrace{\frac{x^6}{6}}_v = \frac{x^6}{6} \sqrt{1+x^2} - \int \frac{x^6}{6} \cdot d(\sqrt{1+x^2})$

$\frac{d}{dx}(\sqrt{1+x^2}) = \frac{1}{2} (1+x^2)^{\frac{1}{2}-1} \cdot 2x = \frac{x}{\sqrt{1+x^2}}$

$I_1 = \int \frac{x^6 \cdot x}{\sqrt{1+x^2}} dx = \int \frac{x^7}{\sqrt{1+x^2}} dx$

$\left(\frac{1}{\sqrt{1+x^2}}\right)' = -\frac{1}{2} (1+x^2)^{-\frac{1}{2}-1} \cdot 2x = -\frac{x}{(1+x^2)\sqrt{1+x^2}}$

$\left(\frac{x}{\sqrt{1+x^2}}\right)' = \frac{x' \cdot \sqrt{1+x^2} - \frac{1}{2} (1+x^2)^{\frac{1}{2}-1} \cdot 2x \cdot x}{1+x^2} = \frac{\sqrt{1+x^2} - \frac{x^2}{\sqrt{1+x^2}}}{1+x^2}$

$= \frac{1+x^2 - x^2}{\sqrt{1+x^2} (1+x^2)} = \frac{1}{(1+x^2)\sqrt{1+x^2}}$

$u = \frac{1}{\sqrt{1+x^2}} \quad du = -\frac{x}{(1+x^2)\sqrt{1+x^2}} dx$

$u^2 = \frac{1}{1+x^2} \quad u^2 + x^2 u^2 = 1$

$x^2 u^2 = 1 - u^2 \quad x^2 = \frac{1-u^2}{u^2} \quad x^4 = \frac{(1-u^2)^2}{u^4}$

$x^4 = \frac{1}{u^4} - \frac{2}{u^2} + 1 = \frac{u^4 - 2u^2 + 1}{u^4}$

$I = \int \sqrt{1+x^2} \cdot x^5 dx = \int x^4 (x \sqrt{1+x^2} dx) = \int \frac{(u^4 - 2u^2 + 1)}{u^4} du =$

$= \frac{u^{-3}}{3} - 2 \frac{u^{-1}}{1} + u = \frac{1}{3} \left(\frac{1}{\sqrt{1+x^2}}\right)^{-3} - 2 \left(\frac{1}{\sqrt{1+x^2}}\right)^{-1} + \frac{1}{\sqrt{1+x^2}} =$

$= \frac{1}{3} \sqrt{(1+x^2)^3} - \frac{2}{1} \sqrt{1+x^2} + \frac{1}{\sqrt{1+x^2}} = \frac{3\sqrt{(1+x^2)^4} - 10(1+x^2) + 15}{15\sqrt{1+x^2}}$

$= \frac{3(1+x^2)^2 - 10(1+x^2) + 15}{15\sqrt{1+x^2}} = \frac{3 + 6x^2 + 3x^4 - 10 - 10x^2 + 15}{15\sqrt{1+x^2}}$

$$I = \frac{8 - 4x^2 + 3x^4}{15\sqrt{1+x^2}}$$

$$(\tan^5 x)' = \left(\frac{\sin^5(x)}{\cos^5(x)} \right)' = \frac{\cos^2(x) + \sin^2(x)}{\cos^2(x)} = \frac{1}{\cos^2(x)} = \sec^2(x)$$

$$\sec(x) = \frac{1}{\cos(x)} \quad \sinh(x) = \frac{e^x - e^{-x}}{2}$$

$$(\tan^5(x))' = 5 \tan^4(x) \cdot \sec^2(x)$$

$$y = \arctg x \quad ; \quad x = \operatorname{tg} y \quad ; \quad dx = \frac{dy}{\cos^2(y)} = (1 + \operatorname{tg}^2(y)) dy$$

$$dx = (1 + x^2) dy \quad dy = \frac{dx}{1+x^2}$$

$$I = \int x^5 \sqrt{1+x^2} dx \quad ; \quad \int \frac{dx}{1+x^2} = \arctg(x) + C$$

$$u = 1+x^2 \quad ; \quad du = 2x dx \quad ; \quad x^2 = u-1$$

$$I = \int x^4 \sqrt{1+x^2} \cdot x dx = \int (u-1)^2 \sqrt{u} \cdot \frac{du}{2} =$$

$$= \frac{1}{2} \int (u^2 - 2u + 1) \sqrt{u} du = \int (u^{5/2} - 2u^{3/2} + \sqrt{u}) du$$

$$= \frac{1}{2} \left(\frac{2}{7} (1+x^2)^{7/2} - \frac{4}{5} (1+x^2)^{5/2} + \frac{2}{3} (1+x^2)^{3/2} \right) =$$

$$= \frac{1}{7} (1+x^2)^{7/2} - \frac{2}{5} (1+x^2)^{5/2} + \frac{1}{3} (1+x^2)^{3/2}$$

EXAMPLE 6 $I = \int \tan x dx$ $(\sec(x))' = \left(\frac{1}{\cos(x)} \right)' = \left(\frac{1}{\cos(x)} \right)' = \frac{\sin(x)}{\cos^2(x)} = \operatorname{tg}(x) \cdot \sec(x)$

$$= -1 \frac{1}{\cos^2(x)} - \sin(x) = \frac{\sin(x)}{\cos^2(x)} = \operatorname{tg}(x) \cdot \sec(x)$$

$$u = \sec(x) \quad du = (\operatorname{tg}(x) \cdot \sec(x)) dx$$

$$I = \left| \frac{u = \sec(x)}{dx = \frac{du}{\operatorname{tg}(x) \sec(x)}} \right| = \int \operatorname{tg}(x) \cdot \frac{du}{\operatorname{tg}(x) \sec(x)} = \int \frac{du}{u} = \ln(u)$$

$$I = \ln(\sec(x)) + C$$

$$I = -\ln(\cos(x)) + C$$

OPTIONAL: $I = \int \frac{\sin(x)}{\cos(x)} dx = \left| \begin{array}{l} u = \cos x \\ du = -\sin x dx \end{array} \right| = \int -\frac{du}{u} = -\ln(u)$

$$I = -\ln(\cos(x)) = \ln|\sec(x)| + C$$

SUBSTITUTION RULE FOR DEFINITE INTEGRALS

$$\int_a^b f(g(x)) g'(x) dx = \int_{g(a)}^{g(b)} f(u) du$$

F - ANTIDERIVATE \int ; $F(g(x))$ is antiderivate of

$$f(g(x))g'(x)$$

$$\int_a^b f(g(x))g'(x)dx = F(g(x)) \Big|_a^b = F(g(b)) - F(g(a))$$

$$\int_{g(a)}^{g(b)} f(u) du = \int_a^b f(g(x))g'(x)dx$$

$u = g(x); du = g'(x)dx$
 $x=a \quad u=g(a)$
 $x=b \quad u=g(b)$

EXAM 7 $\int_0^4 \sqrt{2x+1} dx = \int_1^9 \sqrt{u} \frac{du}{2} = \frac{1}{2} \frac{u^{3/2}}{3/2} \Big|_1^9$

$u = 2x+1;$
 $du = 2dx$
 $x=0; u=1$
 $x=4; u=9$

$$= \frac{1}{3} \left(\sqrt[3]{9^3} - \sqrt[3]{1^3} \right) = \frac{1}{3} (3^3 - 1) = \frac{1}{3} (27-1) = \frac{26}{3}$$

EXAMP 8 $I = \int_1^2 \frac{dx}{(3-5x)^2} = \int_{-2}^{-7} \frac{1}{u^2} \frac{dx}{5} = \int_{-2}^{-7} \frac{du}{5u^2}$

$u = 3-5x$
 $du = -5dx$
 $x=1 \quad u=-2$
 $x=2 \quad u=-7$

$$I = \frac{1}{5} \frac{u^{-2+1}}{-2+1} \Big|_{-2}^{-7} = -\frac{1}{5} \frac{1}{u} \Big|_{-2}^{-7} = \frac{1}{5} \left(\frac{1}{-7} - \frac{1}{-2} \right) = \frac{1}{5} \left(\frac{1}{2} - \frac{1}{7} \right)$$

$$I = \frac{1}{5} \frac{7-2}{14} = \frac{1}{5} \frac{5}{14} = \frac{1}{14}$$

EXAMP 9 $\int_1^e \frac{e^{\ln x}}{x} dx = \int_0^1 u du = \frac{u^2}{2} \Big|_0^1 = \frac{1}{2}$

$u = \ln x$
 $du = \frac{1}{x} dx$
 $x=1 \quad u = \ln 1 = 0$
 $x=e \quad u = \ln e = 1$

SYMMETRY

$f(-x) = f(x)$ even $\Rightarrow \int_{-a}^a f(x) dx = 2 \int_0^a f(x) dx$
 $f(-x) = -f(x)$ odd $\Rightarrow \int_{-a}^a f(x) dx = 0$

$$I = \int_{-a}^a f(x) dx = \int_{-a}^0 f(x) dx + \int_0^a f(x) dx$$

I_1

$$I_1 = \int_a^0 f(-u) du = - \int_a^0 f(-u) du = \int_0^a f(-u) du$$

$x = -u$
 $dx = -du$
 $x = -a \quad u = a$
 $x = 0 \quad u = 0$

even: $f(-u) = f(u) \Rightarrow I = 2 \int_0^a f(x) dx$

odd: $f(-u) = -f(u) \Rightarrow I = 0$

EXAMPLE 10 $f(x) = x^6 + 1$ $f(-x) = (-x)^6 + 1 = x^6 + 1 = f(x)$

$$\int_{-2}^2 (x^6 + 1) dx = 2 \int_0^2 (x^6 + 1) dx = 2 \left(\frac{x^7}{7} + x \right) \Big|_0^2 = 2 \left(\frac{128}{7} + \frac{14}{7} \right) = \frac{142}{7} \cdot 2 = \frac{284}{7}$$

EXAMPLE 11

$$f(x) = \frac{tg(x)}{1+x^2+x^4} \quad \text{odd}$$

$$\int_{-\pi/2}^{\pi/2} f(x) dx = 0$$

EXERCISES

$$(1) \int \cos 3x dx = \left| \begin{array}{l} u = 3x \\ du = 3 dx \end{array} \right| = \int \cos u \frac{du}{3} = \frac{1}{3} \sin u = \frac{1}{3} \sin 3x + C$$

$$(2) \int x(4+x^2)^{10} dx = \left| \begin{array}{l} u = 4+x^2 \\ du = 2x dx \end{array} \right| = \frac{1}{2} \int u^{10} du = \frac{1}{2} \frac{u^{11}}{11} = \frac{1}{22} (4+x^2)^{11} + C$$

$$(3) \int \frac{\sin \sqrt{x}}{\sqrt{x}} dx = \left| \begin{array}{l} u = \sqrt{x} \\ du = \frac{1}{2} x^{-1/2} dx \\ du = \frac{dx}{2\sqrt{x}} \end{array} \right| = 2 \int \sin u du = -2 \cos \sqrt{x} + C$$

$$(6) \int e^{\sin \theta} \cos \theta d\theta = \left| \begin{array}{l} u = \sin \theta \\ du = \cos \theta d\theta \end{array} \right| = \int e^u du = e^u = e^{\sin \theta} + C$$

$$(7) \int 2x(x^2+3)^4 dx = \left| \begin{array}{l} u = x^2+3 \\ du = 2x dx \end{array} \right| = \int u^4 du = \frac{1}{5} u^5 = \frac{1}{5} (x^2+3)^5 + C$$

$$(11) \int \frac{1+4x}{\sqrt{1+x+2x^2}} dx = \left| \begin{array}{l} u = 1+x+2x^2 \\ du = (1+4x) dx \end{array} \right| = \int \frac{du}{\sqrt{u}} = \frac{u^{-1/2+1}}{-1/2+1} =$$

$$= 2 \sqrt{1+x+2x^2}$$

$$(18) \int y^3 \sqrt{2y^4-1} dy = \left| \begin{array}{l} 2y^4-1 = u \\ 8y^3 dy = du \end{array} \right| = \int \sqrt{u} \frac{du}{8} = \frac{1}{12} (2y^4-1)^{3/2} + C$$

$$(21) \int \frac{\ln^2 x}{x} dx = \left| \begin{array}{l} u = \ln x \\ du = \frac{dx}{x} \end{array} \right| = \int u^2 du = \frac{1}{3} u^3 = \frac{1}{3} \ln^3 x + C$$

$$(27) \int e^x \sqrt{1+e^x} dx = \left| \begin{array}{l} u = 1+e^x \\ du = e^x dx \end{array} \right| = \int \sqrt{u} du = \frac{2}{3} (1+e^x)^{3/2} + C$$

$$(30) \int \frac{ax+b}{\sqrt{ax^2+2bx+c}} dx = \left| \begin{array}{l} u = ax^2+2bx+c \\ du = 2ax+2b dx \\ \frac{du}{2} = (ax+b) dx \end{array} \right| = \frac{1}{2} \int \frac{du}{\sqrt{u}} =$$

$$= \frac{1}{2} \frac{(ax^2+2bx+c)^{1/2}}{1/2} = \sqrt{ax^2+2bx+c} + C$$

$$(33) \int \sqrt{\cot x} \sec^2 x dx = \left| \begin{array}{l} u = \cot x \\ du = \frac{1}{\cos^2 x} dx \\ du = \sec^2 x dx \end{array} \right| = \int \frac{du}{\sqrt{u}} = \frac{u^{-1/2+1}}{-1/2+1} =$$

$$= 2 \sqrt{u} = 2 \sqrt{\cot x}$$

$$I = \int \sqrt{\cot x} \csc^2 x dx = \left| \begin{array}{l} u = \cot x \\ du = \frac{-\sin x \cdot \sin x - \cos x \cdot \cos x}{\sin^2 x} dx \\ du = -\frac{1}{\sin^2 x} dx \\ du = -\csc^2 x dx \end{array} \right|$$

$$I = - \int \sqrt{u} du = -\frac{2}{3} u^{3/2} = -\frac{2}{3} \sqrt{\cot^3 x} + C$$

$$(34) \int \frac{\cos(\pi/x)}{x^2} dx = \left| \begin{array}{l} u = \frac{\pi}{x} \\ du = -\frac{\pi}{x^2} dx \end{array} \right| = - \int \frac{1}{\pi} \cos u du = -\frac{1}{\pi} \sin\left(\frac{\pi}{x}\right) + C$$

$$(35) I = \int \cot(x) dx \quad \left(\frac{1}{\sin x}\right)' = (-1) \frac{1}{\sin^2 x} + \cos(x) = -\cot(x) \cdot \csc(x)$$

$$u = \frac{1}{\sin x} \quad ; \quad du = -\cot(x) \cdot \frac{dx}{\sin x} \quad du = -u \cdot \cot(x) dx$$

$$\cot(x) dx = -\frac{du}{u}$$

$$I = -\int \frac{du}{u} = -\ln(u) = -\ln\left|\frac{1}{\sin x}\right| = +\ln|\sin x| + C = -\ln|\csc(x)| + C$$

$$(36) \int \frac{\sin x}{1 + \cos^2 x} dx = \left| \begin{array}{l} u = 1 + \cos^2 x \\ du = -2\cos x \sin x dx \end{array} \right|$$

$$u = \cos x; \quad du = -\sin x dx$$

$$-\int \frac{du}{1+u^2} = -\arctan(u) = -\arctan(\cos x) + C$$

$$(37) I = \int \sec^3 x \tan x dx \quad \left(\frac{1}{\cos x}\right)' = \frac{\sin x}{\cos^2 x} = \tan x \sec(x)$$

$$u = \frac{1}{\cos x}; \quad du = \tan x \sec(x) dx$$

$$I = \int u^2 du = \frac{1}{3} u^3 = \frac{1}{3} \sec^3(x) + C$$

$$(38) I = \int (x^3+1)^{\frac{1}{3}} x^5 dx = \int \sqrt[3]{x^3(x^3+1)} x^4 dx = \int \sqrt[3]{x^6(x^3+1)} x^2 dx$$

$$u = (x^3+1)^{\frac{1}{3}} \quad du = \frac{1}{3} (x^3+1)^{-\frac{2}{3}} \cdot 2x^2 dx$$

$$u = x^3+1 \quad du = 3x^2 dx$$

$$I = \int \sqrt[3]{x^6(x^3+1)} x^2 dx; \quad u = x^3; \quad \begin{array}{l} du = 3x^2 dx \\ \frac{du}{3} = x^2 dx \end{array}$$

$$I = \frac{1}{3} \int \sqrt[3]{u^3(u+1)} du = \frac{1}{3} \int u \sqrt[3]{u+1} du$$

$$u = x^3+1 \quad du = 3x^2 dx \quad \boxed{x^3 = u-1}$$

$$I = \int \sqrt[3]{u} \cdot \frac{x^3}{u-1} \cdot \frac{du}{3} = \frac{1}{3} \int \sqrt[3]{u} (u-1) du =$$

$$= \frac{1}{3} \int u^{4/3} du - \frac{1}{3} \int u^{1/3} du = \frac{1}{3} \frac{u^{7/3}}{7/3} - \frac{1}{3} \frac{u^{4/3}}{4/3}$$

$$I = \frac{4}{7} (x^3+1)^{7/3} - \frac{1}{4} (x^3+1)^{4/3} + C$$

$$(39) \int x^a \sqrt{b+cx^{a+1}} dx = \left| \begin{array}{l} u = b+cx^{a+1} \\ du = c(a+1)x^a dx \\ x^a dx = \frac{du}{c(a+1)} \end{array} \right| =$$

$$= \frac{1}{c(a+1)} \int \sqrt{u} du = \frac{1}{c(a+1)} \frac{2}{3} (b+cx^{a+1})^{3/2} + C$$

$$\textcircled{40} \int \sin t \sec^2(\cos t) dt = \left| \begin{array}{l} u = \cos t \\ du = -\sin t dt \end{array} \right| = -\int \sec^2(u) du$$

$$= -\operatorname{tg} u = -\operatorname{tg}(\cos t)$$

$$\textcircled{41} I = \int \frac{1+x^2}{1+x^2} dx = \int \frac{dx}{1+x^2} + \int \frac{x dx}{1+x^2} = I_1 + I_2$$

$$y = \operatorname{arctg} x \quad x = \operatorname{tg} y \quad dx = (1 + \operatorname{tg}^2 y) dy \quad dy = \frac{dx}{1+x^2}$$

$$I_1 = \int dy = y + C = \operatorname{arctg} x + C$$

$$I_2 = \left| \begin{array}{l} u = x^2 + 1 \\ du = 2x dx \\ x dx = \frac{du}{2} \end{array} \right| = \frac{1}{2} \int \frac{du}{u} = \frac{1}{2} \ln u = \frac{1}{2} \ln(x^2 + 1)$$

$$I = I_1 + I_2 = \operatorname{arctg}(x) + \frac{1}{2} \ln(x^2 + 1) + C$$

$$\textcircled{42} \int \frac{x}{1+x^4} dx = I \quad \begin{array}{l} 1+x^4 = u^4 \\ 4x^3 dx = 4u^3 du \\ x^3 dx = u^3 du \\ x = \sqrt[4]{1+u^4} \end{array}$$

$$= \int \frac{u^3}{1+u^4} du = \frac{1}{2} \int \frac{du}{1+u^2} = \frac{1}{2} \operatorname{arctg}(u) = \frac{1}{2} \operatorname{arctg}(x^2) + C$$

$$\textcircled{43} I = \int \frac{x}{\sqrt[4]{x+2}} dx = \left| \begin{array}{l} u = x+2 \\ du = dx \\ x = u-2 \end{array} \right| = \int \frac{u-2}{\sqrt[4]{u}} du = \int u^{-1/4} du - 2 \int u^{-1/4} du$$

$$I = \int u^{3/4} du - 2 \int u^{-1/4} du = \frac{u^{3/4+1}}{3/4+1} - 2 \frac{u^{-1/4+1}}{-1/4+1} = \frac{4}{7} u^{7/4} - 2 \frac{4}{3} u^{3/4}$$

$$I = \frac{4}{7} (x+2)^{7/4} - \frac{8}{3} (x+2)^{3/4}$$

$$\textcircled{44} I = \int \frac{x^2}{\sqrt{1-x}} dx = \left| \begin{array}{l} u = 1-x \\ du = -dx \\ x = 1-u \end{array} \right| = \int \frac{(1-u)^2}{\sqrt{u}} du = \int \frac{du}{\sqrt{u}} - \int \frac{2u du}{\sqrt{u}} + \int \frac{u^2 du}{\sqrt{u}}$$

$$I = \frac{u^{-1/2+1}}{-1/2+1} - 2 \int \sqrt{u} du + \int u^{2-1/2} du = 2\sqrt{u} - 2 \frac{u^{3/2}}{3/2} + \frac{u^{5/2+1}}{5/2+1}$$

$$I = 2\sqrt{u} - \frac{4}{3} u^{3/2} + \frac{2}{5} u^{5/2} = 2\sqrt{1-x} - \frac{4}{3} (1-x)^{3/2} + \frac{2}{5} (1-x)^{5/2} + C$$

$$\textcircled{45} I = \int \frac{3x-1}{(3x^2-2x+1)^4} dx = \left| \begin{array}{l} u = 3x^2-2x+1 \\ du = (6x-2) dx \\ du/2 = (3x-1) dx \end{array} \right| = \frac{1}{2} \int \frac{du}{u^4} = \frac{1}{2} \frac{u^{-4+1}}{-4+1}$$

$$I = -\frac{1}{6} u^{-3} = -\frac{1}{6} \frac{1}{(3x^2-2x+1)^3}$$

$$\textcircled{46} I = \int \frac{x}{\sqrt{x^2+1}} dx = \left| \begin{array}{l} u = x^2+1 \\ du = 2x dx \\ x dx = \frac{du}{2} \end{array} \right| = \frac{1}{2} \int \frac{du}{\sqrt{u}} = \frac{1}{2} \frac{u^{1/2+1}}{1/2+1} = \sqrt{u}$$

$$I = \sqrt{x^2+1} + C$$

$$g(x) = \sqrt{x^2+1}$$

$$g'(x) = \frac{x}{\sqrt{x^2+1}}$$

$$f(\sqrt{x^2+1}) = \frac{1}{2} (x^2+1)^{1/2-1} \cdot 2x$$

$$= \frac{x}{\sqrt{x^2+1}}$$

$$(47) I = \int \sin^3 x \cos x dx = \left| \begin{array}{l} u = \cos x \\ du = -\sin x dx \\ m = \sin x \\ dm = \cos x dx \end{array} \right|$$

$$I = \int u^3 du = \frac{1}{4} u^4 = \frac{1}{4} \sin^4(x) + C$$

$$(48) I = \int \tan^2 \theta \sec^2 \theta d\theta = \left| \begin{array}{l} u = \tan \theta \\ du = \sec^2 \theta d\theta \end{array} \right| = \int u^2 du = \frac{1}{3} u^3$$

$$I = \frac{1}{3} \tan^3 \theta + C$$

$$(53) I = \int_0^{\pi/4} \sec^2(t/4) dt = \left| \begin{array}{l} u = t/4 \\ du = dt \\ t=0 \quad u=0 \\ t=\pi \quad u=\pi/4 \end{array} \right| = 4 \int_0^{\pi/4} \sec^2(u) du = 4 \tan u \Big|_0^{\pi/4}$$

$$I = 4 \left(\tan \frac{\pi}{4} - \tan 0 \right) = 4(1 - 0) = 4$$

$$(54) I = \int_{\pi/6}^{\pi/2} \csc(\pi t) \cot(\pi t) dt = \int_{\pi/6}^{\pi/2} \frac{1}{\sin(\pi t)} \frac{\cos(\pi t)}{\sin(\pi t)} dt = \left| \begin{array}{l} u = \sin(\pi t) \\ du = \pi \cos(\pi t) dt \\ \frac{du}{\pi} = \cos(\pi t) dt \\ t = \pi/6 \quad u = \sin(\pi/6) = 1/2 \\ t = \pi/2 \quad u = \sin(\pi/2) = 1 \end{array} \right|$$

$$I = \frac{1}{\pi} \int_{0.5}^1 \frac{du}{u^2} = \frac{1}{\pi} \left. \frac{u^{-2+1}}{-2+1} \right|_{0.5}^1 = -\frac{1}{\pi} \frac{1}{u} \Big|_{0.5}^1$$

$$I = -\frac{1}{\pi} (1 - 2) = \frac{1}{\pi}$$

$$(59) I = \int_{\sqrt{3}/2}^{\pi/6} \tan^3 \theta d\theta = \int_{-\pi/6}^{\pi/6} \frac{\sin^3 \theta}{\cos^3 \theta} d\theta = \left| \begin{array}{l} u = \cos \theta \\ du = -\sin \theta d\theta \\ \theta = -\pi/6 \quad u = -\sqrt{3}/2 \\ \theta = \pi/6 \quad u = \sqrt{3}/2 \end{array} \right|$$

$$= - \int_{-\sqrt{3}/2}^{\sqrt{3}/2} \frac{\sin^2 \theta}{u^3} du = - \int_{-\sqrt{3}/2}^{\sqrt{3}/2} \frac{1-u^2}{u^3} du = \int_{-\sqrt{3}/2}^{\sqrt{3}/2} \left(\frac{1}{u} - \frac{1}{u^3} \right) du = \left(\ln|u| - \frac{u^{-3+1}}{-3+1} \right) \Big|_{-\sqrt{3}/2}^{\sqrt{3}/2}$$

$$= \left(\ln|u| + \frac{1}{2u^2} \right) \Big|_{-\sqrt{3}/2}^{\sqrt{3}/2} = \ln\left(\frac{\sqrt{3}}{2}\right) + \frac{1}{2 \cdot \frac{3}{4}} - \ln\left(\frac{\sqrt{3}}{2}\right) - \frac{1}{2 \cdot \frac{3}{4}} = 0$$

$$\frac{1}{2} \tan^2(x) - \frac{1}{2} \ln \left(\frac{\cos^2 x + \sin^2 x}{\cos^2 x} \right) = \frac{1}{2} \frac{\sin^2 x}{\cos^2 x} - \frac{1}{2} (\ln 1 + 2 \ln(\cos x))$$

$$= \frac{1}{2} \left(\frac{1 - \cos^2 x}{\cos^2 x} \right) + \ln(\cos x) = \frac{1}{2} \frac{1}{\cos^2 x} - \frac{1}{2} + \ln(\cos x)$$

$$\ln \left(\frac{1}{\cos^2 x} \right) = -2 \ln(\cos(x)) = \left| x = \frac{\pi}{6} \right| = -2 \ln \frac{\sqrt{3}}{2} =$$

$$= \ln \left(\frac{\sqrt{3}}{2} \right)^{-2} = \ln \left(\frac{2}{\sqrt{3}} \right)^2 = \ln \frac{4}{3}$$

$$(57) \int_1^2 \frac{e^{1/x}}{x^2} dx = \left| \begin{array}{l} u = \frac{1}{x} \\ du = (-1)x^{-2} dx \\ du = -\frac{1}{x^2} dx \\ x=2 \quad u=1/2 \\ x=1 \quad u=1 \end{array} \right| = - \int_1^{1/2} e^u du = \int_{1/2}^1 e^u du = e - \frac{1}{2} e$$

$$(58) \int_0^1 x e^{-x^2} dx = \left| \begin{array}{l} u = -x^2 \quad x=0 \quad u=0 \\ du = -2x dx \quad +=1 \quad u=1 \\ -\frac{du}{2} = x dx \end{array} \right| = -\frac{1}{2} \int_0^{-1} e^u du = \frac{1}{2} \int_{-1}^0 e^u du = \frac{1}{2} (e^0 - e^{-1}) = \frac{1}{2} (1 - \frac{1}{e})$$

$$(59) I = \int_{-\pi/2}^{\pi/2} \frac{x^2 \sin x}{1+x^2} dx \quad y = \arctan x \quad y' = \frac{1}{1+x^2}$$

$$y = \arcsin x \quad x = \sin y \quad dx = \cos y dy; \quad dx = \sqrt{1-\sin^2 y} dy \quad dy = \frac{dx}{\sqrt{1-x^2}}$$

$$\int \frac{dx}{\sqrt{1-x^2}} = \arcsin(x) \quad x = \sin y^2; \quad dx = +\cos(y^2) \cdot 2y \cdot dy =$$

$$x = \cos^2(y) \quad dx = 2 \cos^2 y \cdot (-\sin y) dy = -2 \sqrt{x} \sqrt{1-x} dy$$

$$\cos y = \sqrt{x}$$

$$1 - \sin^2 y = x \quad \sin^2 y = 1-x$$

$$\sin y = \sqrt{1-x}$$

$$\rightarrow y = \arccos(\sqrt{x})$$

$$dy = \frac{-1}{2} \frac{dx}{\sqrt{x-x^2}}$$

$$x^2 = \cos^2 u \quad 2x dx = -\sin u du$$

$$x^3 = \cos^3 u \quad 3x^2 dx = -\sin u du; \quad x^2 = \cos u = \sqrt{1-\sin^2 u}$$

$$x^2 = \sqrt{1-\sin^2(u)} \quad x^4 = 1-\sin^2(u) \quad \sin^2 u = 1-x^4 \quad \sin u = \sqrt{1-x^4}$$

$$y_1 = \frac{x^2}{1+x^6} \rightarrow \text{even function} \quad y_2(x) = \sin(x) - \text{odd function}$$

$$y = y_1(x) \cdot y_2(x) \rightarrow \text{odd function}; \quad \int_{-\pi/2}^{\pi/2} y(x) dx = 0$$

$$(61) \int_0^{23} \frac{dx}{\sqrt{(1+2x)^2}} = \left| \begin{array}{l} u = 1+2x \\ du = 2 dx \\ x=0 \quad u=1 \\ x=11 \quad u=23 \end{array} \right| = \frac{1}{2} \int_1^{23} \frac{du}{u^{3/2}} = \frac{1}{2} \left[\frac{u^{-1/2+1}}{-1/2+1} \right]_1^{23} = \frac{3}{2} \left[\sqrt{u} \right]_1^{23}$$

$$I = \frac{3}{2} (\sqrt{23} - 1) = 2.7658$$

$$(62) I = \int_1^2 x \sqrt{x-1} dx = \left| \begin{array}{l} u = x-1 \\ du = dx \\ x = u+1 \\ x=1 \quad u=0 \\ x=2 \quad u=1 \end{array} \right| = \int_0^1 (u+1) \sqrt{u} du = \int_0^1 (u^{3/2} + u^{1/2}) du$$

$$I = \left(\frac{2}{5} u^{5/2} + \frac{2}{3} u^{3/2} \right) \Big|_0^1 = \frac{2}{5} + \frac{2}{3} = \frac{6+10}{15} = \frac{16}{15}$$

$$(63) I = \int_e^4 \frac{dx}{x \sqrt{\ln x}} = \left| \begin{array}{l} u = \ln x \\ du = \frac{dx}{x} \\ x=e^4, u=4 \\ x=e, u=1 \end{array} \right| = \int_1^4 \frac{du}{\sqrt{u}} = 2 \sqrt{u} \Big|_1^4$$

$$I = 2 (\sqrt{4} - 1) = 2 \cdot 1 = 2$$

(66) $I = \int_0^{1/2} \frac{\arcsin(x)}{\sqrt{1-x^2}} dx$, $u = \arcsin(x)$, $dx = +\cos u du$
 $x = \sin u$, $dx = \sqrt{1-\sin^2 u} du$
 $dx = \sqrt{1-x^2} du$, $du = \frac{dx}{\sqrt{1-x^2}}$
 $x=0$; $u=0$
 $x=1/2$; $u=\frac{\pi}{6}$

$$I = \int_0^{\pi/6} u du = \frac{1}{2} u^2 \Big|_0^{\pi/6} = \frac{1}{2} \left(\frac{\pi^2}{36} - 0 \right) = \frac{\pi^2}{72}$$

(68) $\int_0^a x \sqrt{a^2-x^2} dx = \left| \begin{array}{l} u = a^2-x^2 \\ du = -2x dx \\ x dx = -du/2 \end{array} \right|_{x=0}^{x=a} = \frac{1}{2} \int_0^{a^2} \sqrt{u} du$

~~$I = \frac{1}{3} \sqrt{a^2-x^2} - \frac{2}{3} x \sqrt{a^2-x^2} + \frac{2}{3} \int \frac{1}{\sqrt{a^2-x^2}} dx$~~ $I = \frac{1}{7} \frac{u^{3/2}}{3/2} = \frac{1}{3} a^{2 \cdot \frac{3}{2}} = \frac{1}{3} a^3$

(71) $y = \sqrt{2x+1}$, $0 \leq x \leq 1$, $P_1 \approx \frac{1 \cdot (\sqrt{1+1}) - 1}{2} = \frac{1}{2} \sqrt{2+1} = \frac{\sqrt{3}-1}{2}$

$P_2 = 1 \cdot 1 = 1$, $P = P_1 + P_2 = \frac{1}{2} + \frac{\sqrt{3}}{2} \approx 1.4$

(72) $y = 2 \cdot \sin(x) - \sin(2x)$, $0 \leq x \leq \pi$

$\int_0^{\pi} \sin(x) dx = 2$, $P = 2 \cdot 2 - 0 = 4$

(73) $\int_{-2}^2 (x+3) \sqrt{4-x^2} dx = \int_{-2}^2 x \sqrt{4-x^2} dx + \int_{-2}^2 3 \sqrt{4-x^2} dx$
 I_1 I_2

$I_1 = \left| \begin{array}{l} 4-x^2 = u \\ du = -2x dx \\ x = -2, u=0 \\ x = 2, u=0 \end{array} \right| = -\frac{1}{2} \int \sqrt{u} du = -\frac{1}{2} \frac{u^{3/2}}{3/2} = -\frac{1}{3} u^{3/2}$

$I_1 = -\frac{1}{3} \sqrt{(4-x^2)^3} \Big|_{-2}^2 = -\frac{1}{3} \left(\sqrt{(4-2^2)^3} - \sqrt{(4-2^2)^3} \right) = 0$

$I_2 = 3 \int_{-2}^2 \sqrt{4-x^2} dx = \left| \begin{array}{l} u = 4-x^2 \\ du = -2x dx \\ dx = \frac{du}{-2x} \\ x^2 = 4-u \\ x = \sqrt{4-u} \end{array} \right|$

$I_2 = -3 \int_0^2 \frac{\sqrt{u}}{\sqrt{4-u}} du = -3 \int_0^2 \sqrt{\frac{u}{4-u}} du = 0$

$I_2 = 3 \int_{-2}^2 \sqrt{4-x^2} dx = 3 \cdot 2 \int_0^2 \sqrt{(2-x)(2+x)} dx = \left| \begin{array}{l} u = 2+x \\ du = dx \\ x = u-2 \\ x=0, u=2 \\ x=2, u=4 \end{array} \right|$

$= 6 \int_0^4 \sqrt{(2-u+2)u} du = \int_0^4 \sqrt{(4-u)u} du$

$$I_2 = \int \sqrt{4-x^2} dx = \left| \begin{array}{l} x=2\sin u \\ dx=2\cos u du \end{array} \right| = \int (\sqrt{4-4\sin^2 u}) 2\cos u du$$

$$I_2 = \int \sqrt{4(1-\sin^2 u)} 2\cos u du = \int 2\cos u \cdot 2\cos u du = 4 \int \cos^2 u du$$

$$I_2 = \left| \begin{array}{l} x=-2 \quad -2=2\sin u; u=-\frac{\pi}{2} \\ x=2 \quad 2=2\sin u; u=\frac{\pi}{2} \end{array} \right| = 4 \int_{-\pi/2}^{\pi/2} \cos^2 u du = 8 \int_0^{\pi/2} \cos^2 u du$$

$$I_2 = 8 \int_0^{\pi/2} \cos u d(\sin u) = \left| \begin{array}{l} u = \sin u \\ du = +\cos u du \\ u=0 \quad u=0 \\ u=\pi/2 \quad u=1 \end{array} \right| = 8 \int_0^1 \sqrt{1-u^2} du$$

$$\begin{aligned} 4-x^2 &= 4\sin^2 u; & -x dx &= \sqrt{\cos u} du \\ x^2 &= 4-4\sin^2 u & dx &= -\frac{4\sin u \cos u}{\sqrt{4-4\sin^2 u}} du \\ x &= \sqrt{4-4\sin^2 u} \end{aligned}$$

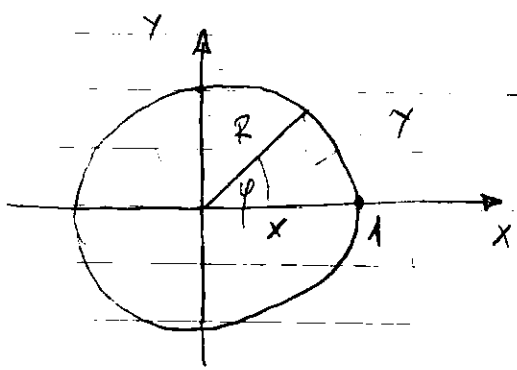
$$I_2 = -\int 2\sin u \frac{4\sin u \cos u}{2\sqrt{1-\sin^2 u}} du = -4 \int \frac{\sin^2 u}{\sqrt{1-\sin^2 u}} d(\sin u)$$

$$I_2 = -4 \int \frac{z^2}{\sqrt{1-z^2}} dz = \left| \begin{array}{l} z = \sin u \\ dz = \cos u du \\ z=0 \quad u=0 \\ z=1 \quad u=\pi/2 \end{array} \right| = -4 \int_0^{\pi/2} \sin^2 u du$$

$$y^2 = 4-x^2 \quad x^2+y^2=4 \quad R=2$$

$$I_2 = 3 \int_{-2}^2 \sqrt{4-x^2} dx = 3 \cdot \left(\frac{R^2 \pi}{2} \right) = 3 \cdot \frac{4 \cdot \pi}{2} = 6\pi$$

$$\textcircled{74} \int_0^1 x \sqrt{1-x^4} dx = \left| \begin{array}{l} u = x^2 \\ du = 2x dx \\ x=0 \quad u=0 \\ x=1 \quad u=1 \end{array} \right| = \frac{1}{2} \int_0^1 \sqrt{1-u^2} du = \frac{1}{2} \left(\frac{R^2 \pi}{4} \right) = \frac{\pi}{8}$$



$$x^2 + y^2 = 1$$

$$y = \sqrt{1 - x^2}$$

$$P = 2 \int_{-1}^1 \sqrt{1 - x^2} dx$$

$$R=1 \quad \sin \varphi = y; \quad \cos \varphi = x; \quad dx = -\sin \varphi d\varphi$$

$$P = -2 \int_0^{\pi} \sqrt{1 - \cos^2 \varphi} \sin \varphi d\varphi$$

$$P = 2^2 \pi = \pi \quad \frac{y}{R} = \sin \varphi \quad y = R \sin \varphi$$

$$\frac{P}{2} = \int_0^{\pi} R \sin \varphi d\varphi = -R \cos \varphi \Big|_0^{\pi} = -R (\cos \pi - \cos 0) = 2R$$

$$\sin \varphi = \frac{y}{R}, \quad y = \sqrt{R^2 - x^2}, \quad \sin \varphi = \frac{1}{R} \sqrt{R^2 - x^2}$$

$$I = \int \sqrt{R^2 - x^2} dx$$

$$\cos \varphi d\varphi = -\frac{1}{R} (R^2 - x^2)^{\frac{1}{2} - 1} \cdot (-2x) dx$$

$$\cos \varphi d\varphi = \frac{1}{R} \frac{x}{\sqrt{R^2 - x^2}} dx; \quad y = R \cdot \sin \varphi$$

$$R \sin \varphi = \sqrt{R^2 - x^2}$$

$$R \cos \varphi d\varphi = \frac{x}{\sqrt{R^2 - x^2}} dx$$

$$R \cos \varphi d\varphi = \frac{x}{R \sin \varphi} dx; \quad x^2 = -R^2 \sin^2 \varphi + R^2 \Rightarrow x = \sqrt{R^2(1 - \sin^2 \varphi)}$$

$$R \cos \varphi \sin \varphi d\varphi = R \sqrt{1 - \sin^2 \varphi} dx$$

$$dx = \frac{R \cos \varphi \sin \varphi}{R \sqrt{1 - \sin^2 \varphi}} d\varphi$$

$$I = \int R \sin \varphi \frac{R \cos \varphi \sin \varphi}{R \sqrt{1 - \sin^2 \varphi}} d\varphi = R^2 \int \frac{\sin^2 \varphi \cos \varphi}{\sqrt{1 - \sin^2 \varphi}} d\varphi$$

$$I = \left| \begin{array}{l} u = \sin \varphi \\ du = \cos \varphi d\varphi \end{array} \right| = R^2 \int \frac{u^2}{\sqrt{1 - u^2}} du = \left| \begin{array}{l} u = \arcsin(u) \\ \sin u = u \\ du = \frac{du}{\sqrt{1 - u^2}} \end{array} \right|$$

$$I = R^2 \int \sin^2 u du$$

$$\cos(u+v) = \cos u \cdot \cos v - \sin u \cdot \sin v$$

$$\cos(2u) = \cos^2 u - \sin^2 u =$$

$$= 1 - \sin^2 u - \sin^2 u = 1 - 2 \sin^2 u$$

$$\cos(2\theta) = 1 - 2\sin^2\theta \quad \sin^2\theta = \frac{1}{2}(1 - \cos 2\theta)$$

$$I = R^2 \int \sin^2\theta d\theta = R^2 \int \frac{1}{2}(1 - \cos 2\theta) d\theta = \frac{R^2}{2} \left(\theta - \underbrace{\int \cos(2\theta) d\theta}_{I^*} \right)$$

$$I^* = \int \cos(2\theta) d\theta = \left| \begin{matrix} w = 2\theta \\ dw = 2 d\theta \end{matrix} \right| = \frac{1}{2} \int \cos(w) dw = \frac{1}{2} \cos w$$

$$I^* = \frac{1}{2} \cos(2\theta); \quad I = \frac{R^2}{2} \left[\theta - \frac{1}{2} \cos(2\theta) \right]$$

$$I = \int \sqrt{R^2 - x^2} dx, \quad x = R \cdot \sin(u), \quad \sin(u) = \frac{x}{R}$$

$$u = \arcsin\left(\frac{x}{R}\right); \quad dx = R \cdot \cos u du;$$

$$I = \int \sqrt{R^2 - R^2 \sin^2 u} \cdot R \cdot \cos u du = R^2 \int \cos^2 u du$$

$$\cos(2u) = \cos(u+u) = \cos^2 u - \sin^2 u = \underline{2\cos^2 u - 1}$$

$$\cos^2 u = \frac{1}{2}(1 + \cos(2u))$$

$$I = R^2 \int \frac{1}{2}(1 + \cos(2u)) du = \frac{R^2}{2} \left[u + \frac{1}{2} \sin(2u) \right]$$

$$I = \frac{R^2}{2} \left[\arcsin\left(\frac{x}{R}\right) + \frac{1}{2} \sin\left(2 \cdot \arcsin\left(\frac{x}{R}\right)\right) \right]$$

~~$$I = \int \sqrt{R^2 - x^2} dx$$~~

$$(*) = \sin\left(2 \cdot \arcsin\left(\frac{x}{R}\right)\right) = \sin(2u) = \cos u \sin u + \sin u \cos u = 2 \sin u \cos u = 2 \cdot \frac{x}{R} \cdot \sqrt{1 - \sin^2 u}$$

$$= 2 \cdot \frac{x}{R} \cdot \sqrt{1 - \frac{x^2}{R^2}} = \frac{2x}{R^2} \sqrt{R^2 - x^2}$$

$$= 2 \cdot \frac{x}{R} \sqrt{1 - \frac{x^2}{R^2}} = \frac{2x}{R^2} \sqrt{R^2 - x^2}$$

$$I = \frac{R^2}{2} \left[\arcsin\left(\frac{x}{R}\right) + \frac{1}{2} \cdot \frac{2x}{R^2} \sqrt{R^2 - x^2} \right]$$

$$I = \frac{x}{2} \sqrt{R^2 - x^2} + \frac{R^2}{2} \arcsin\left(\frac{x}{R}\right)$$

$$\text{ex: } \int \sqrt{4 - x^2} dx = \left| R=2 \right| = \frac{x}{2} \sqrt{4 - x^2} + 2 \arcsin\left(\frac{x}{2}\right)$$

$$\int_{-2}^2 \sqrt{4 - x^2} dx = \frac{2}{2} \sqrt{4 - 4} + 2 \arcsin(1) + \frac{2}{2} \sqrt{4 - 4} - 2 \arcsin(-1)$$

$$= 2 \cdot \frac{\pi}{2} - 2 \left(-\frac{\pi}{2}\right) = \pi + \pi = 2\pi$$

(75) $y = e^{\sqrt{x}}$; $x=0 \rightarrow 1$; $y = 2xe^x$ $x=0 \rightarrow 1$; $y = e^{\sin x} \sin 2x$; $x=0 \rightarrow \pi/2$

(a) $I_1 = \int_0^1 e^{\sqrt{x}} dx = \left| \begin{array}{l} u = \sqrt{x} \quad x=0 \quad u=0 \\ \frac{du}{dx} = \frac{1}{2\sqrt{x}} \quad x=1 \quad u=1 \\ dx = +2u du \end{array} \right| = \int_0^1 e^u \cdot u du$

$\int u du = u \cdot v - \int u dv$

$\int e^u \cdot du = \left| u = \frac{u^2}{2} \right| = \int e^u d\left(\frac{u^2}{2}\right) = \frac{u^2}{2} \cdot e^u - \int \frac{u^2}{2} d(e^u)$

$\int u d(e^u) = u \cdot e^u - \int e^u du = u \cdot e^u - e^u$

$I_1 = +2 \left(u e^u - e^u \right) \Big|_0^1 = \cancel{2} \left(e - 0 - e + 1 \right) = +2$

(b) $y = 2xe^x$ $x=0 \rightarrow 1$

$I_2 = \int_0^1 2xe^x dx = \left| \begin{array}{l} \int u dv = uv - \int u dv \\ u = e^x \end{array} \right| = \int_0^1 2x du =$

$= e^x \cdot 2x \Big|_0^1 - \int_0^1 e^x d(2x) = e^x \cdot 2x \Big|_0^1 - 2e^x \Big|_0^1 = e^2 - 2e^1 + 2 = 2$

(c) $y = e^{\sin x} \sin(2x)$

$I_3 = \int e^{\sin x} \sin(2x) dx$; $I_3 = \int e^{\sin x} 2 \sin x \cos x dx$

$\sin(2x) = 2 \sin x \cos x$; $I_3 = 2 \int e^{\sin x} \sin x d(\sin x) = 2 \int e^y y dy$

$I_3 = 2 \int y e^y dy = 2 \int y d(e^y) = 2 \left(y e^y - \int e^y dy \right) = 2y e^y - 2e^y$

$I_3 = 2 \left[\sin x e^{\sin x} \Big|_0^{\pi/2} - e^{\sin x} \Big|_0^{\pi/2} \right] = 2(1 \cdot e - e + 1) = 2$

(76) $r(t) = 450.268 e^{1.12567t}$ GROW RATE OF BACTERIA PER HOUR

$r(0) = 450.268$

$N_b = 400 + \int_0^3 450.268 e^{1.12567t} dt = 400 + 450.268 \left(e^{1.12567 \cdot 3} - 1 \right) \cdot \frac{1}{1.12567}$

(77) 0.5 L/s - MAXIMUM RATE OF AIR FLOW INTO THE LUNGS □

$f(t) = \frac{1}{2} \sin\left(\frac{2\pi t}{5}\right)$ - RATE OF AIR FLOW

$V(t) = \int_0^t \frac{1}{2} \sin\left(\frac{2\pi t}{5}\right) dt = \frac{1}{2} \int_0^t \sin\left(\frac{2\pi t}{5}\right) dt = \left. \begin{matrix} u = 2\pi t/5 \\ du = \frac{2\pi}{5} dt \end{matrix} \right|_0^t =$

$V(t) = \frac{1}{2} \frac{5}{2\pi} \int_0^t \sin(u) du = -\frac{1}{2} \frac{5}{2\pi} \cos\left(\frac{2\pi t}{5}\right) \Big|_0^t = -\frac{5}{4\pi} \left(\cos\left(\frac{2\pi t}{5}\right) - 1\right)$

$V(t) = \frac{5}{4\pi} \left(1 - \cos\left(\frac{2\pi t}{5}\right)\right)$ [Liters]

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(78) • RATE OF PRODUCTION CALCULATORS

$\frac{dx}{dt} = 5000 \left(1 - \frac{100}{(t+10)^2}\right)$ calculators/week

$x = \int_3^4 5000 \left(1 - \frac{100}{(t+10)^2}\right) dt = \int_3^4 5000 dt - \int_3^4 5000 \frac{100}{(t+10)^2} dt =$
 $= 5000 \cdot 1 - 5 \cdot 10^5 \int_3^4 \frac{dt}{(t+10)^2} = \left. \begin{matrix} u = t+10 \\ du = dt \\ t=3 \Rightarrow u=13 \\ t=4 \Rightarrow u=14 \end{matrix} \right|_3^4 = 5000 - 5 \cdot 10^5 \int_{13}^{14} \frac{du}{u^2} =$
 $= 5000 - 5 \cdot 10^5 \frac{u^{-2+1}}{-2+1} \Big|_{13}^{14} = 5000 + 5 \cdot 10^5 \left(\frac{1}{14} - \frac{1}{13}\right) = 5000 + \frac{5 \cdot 10^5}{14 \cdot 13} \frac{13-14}{14 \cdot 13}$
 $= 5000 - \frac{5 \cdot 10^5}{182} = \frac{205000}{91} = 2252.7473$

(79) $f(x)$ is continuous $\int_0^4 f(x) dx = 10$ $\int_0^2 f(2x) dx = ?$
 $\int_0^2 f(x) dx + \int_2^4 f(x) dx = 10$

$F(4) - F(0) = 10$ $F(0) = -10 + F(4)$

$F(2) - F(0) = ?$ $F(2) - (F(4) - 10) = 10 - F(4) + F(2)$

$I = \int_0^2 f(2x) dx = \left. \begin{matrix} u = 2x \Rightarrow du = 2 dx \\ x=0 \Rightarrow u=0 \\ x=2 \Rightarrow u=4 \end{matrix} \right|_0^2 = \int_0^4 f(u) \frac{du}{2} = \frac{1}{2} \int_0^4 f(u) du$

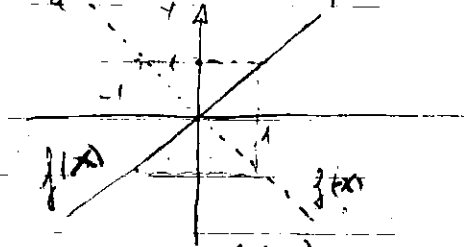
$I = 10/2 = 5$

$$(80) \int_0^3 f(x) dx = 4 \quad I = \int_0^3 x f(x^2) dx = ?$$

$$u = x^2 \quad du = 2x dx \quad x dx = \frac{du}{2}; \quad x=0 \quad u=0; \quad x=3 \quad u=9$$

$$I = \int_0^3 f(x^2) x dx = \frac{1}{2} \int_0^9 f(u) du = \frac{1}{2} \cdot 4 = 2$$

$$(81) \int_a^b f(-x) dx = \left| \begin{array}{l} u = -x \quad x=0 \quad u=-a \\ du = -dx \quad x=b \quad u=-b \end{array} \right| = - \int_{-a}^{-b} f(u) du = \int_{-b}^{-a} f(u) du$$



$$\int_0^1 x dx = \frac{x^2}{2} \Big|_0^1 = \frac{1}{2}$$

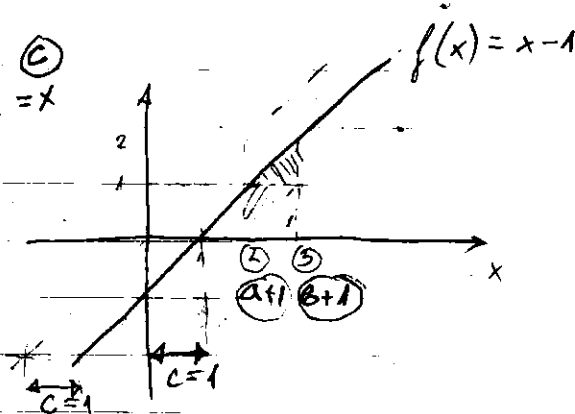
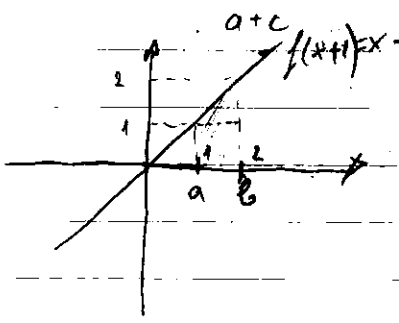
$$\int_{-1}^0 x dx = \frac{x^2}{2} \Big|_{-1}^0 = 0 - \frac{1}{2} = -\frac{1}{2}$$

$$f(x) = x \quad f(-x) = -x$$

$$\int_{-1}^0 f(x) dx = \int_{-1}^0 x dx = \frac{x^2}{2} \Big|_{-1}^0 = 0 - \frac{1}{2} = -\frac{1}{2}$$

$$(82) \int_a^b f(x+c) dx = \int_{a+c}^{b+c} f(x) dx \quad \begin{array}{l} u = x+c \\ du = dx \end{array} \quad \begin{array}{l} x=a \quad u=a+c \\ x=b \quad u=b+c \end{array}$$

$$\int_a^b f(x+c) dx = \int_{a+c}^{b+c} f(u) du$$



$$(83) a, b \geq 0 \quad \int_0^1 x^a (1-x)^b dx = \int_0^1 x^b (1-x)^a dx$$

$$\int_0^1 x^a (1-x)^b dx = \left| \begin{array}{l} u = 1-x \quad du = -dx \\ x = 1-u \\ x=0 \quad u=1; \quad x=1 \quad u=0 \end{array} \right| = - \int_1^0 (1-u)^a \cdot u^b du = \int_0^1 (1-u)^a u^b du$$

$$(84) \quad u = \pi - x \quad I = \int_0^\pi x f(\sin(x)) dx = \int_0^\pi f(\sin(x)) dx$$

$$x = \pi - u$$

$$du = -dx$$

$$x=0; \quad u=\pi$$

$$x=\pi; \quad u=0$$

$$I = - \int_\pi^0 (\pi - u) f(\sin(\pi - u)) du = \int_0^\pi (\pi - u) f(+\sin(u)) du$$

$$I = \pi \int_0^\pi f(\sin(u)) du - \int_0^\pi u f(\sin(u)) du; \quad 2I = \pi \int_0^\pi f(\sin(u)) du$$

$$I = \frac{\pi}{2} \int_0^\pi f(\sin(x)) dx$$

$$(85) \quad M = \pi - x \quad I = \int_0^{\pi} \frac{x \sin x}{1 + \cos^2 x} dx = \left| \begin{array}{l} x = \pi - M \\ t = 0 \quad M = \pi \\ x = \pi \quad M = 0 \\ dM = -dx \end{array} \right| = - \int_{\pi}^0 \frac{(\pi - M) \sin M}{1 + \cos^2(\pi - M)} dM$$

$$I = \int_0^{\pi} \frac{\pi \sin M}{1 + \cos^2 M} dM - \int_0^{\pi} \frac{M \sin M}{1 + \cos^2 M} dM$$

$$2I = \pi \int_0^{\pi} \frac{\sin M}{1 + \cos^2 M} dM \quad I = \frac{\pi}{2} \int_0^{\pi} \frac{-d(\cos M)}{1 + \cos^2 M} = -\frac{\pi}{2} \int_1^{-1} \frac{dz}{1 + z^2}$$

$$\left. \begin{array}{l} z = \cos M \quad dz = -\sin M dM \\ M = 0 \quad z = \cos(0) = 1 \\ M = \pi \quad z = \cos(\pi) = -1 \end{array} \right\} I = -\frac{\pi}{2} \int_{-1}^1 \frac{dz}{1 + z^2} = \frac{\pi}{2} \int_{-1}^1 \frac{dz}{1 + z^2}$$

$$I = \frac{\pi}{2} \operatorname{arctg} z \Big|_{-1}^1 = \frac{\pi}{2} (\operatorname{arctg} 1 - \operatorname{arctg}(-1)) = \frac{\pi}{2} \left(\frac{\pi}{4} + \frac{\pi}{4} \right) = \frac{\pi}{2} \cdot \frac{\pi}{2}$$

$$I = \frac{\pi^2}{4}$$

MORE DA SE COSI SO UCCISTE MA

$$\int_0^{\pi} x f(\sin x) dx = \frac{\pi}{2} \int_0^1 f(\sin x) dx$$

$$I = \int_0^{\pi} \frac{x \sin x}{1 + \cos^2 x} dx = \left| f(\sin(x)) = \frac{\sin x}{1 + 1 - \sin^2 x} = \frac{\sin x}{2 - \sin^2 x} = \frac{t}{2 - t^2} \right| =$$

$$= \int_0^{\pi} x f(\sin x) dx = \frac{\pi}{2} \int_{-1}^1 \frac{\sin x dx}{1 + \cos^2 x} = \left| \begin{array}{l} M = \cos x \\ dM = -\sin x dx \\ +\infty \quad M = 1 \\ x = \pi \quad M = -1 \end{array} \right| =$$

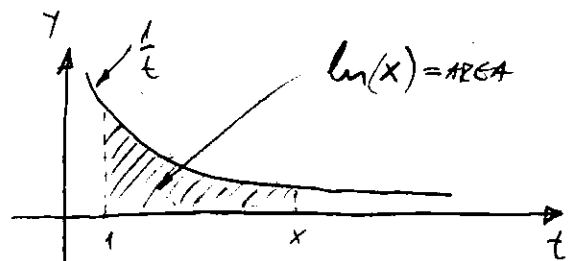
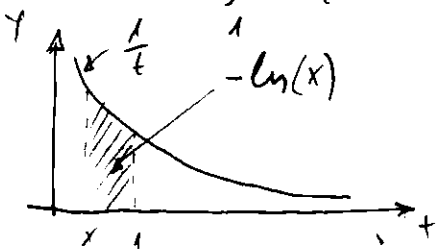
$$= -\frac{\pi}{2} \int_1^{-1} \frac{dM}{1 + M^2} = +\frac{\pi}{2} \int_{-1}^1 \frac{dM}{1 + M^2} = \frac{\pi}{2} [\operatorname{arctg}(1) - \operatorname{arctg}(-1)] = \frac{\pi}{2} \cdot \frac{\pi}{2} = \frac{\pi^2}{4}$$

5.6 LOGARITHM DEFINED AS AN INTEGRAL

$$y = a^x \quad x = \ln_x a$$

NATURAL LOGARITHM

$$\ln(x) = \int_1^x \frac{dt}{t} \quad -x > 0$$



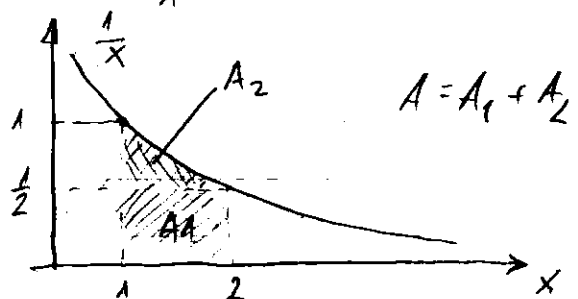
$$\ln(x) = \int_1^x \frac{1}{t} dt = - \int_x^1 \frac{dt}{t} < 0$$

EXAMPLE 1 $\frac{1}{2} < \ln 2 < \frac{3}{4}$

$$A_1 = 1 - \frac{1}{2} = \frac{1}{2}$$

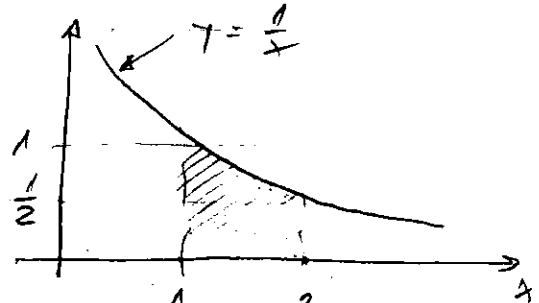
$$A_2 < \left(1 - \frac{1}{2}\right) \cdot \frac{1}{2} = \frac{1}{4}$$

$$A_1 + A_2 < \frac{1}{2} + \frac{1}{4} = \frac{3}{4}$$



$$\ln 2 = \int_1^2 \frac{dt}{t} = A; \quad A = A_1 + A_2$$

$$\boxed{\frac{1}{2} \leq A \leq A_1 + A_2 = \frac{3}{4}}$$



• MIDPOINT RULE $h = 10$

$$A = \sum_{i=1}^n f(x_i) \Delta x_i$$

$$\Delta x_i = \frac{b-a}{n} = \frac{2-1}{n} = \frac{1}{n} = 0.1$$

$$x_i = 1 + \frac{\Delta x_i}{2} \cdot (2i-1)$$

$$x_1 = 1 + \frac{0.1}{2} \cdot 1 = 1.05$$

$$x_2 = 1 + \frac{0.1}{2} \cdot 3 = 1 + \frac{0.3}{2} = 1.15$$

$$A = \sum_{i=1}^{10} f(x_i) \Delta x_i = \sum_{i=1}^{10} \frac{1}{x_i} \cdot \Delta x_i = 0.1 \sum_{i=1}^{10} \frac{1}{x_i}$$

$$A = 0.1 \left(\frac{1}{1.05} + \frac{1}{1.15} + \frac{1}{1.25} + \dots + \frac{1}{1.95} \right) \approx 0.693$$

(FTCA) $g(x) = \int_a^x f(t) dt$ $g'(x) = f(x)$

$$\frac{d}{dx} \int_1^x \frac{1}{t} dt = \frac{1}{x} \Rightarrow \boxed{\frac{d}{dx} (\ln x) = \frac{1}{x}}$$

③ LAWS OF LOGARITHM

1) $\ln(xy) = \ln x + \ln y$

$x, y > 0$ $r = \text{rational constant}$
2) $\ln\left(\frac{x}{y}\right) = \ln x - \ln y$

3) $\ln x^r = r \ln x$

$f = \ln xy$ $e^f = x \cdot y$
Proof: $f(x) = \ln(ax)$

$$\boxed{f'(x) = \frac{1}{ax} \cdot a = \frac{1}{x}}$$

PRODUKT OD
 $\ln(x) + \ln(ax)$
E IS \Rightarrow THE
SE KALKULUSNA
ZA KONSTANTA!!!

1) $\ln(ax) = \ln x + C$

$\ln(2x) = \ln 2 + \ln x = \ln x + 0.69$

$x=1$ $\ln(a) = \ln(1) + C = 0 + C$ $C = \ln(a)$

$\ln(ax) = \ln(x) + \ln(a) \Rightarrow \ln(xy) = \ln(x) + \ln(y)$

2) $x = \frac{1}{y} \Rightarrow \ln \frac{1}{y} + \ln y = \ln\left(\frac{1}{y} \cdot y\right) = \ln 1 = 0$

$\ln\left(\frac{1}{y}\right) = -\ln y$ $-\ln\left(x \cdot \frac{1}{y}\right) = \ln(x) + \ln\left(\frac{1}{y}\right) = \ln(x) - \ln y$

3) $\ln(x^r) = \dots \ln(\underbrace{x \cdot x \cdot \dots \cdot x}_r) = \underbrace{\ln(x) + \ln(x) + \dots + \ln(x)}_r = r \cdot \ln(x)$

(a) $y = \ln(x)$

$\lim_{x \rightarrow \infty} \ln(x) = \infty$ $\lim_{x \rightarrow 0^+} \ln(x) = -\infty$

2.089
2.002

$\ln x^r = r \cdot \ln x$ $x=2$; $r=n$; $\ln 2^n = n \cdot \ln 2$

$\ln 2 > 0 \Rightarrow n \rightarrow \infty \Rightarrow n \ln 2 \rightarrow \infty$ $\ln(x) \uparrow \ln'(x) = \frac{1}{x} > 0$

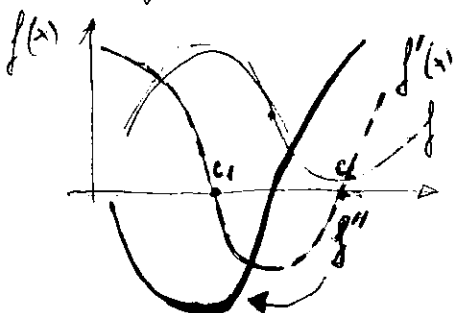
(b) $x = \frac{1}{t} \Rightarrow x \rightarrow 0 \quad t \rightarrow \infty$

$\lim_{x \rightarrow 0} \ln(x) = \lim_{t \rightarrow \infty} \ln\left(\frac{1}{t}\right) = \lim_{t \rightarrow \infty} (-\ln(t)) = -\lim_{t \rightarrow \infty} (\ln(t)) = -\infty$

$y = \ln(x) \quad x > 0$ $\frac{dy}{dx} = \frac{1}{x} > 0$ $\frac{d^2y}{dx^2} = -\frac{1}{x^2} < 0$

Concavity Test

If $f''(x) > 0$ for all x in interval $I \Rightarrow f(x)$ is concave up
 If $f''(x) < 0$ for all x in interval $I \Rightarrow f(x)$ is concave down



$f''(c_1) < 0 \quad f'(c_1) = 0 \Rightarrow f(x)$ MAXIMUM
 $f''(c_2) > 0 \quad f'(c_2) = 0 \Rightarrow f(x)$ MINIMUM

ex6) $f(x) = x^4 - 4x^3$

ex7)

$f(x) = x^{2/3} (6-x)^{1/3}$

ex8) $f(x) = e^{1/x}$

$y = e^x$

$x = \ln(y)$

$\frac{dy}{dx} = \frac{1}{\frac{dx}{dy}} \quad \frac{dx}{dy} = \frac{1}{y} \quad \frac{dy}{dx} = y$

$\frac{dy}{dx} = e^x$

$\frac{d}{dx} (a^x) = \frac{d}{dx} (e^{x \ln a}) = e^{x \ln a} \ln a = a^x \ln a$

Inverse function exist if the function is one-to-one

$y = f(x) \quad f^{-1}(y) = x$

GENERAL LOGARITHMIC FUNCTIONS

$a > 0 \quad a \neq 1$

$f(x) = a^x$ - one-to-one function

$y = \log_a x$

$x = a^y$

$\frac{dx}{dy} = (\ln a) a^y \frac{dy}{dx}$

$\frac{dy}{dx} = \frac{1}{\ln a (a^y)} = \frac{1}{x \ln a}$

$\frac{dx}{dx} = (e^{x \ln a}) \ln a \quad \frac{dx}{dx} = \ln a a^x \frac{dy}{dx}$

$\frac{d}{dx} (\log_a x) = \frac{1}{x \ln a}$

$y = a^x \quad \frac{dy}{dx} = (e^{x \ln a})' = e^{x \ln a} \ln a = a^x \ln a$
 $\frac{d}{dx} (a^x) = a^x \ln a$

$$e = \lim_{x \rightarrow 0} (1+x)^{1/x}$$

$$f(x) = \ln(x)$$

$$f'(x) = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}$$

$$f'(1) = \lim_{h \rightarrow 0} \frac{f(1+h) - f(1)}{h} = \lim_{x \rightarrow 0} \frac{f(1+x) - f(1)}{x} =$$

$$= \lim_{x \rightarrow 0} \frac{\ln(1+x) - \ln(1)}{x} = \lim_{x \rightarrow 0} \frac{1}{x} \ln(1+x) = \lim_{x \rightarrow 0} \ln(1+x)^{1/x}$$

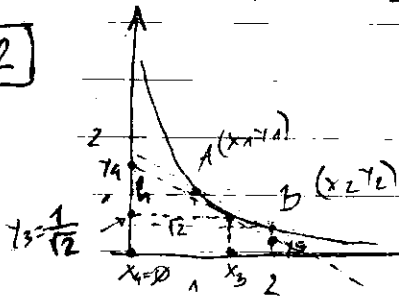
$$f'(1) = \frac{1}{x} \Big|_{x=1} = 1 = \lim_{x \rightarrow 0} \ln(1+x)^{1/x}$$

$$e' = e \lim_{x \rightarrow 0} \ln(1+x)^{1/x} = \lim_{x \rightarrow 0} e^{\ln(1+x)^{1/x}} = \lim_{x \rightarrow 0} \ln(1+x)^{1/x}$$

ex1 $A_1 = \frac{1}{2} \cdot \frac{1}{\frac{3}{2}} = \frac{1}{2} \cdot \frac{2}{3}$ $A_2 = \frac{1}{2} \cdot \frac{1}{2} \cdot \left(1 - \frac{2}{3}\right) = \frac{1}{12}$

$$A = A_1 + A_2 = \frac{2}{6} + \frac{1}{12} = \frac{4+1}{12} = \frac{5}{12}$$

ex2



① $f(x) = \frac{1}{x}$

secant line AB:

$$y - y_1 = \frac{y_2 - y_1}{x_2 - x_1} (x - x_1)$$

$$y - 1 = \frac{\frac{1}{2} - 1}{2 - 1} (x - 1); \quad y = -\frac{1}{2}(x - 1) + 1$$

$$f'(x) = -\frac{1}{x^2} = -\frac{1}{2} \quad x^2 = 2 \quad \boxed{x_3 = \sqrt{2}}$$

$$y_3 = \frac{1}{x_3} = \frac{1}{\sqrt{2}} \quad y_4 = y_1 + y_3 = 1 + \frac{1}{\sqrt{2}} = \frac{\sqrt{2}}{2} + \frac{1}{\sqrt{2}}$$

$$\frac{h}{\sqrt{2}} = \frac{1}{2} \quad \boxed{h = \frac{\sqrt{2}}{2}} \quad y_4 = \frac{\sqrt{2}}{2} + \frac{\sqrt{2}}{2} = 2 \frac{\sqrt{2}}{2} = \sqrt{2}$$

tangent line:

$$y - y_3 = \frac{y_4 - y_3}{x_4 - x_3} (x - x_3) + y - \frac{1}{\sqrt{2}} = \frac{\sqrt{2} - \frac{1}{\sqrt{2}}}{\sqrt{2} - \sqrt{2}} (x - \sqrt{2})$$

$$y = \frac{\sqrt{2}}{2} + \frac{\sqrt{2} - \frac{1}{\sqrt{2}}}{\sqrt{2} - \sqrt{2}} (x - \sqrt{2}) = \frac{\sqrt{2}}{2} - \frac{1}{2} (x - \sqrt{2}) = -\frac{1}{2} (x - \sqrt{2}) + \frac{\sqrt{2}}{2}$$

② $\ln(2) \approx 0.66$ $\ln(2) = \int_1^2 \frac{1}{x} dx$

$$y = -\frac{1}{2}(x - \sqrt{2}) + \frac{\sqrt{2}}{2} \quad x_5 = 2 \Rightarrow y_5 = -\frac{1}{2}(2 - \sqrt{2}) + \frac{\sqrt{2}}{2} = -1 + \frac{\sqrt{2}}{2} + \frac{\sqrt{2}}{2}$$

$$y_5 = \sqrt{2} - 1$$

Area under secant in interval $1 \div 2$

$$A = A_1 + A_2 \quad ; \quad A_1 = 1 \cdot y_5 = 1 \cdot (\sqrt{2} - 1); \quad A_2 = \frac{(1 - y_5) \cdot 1}{2}$$

$$A_2 = \frac{(1 - (\sqrt{2} - 1)) \cdot 1}{2} = \frac{2 - \sqrt{2}}{2}$$

$$A = A_1 + A_2 = (\sqrt{2} - 1) + \frac{2 - \sqrt{2}}{2} = \frac{2\sqrt{2} - 2 + 2 - \sqrt{2}}{2} = \frac{\sqrt{2}}{2} = 0.707$$

$$A_2 = (y_6 - y_5) \cdot \frac{1}{2} \quad y_6 = ? \quad y_6 = -\frac{1}{2}(1 - \sqrt{2}) + \frac{\sqrt{2}}{2} = -\frac{1}{2} + \sqrt{2}$$

$$A_2 = \left(-\frac{1}{2} + \sqrt{2} - \sqrt{2} + 1\right) \cdot \frac{1}{2} = \frac{1}{2} \cdot \frac{1}{2} = \frac{1}{4}$$

$$A = A_1 + A_2 = \sqrt{2} - 1 + \frac{1}{4} = \sqrt{2} - \frac{3}{4} = 0.66$$

$$\boxed{\ln 2 > 0.66} \quad \checkmark$$

Ex 1) ⑥ Midpoint Rule $n = 10$ $\boxed{\ln 1.5} = ?$

$$a = 1 \quad b = 1.5 \quad \Delta x = \frac{1.5 - 1}{10} = \frac{0.5}{10} = 0.05$$

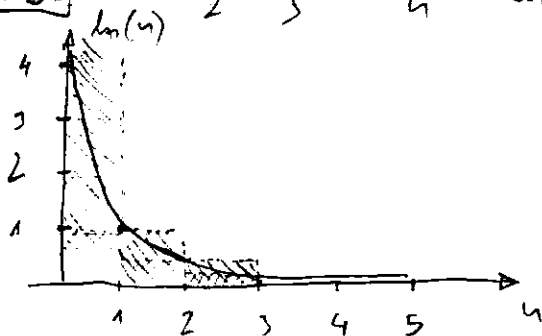
$$S = \sum_{i=1}^n f(x_i) \Delta x \quad f(x) = \frac{1}{x} \quad x_i = 1 + \frac{\Delta x}{2}(2i - 1)$$

$$x_1 = 1 + 0.025 = 1.025$$

$$x_2 = 1 + 3 \cdot 0.025 = 1.075$$

$$S = \sum_{i=1}^{10} \frac{0.05}{1 + 0.025 \cdot (2i - 1)} = 0.05 \left(\frac{1}{1.025} + \frac{1}{1.075} + \dots + \frac{1}{1.475} \right) = 0.40541$$

Ex 3. $\frac{1}{2} + \frac{1}{3} + \dots + \frac{1}{n} < \ln(n) < 1 + \frac{1}{2} + \frac{1}{3} + \dots + \frac{1}{n-1}$



① RIGHT POINT RULE

$$a = 0 \rightarrow b = n$$

$$\Delta x = \frac{b - a}{n} = 1$$

$$S = \sum_{i=1}^n f(x_i) \cdot \Delta x =$$

$$f(x_i) = \frac{1}{x_i} \quad ; \quad x_i = 1 + \Delta x(i - 1) \quad ; \quad S = \sum_{i=1}^n \frac{\Delta x}{1 + \Delta x(i - 1)}$$

$$S_R = \sum_{i=1}^n \frac{1}{1 + (i - 1)} = \sum_{i=1}^n \frac{1}{i} = 1 + \frac{1}{2} + \frac{1}{3} + \dots + \frac{1}{n}$$

② LEFT POINT RULE $\Delta x = \frac{b - a}{n} = 1$

$$S_L = \sum_{i=1}^n \frac{1}{i - 1} \cdot \Delta x = \sum_{i=1}^n \frac{1}{i - 1} = \frac{1}{0} + \frac{1}{1} + \dots + \frac{1}{n - 1}$$

EXCLUDING FIRST TERM FROM S_R AND S_L SUM:

① $S_{R1} = \sum_{i=2}^n \frac{1}{i} = \frac{1}{2} + \frac{1}{3} + \dots + \frac{1}{n}$

② $S_{L1} = \sum_{i=2}^n \frac{1}{i-1} = 1 + \frac{1}{2} + \dots + \frac{1}{n-1}$

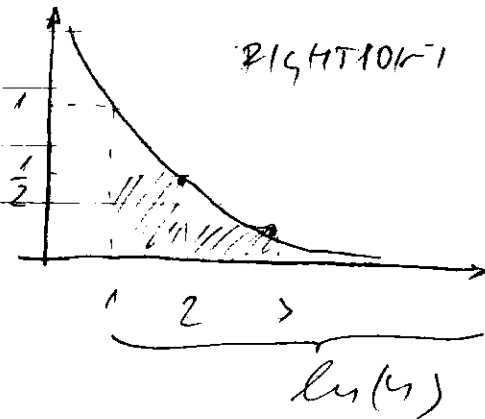
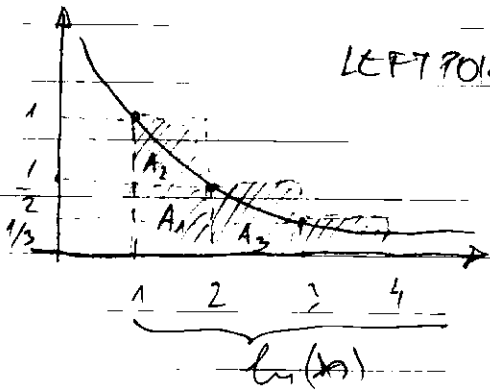
RIGHT POINT: $a=1$ $B=n$ $\Delta x = \frac{n-1}{n} = \left(1 - \frac{1}{n}\right) \approx 1$

$S_R = \sum_{i=2}^n \frac{1}{i} \cdot \Delta x$ $X_i = 1 + i \Delta x = 1 + i$

$S_R = \frac{1}{2} + \frac{1}{3} + \dots + \frac{1}{n}$

LEFT POINT: $S_L = \sum_{i=2}^n \frac{1}{i-1} \cdot \Delta x = 1 + \frac{1}{2} + \dots + \frac{1}{n-1}$

$S_R < \ln(n) < S_L$



Ex 4 $\ln 2 = \int_1^2 \frac{dx}{x} = A_1 + A_2$

$A_1 = 1 \cdot \frac{1}{2} = \frac{1}{2}$ $A_2 < \left(1 \cdot \frac{1}{2}\right) \cdot \frac{1}{2} = \frac{1}{4}$ $A_1 = A_1 + A_2 = \frac{1}{2} + \frac{1}{4} = \frac{3}{4} < 1$

$B = A_1 + A_2 + A_3$ $A_3 = A_{31} + A_{32}$ $A_{31} = \frac{1}{3} \cdot 1 = \frac{1}{3}$ $A_{32} < \left(\frac{1}{2} - \frac{1}{3}\right) \cdot \frac{1}{2}$
 $A_{32} = \frac{3-2}{6} \cdot \frac{1}{2} = \frac{1}{12}$ $A_3 < \frac{1}{3} + \frac{1}{12} = \frac{4+1}{12} = \frac{5}{12}$

$B = \frac{1}{4} + \frac{5}{12} = \frac{3+5}{12} = \frac{8}{12} > 1$

$\ln 2 \approx \frac{3}{4}$ $\ln(3) \approx \frac{7}{6}$ $\ln(e) = 1$

$\ln 2 < \ln(e) < \ln(3) \Rightarrow \boxed{2 < e < 3}$

Ex 5 $a^{x-y} = e^{(x-y)\ln a} = e^{x\ln a - y\ln a} = e^{x\ln a} \cdot e^{-y\ln a} = a^x \cdot a^{-y} = a^x / a^y$

e^x / e^y $\ln e^x / e^y = \ln e^x - \ln e^y = \ln e^{x-y} = e^{x-y} = e^x / e^y$

Ex 7 $(a \cdot b)^x = e^{x \ln(a \cdot b)} = e^{x \ln a + x \ln b} = e^{x \ln a} \cdot e^{x \ln b} = a^x \cdot b^x$

EMO $\log_a(xy) = z$ $a^z = xy$ $a^z = e^{z \ln a}$; $e^{z \ln a} = xy$
 $\ln(xy) = w$ $e^w = xy$

$\log_a(xy) = \log_a e^{z \ln a}$; $\log_a xy = \log e$

$\log_a x = \frac{\ln x}{\ln a}$; $\log_a e^{x \ln a} = x$ $a^x = e^{x \ln a}$

(1°) $a^{x+y} = a^x \cdot a^y$ (2°) $a^{x-y} = a^x / a^y$ (3°) $(a^x)^y = a^{xy}$ (4°) $(ab)^x = a^x b^x$

(a) $\log_a a^{x+y} = x+y$ $\log_a xy = \log_a x + \log_a y$
 $\log_a a^r = r$ $\log_a a^s = s$ $a^r = x$; $a^s = y$
 $x \cdot y = a^r \cdot a^s = a^{r+s}$; $\log_a a^{r+s} = r+s = \log_a x + \log_a y$

(b) $\log_a(x/y) = \log a^r / a^s = \log_a a^{(r-s)} = r-s = \log_a x - \log_a y$

(c) $\log_a(x^y) = \log_a(a^{r \cdot y}) = r \cdot y = y \cdot r = y \cdot \log_a x$

$\log_a x = r$; $x = a^r = e^{r \cdot \ln a}$

$\log_a x = \frac{\ln x}{\ln a}$; $\log_a x = \log_a e^{r \cdot \ln a} = r \cdot \ln a \cdot \log_a e$

$x = a^r / \ln a$ $\ln(x) = r \cdot \ln a$ $r = \frac{\ln(x)}{\ln a}$

$\log_a x = \frac{\ln(x)}{\ln(a)}$

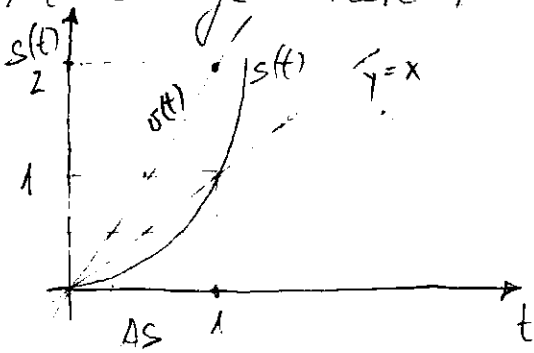
REVIEW

$S = \sum_{i=1}^n f(x_i) \Delta x$; $\int_a^b f(x) dx = \lim_{n \rightarrow \infty} \sum_{i=1}^n f(x_i) \Delta x$

(FTC) (1°) $g(x) = \int_a^x f(t) dt$ $g'(x) = f(x)$ $a \leq x \leq b$

(2°) $\int_a^b f(t) dt = F(b) - F(a)$ $F' = f(x)$

Net Change Theorem



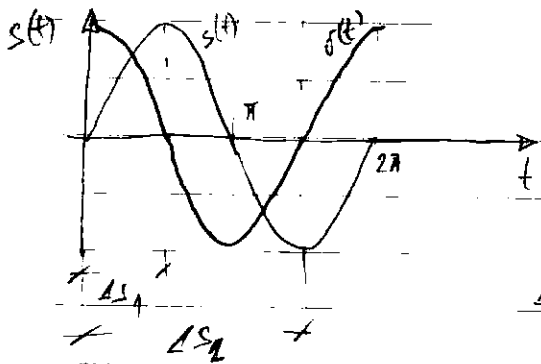
$\int_a^b \frac{ds}{dt} dt = s(b) - s(a)$

$s(t) = t^2$ $t > 0$

$v(t) = \frac{ds(t)}{dt} = 2 \cdot t$

$\int_0^1 v(t) dt = \int_0^1 2t dt = 2 \cdot \left. \frac{t^2}{2} \right|_0^1 = 2 \cdot \frac{1}{2} = 1$

$\Delta s = s(1) - s(0) = 1^2 - 0 = 1$



$$s(t) = \sin(t)$$

$$\Delta s_1 = s\left(\frac{\pi}{2}\right) - s(0) = 1 - 0 = 1$$

$$\Delta s_2 = s\left(\frac{3\pi}{2}\right) - s(0) = -1 - 0 = -1$$

$$\Delta s_2 = \int_0^{3\pi/2} v(t) dt = \int_0^{3\pi/2} \cos(t) dt = \left. \sin(t) \right|_0^{3\pi/2}$$

~~$$\int_0^{3\pi/2} \cos(t) dt = \left. \sin(t) \right|_0^{3\pi/2} = \sin\left(\frac{3\pi}{2}\right) - \sin(0) = -1 - 0 = -1$$~~

$$\int_0^{2\pi} |v(t)| dt = \int_0^{\pi/2} \cos(t) dt + \int_{\pi/2}^{3\pi/2} -\cos(t) dt = \left. \sin(t) \right|_0^{\pi/2} - \left(\left. \sin(t) \right|_{\pi/2}^{3\pi/2} - \left. \sin(t) \right|_{\pi/2}^{\pi} \right)$$

substitution rule

$$\int_a^b f(g(x)) g'(x) dx = \int_{g(a)}^{g(b)} f(u) du$$

$$\int_1^5 \frac{x dx}{1+x^2} \quad \begin{array}{l} u = 1+x^2 \\ du = 2x dx \\ x=1 \quad u=2 \\ x=2 \quad u=5 \end{array} = \frac{1}{2} \int_2^5 \frac{du}{u} = \frac{1}{2} \left[\ln(u) \right]_2^5 = \frac{1}{2} (\ln(5) - \ln(2))$$

$$f(x) = \frac{1/2}{1+x^2} \quad f(g(x)) = \frac{1/2}{1+g(x)^2} \quad 2x dx = g'(x) dx$$

$$\int_a^b \frac{x dx}{1+x^2} = \int_a^b \frac{1/2}{1+g(x)^2} \cdot 2x dx = \int_a^b f(g(x)) g'(x) dx = \int_{g(a)}^{g(b)} f(u) du$$

$$F' = f \quad \int_a^b f(g(x)) g'(x) dx = \int_a^b F'(g(x)) g'(x) dx = F(g(x)) \Big|_a^b + C$$

PROBLEMS

$$\lim_{x \rightarrow 3} \left(\frac{x}{x-3} \int_1^x \frac{\sin t}{t} dt \right) = \lim_{x \rightarrow 3} \frac{x}{x-3} \left[\int_3^x \frac{\sin t}{t} dt + \int_1^3 \frac{\sin t}{t} dt \right]$$

$$= \lim_{x \rightarrow 3} \frac{x}{x-3} \left[\int_0^x \frac{\sin t}{t} dt - \int_0^3 \frac{\sin t}{t} dt \right] = \lim_{x \rightarrow 3} \frac{x [S_1(x) - S_1(3)]}{x-3} = 0$$

$$u = \frac{1}{x-3}; \quad x \rightarrow 3; \quad u \rightarrow \infty; \quad x-3 = \frac{1}{u} \quad x = \frac{1}{u} + 3$$

$$\lim_{u \rightarrow \infty} \frac{\frac{1}{u} + 3}{\frac{1}{u} + 3 - 3} \int_3^{\frac{1}{u} + 3} \frac{\sin(t)}{t} dt = \lim_{u \rightarrow \infty} u \left(\frac{1}{u} + 3 \right) \int_3^{\frac{1}{u} + 3} \frac{\sin(t)}{t} dt$$

$$= \lim_{u \rightarrow \infty} (1 + 3u) \int_3^{\frac{1}{u} + 3} \frac{\sin(t)}{t} dt$$

$$\lim_{x \rightarrow 3} \frac{x}{x-3} \int_3^x \frac{\sin(t)}{t} dt = \lim_{x \rightarrow 3} x \lim_{x \rightarrow 3} \frac{F(x) - F(3)}{x-3}$$

$$\left| F(x) = \int_0^x \frac{\sin(t)}{t} dt \right| = \lim_{x \rightarrow 3} x \frac{F'(x)}{1} = 3 \cdot \frac{\sin(3)}{3} = \sin(3)$$

$$\lim_{x \rightarrow 1} \frac{\ln x}{x-1}$$

L'Hospital's Rule: $f(x)$ $g(x)$ ARE DIFFERENTIABLE $g'(a) \neq 0$ $\lim_{x \rightarrow a} g(x) \neq 0$

$\lim_{x \rightarrow a} f(x) = 0$ $\lim_{x \rightarrow a} g(x) = 0$ OR $\lim_{x \rightarrow a} f(x) = \pm\infty$ $\lim_{x \rightarrow a} g(x) = \pm\infty$

$$\lim_{x \rightarrow a} \frac{f(x)}{g(x)} = \lim_{x \rightarrow a} \frac{f'(x)}{g'(x)}$$

ex.: ① $\lim_{x \rightarrow 1} \frac{\ln x}{x-1} = \lim_{x \rightarrow 1} \frac{1/x}{1} = \lim_{x \rightarrow 1} \frac{1}{x} = 1$

② $\lim_{x \rightarrow \infty} \frac{\ln x}{x-1} = \lim_{x \rightarrow \infty} \frac{1/x}{1} = 0$

③ $L = \lim_{x \rightarrow 3} \frac{x}{x-3} \int_3^x \frac{\sin(t)}{t} dt = \lim_{x \rightarrow 3} x \cdot \lim_{x \rightarrow 3} \frac{f(x)}{g(x)} = \lim_{x \rightarrow 3} \frac{f'(x)}{g'(x)}$

$$f'(x) = \frac{d}{dx} \left[\int_3^x \frac{\sin(t)}{t} dt \right] = \frac{\sin(x)}{x} \quad g'(x) = 1$$

$$L = 3 \cdot \lim_{x \rightarrow 3} \frac{f(x)}{g(x)} = 3 \lim_{x \rightarrow 3} \frac{\frac{\sin(x)}{x}}{1} = 3 \cdot \lim_{x \rightarrow 3} \frac{\sin(x)}{x} = 3 \cdot \frac{\sin(3)}{3} = \sin(3)$$

PROOF OF L'HOSPITAL'S RULE

$\lim_{x \rightarrow a} f(x) = 0$ $\lim_{x \rightarrow a} g(x) = 0$ $g'(a) \neq 0$ THEN

$$\lim_{x \rightarrow a} \frac{f(x)}{g(x)} = \frac{f(a)}{g(a)} = \frac{\lim_{x \rightarrow a} \frac{f(x) - f(a)}{x-a}}{\lim_{x \rightarrow a} \frac{g(x) - g(a)}{x-a}} = \lim_{x \rightarrow a} \frac{f(x) - f(a)}{g(x) - g(a)} = \lim_{x \rightarrow a} \frac{f'(x)}{g'(x)}$$

ex. 2 $\lim_{x \rightarrow \infty} \frac{e^x}{x^2} = \lim_{x \rightarrow \infty} \frac{e^x}{2x} = \lim_{x \rightarrow \infty} \frac{e^x}{2} = \infty$

ex. 3 $\lim_{x \rightarrow \infty} \frac{\ln x}{\sqrt{x}} = \lim_{x \rightarrow \infty} \frac{1/x}{1/2\sqrt{x}} = \lim_{x \rightarrow \infty} \frac{2}{x \cdot \sqrt{x}} = \lim_{x \rightarrow \infty} \frac{2}{x^{3/2}} = 0$

PROBLEM 15 ① $x \sin(\pi/x) = \int_0^{x^2} f(t) dt$ $f(t)$ continuous $f'(a) = ?$

$$x \sin(\pi x) = \int_0^{x^2} f(t) dt \quad \left| \frac{d}{dx} \right. \quad \sin(\pi x) + x \cdot \cos(\pi x) \cdot \pi =$$

$$= f(x^2) \cdot 2x$$

$$f(4) = ? \quad 2 \cdot x \cdot f(x^2) = \sin(\pi x) + \pi x \cos(\pi x) \quad \Big|_{x=2} \quad 2 \cdot 2 \cdot f(4) = \sin(2\pi) + 2\pi \cdot \cos(2\pi)$$

$$4 \cdot f(4) = 2\pi \cdot 1 \quad \boxed{f(4) = \frac{\pi}{2}}$$

② $y = f(x)$ PASSES THROUGH $(1, 1)$ $\int_0^1 f'(x) dx = ?$

$$\int_0^1 f'(x) dx = f(1) - f(0) = 1 - f(0) = 1$$

③ $\int \frac{dx}{1+x^4} = \int \frac{dx}{1+(x^2)^2} \quad \left| \begin{array}{l} u = x^2 \\ du = 2x dx \\ x = \sqrt{u} \end{array} \right. = \int \frac{1}{2\sqrt{u}} \frac{du}{1+u^2} = \frac{1}{2} \int \frac{1}{\sqrt{u}} \frac{du}{1+u^2}$

$$I = \int \frac{dx}{1+x^2} = \int \frac{dx}{1+\tan^2 x} = \int \frac{dx}{\sec^2 x} = \int \cos^2 x dx = \int \frac{1+\cos(2x)}{2} dx = \frac{x}{2} + \frac{\sin(2x)}{4} + C$$

$$u = \arctan(x); \quad x = \tan(u) \quad \frac{dx}{dx} = (1+\tan^2(u)) \frac{du}{du}$$

$$dx = (1+x^2) du \quad \frac{dx}{1+x^2} = du$$

$$I = \int du = u = \arctan(x)$$

$$I_1 = \frac{1}{2} \int \frac{1}{\sqrt{u}} \frac{du}{1+u^2} = \int \frac{1}{2\sqrt{u}} \frac{du}{1+u^2} = \frac{1}{2} \int \frac{1}{\sqrt{u}} \frac{du}{1+u^2}$$

$$I_1 = \frac{1}{2} \int \frac{1}{\sqrt{u}} d[\arctan(u)] = \arctan(u) \cdot \frac{1}{\sqrt{u}} - \int \arctan(u) d\left(\frac{1}{\sqrt{u}}\right)$$

$$I_2 = \int \arctan(u) \cdot \frac{1}{2} u^{-\frac{1}{2}-1} du = \frac{1}{2} \int \frac{\arctan(u)}{\sqrt{u}} du$$

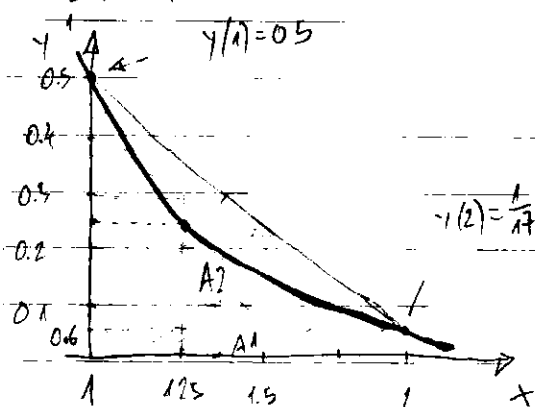
$$\int \frac{dx}{1+x^4} = ?$$

$$A = A_1 + A_2 \quad A_1 = \frac{1}{17} \cdot 1 = \frac{1}{17}$$

$$A_2 = \left(\frac{1}{2} - \frac{1}{17}\right) \cdot \frac{1}{2} = \frac{17-2}{34} \cdot \frac{1}{2} = \frac{15}{68}$$

$$A_1 = \frac{1}{17} < \int \frac{dx}{1+x^4} < A = \frac{1}{17} + \frac{15}{68}$$

$$= \frac{4+15}{68} = \frac{19}{68}$$



④ $f(x) = (2cx - x^2)/c^3 \quad c > 0$

$f(x) = -\frac{1}{c^3}x^2 + \frac{2cx}{c^3} \quad ; \quad f'(x) = -\frac{1}{c^3} \cdot 2x + \frac{2 \cdot 1}{c^2} = 0$

$\frac{2}{c^2}x = \frac{2}{c^2} \quad \boxed{x=c} \rightarrow \boxed{f(c)=0}$

$f''(x) = -\frac{2}{c^3} < 0 \Rightarrow$

⑤ $f(x) = \int_0^{g(x)} \frac{dt}{\sqrt{1+t^2}} \quad g(x) = \int_0^{\cos x} [1 + \sin(t^2)] dt \quad f'(x) = ?$

$f'(x) = \frac{1}{\sqrt{1+g^2(x)}} \cdot \frac{dg(x)}{dx} \quad ; \quad \frac{dg(x)}{dx} = [1 + \sin(\cos^2(x))](-\sin(x))$

$g(x) = \int_0^{\cos(x)} dt + \int_0^{\cos(x)} \sin(t^2) dt = \cos(x) + I_1$

$I_1 = \int_0^{\cos(x)} \sin(t^2) dt = \left| \begin{array}{l} u = t^2 \\ du = 2t dt \\ dt = \frac{du}{2t} \end{array} \right|$

$u = \cos(t^2) \quad ; \quad du = -\sin(t^2) \cdot 2t dt \quad ; \quad -\frac{du}{2t} = \sin(t^2) dt$

$t^2 = \arccos(u) \quad ; \quad t = \sqrt{\arccos u} \quad ; \quad -\frac{du}{2\sqrt{\arccos u}} = \sin(t^2) dt$

$I_1 = -\int \frac{du}{2\sqrt{\arccos(u)}} = \left| \begin{array}{l} v = \arccos u \\ dv = -\frac{1}{\sqrt{1-u^2}} du \\ du = -\sqrt{1-u^2} dv \end{array} \right| \quad \begin{array}{l} u = \cos(v) \\ \frac{du}{dv} = -\sin(v) = -\sqrt{1-\cos^2 v} \end{array}$

$dv = -\frac{du}{\sqrt{1-u^2}} \quad du = -\sqrt{1-\cos^2 v} dv$

$I_1 = \int \frac{\sqrt{1-\cos^2 v}}{\sqrt{v}} dv = \int \sqrt{\frac{1-\cos^2 v}{v}} dv = \int \frac{\sin v}{\sqrt{v}} dv$

$f'(x) = \frac{-\sin(x)[1 + \sin(\cos^2(x))]}{\sqrt{1 + (\cos(\frac{\pi}{2} \text{ Fresnel S}(\frac{\sqrt{2}}{\pi} \cos(x)))^2}}$

⑥ $f(x) = \int_0^x x^2 \sin(t^2) dt \quad f'(x) = ?$

$f(x) = x^2 \int_0^x \sin(t^2) dt \quad f'(x) = 2x \int_0^x \sin(t^2) dt + x^2 \cdot \sin(x^2)$

Fresnel S = $\int_0^x \sin(\frac{\pi}{2} t^2) dt$

$I = \left| \begin{array}{l} t^2 = \frac{\pi}{2} u^2 \\ dt = \frac{\pi}{2t} u du \\ dt = \frac{\pi}{2t} \sqrt{\frac{2}{\pi}} u du \end{array} \right| \quad \left| \begin{array}{l} u = \sqrt{\frac{2}{\pi}} t \\ dt = \sqrt{\frac{\pi}{2}} du \end{array} \right|$

$t=0 \quad u=0 \quad ; \quad t=x \quad u = \sqrt{\frac{2}{\pi}} x \quad ; \quad I = \int_0^{\sqrt{\frac{2}{\pi}} x} \sin(\frac{\pi}{2} u^2) \sqrt{\frac{\pi}{2}} du$

$$I = \int_0^{\sqrt{\frac{2}{\pi}}x} \sin\left(\frac{\pi}{2}u^2\right) du = \sqrt{\frac{1}{2}} \text{FresnelS}\left(\sqrt{\frac{2}{\pi}}x\right)$$

$$f'(x) = 2x \sqrt{\frac{1}{2}} \text{FresnelS}\left(\sqrt{\frac{2}{\pi}}x\right) + x^2 \sin(\pi x)$$

$$\textcircled{7} L = \lim_{x \rightarrow 0} \frac{1}{x} \int_0^x (1 - \tan(2t))^{1/4} dt = \lim_{x \rightarrow 0} (1 - \tan(2x))^{1/4} =$$

$$= \lim_{x \rightarrow 0} e^{\frac{1}{4} \ln(1 - \tan(2x))} = e^{\lim_{x \rightarrow 0} \frac{\ln(1 - \tan(2x))}{4}}$$

$$\textcircled{*} = \left| \frac{0}{0} \right| = \lim_{x \rightarrow 0} \frac{1}{1 - \tan(2x) \cdot \cos^2(2x)} = -2 \lim_{x \rightarrow 0} \frac{1}{(1 - \tan(2x)) \cos^2(2x)}$$

$$\textcircled{*} = -2 \quad L = e^{-2}$$

$$\textcircled{8} L = \lim_{t \rightarrow 0} \frac{\int_0^t \sin(x^2) dx}{\frac{1}{2} t \cdot \sin(t^2)} = \left| \frac{0}{0} \right| = \lim_{t \rightarrow 0} 2 \cdot \frac{\sin(t^2)}{\sin(t^2) + t \cdot 2t \cdot \cos(t^2)}$$

~~$$= \lim_{t \rightarrow 0} \frac{\sin(t^2)}{\sin(t^2) + 2t^2 \cos(t^2)} = \lim_{t \rightarrow 0} \frac{2t \cos(t^2)}{2t \cos(t^2) + 4t^2 \cos(t^2) - 4t^2 \sin(t^2)}$$~~

$$L = 2 \lim_{t \rightarrow 0} \frac{\sin(t^2)}{\sin(t^2) + 2t^2 \cos(t^2)} = 2 \lim_{t \rightarrow 0} \frac{2t \cos(t^2)}{2t \cos(t^2) + \textcircled{*}}$$

$$\textcircled{*} = [2t^2 \cos(t^2)]' = 4t \cdot \cos(t^2) - 2t^2 \cdot 2t \cdot \sin(t^2)$$

$$L = 2 \lim_{t \rightarrow 0} \frac{2t \cos(t^2)}{2t \cos(t^2) + 4t \cos(t^2) - 4t^3 \sin(t^2)} =$$

$$= 2 \lim_{t \rightarrow 0} \frac{\cos(t^2)}{\cos(t^2) + 2 \cos(t^2) - 2t^2 \sin(t^2)} = 2 \cdot \frac{1}{1+2} = \frac{2}{3}$$

$$\textcircled{9} I = \int_a^b (-x^2 + x + 2) dx \quad (a, b) = ? \quad \text{thus } I = \text{MAX}$$

$$\frac{dI}{db} = 0 \quad \frac{d}{db} \int_a^b (-x^2 + x + 2) dx = 0 \quad -b^2 + b + 2 = 0$$

$$b^2 - b - 2 = 0$$

$$b_{1,2} = \frac{+1 \pm \sqrt{1+8}}{2} = \frac{1 \pm 3}{2} = \begin{cases} 2 \\ -1 \end{cases}$$

$$\frac{dI}{da} = 0 \quad \frac{d}{da} \left[- \int_a^b (-x^2 + x + 2) dx = 0 \right] \quad a^2 - a - 2 = 0$$

$$a_{1,2} = \begin{cases} 2 \\ -1 \end{cases}$$

$$I = \int_{-\pi/2}^{\pi} \sin(x) dx = \left. \begin{array}{l} y = -x \\ dy = -dx \\ \sin(-x) = -\sin(x) \\ x = -\pi/2 \quad y = \pi/2 \quad x = \pi \quad y = -\pi \end{array} \right| = \int_{\pi/2}^{-\pi} \sin(x) dx$$

$$I = \left. \begin{array}{l} y = \frac{\pi}{2} - x \quad dy = -dx \\ \sin\left(\frac{\pi}{2} - y\right) = \cos(y) \\ x = -\pi/2 \quad y = \pi \\ x = \pi \quad y = -\pi/2 \end{array} \right| = - \int_{\pi}^{\pi/2} \cos(y) dy$$

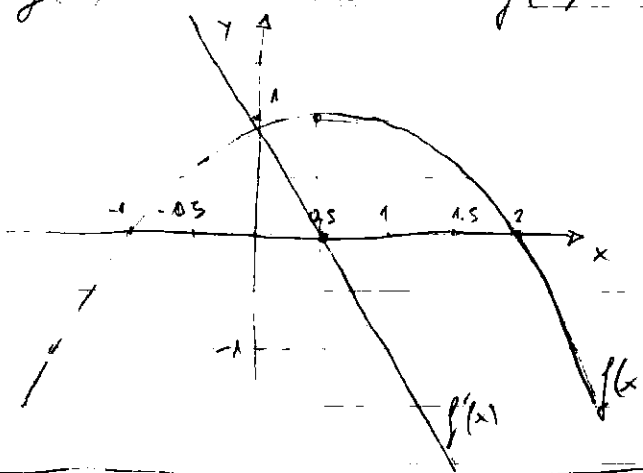
$$f(x) = -x^2 + x + 2$$

$$f'(x) = -2x + 1 = -2\left(x - \frac{1}{2}\right)$$

$$f'(x_0) = 0 \quad -2x + 1 = 0 \quad \left[x = \frac{1}{2} \right]$$

$$f(x_0) = -\frac{1}{4} + \frac{1}{2} + 2 = \frac{2-1}{4} + 2 = \frac{2+8}{4} = \frac{10}{4} = \frac{5}{2}$$

$$f''(x_0) = -2 < 0 \Rightarrow \text{MAX}$$



(i, k) k-th user connected to i-th base station

P_{ik} - transmitting power	s_{ik} - message signal
r_{ik} - transmitting rate	w_{ik} - weight of j-th diversity branch

OUTPUT OF THE COMBINER FOR USER (i, k)

$$y_{ik} = \sum_{j=1}^M (w_{ik}^j)^* x_{ik}^j \quad x_{ik}^j = \sum_{n=1}^N \sum_{l=1}^{K_n} \sqrt{P_{ik}} a_{(i,k),l}^j s_{ik} + n_{ik}^j$$

$a_{(i,k),l}^j$ - array gain between user (i, k) and base station i on j -th diversity route

n_{ik}^j - noise at the j -th diversity branch of i -th base station

d_{ik}^j - received signal of user (i, k) at j -th diversity branch

$$d_{ik}^j = \sqrt{P_{ik}} a_{(i,k),l}^j s_{ik}$$

$$\text{SINR (per bit)} \quad E_{ik} = \frac{E_b}{I_0} = \frac{w_{ik}^H S_{ik} w_{ik}}{w_{ik}^H \Phi_i w_{ik} - w_{ik}^H S_{ik} w_{ik}} \frac{f_w}{V_{ik}}$$

TOTAL RECEIVED SIGNAL (CORRELATION METR)

$$\Phi_i = E(x_{ik} x_{ik}^H) \quad S_{ik} = E(d_{ik} d_{ik}^H) \rightarrow \text{received signal of interest}$$

- Message signals are uncorrelated with zero mean

$$E(|s_{ik}|^2) = 1 \Rightarrow S_{ik} = P_{ik} a_{(i,k),l} a_{(i,k),l}^H \quad \Phi_i = \sum_{n,l} P_{n,l} a_{(i,k),l} a_{(i,k),l}^H + N_i I$$

$$E_{ik} = \frac{P_{ik} w_{ik}^H a_{(i,k),l} a_{(i,k),l}^H w_{ik}}{\sum_{(n,l) \neq (i,k)} P_{n,l} w_{ik}^H a_{(n,l),l} a_{(n,l),l}^H w_{ik} + N_i w_{ik}^H w_{ik}} \frac{f_w}{V_{ik}}$$

With MVDR combining for user (i, k)

$$\epsilon_{ik} = P_{ik} (a_{ik}^H (P_i - P_{ik})^{-1} a_{ik}) / w_{ik}$$

Q_{ik} - SINR REQUIREMENT OF USER (i, k)

$$\epsilon_{ik} \geq Q_{ik}$$

P_{ik}^0 - power of user (i, k) for base station assignment \mathcal{L}

$T_{\mathcal{L}}$ - TOTAL POWER OF base station assignment \mathcal{L}

$\mathcal{L} > 1$ - \mathcal{B} - \mathcal{B} TOTAL DIFFERENT BS assignment (not configs)

T_{min} - MINIMAL TOTAL POWER

$P_{\mathcal{L}} = \{P_{ik}^0\}$ - set of all users' power for BS assignment \mathcal{L}

P_{min} = set that results in minimal power

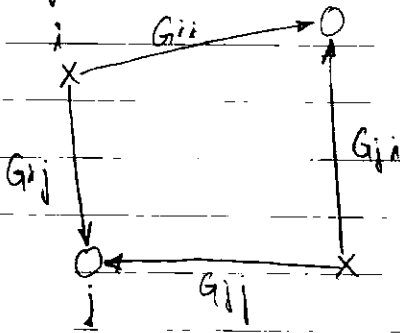
JOINT OPTIMAL POWER CONTROL AND BEAMFORMING

G_{ij} - LINK GAIN between transmitter (i) and receiver (j)

P_i - transmitter power

$G_{ji} P_j$ - power received at receiver (i) from transmitter (j)

interfering signal at (i)



$$I_i = \sum_{j \neq i} G_{ji} P_j$$

CIR - Carrier to Interference

$$\Gamma_i = \frac{G_{ii} P_i}{\sum_{j \neq i} G_{ji} P_j} \geq \gamma_0$$

$$\boxed{2.} \quad P \geq \gamma_0 F P, \quad P = [P_1, P_2, \dots, P_M]^T \text{ - power vector}$$

$$[F]_{ji} = \begin{cases} 0 & j=i \\ \frac{G_{ji}}{G_{ii}} > 0 & j \neq i \end{cases}$$

$$\Gamma_i = \frac{G_{ii} P_i}{\sum_{j \neq i} G_{ji} P_j} + N_i \text{ (MINIMAL NOISE)}$$

$$\boxed{\Gamma_i \geq \gamma_0 \quad 1 \leq i \leq M}$$

$$[I - \gamma_0 F] P \geq M; \quad M_i = \frac{\gamma_0 N_i}{G_{ii}}; \quad 1 \leq i \leq M$$

Power Control Problem:

$$\begin{aligned} &\text{minimize } \sum_i P_i \\ &\text{s.t. } [I - \gamma_0 F] P \geq M \end{aligned}$$

98, 141, 506, 372

$$\hat{P} = [I - \gamma_0 F]^{-1} M$$

BEAMFORMING: $P_i G_{ii}$

$$\Gamma_i = \frac{P_i G_{ii}}{\sum_{j \neq i} G_{ji} G_{ii} (w_i, a_{ji}) P_j + N_i w_i^H w_i}$$

SINR

(10) Use integral to estimate.

$$S = \sum_{i=1}^{100000} \sqrt{i} \quad I = \int_1^{100000} \sqrt{x} dx = \frac{x^{\frac{1}{2}+1}}{\frac{1}{2}+1} \Big|_1^{10^5} = \frac{2}{3} \sqrt{x^3} \Big|_1^{10^5}$$

$$I = \frac{2}{3} (\sqrt{10^{15}} - 1) =$$

(11) $\int_0^u |x| dx = \int_0^u x dx = \frac{x^2}{2} \Big|_0^u = \frac{u^2}{2} \quad u \geq 0$

$$\int_a^b |x| dx = |a < b| = \int_a^b x dx = \frac{x^2}{2} \Big|_a^b = \frac{1}{2} (b^2 - a^2)$$

(12) $I = \frac{d^2}{dx^2} \int_0^x \left(\int_1^{\sin t} \sqrt{1+u^4} du \right) dt = \frac{d}{dx} \left[\frac{d}{dx} \int_0^x \left(\int_1^{\sin t} \sqrt{1+u^4} du \right) dt \right] =$
 $= \frac{d}{dx} \left[\int_1^{\sin x} \sqrt{1+u^4} du \right] = \sqrt{1+\sin^4 x} \cdot \frac{d}{dx} (\sin x) = \underline{\underline{\cos(x) \cdot \sqrt{1+\sin^4(x)}}}$

$$I\left(\frac{\pi}{6}\right) = \frac{\sqrt{3}}{2} \sqrt{1 + \left(\frac{1}{2}\right)^4} = \frac{\sqrt{3}}{2} \sqrt{\frac{17}{16}} = \frac{\sqrt{51}}{8}$$

$$I\left(\frac{\pi}{3}\right) = \frac{1}{2} \sqrt{1 + \left(\frac{\sqrt{3}}{2}\right)^4} = \frac{1}{2} \sqrt{1 + \frac{9}{16}} = \frac{1}{2} \sqrt{\frac{16+9}{16}} = \frac{5}{8} //$$

(13) $\int_0^x f(t) dt = [f(x)]^2 \quad / \quad \frac{d}{dx}$

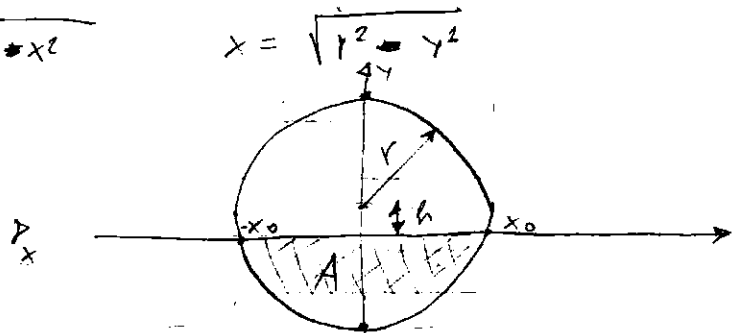
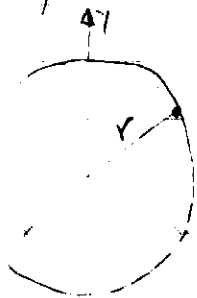
$$f'(x) = 2f(x) \cdot \frac{d f(x)}{dx} \quad \frac{d f(x)}{dx} = \frac{1}{2} \quad f(x) = \frac{1}{2} \int_0^x dx$$

$$f(x) = \frac{x}{2} \quad \int_0^x \frac{t}{2} dt = \frac{t^2}{2} \cdot \frac{1}{2} = \frac{t^2}{4} = \left(\frac{f(x)}{2}\right)^2$$

$$\left(\cos^2(x)\right)' = 2 \cos(x) \cdot (-\sin(x)) = -2 \sin(x) \cos(x)$$

(14) $x^2 + y^2 = r^2 \quad y = \sqrt{r^2 - x^2}$

$$x = \sqrt{r^2 - y^2}$$



$$y = h - \sqrt{r^2 - x^2}$$

$$A = \int_{-x_0}^{x_0} y(x) dx = 2 \int_0^{x_0} y(x) dx$$

$$0 = h - \sqrt{r^2 - x_0^2} \quad r^2 - x_0^2 = h^2 \quad ; \quad x_0 = \sqrt{r^2 - h^2}$$

$$A = 2 \int_0^{\sqrt{r^2 - h^2}} [h - \sqrt{r^2 - x^2}] dx$$

$$A = 2 \int_0^{\sqrt{r^2 - l^2}} (h - \sqrt{r^2 - x^2}) dx ; \quad \frac{dA}{dl} = 0, \quad \frac{d}{dl} 2 \int_0^{\sqrt{r^2 - l^2}} (h - \sqrt{r^2 - x^2}) dx =$$

$$= 2 \left[h - \sqrt{r^2 - (r^2 - l^2)} \right] \cdot \frac{d}{dl} \left(\sqrt{r^2 - l^2} \right) = \frac{1}{2} 2h (r^2 - l^2)^{\frac{1}{2} - 1} \cdot (-2l)$$

$$= \frac{-4l^2}{\sqrt{r^2 - l^2}}$$

$$\frac{dA}{dl} = 2 \cdot \frac{d}{dl} \left[\underbrace{h \int_0^{\sqrt{r^2 - l^2}} dx}_{(*)} - \underbrace{\int_0^{\sqrt{r^2 - l^2}} \sqrt{r^2 - x^2} dx}_{(**)} \right]$$

$$(*) = \frac{d}{dl} \left[h \sqrt{r^2 - l^2} \right] = \sqrt{r^2 - l^2} + h (r^2 - l^2)^{\frac{1}{2}} (-2l) = \sqrt{r^2 - l^2} - \frac{2hl^2}{\sqrt{r^2 - l^2}}$$

$$(**) = \frac{r^2 - l^2 - l^2}{\sqrt{r^2 - l^2}} = \frac{r^2 - 2l^2}{\sqrt{r^2 - l^2}}$$

$$(***) = \frac{d}{dl} \left[\int_0^{\sqrt{r^2 - l^2}} \sqrt{r^2 - x^2} dx \right] = \frac{1}{2} \frac{1}{\sqrt{r^2 - l^2}} (-2l) = -\frac{l^2}{\sqrt{r^2 - l^2}}$$

$$2 \left[(*) - (***) \right] = 2 \left[\frac{r^2 - 2l^2}{\sqrt{r^2 - l^2}} + \frac{l^2}{\sqrt{r^2 - l^2}} \right] = \frac{r^2 - l^2}{\sqrt{r^2 - l^2}}$$

$$= 2 \sqrt{r^2 - l^2}$$

$$\left[r^2 \pi = 2 \int_0^{\sqrt{r^2 - l^2}} (h - \sqrt{r^2 - x^2}) dx \right] \quad \left| \frac{d}{dr} \right.$$

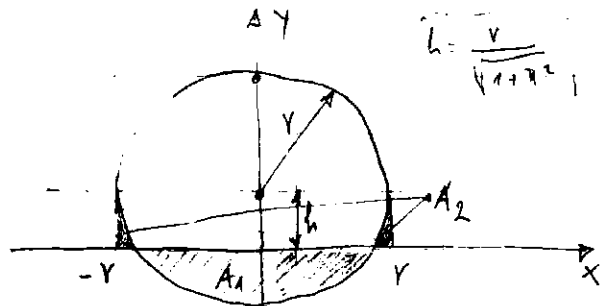
$$A = 2 \int_0^{\sqrt{r^2 - l^2}} h dx - 2 \int_0^{\sqrt{r^2 - l^2}} \sqrt{r^2 - x^2} dx = 2h \sqrt{r^2 - l^2} - 2 \left[\frac{x}{2} \sqrt{r^2 - x^2} + \frac{r^2}{2} \arcsin \frac{x}{r} \right]_0^{\sqrt{r^2 - l^2}}$$

$$A = 2h \sqrt{r^2 - l^2} - \left[\sqrt{r^2 - l^2} \cdot \sqrt{r^2 - x^2 + l^2} + r^2 \cdot \arcsin \frac{\sqrt{r^2 - l^2}}{r} \right] + 2h\pi$$

$$A = 2h \sqrt{r^2 - l^2} - h \sqrt{r^2 - l^2} - r^2 \arcsin \frac{\sqrt{r^2 - l^2}}{r}$$

$$A = h \sqrt{r^2 - l^2} - r^2 \arcsin \frac{\sqrt{r^2 - l^2}}{r}$$

$$A = 0 \Rightarrow h \sqrt{r^2 - l^2} = r^2 \arcsin \left(\frac{\sqrt{r^2 - l^2}}{r} \right)$$



$$h = \frac{v}{\sqrt{1+v^2}}$$

$$y = h - \sqrt{r^2 - x^2}$$

$$r = 2 \Rightarrow y = h - \sqrt{4 - x^2}$$

$$y = 0$$

$$h = \sqrt{r^2 - x^2}, \quad x = \sqrt{r^2 - h^2}$$

$$\int \sqrt{r^2 - x^2} dx = \frac{x}{2} \sqrt{r^2 - x^2} + \frac{r^2}{2} \arcsin\left(\frac{x}{r}\right)$$

$$A_{\pm} = A_1 + A_2 = \int_{-r}^r (h - \sqrt{r^2 - x^2}) dx = 2 \int_0^r (h - \sqrt{r^2 - x^2}) dx$$

$$A_{\pm} = 2 \left[h x \Big|_0^r - \left(\frac{x}{2} \sqrt{r^2 - x^2} + \frac{r^2}{2} \arcsin\left(\frac{x}{r}\right) \right) \Big|_0^r \right] = 2 \left[h \cdot r - \frac{r^2}{2} \arcsin(1) \right]$$

$$A_{\pm} = 2 \left[h \cdot r - \frac{r^2 \pi}{4} \right] = 2 h \cdot r - r^2 \frac{\pi}{2}$$

$$A_{\pm} = 0 \quad 2 h \cdot r = r^2 \frac{\pi}{2}$$

$$A_1 = h \sqrt{r^2 - h^2} - r^2 \arcsin \frac{\sqrt{r^2 - h^2}}{r}$$

$$h = \frac{r \pi}{4}$$

$$h = 0 \quad A_1 = -r^2 \arcsin \frac{r}{r} = -r^2 \cdot \frac{\pi}{2}$$

$$(15) \quad \int_0^x f(m) (x-m) dm = \int_0^x \left(\int_0^m f(t) dt \right) dm$$

$$\int_0^x f(m) dm - \int_0^x m f(m) dm = x [F(x) - F(0)]$$

$$x - m = t \quad -dm = dt \quad m = 0 \quad t = x \quad m = x \quad t = 0$$

$$= \int_x^0 t f(x-t) dt = \int_0^x t f(x-t) dt$$

$$\frac{d}{dx} (I_1) = \frac{d}{dx} \left[\int_0^x f(m) dm - \int_0^x m f(m) dm \right] = x f(x) - x f(x) = 0$$

$$\frac{d}{dx} (I_2) = \int_0^x f(t) dt$$

$$f(m) = x^2$$

$$I_1 = \int_0^x m^2 (x-m) dm = x \int_0^x m^2 dm - \int_0^x m^3 dm = x \frac{x^3}{3} - \frac{x^4}{4} = \frac{4x^4 - 3x^4}{12} = \frac{x^4}{12}$$

$$I_2 = \int_0^x \left(\int_0^m f(t) dt \right) dm = \int_0^x F(m) dm \quad \underline{F'(m) = f(m)}$$

$$I_1 = x \int_0^x f(m) dm - \int_0^x m f(m) dm = x \int_0^x F'(m) dm - \int_0^x m F'(m) dm$$

$$= x (F(x) - F(0)) - \int_0^x m F'(m) dm \quad \Rightarrow \textcircled{*} = m \cdot F'(m) \Big|_0^x - \int_0^x F'(m) dm$$

$$\int_0^x m dv = mv - \int_0^x v dm$$

$$\int_0^x f(t)(x-t) dt = \int_0^x \left(\int_0^t f(t) dt \right) dx$$

$$x \int_0^x f(t) dt - \int_0^x t f(t) dt = \int_0^x \left(\int_0^t f(t) dt \right) dx$$

$$x F(x) - \int_0^x t f(t) dt = \int_0^x F(t) dt \quad ; \quad x F(x) - \int_0^x t f(t) dt = F(x) - F(0)$$

$$\textcircled{*} = \int_0^x t f'(t) dt = t F(t) \Big|_0^x - \int_0^x F(t) dt = x F(x) - \int_0^x F(t) dt$$

$$\int_0^x x dx = \frac{x^2}{2} \quad \frac{dF(x)}{dx} = \frac{2x}{2} = x$$

$$\int x e^x dx = \int x d e^x = x e^x - \int e^x dx = x e^x - e^x$$

$$\int x e^{-x} dx = \int x d(-e^{-x}) = -x e^{-x} + \int e^{-x} dx = -e^{-x} - x e^{-x} = -(1+x)e^{-x}$$

$$\int e^{-x} dx = \int_{-dx = -dm}^{-x = m} -1 dm = -e^m = -e^{-x}$$

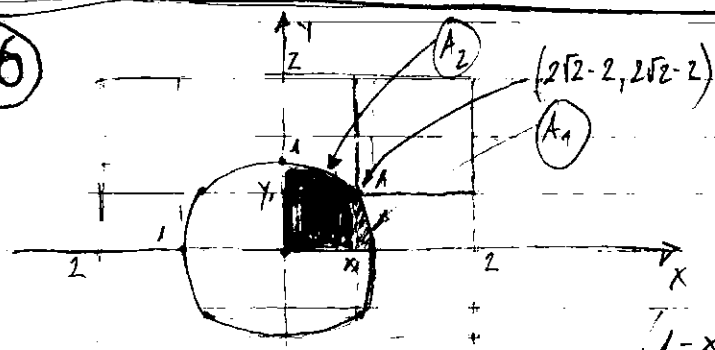
$$x F(x) - x F(x) + \int_0^x F(t) dt = \int_0^x F(t) dt \quad \boxed{\cancel{F(x)} = \cancel{F(x)}}$$

$$x \int_0^x f(t) dt - \int_0^x t f(t) dt = \int_0^x \left(\int_0^t f(t) dt \right) dx$$

$$x F(x) - [t F(t)]_0^x - \int_0^x F(t) dt = \int_0^x F(t) dt$$

$$\cancel{x F(x)} - \cancel{x F(x)} + \int_0^x F(t) dt = \int_0^x F(t) dt$$

16



$$x_1^2 + y_1^2 = z^2 \quad \boxed{z=1}$$

$$A = 8 \cdot A_1 + 2x_1 \cdot 2y_1$$

$$(1-x_1) + 1 = z \Rightarrow 2-x_1 = \sqrt{x_1^2 + y_1^2}$$

$$4 - 4x_1 + x_1^2 = x_1^2 + y_1^2 \quad \boxed{y = \sqrt{4-4x}}$$

$$A_1 = \int_0^1 \sqrt{4-4x} dx = \sqrt{4} \int_0^1 \sqrt{1-x} dx = \left[-\sqrt{2} \int_0^1 \sqrt{1-x} dx \right]$$

$$A_1 = \frac{1}{\sqrt{2}} \int_0^1 \sqrt{1-x} dx = \frac{1}{\sqrt{2}} \left[\frac{2}{3} (1-x)^{3/2} \right]_0^1 = \frac{2\sqrt{2}}{3} (1-0) = \frac{2\sqrt{2}}{3}$$

$$A = 4 \cdot A_1 = \frac{8\sqrt{2}}{3} \quad A_1 = \frac{4}{3}$$

$$1-y_1+1 = \sqrt{x_1^2+y_1^2} \quad (2-y_1)^2 = x_1^2+y_1^2 \quad 4-4y_1+y_1^2 = x_1^2+y_1^2$$

$$x = \sqrt{4-4y} = 2\sqrt{1-y} \quad \begin{cases} x^2 = 4-4y \\ y^2 = 4-4x \end{cases} \Rightarrow \begin{cases} y = 1 - \frac{x^2}{4} \\ y = 2\sqrt{1-x} \end{cases}$$

$$x^2 = 4 - 4\sqrt{4-4x} = 4 - 8\sqrt{1-x} \quad x^2 - 4 = -8\sqrt{1-x} \quad ()^2$$

$$x^4 - 8x^2 + 16 = 64(1-x) \quad x^4 - 8x^2 + 64x - 64 + 16 = 0$$

$$x^4 - 8x^2 + 64x - 48 = 0 \Rightarrow x_0 = 2\sqrt{2} - 2$$

$$4-4y = x^2 \quad 4y = 4-x^2 \quad y = 1 - \frac{x^2}{4}$$

$$y_0 = \sqrt{4 - 4(2\sqrt{2} - 2)} = \sqrt{4 - 8\sqrt{2} + 8} = \sqrt{12 - 8\sqrt{2}}$$

$$A = A_1 + A_2 = \int_{2\sqrt{2}-2}^1 2\sqrt{1-x} dx + \int_0^{2\sqrt{2}-2} \left(1 - \frac{x^2}{4}\right) dx$$

$$A_1 = \left| \begin{array}{l} u = 1-x \quad du = -dx \\ x = 2\sqrt{2}-2 \quad u = 1-2\sqrt{2}+2 \\ x = 1 \quad u = 1-1=0 \end{array} \right| = -2 \int_{3-2\sqrt{2}}^0 \sqrt{u} du = 2 \int_0^{3-2\sqrt{2}} \sqrt{u} du = \frac{4}{3} u\sqrt{u} \Big|_0^{3-2\sqrt{2}}$$

$$A_1 = \frac{4}{3} (3-2\sqrt{2}) \sqrt{3-2\sqrt{2}} = 0.095 \quad A_2 = \int_0^{2\sqrt{2}-2} \left(1 - \frac{x^2}{4}\right) dx = 0.78$$

$$A_1 + A_2 = 0.8758 \quad A_{\text{tot}} = 4 \cdot (A_1 + A_2) \quad A_{\text{tot}} = 3.5032$$

(17) $\lim_{n \rightarrow \infty} \left(\frac{1}{\sqrt{n}\sqrt{n+1}} + \frac{1}{\sqrt{n}\sqrt{n+2}} + \dots + \frac{1}{\sqrt{n}\sqrt{n+n}} \right)$

$$\frac{1}{\sqrt{n^2+n \cdot i}} = \frac{1}{n\sqrt{1+\frac{i}{n}}} = \frac{\frac{1}{n}}{\sqrt{1+\frac{i}{n}}}$$

$$\lim_{n \rightarrow \infty} \left(\sum_{i=1}^n \frac{\frac{1}{n}}{\sqrt{1+\frac{i}{n}}} \right) = S = \int_0^1 \frac{1}{\sqrt{1+x}}$$

$$\lim_{n \rightarrow \infty} \frac{1}{\sqrt{2n^2}} = \lim_{n \rightarrow \infty} \frac{1}{\sqrt{2}n} = 0$$

$$\lim_{n \rightarrow \infty} \sum_{i=1}^n f(x_i) \Delta x = \left| \begin{array}{l} \Delta x = \frac{1}{n} \\ b=1 \quad a=0 \end{array} \right| = \int_0^1 \frac{dx}{\sqrt{1+x}}$$

$$\lim_{n \rightarrow \infty} \sum_{i=1}^n f(x_i) \Delta x = \int_a^b f(x) dx \quad \boxed{\Delta x = \frac{b-a}{n}}$$

$$I = \int_0^1 \frac{1}{\sqrt{1+x}} dx = \left. \begin{array}{l} u = 1+x \\ du = dx \\ x=0 \quad u=1 \\ x=1 \quad u=2 \end{array} \right| = \int_1^2 \frac{du}{\sqrt{u}} = \left. \frac{u^{-\frac{1}{2}+1}}{\frac{1}{2}} \right|_1^2 = 2\sqrt{u} \Big|_1^2$$

$$\boxed{I = 2\sqrt{2} - 2}$$

(18) ANY NUMBER "c" $f_c(x) < (x-c)^2$ $f_c(x) < (x-c-2)^2$
 $g(c) = \int_0^1 f_c(x) dx$ $-2 \leq c \leq 2$ find MAX & MIN of $g(c)$

$c = -2 \dots 1$ $\boxed{c=-2}$ $g(c) = \int_0^1 x^2 dx = \frac{x^3}{3} \Big|_0^1 = \frac{1}{3}$

$\boxed{c=-1}$ $g(c) = \int_0^1 (x-1)^2 dx = \int_0^{-1} u^2 du = \frac{u^3}{3} \Big|_0^{-1} = \frac{(-1)^3}{3} = -\frac{1}{3}$

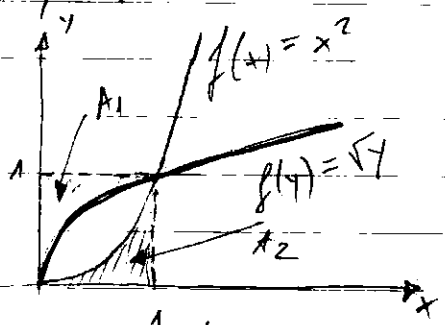
$c > 1$ $\boxed{c=2}$ $g(c) = \int_0^1 (x-2)^2 dx = \int_{-2}^{-1} u^2 du = \frac{u^3}{3} \Big|_{-2}^{-1} = \frac{(-1)^3}{3} - \frac{(-2)^3}{3} = -\frac{1}{3} + \frac{8}{3} = \frac{7}{3}$

$-\frac{1}{3} + \frac{8}{3} = \frac{8-1}{3} = \frac{7}{3}$ MAX

$\boxed{\text{Max}\{g(c)\} = \frac{7}{3} \quad \text{Min}\{g(c)\} = -\frac{1}{3}}$

(19) $f(0) = 0$ $f(1) = 1$ $f'(x) \geq 0$ $A_2 = \int_0^1 f(x) dx = \frac{1}{3}$

$\int_0^1 f''(y) dy = ?$

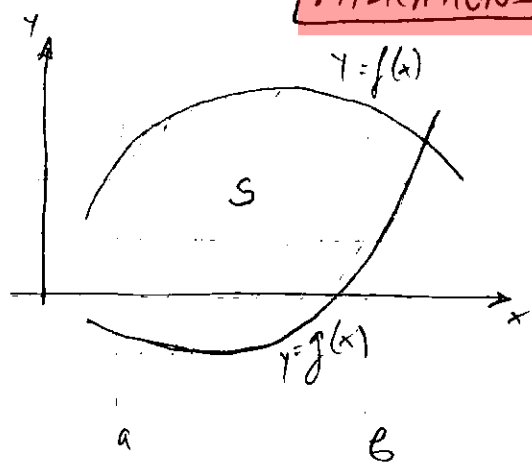


$f(x) = x^2$ $y = x^2$
 $\int_0^1 x^2 dx = \frac{x^3}{3} \Big|_0^1 = \frac{1}{3}$
 $x = \sqrt{y}$

$A_1 = \int_0^1 f''(y) dy = \int_0^1 (1 - f'(x)) dx = \int_0^1 dx - \int_0^1 f'(x) dx = 1 - \int_0^1 f'(x) dx$

$A_1 = \int_0^1 f''(y) dy = \int_0^1 f'(x) dx = \frac{1}{3}$ $\left\{ \begin{array}{l} 1 - \int_0^1 \sqrt{x} dx = 1 - \frac{2}{3} \sqrt{x} \Big|_0^1 = 1 - \frac{2}{3} \cdot 1 = \frac{1}{3} \end{array} \right.$

APPLICATIONS OF INTEGRATION



$$f(x) \geq g(x) \quad \forall x \in [a, b]$$

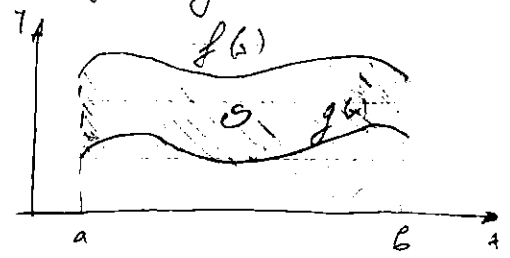
$$\sum_{i=1}^n [f(x_i) - g(x_i)] \Delta x$$

$$A = \lim_{n \rightarrow \infty} \sum_{i=1}^n [f(x_i) - g(x_i)] \Delta x$$

$$A = \int_a^b [f(x) - g(x)] dx$$

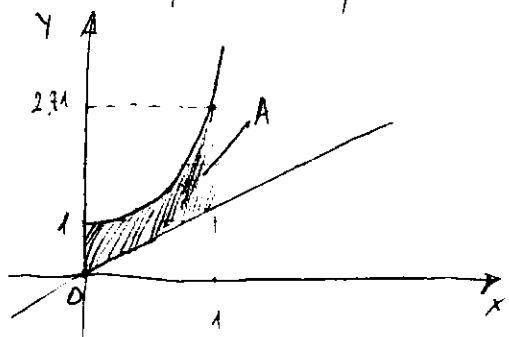
$$x^2 - 2x + 1 = 0 \rightarrow x_{1,2} = \frac{2 \pm \sqrt{4-4}}{2} \rightarrow x_{1,2} = 1$$

If: $f(x), g(x) \geq 0$ it is obvious:

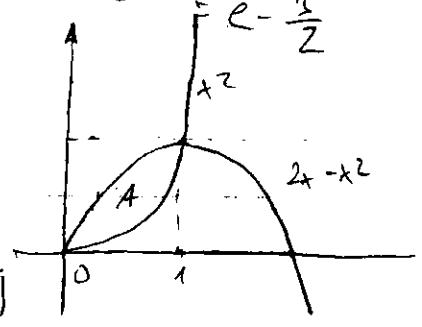


$$S = A_f - A_g = \int_a^b f(x) dx - \int_a^b g(x) dx = \int_a^b [f(x) - g(x)] dx$$

Ex. 1 $y = e^x, y = x \quad x=0, x=1$



$$\int_0^1 (e^x - x) dx = e^x \Big|_0^1 - \frac{x^2}{2} \Big|_0^1 = e - 1 - \frac{1}{2} = e - \frac{3}{2}$$



Ex. 2 $y = x^2; y = 2x - x^2 \quad y = (2-x)x$
 $x^2 = 2x - x^2 \quad ; \quad 2x^2 = 2x \quad \boxed{x=1 \quad x=0}$

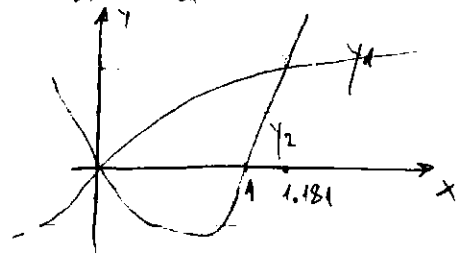
$$A = \int_0^1 (2x - x^2 - x^2) dx = \int_0^1 (2x - 2x^2) dx = 2 \int_0^1 (x - x^2) dx = 2 \left(\frac{x^2}{2} - \frac{x^3}{3} \right) \Big|_0^1$$

$$A = 2 \left(\frac{1}{2} - \frac{1}{3} \right) = 2 \cdot \frac{1}{6} = \frac{1}{3}$$

Ex. 3 $y_1 = \frac{x}{\sqrt{x^2+1}} \quad y_2 = x^4 - x \quad \frac{x}{\sqrt{x^2+1}} = x^4 - x \quad ()^2$

$$\frac{x^2}{x^2+1} = x^8 - 2x^5 + x^2 \quad ; \quad x^2 = (x^2+1)(x^8 - 2x^5 + x^2)$$

$$x^{10} - 2x^7 - 2x^5 + x^4 = 0$$



$$x^4 (x^6 - 2x^3 - 2x + 1) = 0 \quad x=0$$

$$I_1 = \int \frac{x}{\sqrt{x^2+1}} dx = \frac{1}{2} \int \frac{d(x^2+1)}{\sqrt{x^2+1}} = \frac{1}{2} \int \frac{du}{\sqrt{u}}$$

$$= \frac{1}{2} \frac{\sqrt{u}}{1/2} \Big|_{1.181}^{1.181} = \sqrt{1.181^2+1} = \frac{1.5475 - 1}{2} = 0.5475$$

$$I_2 = \int_0^{1.181} (x^4 - x) dx = \left(\frac{x^5}{5} - \frac{x^2}{2} \right) \Big|_0^{1.181} = \frac{(1.181)^5}{5} - \frac{(1.181)^2}{2} = -0.2378$$

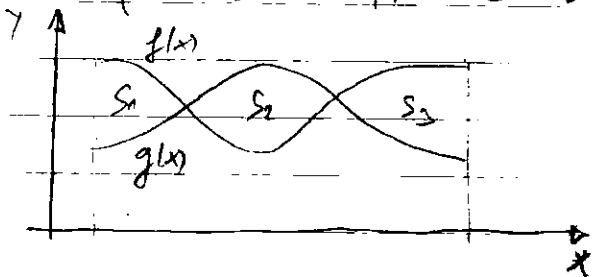
$$A = I_1 - I_2 = 0.5475 + 0.2378 = 0.7853$$

$$I_1 = \int_0^{1.181} \frac{x}{\sqrt{x^2+1}} dx = \int_1^{(1.181)^2+1} \frac{\frac{1}{2} dM}{\sqrt{M}} = \left[\sqrt{M} \right]_1^{(1.181)^2+1}$$

$$I_1 = \sqrt{1.181^2+1} - 1 = 0.5475$$

Ex. 4 $A_n = \sum_{i=1}^n f(x_i) \Delta x$; $\Delta x = 2$ $n = 8$ $\Delta x = \frac{16-0}{8} = 2$

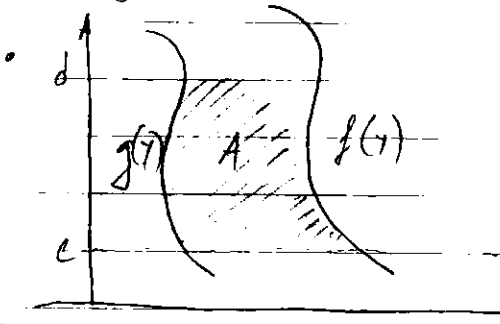
$$A_n = (25 + 30 + 42.5 + 48 + 55 + 58 + 62.5 + 65) \cdot 2$$



$$A = \int_a^b |f(x) - g(x)| dx$$

Ex. 5 $f_1 = \sin(x)$ $f_2 = \cos(x)$ $x=0$; $x = \frac{\pi}{2}$ Area = ?

$$\int_0^{\pi/2} |\cos(x) - \sin(x)| dx = \sqrt{2} - 2$$



$$A = \int_c^d [f(x) - g(x)] dx$$

$$A = \int_c^d (x_R - x_L) dx$$

Ex. 6 $y = x - 1$ $y^2 = 2x + 6$
 $x = y + 1$ $x = \frac{y^2 - 6}{2}$

Exercises [1] $y = 5x - x^2$ $y' = 5 - 2x = 0$ $x = 2.5$
 $y = x$

[9] $y = \frac{1}{x}$; $y = \frac{1}{x^2}$ $x = 2$ [10] $x = 1 - y^2$; $x = y^2 - 1$
 $y = \pm \sqrt{1-x}$ $y = \pm \sqrt{x+1}$

$1-x = 1+x$ $2x = 0$ $[x = 0]$

[20] $\sin(\frac{\pi}{2}x)$; $y = x$ [21] $y = \cos x$, $y = \sin 2x$, $x=0$ $x = \pi/2$

$\sin(2x) = \cos x$ $x = ?$ $\sin(2x) = \sin^2(x) = \cos^2(x)$

$\sin^2(x) = 1 + \sin^2(x)$ $\sin(x)$ $2 \sin^2(x) = \sin(x) = 1 = 0$
 $2y^2 = y - 1 = 0$ $y = \pm \frac{1}{2}$

$$\sin\left(\frac{\pi}{2}\right) = 1 \quad x_1 = \frac{\pi}{2} \quad -\sin(x_2) = -\frac{1}{2} \quad x_2 = -\frac{\pi}{6}$$

$$\sin(2x) = \sin x \cdot \cos x + \sin x \cdot \cos x = 2 \sin x \cos x$$

$$2 \sin x \cos x = \cos x$$

$$2 \sin x \cos x - \cos x = 0$$

$$\sin x = \frac{1}{2}$$

$$\cos(x)(2 \sin x - 1) = 0 \quad x = \frac{\pi}{6} \quad x = 0$$

PI X 515
6

100000

$x = \frac{\pi}{6}$ $x = 0$

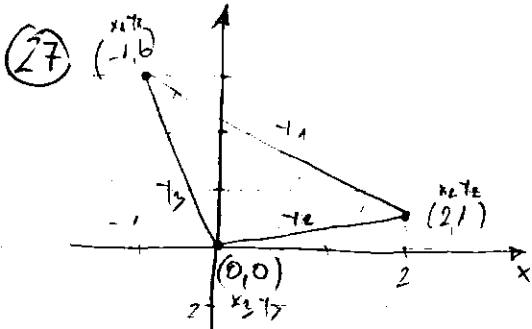
$$(22) \quad y_1 = \sin(2x) \quad y_2 = \sin(x)$$

$$2 \sin x \cos x = \sin x$$

$$(2 \cos x - 1) \sin x = 0 \quad x = 0 \quad x = \pi$$

$$\cos x = \frac{1}{2}$$

$$x = \frac{\pi}{3}$$



$$y - 6 = \frac{1 - 6}{2 + 1} (x + 1)$$

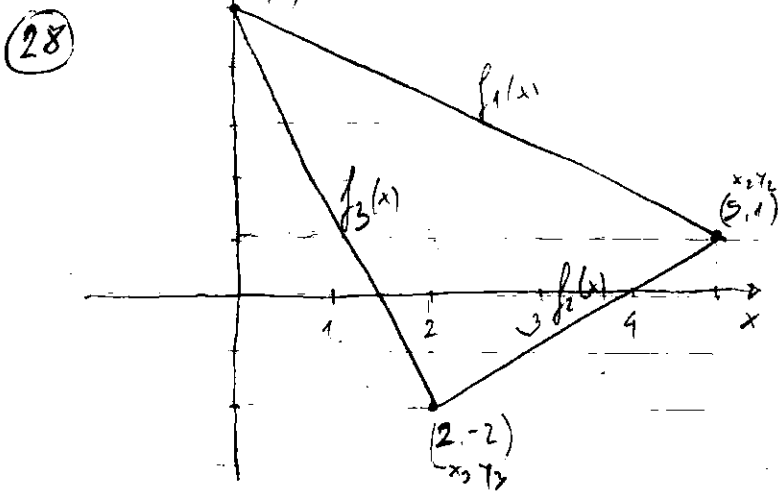
$$y = -\frac{5}{3}(x + 1) + 6 \quad (1)$$

$$y - 6 = \frac{0 - 6}{0 + 1} (x + 1) \rightarrow y = -6(x + 1) + 6$$

$$y = -6x \quad (2)$$

$$y - 1 = \frac{0 - 1}{0 - 2} (x - 2); y - 1 = \frac{1}{2}(x - 2)$$

$$y = \frac{1}{2}x - 1 + 1 = \frac{1}{2}x \quad (3)$$



$$f_1(x) - 5 = \frac{1 - 5}{5 - 0} (x - 0)$$

$$f_1(x) = -\frac{4}{5}x + 5 \quad (1)$$

$$f_2(x) - 1 = \frac{-2 - 1}{2 - 5} (x - 5)$$

$$f_2(x) = x - 5 + 1 = x - 4 \quad (2)$$

$$f_3(x) - 5 = \frac{-2 - 5}{2 - 0} (x - 0)$$

$$f_3(x) = -\frac{7}{2}x + 5 \quad (3)$$

$$(31) \quad y_1 = \sin^2\left(\frac{x+\pi}{4}\right); \quad y_2 = \cos^2\left(\frac{x+\pi}{4}\right)$$

$$a = 0 \quad b = 1$$

$$\Delta x = \frac{b - a}{n} = \frac{1}{4} = 0.25$$

$$\frac{\Delta x}{2} = 0.125$$

$$S = \sum_{i=1}^n (y_1(x_i) - y_2(x_i)) \Delta x$$

$$x_i = (i - 1) \frac{\Delta x}{2}$$

$$x_1 = 0.125 \quad x_2 = 0.375$$

$$x_3 = 0.625 \quad x_4 = 0.875$$

$$(38) \quad (1) \quad x - 2y^2 \geq 0$$

$$(2) \quad 1 - x - |y| \geq 0$$

$$(1) \quad x \geq 2y^2$$

$$y \leq \sqrt{\frac{x}{2}}$$

$$(2) \quad 1 - x \geq |y|$$

$$|y| \leq -x + 1$$

① $x - 27^2 \geq 0$ $x \geq 27^2$
 ② $1 - x - |7| \geq 0$ $x \leq 1 - |7|$

33

t	0	1	2	3	4	5	6	7	8	9	10
v_c	0	43	68.8	91	111.2	133.4	148.4	161.6	173.2	183.6	192.6
v_r	0	27	54.3	81.6	89.5	117.3	126.1	136.4	143.7	149.1	149.1

$20 \left[\frac{\text{miles}}{\text{hours}} \right] = 20 \frac{5280 \text{ feet}}{3600 \text{ sec}}$ $n=5$ $\Delta t = \frac{10-0}{5} = 2$

$$\Delta s = \sum_{i=1}^5 [v_r(t_i) - v_c(t_i)] \Delta t$$
 $t_i = (2i-1) \frac{\Delta t}{2} = (2i-1)$
 $t_1=1; t_2=3; t_3=5; \dots; t_5=9$

$$\Delta s = 2 \sum_{i=1}^5 [v_r(t_i) - v_c(t_i)] =$$

$1 \text{ sec} = \frac{1}{3600} \text{ hr}$ $\Delta t = \frac{10}{5} = \frac{1}{360} \cdot \frac{1}{5} = \frac{1}{1800}$

$$\Delta s = \frac{1}{1800} \sum_{i=1}^5 [v_r(t_i) - v_c(t_i)] =$$

46 $\int_1^a \frac{1}{x^2} dx = \frac{x^{-2+1}}{-2+1} \Big|_1^a = -\frac{1}{x} \Big|_1^a = \frac{1}{x} \Big|_a^1 = \left(1 - \frac{1}{a}\right)$

$1 - \frac{1}{a} = \frac{3}{8}$ $\frac{1}{a} = 1 - \frac{3}{8} = \frac{5}{8}$ $a = \frac{8}{5} = 1.6$

47 $2 \int_{-c}^c (c^2 - x^2) dx = 2 \left[c^2(x) - \frac{x^3}{3} \Big|_{-c}^c \right] = 2 \left[2c^3 - \left(\frac{c^3}{3} + \frac{c^3}{3} \right) \right]$

$= 2 \left[2c^3 - \frac{2c^3}{3} \right] = 2c^3 \left(2 - \frac{2}{3} \right) = 2c^3 \frac{6-2}{3} = \frac{8c^3}{3}$

$\frac{8c^3}{3} = 576$ $c^3 = \frac{576 \cdot 3}{8} = 216$ $c = \sqrt[3]{216} = 6$

46b. $y = \frac{1}{x^2}$ $x^2 = \frac{1}{1/16}$ $x = \frac{1}{1/4}$ $y = 6$

$\int_1^4 \frac{1}{x^2} dx = \frac{3}{4}$ $\int \left(\frac{1}{x^2} - 6 \right) dx = \frac{1}{2} \frac{3}{4}$

$b = \frac{1}{x^2}$ $x = \frac{1}{1/16}$

(48) $0 < c < \pi/2$ $\gamma_1(x) = \cos(x)$; $\gamma_2(x) = \cos(x-c)$

$\cos(x) = \cos(x-c) = \cos x \cdot \cos c + \sin x \cdot \sin c$; $A = \cos c$

$\cos(x) = A \cdot \cos(x) + A \sqrt{1-\cos^2(c)}$; $(1-A) \cos(x) = A \sqrt{1-\cos^2(c)}$ (*)²

$(1-A)^2 \cdot \cos^2(x) = A^2(1-\cos^2(c))$; $(1-2A+A^2) \cos^2(x) = A^2 - A^2 \cos^2(c)$

$\cos^2(x) - 2 \cos^2(x) + A^2 \cos^2(x) = A^2 - A^2 \cos^2(c)$

$(1-2A+2A^2) \cos^2(x) = A^2$; $\cos^2(x) = \frac{A^2}{2A^2-2A+1}$

$\cos(x) = \frac{A}{\sqrt{2A^2-2A+1}} = \frac{\cos(c)}{\sqrt{2\cos^2(c)-2\cos(c)+1}}$ (*)

(*) $\cos^2(c) + \cos^2(c) - 2\cos(c) + 1 = \cos^2(c) + (\cos(c)-1)^2$

$\cos(x) = \cos x \cos c + \sin x \sin c$

$(1-\cos c) \cos(x) = \sin x \sin c$

$\tan x = \frac{1-\cos(c)}{\sin(c)}$

$x_0 = \arctan \left[\frac{1-\cos(c)}{\sin(c)} \right]$

$A_1 = \int_0^{x_0} [\cos(x) - \cos(x-c)] dx = \sin(x) \Big|_0^{x_0} - \int_0^{x_0} \cos(x-c) dx = \left. \begin{matrix} u = x-c \\ du = dx \\ x=0 \Rightarrow u=-c \\ x=x_0 \Rightarrow u=x_0-c \end{matrix} \right| =$

$= \sin(x_0) - \sin(0) - \int_{x_0-c}^{x_0} \cos(u) du = \sin(x_0) - \sin(x_0-c) + \sin(-c)$

$A_1 = \sin(x_0) - \sin(x_0-c) - \sin(c)$

$x_0 = \frac{\pi}{4}$; $c = \frac{\pi}{2}$; $A_1 = \frac{\sqrt{2}}{2} - \sin\left(\frac{\pi}{4} - \frac{\pi}{2}\right) - \sin\left(\frac{\pi}{2}\right) = \frac{\sqrt{2}}{2} + \sin\left(\frac{\pi}{4}\right) - 1 = \frac{\sqrt{2}}{2} + \frac{\sqrt{2}}{2} - 1 = \sqrt{2} - 1$

$\gamma = \cos(x-c)$

$x-c = \arccos y$

$x_1 = c + \arccos(y)$

$x_2 = \pi$

$A_2 = \int_c^{\frac{\pi}{2}+c} [1-\cos(x-c)] dx + \left[\pi - \left(\frac{\pi}{2}+c\right) \right] \cdot 1$ (*)

$\begin{matrix} u = x-c & du = dx \\ x=c & u=0 \\ x=\frac{\pi}{2}+c & u=\frac{\pi}{2} \end{matrix}$

$A_2 = \left. \begin{matrix} \text{---} \\ \text{---} \\ \text{---} \end{matrix} \right|_c^{\frac{\pi}{2}+c} - \int_c^{\frac{\pi}{2}+c} \cos(x-c) dx = \frac{\pi}{2} + c - c - \int_0^{\frac{\pi}{2}} \cos(u) du = \frac{\pi}{2} - \sin(u) \Big|_0^{\frac{\pi}{2}}$

$A_2 = \frac{\pi}{2} - \sin\left(\frac{\pi}{2}\right) = \frac{\pi}{2} - 1 = \frac{\pi}{2} - 1$

$A_1 = A_2 \Rightarrow$

$\sin(x_0) - \sin(x_0-c) - \sin(c) = \frac{\pi}{2} - c - 1$; $c = ?$

$x_0 = \arctan \left[\frac{1-\cos(c)}{\sin(c)} \right]$

$$\sin(x_0) - \sin(x_0 - c) - \sin(c) = \pi - c - 1$$

$$\frac{\sin(x_0)}{\cos(x_0)} = \tan x_0 = \frac{1 - \cos(c)}{\sin(c)}$$

$$\sin(c) = (1 - \cos(c)) \frac{\cos(x_0)}{\sin(x_0)}$$

$$\sin(x_0) - \sin(x_0) \cos(c) + \sin(c) \cos(x_0) - \sin(c) = \pi - c - 1$$

$$\sin(x_0) (1 - \cos(c)) + \cos(x_0) \sin(c) = \pi - c - 1 + \sin(c)$$

$$\cos(x_0) \left[\frac{1}{\sin(x_0)} (1 - \cos(c)) + \sin(c) \right] = \pi - c - 1 + \sin(c)$$

$$\cos(x_0) \left[\frac{(1 - \cos(c))^2 + \sin^2(c)}{\sin(c)} \right] = \pi - c - 1 + \sin(c)$$

$$\cos(x_0) \cdot \frac{1 - 2\cos(c) + \cos^2(c) + \sin^2(c)}{\sin(c)} = \pi - c - 1 + \sin(c)$$

$$\cos(x_0) \frac{2(1 - \cos(c))}{\sin(c)} = 2 \cos(x_0) \tan x_0 = 2 \cos(x_0) \frac{\sin(x_0)}{\cos(x_0)}$$

$$2 \sin(x_0) = \pi - c - 1 + \sin(c)$$

$$x_0 = \arcsin \frac{\pi - c - 1 + \sin(c)}{2}$$

$$2 \sin(x_0) - \sin(c) = \pi - c - 1$$

$$2 \sin(x_0) - (1 - \cos(c)) \frac{\cos(x_0)}{\sin(x_0)} = \pi - c - 1$$

$$2 \sin^2(x_0) - \cos^2(x_0) + \cos(c) \cos(x_0) = \pi - c - 1$$

$$\arctan \frac{1 - \cos(c)}{\sin(c)} = \arcsin \frac{\pi - c - 1 + \sin(c)}{2}$$

$$\cos(x_0) = \frac{\cos(c)}{\sqrt{2\cos^2(c) - 2\cos(c) + 1}}$$

$$\sqrt{1 - \cos^2(x_0)} = \frac{\pi - c - 1 + \sin(c)}{2}$$

$$1 - \cos^2(x_0) = \frac{(\pi - c - 1 + \sin(c))^2}{4}; \quad 1 - \frac{\cos^2(c)}{2\cos^2(c) - 2\cos(c) + 1} = \frac{(\pi - c - 1 + \sin(c))^2}{4}$$

$$\frac{2\cos^2(c) - 2\cos(c) + 1 - \cos^2(c)}{2\cos^2(c) - 2\cos(c) + 1} = \frac{(\pi - c - 1 + \sin(c))^2}{4}$$

$$\int_0^{\pi/2} [\cos x - \cos(x-c)] dx = - \int_{\pi/2+c}^{\pi} \cos(x-c) dx$$

$$\lambda = \frac{\pi}{2} + c \quad \mu = \frac{\pi}{2}$$

$$x = \pi \quad \mu = \pi - c$$

$$\sin(x) \Big|_0^{\pi/2} - \int_0^{\pi/2} \cos(x-c) dx = - \int_{\pi/2+c}^{\pi} \cos(x-c) dx$$

$$x - c = \mu$$

$$dx = d\mu$$

$$x = 0 \quad \mu = -c$$

$$x = \frac{c}{2} \quad \mu = -\frac{c}{2}$$

$$\sin\left(\frac{c}{2}\right) - \int_{-c}^{-c/2} \cos(\mu) d\mu = - \sin(\mu) \Big|_{\pi/2}^{\pi-c}$$

$$\sin\left(\frac{c}{2}\right) - \sin(\pi) \Big|_{-c}^{-c/2} = -\sin(\pi - c) + 1; \quad \sin\left(\frac{c}{2}\right) = \left(-\sin\left(\frac{c}{2}\right) + \sin(c)\right) = -\sin\left(\frac{c}{2}\right) + 1$$

$$2 \sin\left(\frac{c}{2}\right) - \sin(c) = -\sin(c) + 1 \quad \Rightarrow \quad 2 \sin\left(\frac{c}{2}\right) = 1 \quad \Rightarrow \quad \sin\left(\frac{c}{2}\right) = \frac{1}{2}$$

$$\sin\left(\frac{c}{2}\right) = \frac{1}{2} \quad \Rightarrow \quad \frac{c}{2} = \frac{\pi}{6} \quad \boxed{c = \frac{\pi}{3}}$$

$$\sin(x_0) - \sin(x_0 - c) - \sin(c) = 1 - \sin(c)$$

$$\sin(x_0) = \sin(x_0 - c) \quad \Rightarrow \quad x_0 = x_0 - c \quad \Rightarrow \quad c = 0$$

$$\sin(x_0) - \sin(x_0 - c) = 1$$

$$\sin(x_0) - \sin(x_0) \cdot \cos(c) + \sin(c) \cdot \cos(x_0) = 1$$

$$\sin(x_0) (1 - \cos(c)) + \sin(c) \cdot \cos(x_0) = 1$$

(49) $\frac{x}{x^2+1} = mx$ $1 = mx^2 + m$; $mx^2 + m - 1 = 0$

$$x_2 = \frac{1-m}{m} \quad x_0 = \pm \sqrt{\frac{1-m}{m}} \quad \boxed{0 < m < 1}$$

$$y_1 = mx \quad ; \quad y_2 = \frac{x}{x^2+1}$$

$$A = 2 \int_0^{\sqrt{\frac{1-m}{m}}} \left(\frac{x}{x^2+1} - mx \right) dx; \quad A_1 = \left. \begin{array}{l} x^2+1 = u \\ 2x dx = du \\ x=0 \quad u=1 \\ x=x_0 \quad u=x_0^2+1 \end{array} \right| = \int_1^{x_0^2+1} \frac{du}{u} = \ln(u) \Big|_1^{x_0^2+1}$$

$$\boxed{A_1 = \ln\left(\left(\frac{1-m}{m}\right)^2 + 1\right) - 0} \quad A_2 = \ln\left(\frac{1-m}{m} + 1\right) = \ln\left(\frac{1-m+m}{m}\right) = \ln\left(\frac{1}{m}\right)$$

$$A_2 = 2 \int_0^{\sqrt{\frac{1-m}{m}}} mx dx = 2 \cdot m \cdot \frac{x^2}{2} \Big|_0^{\sqrt{\frac{1-m}{m}}} = m \left(\frac{1-m}{m} - 0 \right) = 1-m$$

$$A = A_1 - A_2 = \ln\left(\frac{1}{m}\right) - (1-m) = \ln\left(\frac{1}{m}\right) - 1 + m = \underline{m - \ln(m) - 1}$$

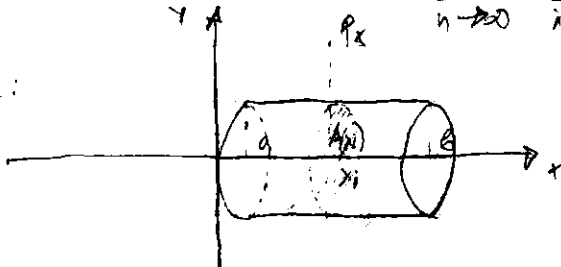
VOLUMES

$$V(\xi) \approx A(x_i^*) \Delta x \quad ; \quad V = \sum_{i=1}^n A(x_i^*) \Delta x$$

Def. $x = a \dots b$

$$V = \lim_{n \rightarrow \infty} \sum_{i=1}^n A(x_i^*) \Delta x = \int_a^b A(x) dx$$

CYLINDER:



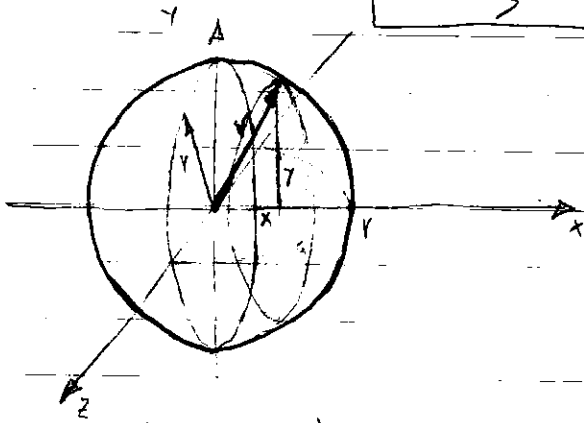
$$A(x) = A = r^2 \pi \Rightarrow \text{CIRCULAR CYLINDER}$$

$$V = \int_a^b A dx = A(b-a) = A \cdot l$$

$$\boxed{V_0 = A \cdot l = r^2 \pi l}$$

Ex. 1 Show THAT the volume of a sphere is:

$$V = \frac{4}{3} \pi r^3$$



$$V = 2 \int_0^r A(x) dx$$

$$A(x) = y^2 \cdot \pi$$

$$y = \sqrt{r^2 - x^2}$$

$$A(x) = \pi (r^2 - x^2)$$

$$V = 2 \int_0^r \pi (r^2 - x^2) dx = 2\pi \left(r^2 x \Big|_0^r - \frac{x^3}{3} \Big|_0^r \right)$$

$$V = 2\pi \left(r^2 - \frac{r^3}{3} \right) = 2\pi \frac{3r^2 - r^3}{3} = 2\pi \frac{2r^3}{3} = \frac{4\pi r^3}{3}$$

$$z^2 = r^2 - x^2 - y^2$$

$$z = \sqrt{r^2 - x^2 - y^2}$$

$$\int_0^r \int_0^{\sqrt{r^2 - x^2}} \sqrt{r^2 - x^2 - y^2} dx dy$$

$$I_1 = \int_0^r \sqrt{(r^2 - y^2) - x^2} dx = \frac{r^2}{2} \arcsin\left(\frac{x}{r}\right) + \frac{x}{2} \sqrt{r^2 - x^2}$$

Ex. 2 $y = \sqrt{x}$, $A(x) = y^2 \cdot \pi = x \cdot \pi$

$$\int_0^1 A(x) dx = \int_0^1 x \cdot \pi dx = \frac{x^2 \pi}{2} \Big|_0^1 = \frac{\pi}{2}$$

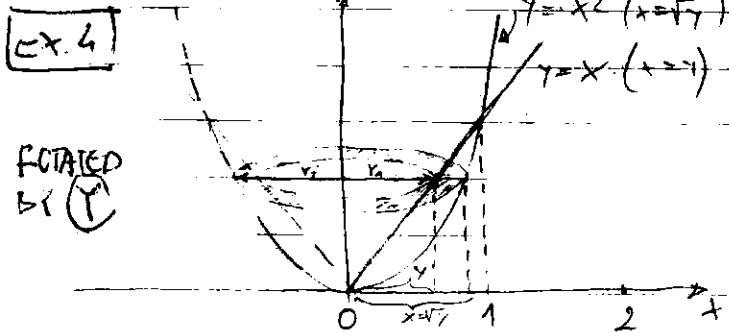
Ex. 3 $y = x^3$, $y = 8$, $x = 0$
 $x = y^{1/3} = \sqrt[3]{y}$

$$V = \int_0^8 A(y) dy$$

$$A(y) = x^2 \pi = \sqrt[3]{y^2} \pi$$

$$V = \int_0^8 \sqrt[3]{y^2} \pi dy = \pi \frac{y^{\frac{2}{3}+1}}{\frac{2}{3}+1} \Big|_0^8 = 3\pi \frac{\sqrt[3]{y^5}}{5} \Big|_0^8 = \frac{3\pi}{5} \cdot y \sqrt[3]{y^2} \Big|_0^8$$

$$V = \frac{3\pi}{5} \cdot 8 \sqrt[3]{64} = \frac{3\pi}{5} \cdot 8 \cdot 4 = \frac{3 \cdot 32 \pi}{5} = \frac{96 \pi}{5}$$



$$y_1 = x, \quad y_2 = x^2$$

$$A = (y_2^2 - y_1^2) \pi$$

$$x_2 = \sqrt{y_2} = \sqrt{y}, \quad x_1 = y_1 = y$$

$$A(y) = [(\sqrt{y})^2 - y^2] \pi$$

ROTATED BY (Y)

$$V = \pi \int_0^1 (y - y^2) dy = \pi \left(\frac{y^2}{2} - \frac{y^3}{3} \right) \Big|_0^1 = \pi \left(\frac{1}{2} - \frac{1}{3} \right) = \frac{3-2}{6} \pi = \frac{\pi}{6}$$

ROTATED BY X

$$A(x) = (x^2 - x^4) \pi$$

$$V = \int_0^1 (x^2 - x^4) \pi dx = \pi \left(\frac{x^3}{3} - \frac{x^5}{5} \right) \Big|_0^1 = \pi \frac{5-3}{15} = \frac{2\pi}{15}$$

EX. 5

$$A(x) = (v_2^2 - v_1^2) \pi$$

$$r_2 = x, \quad r_1 = x^2$$

$$v_2 = 2 - r_2 = 2 - x^2$$

$$v_1 = 2 - r_1 = 2 - x$$

$$V = \int_0^1 A(x) dx = \int_0^1 \left[(2 - x^2)^2 - (2 - x)^2 \right] dx = \frac{8\pi}{15}$$

EX. 6

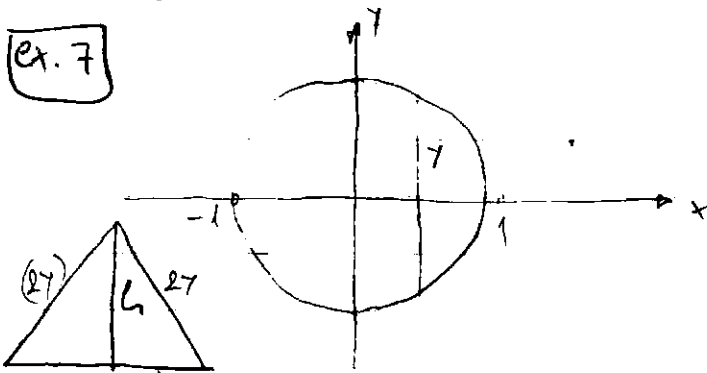
$$A(y) = (v_2^2 - v_1^2) \pi$$

$$r_1 = 1 + y$$

$$r_2 = 1 + \sqrt{y}$$

$$V = \int_0^1 \left[(1 + \sqrt{y})^2 - (1 + y)^2 \right] dy = \frac{\pi}{2}$$

EX. 7



$$x^2 + y^2 = 1 \quad y = \sqrt{1 - x^2}$$

$$A(x) = 2y \cdot \frac{l}{2} = y \cdot l$$

$$l^2 = 1^2 - \left(\frac{x}{2}\right)^2 = 1 - \frac{x^2}{4}$$

$$l^2 = \frac{4 - x^2}{4} \Rightarrow l = \frac{\sqrt{4 - x^2}}{2} = \sqrt{1 - x^2}$$

$$l^2 = (2y)^2 - y^2 = 4y^2 - y^2 = 3y^2$$

$$A(x) = y \cdot l = \sqrt{1 - x^2} \cdot \sqrt{1 - x^2} = \sqrt{1 - x^2}$$

$$V = \int_{-1}^1 A(x) dx = \int_{-1}^1 \sqrt{1 - x^2} dx = \left[\frac{x}{2} \sqrt{1 - x^2} + \frac{1}{2} \arcsin(x) \right] \Big|_{-1}^1$$

$$V = \left[\left(\frac{1}{2} \sqrt{1-1} + \frac{1}{2} \cdot \frac{\pi}{2} \right) - \left(0 + \frac{1}{2} \left(-\frac{\pi}{2} \right) \right) \right] = \sqrt{3} \left(\frac{\pi}{4} + \frac{\pi}{4} \right) = \frac{\sqrt{3}}{2} \pi$$

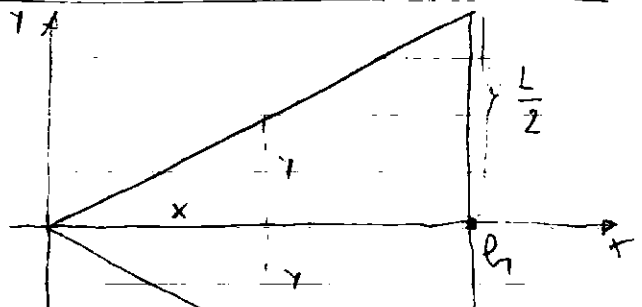
$$V = \sqrt{3} \int_{-1}^1 (1 - x^2) dx = \frac{4}{3} \sqrt{3}$$

EX. 8

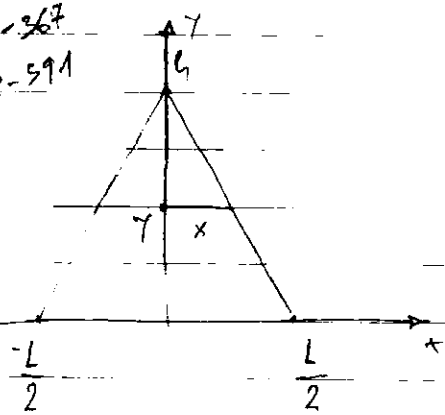
$$V = \int A(x) dx$$

$$\frac{h}{x} = \frac{L/2}{y} \quad y = \frac{L}{2h} \cdot x$$

$$A(x) = 2y \cdot 2y = 4y^2 = 4 \cdot \frac{L^2}{4h^2} x^2 = \frac{L^2 x^2}{h^2} = \frac{L^2 L}{3} = V$$



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$$\frac{\frac{L}{2}}{x} = \frac{h}{(h-y)}$$

$$\frac{L}{2x} = \frac{h}{(h-y)}$$

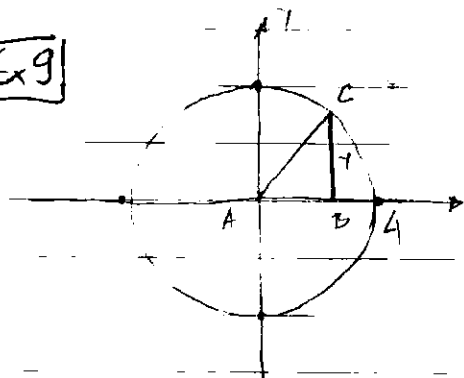
$$x = \frac{L(h-y)}{2h}$$

$$A(y) = 2x \cdot 2x = 4x^2$$

$$A(x) = A \cdot \frac{L^2(h-y)^2}{4h^2} = \frac{L^2(h-y)^2}{h^2}$$

$$V = \int_0^h \frac{L^2(h-y)^2}{h^2} dy = \frac{L^2}{3}$$

Ex 9



$$A(x) = y \cdot h / 2 = h \cdot \frac{1}{2} \sqrt{4^2 - x^2}$$

$$\frac{h}{y} = \operatorname{tg} \alpha, \quad \alpha = 30^\circ$$

$$\frac{h}{y} = \operatorname{tg}(30^\circ) = \frac{\sin 30^\circ}{\cos 30^\circ} = \frac{\frac{1}{2}}{\frac{\sqrt{3}}{2}} = \frac{\sqrt{3}}{3}$$

$$h = \frac{\sqrt{3}}{3} \cdot y$$

$$A(x) = \frac{1}{2} \cdot \frac{\sqrt{3}}{3} \cdot y^2 = \frac{1}{2} \cdot \frac{\sqrt{3}}{3} \left(\sqrt{4^2 - x^2} \right)^2 = \frac{1}{2} \cdot \frac{\sqrt{3}}{3} (16 - x^2)$$

$$V = \frac{\sqrt{3}}{3} \int_{-4}^4 (16 - x^2) dx = \frac{128}{9} \sqrt{3}$$

EXERCISES

exc 7

$$y_1 = x^2 \quad y_2 = x \quad y_2 = \sqrt{x} \quad ; \quad A(x) = (y_2^2 - y_1^2) \pi$$

$$\pi \int (x - x^4) dx = \frac{3\pi}{10}$$

exc. 8

$$y_1 = 1 \quad y_2 = \sec(x) \quad ; \quad A(x) = (y_2^2 - y_1^2) \pi = (\sec^2(x) - 1) \pi$$

$$V = -\pi \int_{-1}^1 (1 - \sec^2(x)) dx = -\pi \int_{-1}^1 \left(1 - \frac{1}{\cos^2(x)} \right) dx = \pi \int_{-1}^1 \frac{1 - \cos^2(x)}{\cos^2(x)} dx$$

$$V = \pi \int_{-1}^1 \operatorname{tg}^2(x) dx \quad \left\{ \begin{array}{l} (\sec(x))' = \left(\frac{1}{\cos(x)} \right)' = (-1 \cos^{-1}(x)) (-\sin(x)) \\ (\sec(x))' = \frac{\sin(x)}{\cos^2(x)} = \sec(x) \operatorname{tg}(x) \end{array} \right.$$

$$\left(\frac{1}{\operatorname{tg}(x)} \right)' = \left(\frac{\sin(x)}{\cos(x)} \right)' = \frac{\cos(x) \cdot \cos(x) - \sin(x) \cdot \sin(x)}{\cos^2(x)} = \frac{1}{\cos^2(x)} = \sec^2(x)$$

$$V = +2\pi \int_{-1}^1 (\sec^2(x) - 1) dx = 2\pi \left(\operatorname{tg}(x) - x \right) \Big|_{-1}^1 = 2\pi (\operatorname{tg}(1) - 1)$$

Exc. 9 $r_1 = \sqrt{x}$; $r_2 = \frac{1}{2}x$; $x_1 = 4$; $x_2 = 2y$

$\sqrt{x} = \frac{1}{2}x \implies x = \frac{1}{4}x^2 \implies \frac{1}{4}x^2 - x = 0 \implies x^2 - 4x = 0$

$x(x-4) = 0 \implies x=0 \text{ or } x=4 \implies r_1(4) = \sqrt{4} = 2$

$A(y) = (r_2^2 - r_1^2)\pi$; $A(y) = [(2y)^2 - (\sqrt{y})^2]\pi$

$V = \pi \int_0^2 (4y^2 - y^4) dy = \pi \left(\frac{4y^3}{3} - \frac{y^5}{5} \right) \Big|_0^2$

$V = \pi \left(4 \cdot \frac{8}{3} - \frac{32}{5} \right) = \pi \frac{32 \cdot 5 - 32 \cdot 3}{15} = \frac{64\pi}{15}$

Exc. 11 $A(x) = (r_1^2 - r_2^2)\pi$ $r_2 = \sqrt{x}$; $r_1 = x$
 $A(x) = [(1-x)^2 - (1-\sqrt{x})^2]\pi$

$V = \int_0^1 [(1-x)^2 - (1-\sqrt{x})^2]\pi dx = \frac{\pi}{6}$

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Exc. 17 $r_1 = 1+y$; $r_2 = y^2$ $r_1 = x^2$; $r_2 = \sqrt{x}$

$A(y) = [(1+y)^2 - (1+y^2)]\pi$ $\int_0^1 A(y) dy =$

Exc. 18 $A = (r_2^2 - r_1^2)\pi$ $b=4$; $r_1 = y$; $r_2 = 2$
 $A(y) = (16 - y^2)\pi$ $y = 2 \dots 4$

$V = \int_0^2 (16-4)\pi dy + \int_2^4 (16-y^2)\pi dy$

ROTATED BY $x=1$

$y = 0 \dots 2$ $r_2 = 4-1=3$; $r_1 = 2-1=1$

$V_1 = \int_0^2 (9-1)\pi dy = 8\pi y \Big|_0^2 = 16\pi$

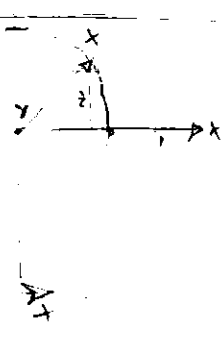
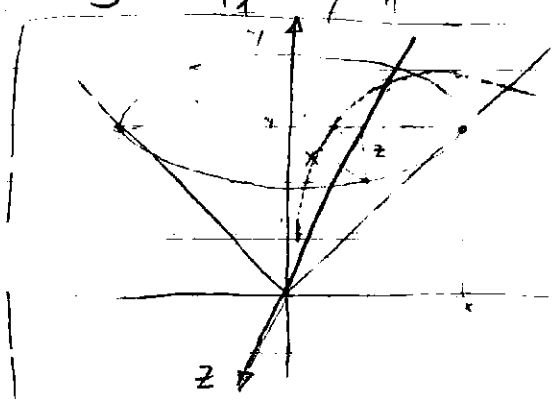
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$y = 2 \dots 4$ $r_2 = 4-1=3$ $r_1 = y-1$

$V_2 = \pi \int_2^4 [9 - (y-1)^2] dy$

$V = V_1 + V_2$

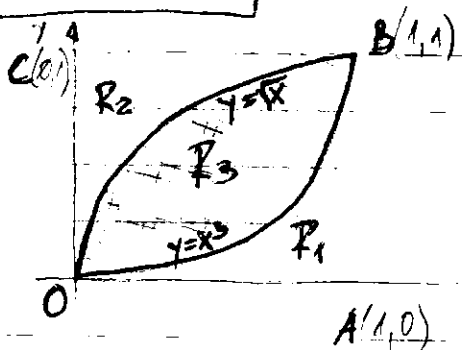
$V = 76 \frac{\pi}{3}$



MARLE VOLUME OF REVOLUTION

Volume of Revolution ($x^2 + 1, x = 0 \dots 1$)

Exercise 19



$$y_1(x) = \sqrt{x}$$

$$y_2(x) = x^3$$

[21] $y_1 = x^3$ $y_2 = (x+2)^3$
 $x_1 = \sqrt[3]{y}$ $y^{1/3} = -x+2$
 $x_2 = 2 - \sqrt[3]{y}$

$A(y) = y^2 \pi$; $2y = 2 - \sqrt[3]{y} - \sqrt[3]{y} = 2(1 - \sqrt[3]{y})$; $r = 1 - \sqrt[3]{y}$

CIRCULAR CYLINDER :

$$y^2 \pi \cdot L = 1^2 \cdot \pi \cdot 1 = \pi$$

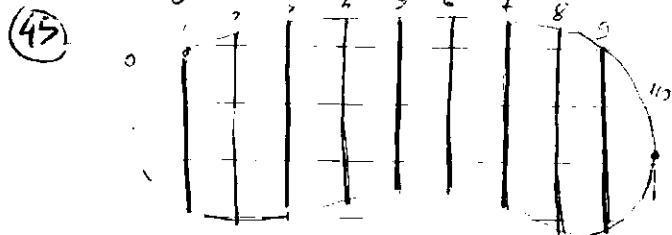
(19) = $\frac{\pi}{7}$ (23) = $\frac{\pi}{2}$ (27) = $\frac{5\pi}{14}$ $\frac{\pi}{7} + \frac{\pi}{2} + \frac{5\pi}{14} = \frac{2+7+5}{14}\pi = \pi$
 (20) = $\frac{10\pi}{21}$ (22) = $\frac{5\pi}{14}$ (26) = $\frac{\pi}{6}$ (30) + (28) + (26) = π

[31] $\tan^2(x) = 1$ $\tan(x) = 1$ $x = \frac{\pi}{4}$

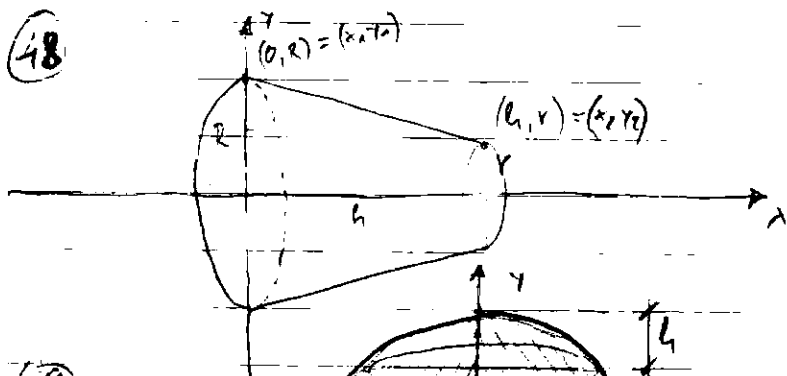
[43] $\pi \int_0^1 (y^4 - y^8) dy$

$y_1 = \sqrt{x}$ $x_1 = y_1^2$; $y_2 = \sqrt[4]{x}$ $x_2 = y^4$

[44] $\pi \int_0^{\pi/2} [(1 + \cos x)^2 - 1^2] dx$



$n = 6$ $\Delta x = \frac{b-a}{n} = \frac{15-0}{6} = 3 \text{ cm}$
 $V = \sum_{i=1}^6 A(x_i) \Delta x = 3 \cdot \sum_{i=1}^6 A(x_i)$



$$y - R = \frac{r - R}{h - 0} (x - 0)$$

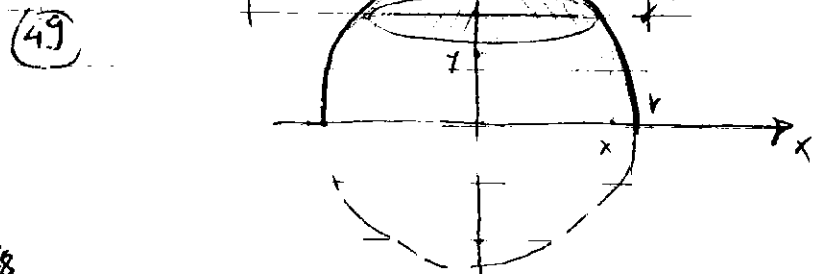
$$y = \frac{r - R}{h} x + R$$

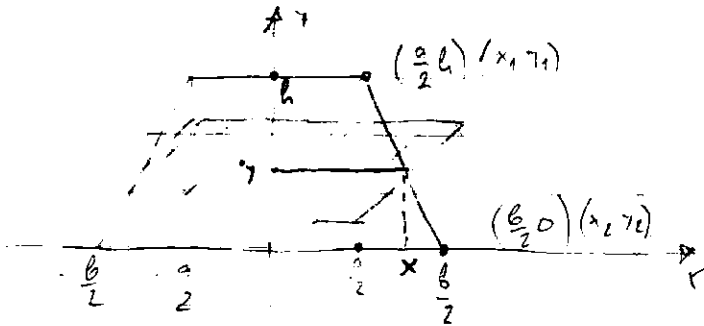
$$V = \int_0^h \pi y^2(x) dx$$

$$y^2 + x^2 = r^2$$

$$x = \sqrt{r^2 - y^2}$$

$$y = \sqrt{r^2 - x^2}$$





$$y-h = \frac{0-h}{\frac{b}{2}-\frac{a}{2}} \left(x - \frac{a}{2}\right)$$

$$y-h = \frac{2h}{a-b} \left(x - \frac{a}{2}\right)$$

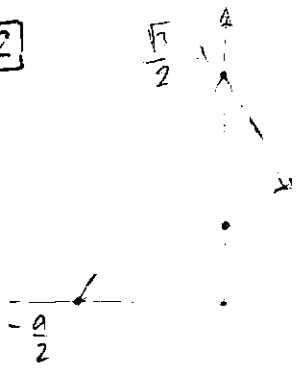
$$x = \frac{a-b}{2h} (y-h) + \frac{a}{2}$$

$$A(x) = (2x)(2x) = 4x^2$$

$$V = 4 \int_0^h \left[\frac{a-b}{2h} (y-h) + \frac{a}{2} \right]^2 dy$$

$$\rightarrow \frac{a-b}{2h} y - \frac{a-b}{2} + \frac{a}{2} = \frac{a-b}{2h} y - \frac{a}{2} + \frac{b}{2} + \frac{a}{2} = \frac{a-b}{2h} y + \frac{b}{2}$$

52



$$\left(\frac{\sqrt{3}}{2}\right)^2 + \left(\frac{1}{2}\right)^2 = \frac{3}{4} + \frac{1}{4} = 1$$

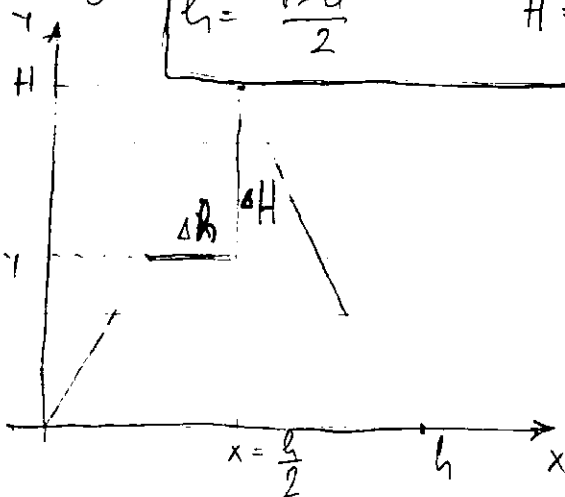
$$P = \frac{a \cdot h}{2} = \frac{a \cdot \frac{\sqrt{3}}{2} a}{2} = \frac{a^2 \sqrt{3}}{4}$$

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$$h = \frac{\sqrt{3}a}{2}; H = \sqrt{h^2 - \left(\frac{h}{2}\right)^2} = \sqrt{\left(\frac{\sqrt{3}}{2}\right)^2 - \left(\frac{1}{4}\right)^2} = a \sqrt{\frac{3}{4} - \frac{1}{16}} = a \sqrt{\frac{12-1}{16}} = \sqrt{\frac{11}{16}} = \frac{\sqrt{11}}{4}$$

$$\int_0^H A(y) dy \quad y=0 \quad A(0) = \frac{a \cdot h}{2}$$

$$h = \frac{\sqrt{3}a}{2} \quad H = \frac{3a}{4}$$



$$\frac{\Delta H}{\Delta h} = \frac{H}{h/2} \quad \frac{\Delta H}{\Delta h} = \frac{2H}{h}$$

$$\Delta h = \frac{h}{2H} \Delta H = \frac{h}{2H} (H - y)$$

$$2 \Delta h = \frac{\sqrt{3} \Delta a}{2} \quad \Delta a = \frac{4 \Delta h}{\sqrt{3}}$$

$$A(y) = \frac{\Delta a \cdot \Delta h}{2} = \frac{\Delta h \cdot 4 \Delta h}{2} = \frac{4 \sqrt{3}}{3} \Delta h^2$$

$$A(y) = \frac{4 \sqrt{3}}{3} \left[\frac{h}{2H} (H - y) \right]^2$$

$$V = \frac{\sqrt{3}}{16} a^3$$

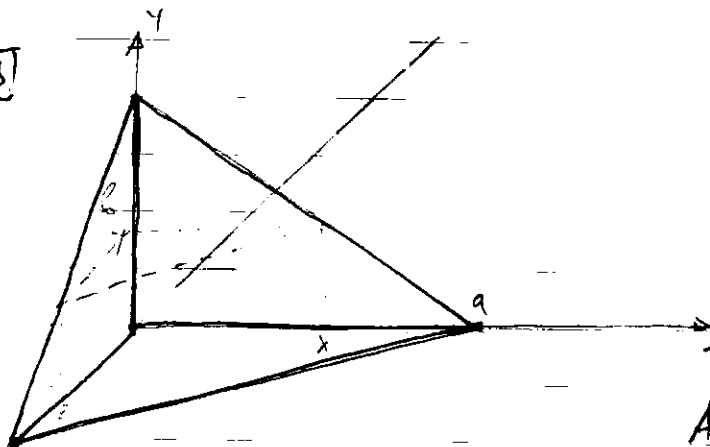
$$\Delta h = \frac{h}{2H} (H-y) \quad ; \quad \Delta h = \frac{h}{2} \left(1 - \frac{y}{H}\right)$$

$$\Delta a = \frac{4\Delta h}{\sqrt{3}} = \frac{4}{\sqrt{3}} \cdot \frac{h}{2} \left(1 - \frac{y}{H}\right) = \left| h = \frac{\sqrt{3}}{2} a \right| = \frac{4}{\sqrt{3}} \cdot \frac{1}{2} \cdot \frac{\sqrt{3}}{2} a \left(1 - \frac{y}{H}\right)$$

$$\Delta a = a \left(1 - \frac{y}{H}\right)$$

$$V = \int_0^H A(y) dy = \int_0^H \frac{4\sqrt{3}}{3} \left[\frac{h}{2H} (H-y) \right]^2 dy = \frac{\sqrt{3}}{16} a^3 = \frac{\sqrt{3}}{12} a^2 \cdot H$$

53



$$a=3; \quad b=4; \quad c=5; \quad [\text{cm}]$$

$$V = ?$$

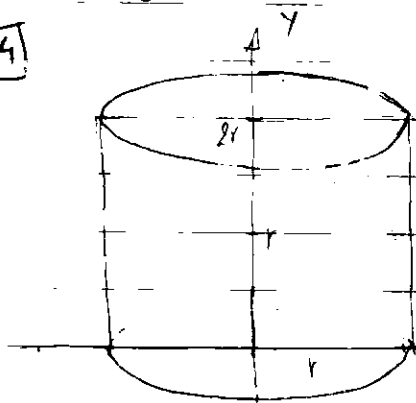
$$\frac{a}{b} = \frac{x}{y} = \frac{3}{4}; \quad x = \frac{3}{4} y$$

$$\frac{c}{b} = \frac{z}{y} = \frac{5}{4}; \quad z = \frac{5}{4} y$$

$$A(y) = \frac{x \cdot z}{2} = \frac{1}{2} \cdot \frac{3}{4} \cdot \frac{5}{4} y^2 = \frac{15}{32} y^2$$

$$V = \int_0^4 A(y) dy = \int_0^4 \frac{15}{32} y^2 dy = \frac{15}{32} \frac{y^3}{3} \Big|_0^4 = 5 \cdot \frac{64}{32} = 25 \cdot 10$$

54



$$V = r^2 \pi \cdot h = r^2 \pi \cdot 2r = 2r^3 \pi$$

$$x = r$$

$$V = \int_0^{2r} x^2(y) \pi dy = \int_0^{2r} r^2 \pi dy = r^2 \pi y \Big|_0^{2r}$$

$$V = 2r^3 \pi$$

PIESECE NE SE KVAADRATI !!

$$x^2 + y^2 = r^2 \quad A(x) = (2y)(2y) = 4y^2 = 4(r^2 - x^2)$$

$$V = \int_{-r}^r A(x) dx = \int_{-r}^r 4(r^2 - x^2) dx = 2 \int_0^r 4(r^2 - x^2) dx = \frac{16r^3}{3}$$

$$55) \quad 9x^2 + 4y^2 = 36$$

$$4y^2 = 36 - 9x^2$$

$$y = \sqrt{\frac{9 - 9x^2}{4}}$$

$$y = 3 \sqrt{1 - \left(\frac{x}{2}\right)^2}$$

$$\frac{9x^2}{36} + \frac{4y^2}{36} = 1$$

$$\frac{x^2}{4} + \frac{y^2}{9} = 1$$

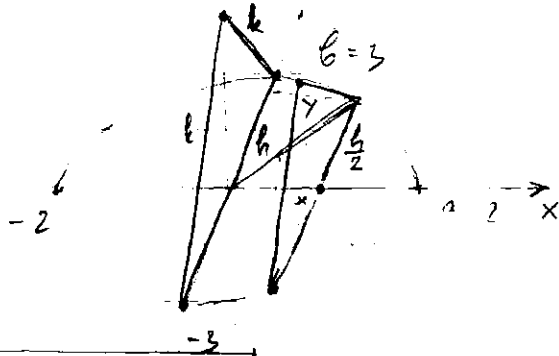
$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$$

$$a = 2$$

$$b = 3$$

11.11

AE AY



$$h^2 = k^2 + k^2$$

$$h = \sqrt{2}k$$

$$P = k \cdot k / 2 = \frac{k^2}{2}$$

$$y = h/2 = \frac{\sqrt{2}k}{2}$$

$$y = 3 \sqrt{1 - \left(\frac{x}{2}\right)^2}$$

$$\frac{\sqrt{2}k}{2} = 3 \sqrt{1 - \left(\frac{x}{2}\right)^2}$$

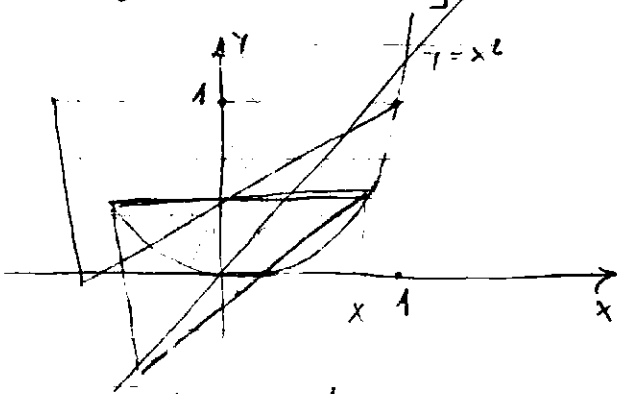
$$k = \frac{6}{\sqrt{2}} \sqrt{1 - \left(\frac{x}{2}\right)^2} = 3\sqrt{2} \sqrt{1 - \left(\frac{x}{2}\right)^2}$$

$$k = 3 \sqrt{2 - \frac{x^2}{2}}$$

$$A(x) = \frac{k^2}{2} = \frac{1}{2} \cdot 9 \left(2 - \frac{x^2}{2}\right) = \frac{9}{4} (4 - x^2)$$

$$A(x) = 9 \left(1 - \left(\frac{x}{2}\right)^2\right)$$

56) $R = \{(x,y) \mid x^2 \leq y \leq 1\}$



$$y = x^2 \quad x = \sqrt{y}$$

$$A(y) = \frac{2x \cdot h}{2} = x \cdot h$$

$$h^2 + \left(\frac{a}{2}\right)^2 = a^2 \quad h^2 = a^2 - \frac{a^2}{4}$$

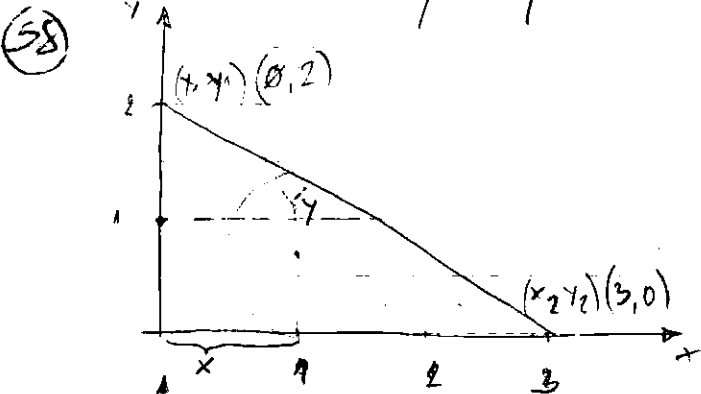
$$h = \frac{a\sqrt{3}}{2}; \quad a = 2x; \quad h = x\sqrt{3}$$

$$A(y) = x(y) \cdot x(y) \sqrt{3}$$

$$A(y) = (\sqrt{y})^2 \frac{\sqrt{3}}{2} = \frac{\sqrt{3}y}{2}$$

$$V = \int_0^1 \frac{\sqrt{3}y}{2} dy = \left. \frac{\sqrt{3}}{2} \frac{y^2}{2} \right|_0^1 = \frac{\sqrt{3}}{4}$$

57) $A(y) = a \cdot a = |a = 2x| = 4x^2 = 4y; \quad V = \int_0^1 4y dy = 4 \frac{y^2}{2} \Big|_0^1 = 2$



$$y - 2 = \frac{0 - 2}{3 - 0} (x - 0)$$

$$y = -\frac{2}{3}x + 2 = -\frac{2}{3}(x - 3)$$

$$A(x) = \frac{y^2(x)}{4} \cdot \frac{\pi}{2}$$

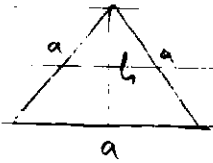
$$V = \frac{\pi}{8} \int_0^3 \left[-\frac{2}{3}(x-3)\right]^2 dx = 2\pi$$

$$A(y) = \left(\frac{x(y)}{2}\right)^2 \cdot \frac{\pi}{2}$$

$$\frac{2}{3}x = 2 - y \quad x = -\frac{3}{2}(y - 2)$$

$$V = \frac{\pi}{8} \int_0^2 \left[-\frac{3}{2}(y-2)\right]^2 dy = \frac{3\pi}{4}$$

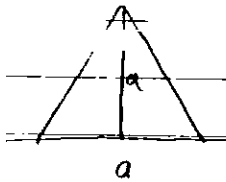
(59) $x = -\frac{3}{2}(y-2)$



$h = \sqrt{a^2 - \frac{a^2}{4}} = \frac{\sqrt{3}}{2} a$ $D = a \cdot h/2$

$A(y) = x(y) \cdot h/2 = \frac{1}{2} x^2(y) \cdot \frac{\sqrt{3}}{2} = \frac{\sqrt{3}}{4} x^2(y)$

$V = \int_0^2 \frac{\sqrt{3}}{4} x^2(y) dy = \frac{\sqrt{3}}{4} \int_0^2 \frac{9}{4} (y-2)^2 dy =$

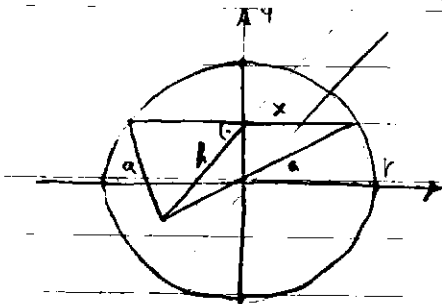


$A(y) = a \cdot h/2 = \frac{a^2}{2} = \frac{x^2(y)}{2}$

$\frac{1}{2} \int_0^2 x^2(y) dy = 3$

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KIRI MASCOV

(60)

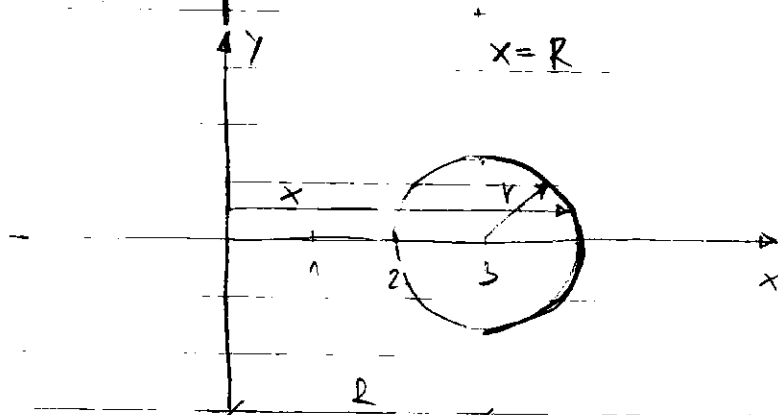


$x = \sqrt{r^2 - y^2}$

$A(y) = h \cdot x = h \sqrt{r^2 - y^2}$

$V = \int_{-r}^r h \sqrt{r^2 - y^2} dy = \frac{h \cdot r^2 \pi}{2}$

(61)



GJOWO
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$y = \sqrt{r^2 - (x-R)^2}$ $A_1(y) = (r_2^2 - r_1^2) \pi$

$r_2 = x - \sqrt{r^2 - (x-R)^2}$ $r_1 = R$ $A_1 = (r^2 - (x-R)^2 - R^2) \pi$

~~$A_2(y) = (R^2 - r^2 + (y-R)^2) \pi$~~

~~$A(y) = A_1(y) + A_2(y) = [r^2 - (x-R)^2 - R^2 + R^2 - r^2 + (y-R)^2] \pi$~~

$A_2(y) = (r_2^2 - r_1^2) \pi$; $r_2 = R$; $r_1 = R - \sqrt{r^2 - (y-R)^2}$

~~$A_2(y) = \pi [R^2 - (R - \sqrt{r^2 - (y-R)^2})^2] = \pi [R^2 - R^2 + 2R\sqrt{r^2 - (y-R)^2} - (r^2 - (y-R)^2)] = \pi (2R\sqrt{r^2 - (y-R)^2} - r^2 + (y-R)^2)$~~

~~$A(y) = A_1(y) + A_2(y) = \pi [r^2 - (x-R)^2 - R^2 + 2R\sqrt{r^2 - (y-R)^2} - r^2 + (y-R)^2]$~~

~~$A(y) = 2R\sqrt{r^2 - (y-R)^2} - R^2$~~

~~$V = \int_{-r}^r A(y) dy = \int_{-r}^r (2R\sqrt{r^2 - (y-R)^2} - R^2) dy$~~

$$y = \sqrt{r^2 - (x-R)^2} \quad r^2 + (x-R)^2 = r^2$$

$$y^2 + x^2 - 2Rx + R^2 = r^2 \quad \hookrightarrow \quad (x-R)^2 = r^2 - y^2 \quad x = R + \sqrt{r^2 - y^2}$$

$$x(y) = R + \sqrt{r^2 - y^2} \quad ; \quad A_1(y) = (x^2(y) - R^2) \pi$$

$$A_2(y) = -\left((2-x(y))^2 + R^2 \right) \pi \quad ; \quad A(y) = A_1(y) + A_2(y) = (x^2 - R^2 + R^2 - (2-x)^2) \pi$$

$$A(y) = \pi (x^2 - R^2 + 2Rx - x^2) = \pi (2Rx - R^2) = \pi (2R(R + \sqrt{r^2 - y^2}) - R^2)$$

$$A(y) = \pi (R^2 + 2R\sqrt{r^2 - y^2})$$

$$V = \pi \int_0^r (R^2 + 2R\sqrt{r^2 - y^2}) dy$$

$$V = (2R^2 \cdot r + Rr^2 \pi) \pi$$

DVA NL € DODKO ZATOJA:

$$x_1(y) = R + \sqrt{r^2 - y^2} \quad x = f(y) = R + \sqrt{r^2 - y^2}$$

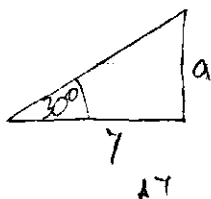
$$x_2(y) = R - \sqrt{r^2 - y^2} \quad x = g(y) = R - \sqrt{r^2 - y^2}$$

$$A(y) = (x_1^2 - x_2^2) \pi = \pi (R^2 + 2R\sqrt{r^2 - y^2} + (r^2 - y^2) - R^2 + 2R\sqrt{r^2 - y^2} - (r^2 - y^2))$$

$$A(y) = 4R\pi \sqrt{r^2 - y^2}$$

$$V = \int_{-r}^r 4R\pi \sqrt{r^2 - y^2} dy = 2\pi \int_0^r 4R \sqrt{r^2 - y^2} dy = 8\pi R \cdot \frac{r^2 \pi}{4} = 2\pi^2 R r^2$$

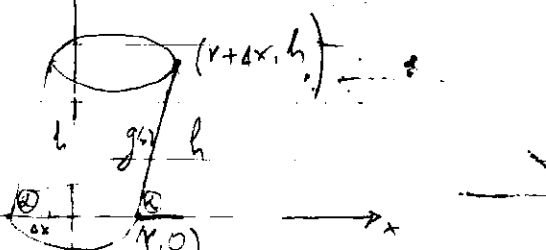
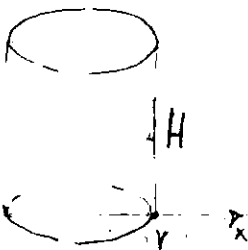
62 $x = \sqrt{16 - y^2} \quad \operatorname{tg}(30^\circ) = \frac{a}{y} = \frac{\sin 30}{\cos 30} = \frac{\frac{1}{2}}{\frac{\sqrt{3}}{2}} = \frac{\sqrt{3}}{3}$



$$a = \frac{\sqrt{3}}{3} \cdot y \quad A(y) = 2a \cdot x = 2 \cdot \frac{\sqrt{3}}{3} \cdot y \cdot \sqrt{16 - y^2}$$

$$V = \int_0^4 \frac{2\sqrt{3}}{3} \cdot y \cdot \sqrt{16 - y^2} dy = \frac{128\sqrt{3}}{9}$$

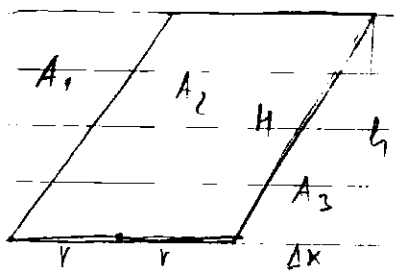
63



$$V = \int_0^h r^2 \pi dy = r^2 \pi y \Big|_0^h = r^2 \pi h \quad \operatorname{tg}(\alpha) = \frac{h}{4x} \quad ax = \frac{h}{\operatorname{tg}(\alpha)}$$

$$g(x) = \operatorname{tg}(\alpha) (x-r) = \frac{h}{\sqrt{H^2 - r^2}} (x-r) \quad \frac{\sqrt{H^2 - r^2}}{h} y = x-r, \quad x = \frac{\sqrt{H^2 - r^2}}{h} \cdot y + r$$

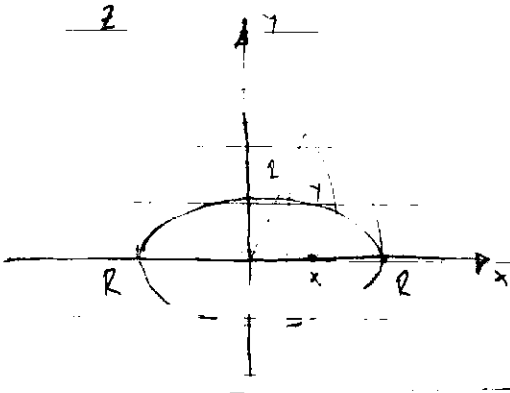
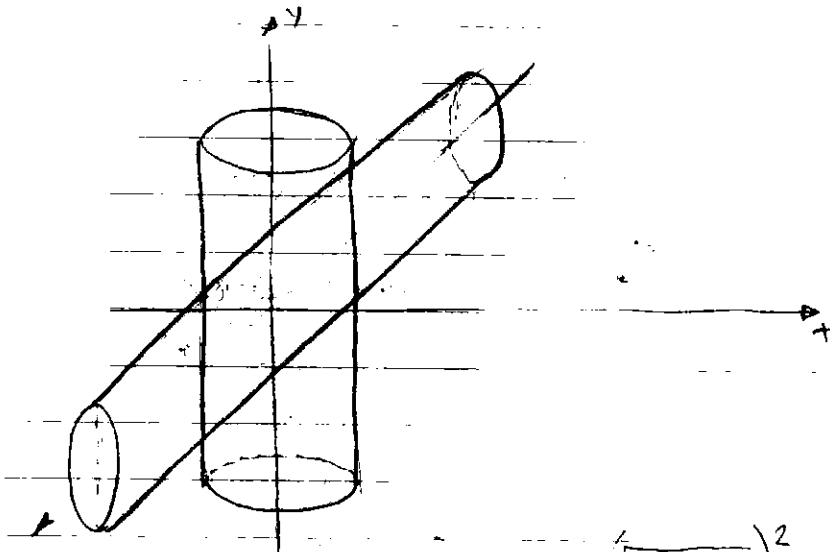
$$V = \int_0^h (x-r)^2 \pi dy = \pi \int_0^h \frac{H^2 - r^2}{h^2} \cdot y^2 dy = \pi \frac{H^2 - r^2}{h^2} \frac{y^3}{3} \Big|_0^h = \frac{\pi (H^2 - r^2)}{3} h$$



$$A = (\Delta x + 2r) \cdot h - \frac{2\Delta x \cdot h}{2}$$

$$A = \Delta x \cdot h + 2r \cdot h - \Delta x \cdot h = 2r \cdot h$$

$$V = \int_0^h r^2 \pi \, dy = r^2 \pi h$$



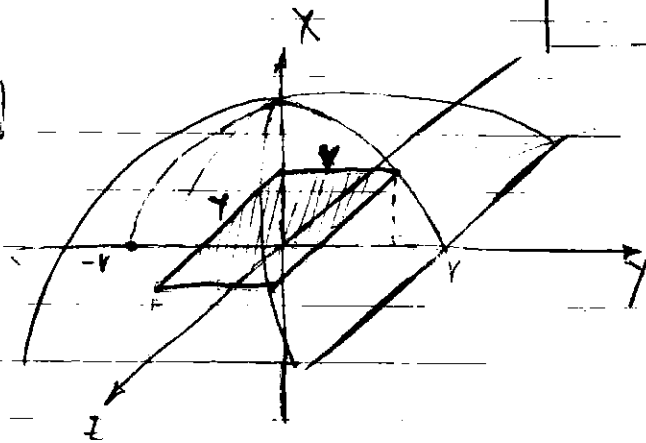
$$A(x) = \left(\sqrt{R^2 - x^2} \right)^2 \pi$$

$$\int_{-R}^R (\sqrt{R^2 - x^2})^2 \pi \, dx = 2 \int_0^R (R^2 - x^2) \pi \, dx$$

$$= 2\pi R^2 x \Big|_0^R - 2\pi \frac{x^3}{3} \Big|_0^R = 2\pi \left(R^3 - \frac{R^3}{3} \right)$$

$$= 2\pi \frac{2R^3}{3} = \frac{4\pi R^3}{3}$$

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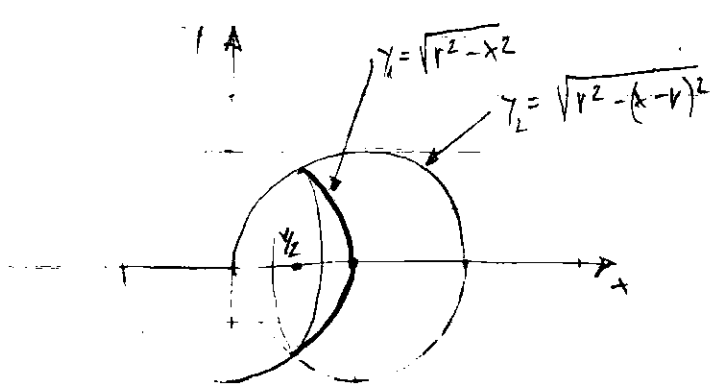


$$y = \sqrt{r^2 - x^2}$$

$$z = \sqrt{r^2 - y^2}$$

$$A(x) = 4yz = 4(r^2 - x^2)$$

$$V = \int_{-r}^r 4(r^2 - x^2) \, dx = \frac{16r^3}{3}$$



$$0 < x < \frac{r}{2} \quad y_1 = \sqrt{r^2 - (x-r)^2}$$

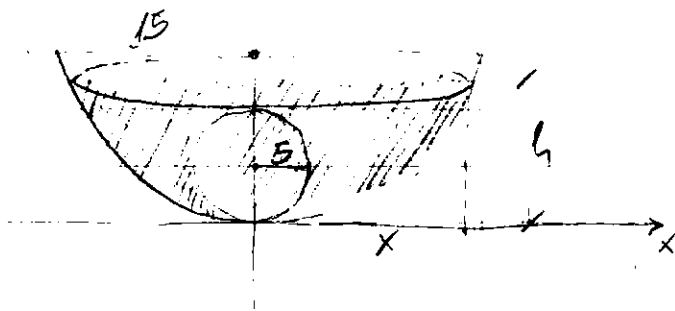
$$\frac{r}{2} < x < r \quad y_1 = \sqrt{r^2 - x^2}$$

$$V = \int_0^{\frac{r}{2}} \pi(r^2 - (x-r)^2) dx + \int_{\frac{r}{2}}^r \pi(r^2 - x^2) dx$$

Volume of the cap: $V_c = \frac{1}{3} \pi h^2 (3r - h) = \left(h = \frac{r}{2} \right) = \frac{1}{3} \pi \frac{r^2}{4} (3r - \frac{r}{2})$

$$V_c = \frac{r^2 \pi}{12} \frac{6r - r}{2} = \frac{12\pi \cdot 5r}{24} = \frac{5\pi r^3}{24} ; \quad V = 2V_c = \frac{5\pi r^3}{12}$$

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$$x = \sqrt{15^2 - (y-15)^2}$$

if: $h \geq 10$ cm

$$V = \int_0^h (\pi(15^2 - (y-15)^2)) dy - \frac{4}{3} \pi (15^3)$$

$$y = 30 + \sqrt{30^2 - x^2}$$

$$(y-30)^2 = 30^2 - x^2 \quad x = \sqrt{30^2 - (y-30)^2}$$

$$V = -\frac{1}{3} \pi h^3 + 180\pi h^2 - \frac{5000}{3} \pi$$

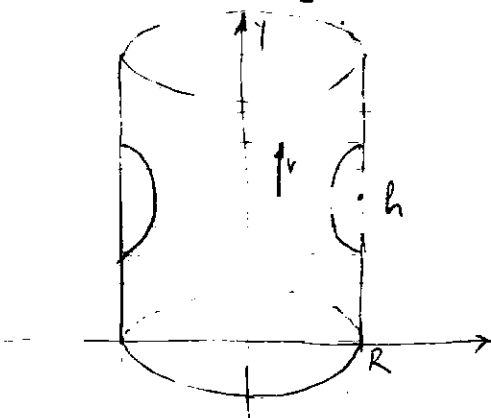
eg: $h = 30 \Rightarrow V(30) = \frac{13000}{3} \pi \text{ [cm}^3]$

if: $h \leq 20$ cm

$$V = \int_0^h (\pi(30^2 - (y-30)^2)) dy - \int_0^h (\pi(10^2 - (y-10)^2)) dy = 40\pi h^2$$

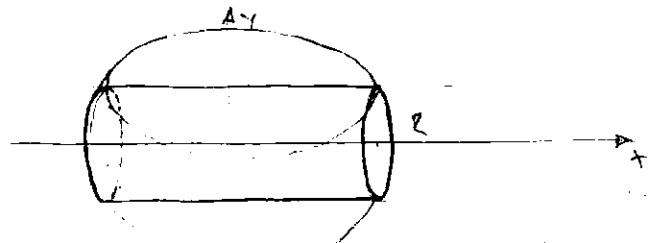
eg: $V(8) = 640\pi \text{ [cm}^3]$

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$$V = V_1 + V_2$$

$$V_1 = R^2 \pi \cdot (h - 2r)$$



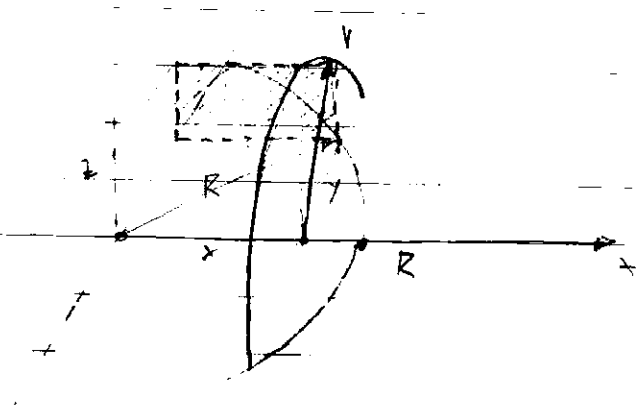
$$V_2 = R^2 \pi \cdot 2r - r^2 \pi \cdot 2R$$

$$V = V_1 + V_2 = R^2 \pi h - R^2 \pi \cdot 2r + R^2 \pi \cdot 2r - r^2 \pi \cdot 2R = R^2 \pi h - r^2 \pi \cdot 2R$$

$$x = \sqrt{R^2 - y^2} \quad z = \sqrt{r^2 - y^2} ; \quad A(y) = x \cdot z = \sqrt{R^2 - y^2} \sqrt{r^2 - y^2}$$

$$V = \int_{-r}^r A(y) dy = \int_{-r}^r \sqrt{R^2 - y^2} \sqrt{r^2 - y^2} dy =$$

Δz



$$f(z) = z \cdot x$$

$$z = \sqrt{r^2 - y^2}$$

$$x = \sqrt{R^2 - y^2}$$

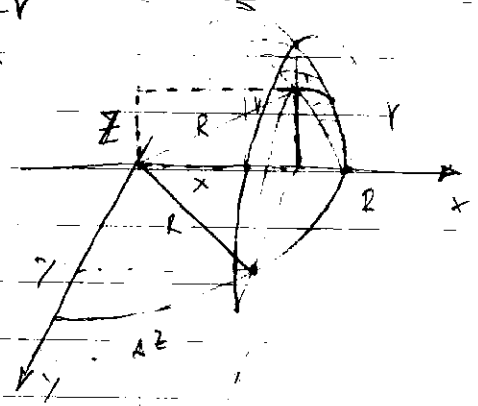
$$V = \int_{-y}^y 4 \sqrt{r^2 - y^2} \sqrt{R^2 - y^2} dy$$

$$= 8 \int_0^y \sqrt{r^2 - y^2} \sqrt{R^2 - y^2} dy$$

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Δz

$x \geq R - y$



$$V = V_1 + V_2$$

$$V_1 = 2 \int_0^R (\sqrt{R^2 - x^2})^2 \pi dx$$

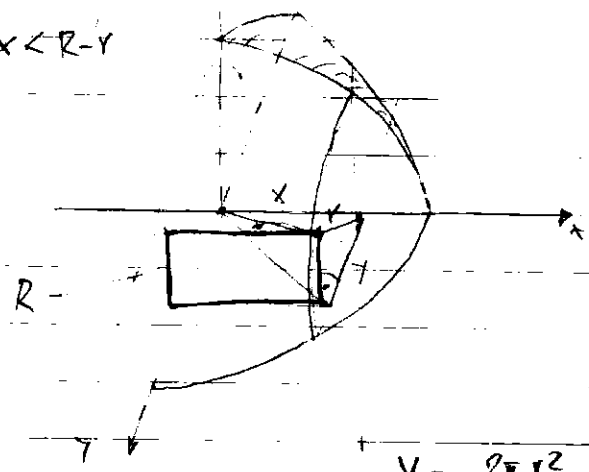
$$R - y$$

$$V_1 = 2 \cdot \pi \cdot R^2 \left(R - \frac{y}{3} \right) = 2 \cdot \frac{\pi R^2}{3} (3R - y)$$

$$x = \sqrt{R^2 - y^2}$$

$$z = \sqrt{r^2 - y^2}$$

$x < R - y$



$$V_2 = \int_{-y}^y 4 \sqrt{R^2 - y^2} \cdot \sqrt{r^2 - y^2} dy =$$

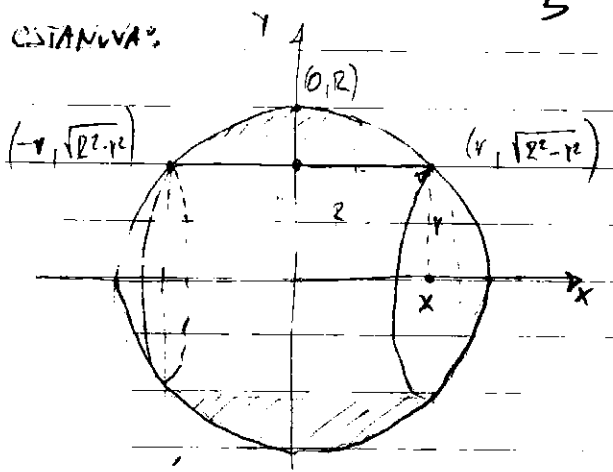
$$= 8 \sqrt{R^2 - y^2} \int_0^y \sqrt{r^2 - y^2} dy$$

$$V_2 = 2 \sqrt{R^2 - y^2} \cdot y^2 \pi = 2x \cdot y^2 \pi$$

$$V = \frac{2\pi R^2}{3} (3R - y) + 2 \sqrt{R^2 - y^2} y^2 \pi$$

volume of cylinder
revisited!

• CISTARNA:

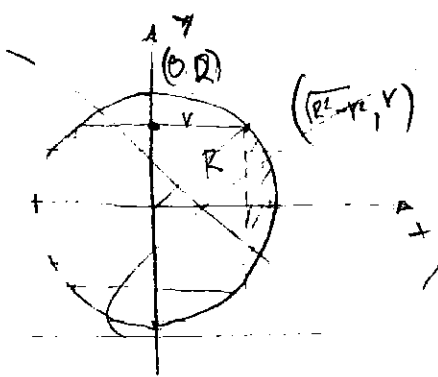


$$y = \sqrt{R^2 - x^2} = y_2 ; y_1 = y ;$$

$$A(x) = \pi(y_2^2 - y_1^2) = 2 \int_{\sqrt{R^2 - y^2}}^y \pi (R^2 - x^2 - y^2) dx$$

$$V = 2 \int_0^{\sqrt{R^2 - y^2}} \pi (R^2 - x^2 - y^2) dx$$

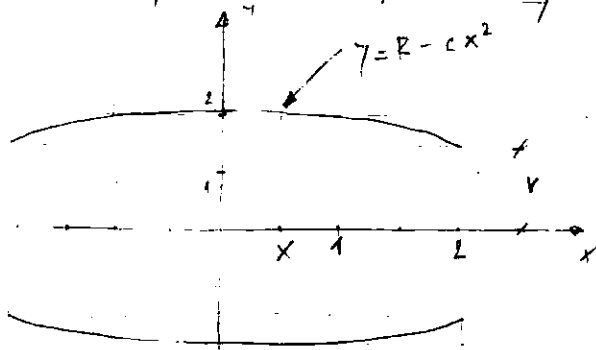
$$= \frac{4\pi}{3} (R^2 - y^2)^{3/2}$$



$$x = \frac{\sqrt{R^2 - r^2}}{\sqrt{R^2 - r^2}} = 1$$

$$\int_0^L \pi (R^2 - x^2) dx$$

69) $R = 2m; h = 2m; c = 0.5;$



$$y = R - cx^2; d = \frac{cR^2}{4}$$

$$r = R - d$$

① $r(\frac{h}{2}) = R - c \frac{h^2}{4} = r$

$$r = R - c \frac{h^2}{4} = R - d$$

$$d = \frac{cR^2}{4}$$

② $A(x) = \pi r^2; cx^2 = R - y$

$$x = \sqrt{\frac{R-y}{c}}$$

$$V = 2 \int_0^{h/2} \pi (R - cx^2)^2 dx = 2 \int_0^{h/2} \pi (R - \frac{4d}{R^2} x^2)^2 dx$$

$$V = \frac{1}{3} \pi h (2R^2 + r^2 - \frac{2}{3} d^2)$$

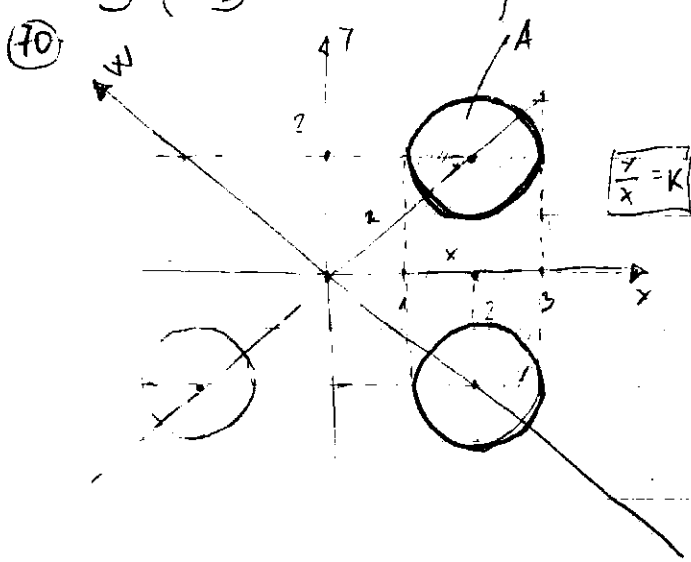
$$r = R - d \rightarrow d = R - r$$

$$V = 2 \left(\frac{1}{10} \pi d^2 h - \frac{1}{3} \pi R d h + \frac{1}{2} \pi R^2 h \right) = 2 \pi h \left(\frac{d^2}{10} - \frac{Rd}{3} + \frac{R^2}{2} \right)$$

$$= 2 \pi h \left(\frac{d^2}{10} - \frac{2(R-r)}{3} + \frac{R^2}{2} \right) = \pi h \left(\frac{d^2}{10} - \frac{2R}{3} + \frac{2r}{3} + \frac{R^2}{2} \right)$$

$$= 2 \pi h \left(\frac{d^2}{10} + \frac{3R^2 - 2R^2}{6} + \frac{2r}{3} \right) = \pi h \left(\frac{d^2}{5} + \frac{R^2}{3} + \frac{2R \cdot r}{3} \right) =$$

$$= \frac{\pi h}{3} \left(\frac{3d^2}{5} + R^2 + 2R \cdot r \right)$$



$$V_1 = \int_{z-r}^{z+r} A(x) dx = \pi \int_{z-r}^{z+r} \left(2 + \sqrt{1 - (x-2)^2} \right)^2 dx$$

$$= \left(2 - \sqrt{1 - (x-2)^2} \right)^2 dx = 4\pi^2$$

$$z = x^2 + y^2 = x^2 + k^2 x^2 = x^2 \sqrt{1+k^2}$$

If $k=2$ then $z = x \sqrt{5}$

$$V_2 = \pi \int_{2\sqrt{2}-r}^{2\sqrt{2}+r} \left(2\sqrt{2} + \sqrt{1 - (x-2\sqrt{2})^2} \right)^2 - \left(2\sqrt{2} - \sqrt{1 - (x-2\sqrt{2})^2} \right)^2 dx$$

$$V_2 = \frac{2\sqrt{2}-r}{\sqrt{2}} V_1$$

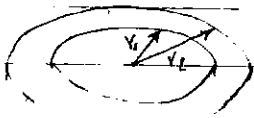
$$V_2 = \sqrt{k^2 + 1} V_1$$

$$f(x) > g(x) \quad [a, b]$$

$$V = \pi \int_a^b [f(x)+k]^2 - [g(x)+k]^2 dx = \pi \int_a^b [f^2(x) + 2kf(x) + k^2 - g^2(x) - 2kg(x) - k^2] dx$$

$$V = \pi \underbrace{\int_a^b [f^2(x) - g^2(x)] dx}_{V_1} + 2k\pi \underbrace{\int_a^b [f(x) - g(x)] dx}_A = \underline{\underline{V_1 + 2k\pi A}}$$

VOLUMES BY CYLINDRICAL SHELLS



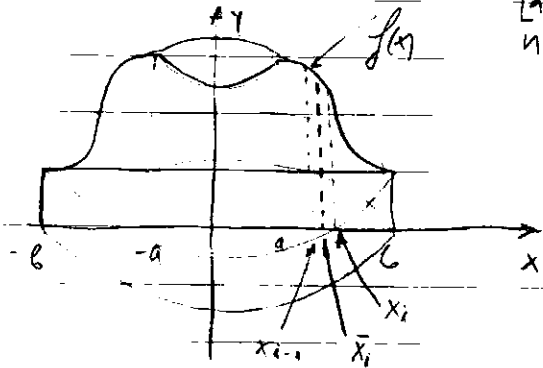
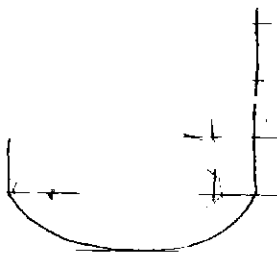
$$V = V_2 - V_1 = r_2^2 \pi h - r_1^2 \pi h = \pi h \cdot (r_2^2 - r_1^2)$$

$$V = 2\pi h \frac{r_1 + r_2}{2} (r_2 - r_1) = 2\pi r h \cdot \Delta r$$

$$\Delta r = r_2 - r_1 \quad r = \frac{r_1 + r_2}{2}$$

$$V = 2\pi r h \cdot \Delta r$$

$$V = [\text{circumference}] [\text{height}] [\text{thickness}]$$



[a, b]
n-subintervals $[x_{i-1}, x_i]$ Δx $x_i = \frac{x_i + x_{i-1}}{2}$

$$V_i = 2\pi \bar{x}_i f(\bar{x}_i) \Delta x$$

$$V = \sum_{i=1}^n 2\pi \bar{x}_i f(\bar{x}_i) \Delta x = \sum_{i=1}^n V_i$$

$$\lim_{n \rightarrow \infty} \sum_{i=1}^n 2\pi \bar{x}_i f(\bar{x}_i) \Delta x = \int_a^b 2\pi x f(x) dx$$

$$V = \int_a^b 2\pi x f(x) dx \quad 0 \leq a < b$$

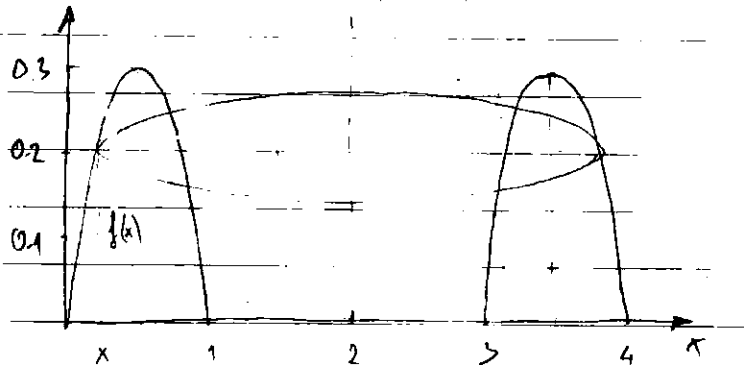
EXAMPLE 1

$$y(x) = 2x^2 - x^3$$

$$V = 2 \int_0^2 2\pi x f(x) dx = \frac{32\pi}{5}$$

EX 4

$$y = x - x^2; \quad y = 0; \quad x = 2$$



$$\int_0^1 2\pi(2-x) f(x) dx$$

EXERCISES

1 $y = x(x-1)^2$

2 $y = \sin(x^2); \quad +^2 = \text{sgn}(\arcsin(y))$

$$V = \int_0^{\sqrt{\pi}} 2\pi x \sin(x^2) dx$$

$$\int_0^1 \pi \arcsin(y) dy$$

$$V = \int_1^2 2\pi x \ln(x) dx = 2\pi \int_1^2 x \ln(x) dx = 2\pi \left(\frac{x^2}{2} \ln(x) - \int \frac{x^2}{2} d \ln(x) \right) =$$

$$= 2\pi \left(2 \ln(2) - \int_1^2 \frac{x^2}{2} \cdot \frac{1}{x} dx \right) = 2\pi \left(2 \ln(2) - \frac{1}{2} \int_1^2 x dx \right) =$$

$$2\pi \left(2 \ln(2) - \frac{1}{2} \frac{x^2}{2} \Big|_1^2 \right) = 2\pi \left(2 \ln(2) - \frac{1}{4} (4-1) \right) = 2\pi \left(2 \ln(2) - \frac{3}{4} \right)$$

$$\boxed{V = -\frac{3}{2}\pi + 4\pi \ln 2}$$

27) $n=4$; $y = \tan(x)$ $0 \leq x \leq \pi/4$

$$\Delta x = \frac{b-a}{n} = \frac{\pi/4 - 0}{4} = \frac{\pi}{16}$$

$$x_i = \left[0, \frac{\pi}{16}, \frac{2\pi}{16}, \frac{3\pi}{16}, \frac{4\pi}{16} \right]$$

$$x_i = \left[\frac{\pi}{32}, \frac{3\pi}{32}, \frac{5\pi}{32}, \frac{7\pi}{32} \right]; \quad V = \sum_{i=1}^n 2\pi x_i f(x_i) \Delta x$$

28) $n=5$ $\Delta x = \frac{b-a}{n} = \frac{12-2}{5} = 2$

$$V = \sum_{i=1}^n 2\pi x_i \cdot f(x_i) \cdot \Delta x = 2\pi \Delta x (x_1 f(x_1) + x_2 f(x_2) + \dots + x_n f(x_n))$$

29) $\int_0^3 2\pi x^5 dx = \int_0^3 2\pi x^4 dx$

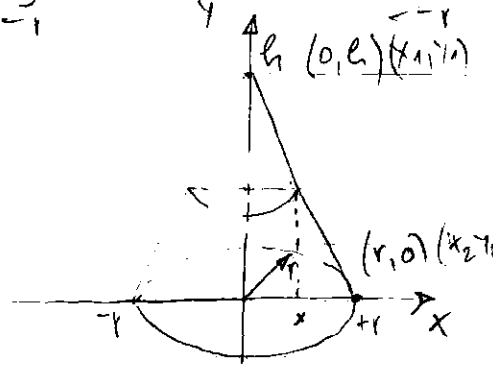
31) $x = 1 - y^2$ $y = \sqrt{1-x}$

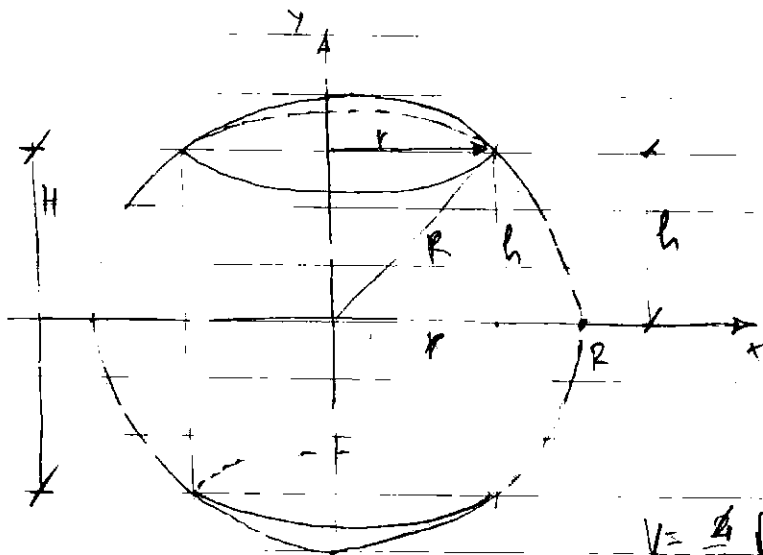
41) $x^2 + (y-1)^2 = 1$; $(y-1)^2 = 1 - x^2$ $y = 1 \pm \sqrt{1-x^2}$

$$V = \frac{4\pi}{3} r^3 \quad \boxed{V = \frac{4\pi}{3}} \quad x = \sqrt{1 - (y-1)^2}$$

44) $V = 2 \int_{R-v}^{R+v} 2\pi x \sqrt{r^2 - x^2} \cdot 2 dx = \left. \begin{array}{l} u = x - R \\ du = dx \\ x = R + u \quad u = R + x - R = x \\ x = R - u \quad u = R - x - R = -x \end{array} \right\} = 2 \int_{R-v}^{R+v} 2\pi (R+u) \sqrt{r^2 - u^2} du$

$$V = 2 \int_{-v}^v 2\pi R \sqrt{r^2 - u^2} du + 2 \int_{-v}^v 2\pi u \sqrt{r^2 - u^2} du = 2\pi R \cdot \frac{12\pi}{2} = 2\pi^2 R v^2$$

45)  $y - h = \frac{0-h}{v} (x-0)$ $\boxed{y = -\frac{h}{v}x + h}$



$$r = \sqrt{R^2 - h^2}$$

$$y = \sqrt{R^2 - x^2}; \quad x = \sqrt{R^2 - y^2}$$

$$V = \int_0^R 2\pi x \sqrt{R^2 - x^2} dx$$

$$V = \frac{4}{3} \sqrt{R^2 - r^2} \pi R^2 - \frac{4}{3} \sqrt{R^2 - r^2} \pi r^2$$

$$V = \frac{4\pi}{3} \sqrt{R^2 - r^2} (R^2 - r^2) = \frac{4\pi}{3} (R^2 - r^2)^{3/2} = \frac{4\pi}{3} (R^2 - (R^2 - h^2))^{3/2}$$

$$V = \frac{4\pi}{3} (h^2)^{3/2} = \frac{4\pi}{3} h^3$$

$$h = \frac{H}{2}; \quad V = \frac{4\pi}{3} \frac{H^3}{8} = \frac{\pi H^3}{6}$$

$$R = 2; \quad r = 1; \quad h = \sqrt{4 - 1} = \sqrt{3} \quad V = \frac{4\pi}{3} \sqrt{3}^3 = \frac{4\pi}{3} \cdot 3\sqrt{3} = 4\pi\sqrt{3}$$

$$V = \frac{4\pi R^3}{3} - r^2 \pi H - V_{cap}$$

$$V_{cap} = 2 \int_0^h \pi (\sqrt{R^2 - y^2})^2 dy = \frac{4}{3} \pi R^3 + \frac{2}{3} \pi h^3 - 2\pi R^2 h$$

$$V_{cap} = \frac{1}{3} \pi (R-h)^2 (3R - R + h) = \frac{\pi}{3} (R^2 - 2Rh + h^2) (2R + h)$$

CAP FORMULA

$$V_{cap} = \frac{4}{3} \pi R^3 + \frac{2}{3} \pi \frac{H^3}{8} - 2\pi R^2 \cdot \frac{H}{2}$$

$$V = \frac{4\pi R^3}{3} - r^2 \pi H - \frac{4\pi R^3}{3} - \frac{2\pi H^3}{24} + \frac{2\pi R^2 H}{2}$$

$$= \cancel{\frac{4\pi R^3}{3}} - \left(R^2 - \frac{H^2}{4}\right) \cdot \pi \cdot H - \frac{\pi H^3}{4R} + \pi R^2 H$$

$$= \cancel{\frac{4\pi R^3}{3}} - R^2 \pi H + \frac{\pi H^3}{4} - \frac{\pi H^3}{12} + \pi R^2 H = \frac{3\pi H^3 - \pi H^3}{12}$$

$$= \frac{2\pi H^3}{12} = \frac{\pi H^3}{6}$$

64 WORK

Second Newton Law:

$$F = m \cdot \frac{d^2 s}{dt^2}; \quad 1 \text{ N} (=) \text{ kg} \frac{\text{m}}{\text{s}^2}$$

$$W = F \cdot d \quad \text{work} = \text{force} \cdot \text{Distance}$$

$$1 \text{ J} (=) \text{ N} \cdot \text{m}$$

ex 1) a) BOOK 1.2 kg, DESK 0.7m HIGH, $g = 9.8 \text{ m/s}^2$
 $W = d \cdot F$ $E = m \cdot \frac{d^2 s}{dt^2}$ $F = m \cdot g = 1.2 \cdot 9.8$

$F = 11.76 \text{ [N]}$; $W = 8.232 \text{ [J]}$

b) 20 lb 6 [ft] $1 \text{ [ft]} = 0.305 \text{ [m]}$ $1 \text{ [lb]} = 0.454 \text{ [kg]}$

$W_i = f(x_i) \Delta x$ $W = \sum_{i=1}^n f(x_i) \Delta x$

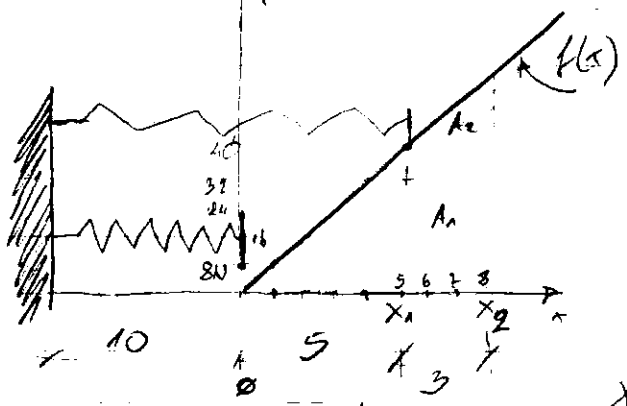
$W = \lim_{n \rightarrow \infty} \sum_{i=1}^n f(x_i) \Delta x = \int_a^b f(x) dx$

ex 2) $f(x) = x^2 + 2x$ $W = \int_1^3 f(x) dx = \left(\frac{x^3}{3} + x^2 \right) \Big|_1^3 = \frac{27}{3} + 9 - \left(\frac{1}{3} + 1 \right)$

$W = \frac{27 + 27 - 1 - 3}{3} = \frac{50}{3}$

$\frac{1 \text{ cm}}{10^2 \text{ m}}$

ex 3)



$f(x) = k \cdot x$
 $40 \text{ N} = k \cdot 5 \cdot 10^{-2} \text{ m}$
 $k = \frac{40}{5} \cdot 10^2 = 8 \cdot 10^2 = 800 \text{ [N/m]}$

$f(x_2) = 800 \cdot 8 \cdot 10^{-2} = 64 \text{ N}$
 $f(x_1) = 40 \text{ N}$

~~$W = \int_{f(x_1)}^{f(x_2)} f(x) dx = \int_{40}^{64} 2 \cdot 10^2 dx = 2 \cdot 10^2 \cdot (64 - 40)$~~

~~$W = 32 \cdot 10^2 = 0.32 \text{ [J]}$~~

$W = \int_{0.05}^{0.08} k \cdot x dx = k \cdot \frac{x^2}{2} \Big|_{0.05}^{0.08} = 1.56 \text{ [J]}$

$W = A_1 + A_2 = 40 \cdot 2 \cdot 10^{-2} + \frac{1}{2} (24 \cdot 3 \cdot 10^{-2}) = \frac{120}{100} + \frac{36}{100} \cdot \frac{1}{2} = 1.2 + \frac{0.36}{2}$

$W = 1.2 + 0.36 = 1.56 \text{ [J]}$

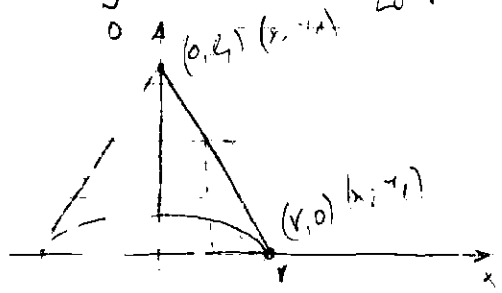
ex 4) 200 lb cable 100 [ft] LONG

$F = (100 - x)$

~~$W = \int_0^{100} (100 - x) dx$~~

PODOLNA SILA - $g = \frac{200}{100} = 2 \frac{\text{lb}}{\text{ft}}$ $A = g \cdot x$

$W = \int_0^{100} g \cdot x dx = 2 \left[\frac{\text{lb}}{\text{ft}} \right] \cdot \frac{x^2}{2} \Big|_0^{100} = (10^2)^2 = 10^4 = 10,000 \text{ lb-ft}$

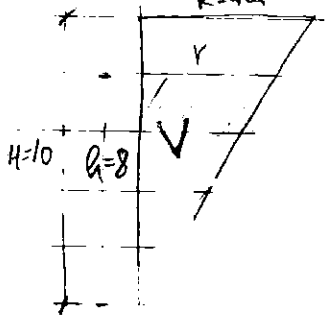


$r = h_1 = \frac{h}{r} \cdot x$ $y = h - \frac{h}{r} x$
 $V = \int_0^r 2\pi x \cdot \left(h - \frac{h}{r} x \right) dx = \frac{\pi h r^2}{2}$

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ex 5

$$V = \frac{\pi r^2 \cdot h}{2}$$



$$\frac{H}{R} = \frac{h}{r} \quad r = \frac{R}{H} \cdot h = \frac{8}{10} \cdot 8 = \frac{16}{5} \text{ m} = 3.2 \text{ m}$$

$$V = \frac{\pi r^2 \cdot h}{2} = \frac{1024}{5} \pi$$

density of the water $\rho = 1000 \frac{\text{kg}}{\text{m}^3}$

$$m = \rho \cdot V = 1000 \cdot \frac{1024}{5} \pi = 40960 \pi \text{ kg}$$

$$F = m \cdot g = 40.960 \pi \cdot 9.8 \quad W = F \cdot H = 4.0141 \cdot 10^6 \pi \text{ [J]}$$

SEPAK NE SITE DIZOVI TREBA DA SE KRETA ZA H

$$\frac{y_i}{10-x_i} = \frac{4}{10} \quad y_i = \frac{4}{10} (10-x_i) = \frac{2}{5} (10-x_i)$$

$$V_i = \pi r_i^2 \cdot \Delta x = \frac{4\pi}{25} (10-x_i)^2 \Delta x$$

$$m_i = \rho \cdot V_i = 1000 \cdot V_i = 160 \pi (10-x_i)^2 \Delta x$$

$$F_i = m_i g \approx 9.8 \cdot 160 \pi (10-x_i)^2 \Delta x = 1570 \pi (10-x_i)^2 \Delta x$$

$$W_i = F_i \cdot x_i = 1570 \pi x_i (10-x_i)^2 \Delta x$$

$$W = \lim_{n \rightarrow \infty} \sum_{k=1}^n 1570 \pi x_i (10-x_i)^2 \Delta x = \int_0^{10} 1570 \pi x (10-x)^2 dx$$

exc 1

$$W = ? \quad d = 8 \text{ m} \quad F = 900 \text{ N} \quad W = F \cdot d = 900 \cdot 8 = 7200 \text{ J}$$

exc 2

$$W = ? \quad m = 60 \text{ kg} \quad F = m \cdot g = 60 \cdot 9.8 = 588 \text{ N}$$

$$W = d \cdot F = 1176 \text{ J} \quad d = 2 \text{ m}$$

exc 3

$$F = \frac{10}{(1+x)^2} \text{ pounds} \quad d = 9 \text{ ft}$$

$$\int_0^9 \frac{10 dx}{(1+x)^2} = 9 \text{ ft} \cdot \text{lb}$$

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exc 4

$$F = 100 (\pi x / 3)$$

exc 5

$$W = \lim_{n \rightarrow \infty} \sum_{k=1}^n F(x_i) \cdot \Delta x$$

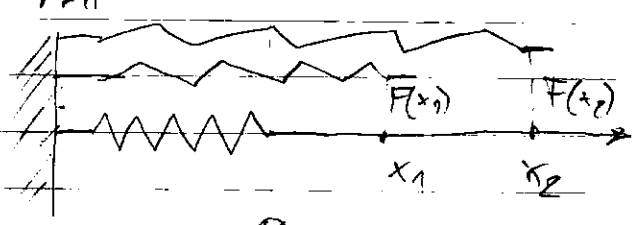
$$\Delta x = \frac{8-0}{4} = \frac{8-0}{4} = 2$$

$$F(x) = \frac{30}{4} \cdot x \quad F(1) = \frac{30}{4} = 7.5; \quad F(3) = \frac{30}{4} = 22.5$$

$$x = 4.8 \quad F(x) = 30$$

$$W \approx \sum_{i=1}^4 F(x_i) \cdot \Delta x = [7.5 + 22.5 + 30 + 30] \cdot 2$$

exc 7



$$F(x) = k \cdot x$$

$$10 \text{ lb} = k \cdot \frac{6}{12} \text{ ft}$$

$$k = \frac{120}{4} \frac{\text{lb}}{\text{ft}}$$

$$k = 30 \left[\frac{\text{lb}}{\text{ft}} \right]$$

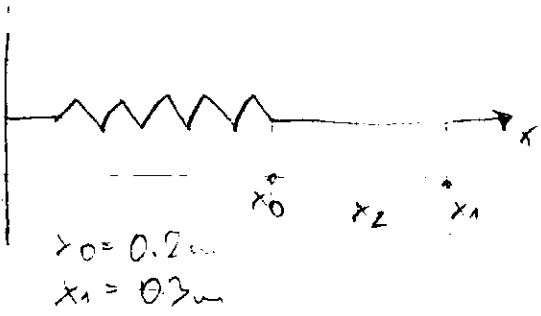
$$W = \int_0^{6/12} F(x) dx = \int_0^{0.5} 30 \cdot x dx = 30 \frac{x^2}{2} \Big|_0^{0.5} = 15 \left(\frac{1}{4} \right) = \frac{15}{4} [1.6]$$

exc 8 $F(0.3) = 25 \text{ N}$

$$F(0.3) = k(x_1 - x_2) = 0.1 \cdot k [m]$$

$$0.10k = 25 \text{ N}$$

$$k = 250 \frac{N}{m}$$



$$W = \int_0^{0.05} 250 \cdot x dx = 250 \frac{x^2}{2} \Big|_0^{0.05}$$

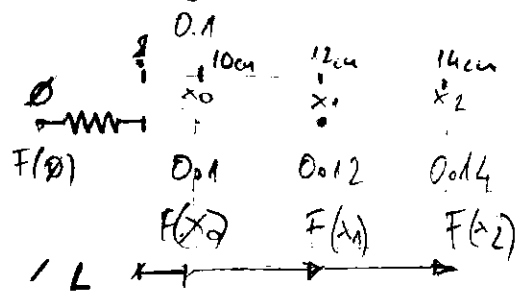
$$W = \frac{250}{2} (0.05^2 - 0) = 0.3125 \text{ J}$$

(11) $2 \text{ J} = \int_0^{0.12} kx dx = k \frac{x^2}{2} \Big|_0^{0.12} = k \cdot 0.0072 \quad \left[k = 277.8 \frac{N}{m} \right]$

$$F(x) = 30 \text{ N} = k \cdot x_0 \quad ; \quad x_0 = \frac{F(x)}{k} = \frac{30}{277.8} = 0.108 \text{ m}$$

$x_0 = 10.8 \text{ cm}$

(12) $6 = F(0) \int_0^{0.12} kx dx = k \frac{x^2}{2} \Big|_0^{0.12} = k \cdot 0.0072 + 6 \quad k = \frac{6}{0.0072} = 277.777$



$$10 \text{ J} = \int_{0.1}^{0.12} kx dx = 0.0002k$$

$$k = 3846.1545 \frac{N}{m}$$

$$6 = \int_{0.1}^{0.12-L} kx dx = 0.0002k(11 - 100L) \quad (1^o)$$

$$10 = \int_{0.1-L}^{0.14-L} kx dx = 0.0002k(13 - 100L) \quad (2^o)$$

$$(1^o) \rightarrow k = \frac{30000}{11 - 100L}$$

$$(2^o) \quad 50000 = \frac{30000}{11 - 100L} (13 - 100L) \quad 5(11 - 100L) = 3(13 - 100L)$$

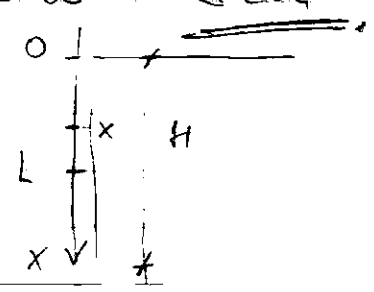
$$55 - 500L = 39 - 300L \quad 55 - 39 = 500L - 200L$$

$$16 = 200L \quad L = \frac{16}{200} = \frac{8}{100} = \frac{2}{25} = 0.08 \text{ m} = 8 \text{ cm}$$

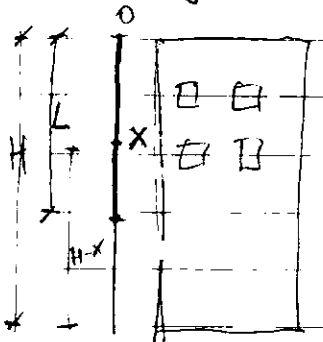
(13) $L = 50 \text{ ft}$; $\delta = 0.5 \frac{lb}{ft}$; $H = 120 \text{ ft}$

$$W = F \cdot d \quad ; \quad W = \int_0^L F(x) dx$$

$$F(x) = g \cdot (x \cdot \delta) \quad ; \quad W = \int_0^L g(x \cdot \delta) dx =$$



$L = 50 \text{ ft}$ $wl = 0.5 \text{ lb/ft}$ $H = 120 \text{ ft}$



$F = g \cdot m$ $W = F \cdot d$

$\Delta I = g \cdot \overbrace{m \Delta x}^{wl}$ $\Delta W = \Delta F \cdot x = g \cdot \overbrace{m \Delta x}^{wl} \cdot x$

$\Delta F = wl \cdot \Delta x$ $\Delta W = g \cdot x \cdot wl \cdot \Delta x$

$W = \sum_{x=1}^n g \cdot x_i \cdot wl \cdot \Delta x$

$W = \int_0^L g \cdot x \cdot wl \cdot dx = 9.8 \cdot 0.5 \int_0^L x dx = 9.8 \cdot 0.5 \cdot \frac{x^2}{2} \Big|_0^L$

$W = 0.5 \cdot \frac{1}{2} (50^2) = 0.5 \cdot 0.5 \cdot 2500 = 625 \text{ ft-lb}$

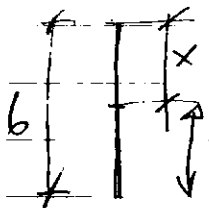
$W = \int_0^L 0.5x dx = 625 \text{ ft-lb}$ $W_1 = \int_0^{L/2} 0.5x dx = \frac{625}{4} \text{ ft-lb}$

$W_2 = \int_{L/2}^L 0.5x dx = \int_{25}^{50} 0.5x dx = \frac{625}{2}$

$W = W_1 + W_2$
 $\frac{625}{4} + 1250 = \frac{1875}{4}$

(14) $L = 10 \text{ m}$ $m = 80 \text{ kg}$ $wl = \frac{80}{10} = \frac{4}{5} = 8 \frac{\text{kg}}{\text{m}}$

$F = g \cdot m$ $\int_0^6 g \cdot m(6-x) dx = 9.8 \cdot 8 \int_0^6 (6-x) dx = 1411.2 \text{ J}$



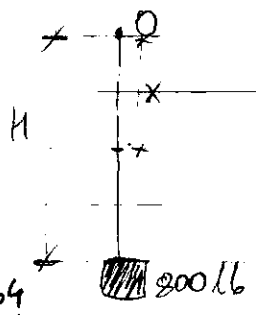
$\Delta W = \Delta F \cdot (H-x) = \frac{4m \cdot g}{5} (H-x)$

$\delta = \frac{80}{10} = 8 \frac{\text{kg}}{\text{m}}$

$\Delta W = 8 \cdot g \cdot (4-x) \Delta x \Rightarrow W = \sum_{x=1}^n 8 \cdot g \cdot (4-x) \Delta x$

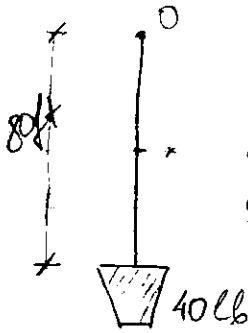
$W = \int_0^6 8 \cdot g \cdot (4-x) dx$

(15) Cable weight 2 lb/ft 800 lb coal
 $H = 500 \text{ ft}$ → depth of the mineshaft



$W = 800 \cdot 500 + \int_0^H 2 \cdot x dx = 40 \cdot 10^4 + 2 \cdot \frac{x^2}{2} \Big|_0^{500} = 4 \cdot 10^5 + (5 \cdot 10^2)^2 = 4 \cdot 10^5 + 25 \cdot 10^4 = 6.5 \cdot 10^5 = 650000 \text{ lb-ft}$

16) bucket weights: 4 lb
well depth $H = 80$ ft



$v = 2$ ft/sec ; $v = \frac{ds}{dt}$; $t = \frac{s}{v} = \frac{80}{2} = 40$ sec
water leaks at rate 0.2 lb/s
time to draw bucket to the top!

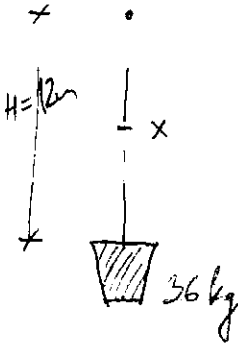
lost weight on height H

$G_{\text{lost}} = 0.2 \text{ lb/s} \cdot 40 \text{ s} = 8 \text{ lb}$

$G_{\text{leak}} = 0.2 \text{ [lb/s]} \cdot \frac{(H-x)}{v} \text{ [sec]} = \frac{0.2(H-x)}{2} = 0.1(H-x) \text{ [lb]}$

$W = \int_0^{80} [44 - 0.1(80-x)] dx = 3200 \text{ lb-ft}$

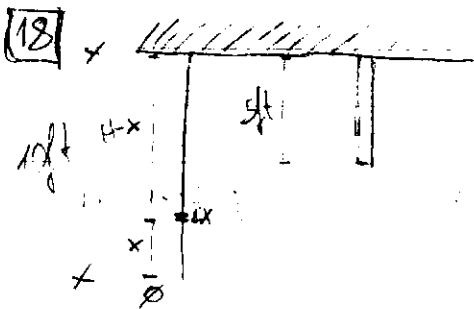
17) bucket weight 10 kg; rope weights 0.8 kg/m



$M_x = \frac{36}{H} \cdot x$; $x=0$ $M_x = 0$; $x=H$ $M_x = 36$ kg bucket

$W = g \int_0^H \left(\frac{36}{H} x + 0.8x \right) dx + 10 \cdot 12 \cdot g = 3857 \text{ J}$

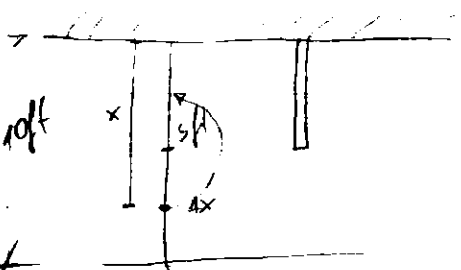
$M = \frac{36}{12} \cdot x + 0.8x + 10 = (3.8x + 10)$



chain weights 25 lb (wt = 2.5 lb/ft)

$\Delta W = \text{wt} \cdot \Delta x \cdot (H-x)$

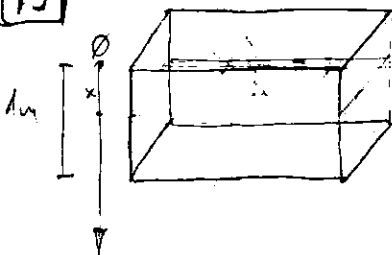
$W = \int_0^{10/2} 2.5(H-x) dx = 2.5 \int_0^5 (10-x) dx = 93.75 \text{ ft-lb}$



$\Delta W = \text{wt} \cdot \Delta x \cdot 2(x-5)$

$W = \int_5^{10} 2.5 \cdot 2(x-5) dx = 5 \int_5^{10} (x-5) dx = 62.5 \text{ [ft-lb]}$

19)

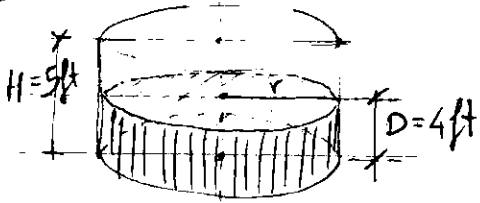


$w_i = 2 \cdot 1 \cdot \Delta x \cdot 1000 = 2000 \Delta x$

$F_i = g \cdot w_i = 9.8 \cdot 2000 \Delta x$

$W = \int_0^{0.5} g \cdot w_i \cdot x dx = \int_0^{0.5} 9.8 \cdot 2000 \cdot x dx = 2450 \text{ J}$

20



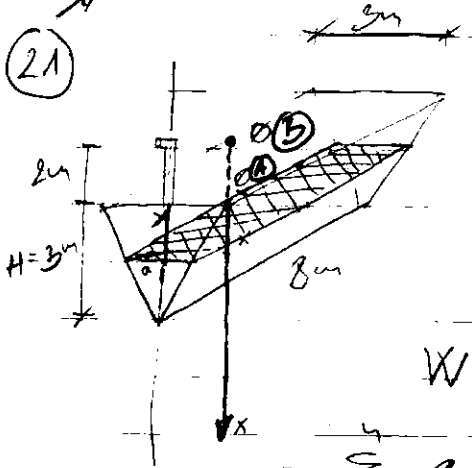
$2r = 24 \text{ ft} \quad r = 12 \text{ ft}; \quad \rho = 62.5 \text{ lb/ft}^3$

$\Delta W_i = 62.5 \cdot r^2 \pi \cdot \Delta x$

$W = \int_0^5 x \cdot 62.5 \cdot r^2 \pi \cdot dx = 62.5 r^2 \pi \int_0^5 x dx$
 $W = 1.08 \cdot 10^8 \pi \text{ ft-lb}$

VIDI-RESERVOIR 25

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(A) $\frac{3}{3-x} = \frac{1.5}{a} \quad a = \frac{1.5}{3} (3-x) = \frac{1}{2} (3-x)$

$V = 2a \cdot 8 \cdot \Delta x = 8(3-x) \Delta x$

$\Delta W = \rho \cdot V = 8000(3-x) \Delta x$

$\Delta F = g \Delta W$

$W_i = \Delta F \cdot x_i; \quad W = \sum_{i=1}^n \Delta F \cdot x_i =$

$= \sum_{x=0}^3 g \cdot 8000(3-x) \Delta x = 9.8 \cdot 8000 \int_0^3 x(3-x) dx$
 $= ~~3.528 \cdot 10^5~~ \text{ J} \quad 1.0584 \cdot 10^6 \text{ J}$

(B)

$\frac{3}{3-(x-2)} = \frac{1.5}{a} \quad a = \frac{1}{2} (3-x+2) = \frac{1}{2} (5-x)$

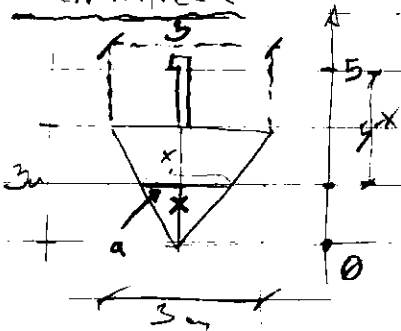
$\Delta V = 2a \cdot 8 \cdot \Delta x = 8(5-x) \Delta x$

$\Delta W = 8000(5-x) \Delta x$

$\Delta F = g \Delta W \quad W_i = g \Delta W \cdot x_i$

$W = 9.8 \int_0^5 8000(5-x) dx = ~~1.0584 \cdot 10^6~~ \text{ J}$

ALTERNATIVE 2X



$\Delta V = 8 \cdot x \Delta x \quad \Delta W = 8000x \Delta x$

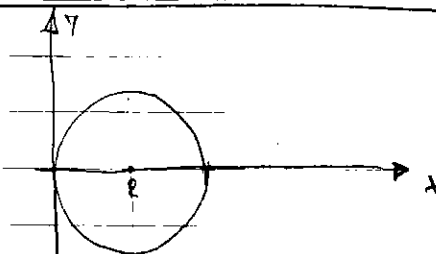
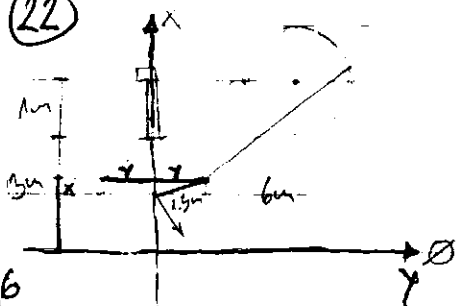
$\Delta F = 9.8 \cdot 8000x \Delta x$

$\Delta W = 9.8 \cdot 8000x \Delta x (5-x)$

$W = \int_0^3 9.8 \cdot 8000x(5-x) dx =$

$\left[\frac{3}{x} = \frac{1.5}{a} \quad a = \frac{1}{2} x \right]$

22



$y = \sqrt{2^2 - (x-1.5)^2}$

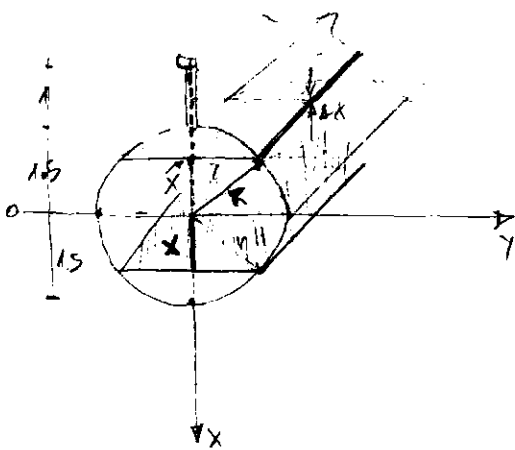
$\Delta V = 6 \cdot \Delta x$

$N = 12 \sqrt{(1.5)^2 - (x-1.5)^2} \Delta x$

$$\Delta u = \gamma \cdot \Delta V = 12000 \sqrt{1.5^2 - (x-1.5)^2}; \Delta F = \Delta u \cdot g; W_i = \Delta u \cdot g \cdot (4-x)$$

$$W = \int_0^3 9.8 \cdot 12000 \sqrt{1.5^2 - (x-1.5)^2} \cdot (4-x) dx = \underline{1.039 \cdot 10^6 \text{ J}}$$

ACTOR ACTIVEZ:

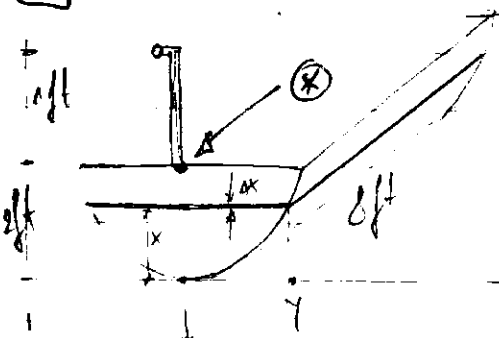


$$W_i = 9.8 \cdot 12000 \left(\underbrace{2}_{1.5} \sqrt{1.5^2 - x^2} \right) \cdot \underbrace{(6 \cdot 1x)}_{2y} \cdot \underbrace{(2.5+x)}_{\Delta u}$$

$$W = \int_{-1.5}^{1.5} 9.8 \cdot 12000 \sqrt{1.5^2 - x^2} (2.5+x) dx$$

$$W = \underline{1.039 \cdot 10^6 \text{ J}}$$

23



$$\Delta u = 62.5 \cdot \Delta V;$$

$$\Delta V = \Delta x \cdot 8 \cdot 2y = 16 \Delta x \sqrt{2^2 - (x-2)^2}$$

$$W_i = 62.5 \cdot 16 \Delta x \sqrt{4 - (x-2)^2} \cdot \underline{(3-x)}$$

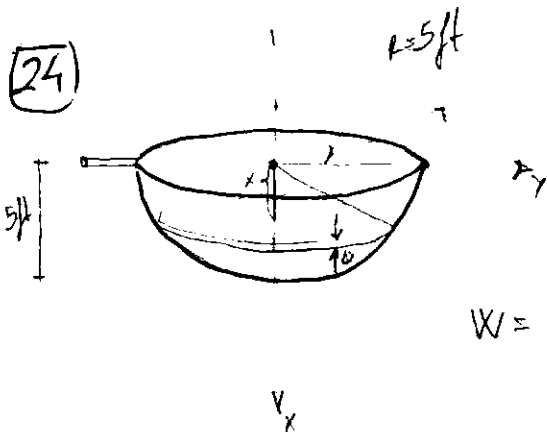
$$W = \int_0^2 1000 \sqrt{4 - (x-2)^2} (3-x) dx$$

$$W = 1000 \left(\pi + \frac{8}{3} \right) \text{ [ft-lb]}$$

Avu $x=0$ se stavi vo $\textcircled{8}$ TOCAȘ PLEINĂ ÎN ALTA:

$$W_i = 62.5 \cdot 8 \cdot 2 \sqrt{4-x^2} \Delta x (x+1); \quad W = \int_0^2 1000 \sqrt{4-x^2} (x+1) dx$$

24



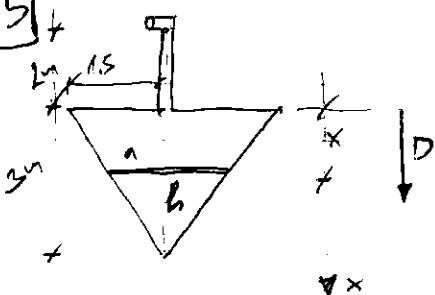
$$\Delta u = 62.5 \cdot \Delta V$$

$$\Delta V = \left(\sqrt{25 - x^2} \right)^2 \pi \cdot \Delta x$$

$$W_i = 62.5 \pi (25 - x^2) \cdot \Delta x \cdot x$$

$$W = \int_0^5 62.5 \pi (25 - x^2) x dx = 30675.616 \text{ ft-lb}$$

25



$$\frac{3}{1.5} = \frac{3-x}{a} \quad a = \frac{1}{2} (3-x)$$

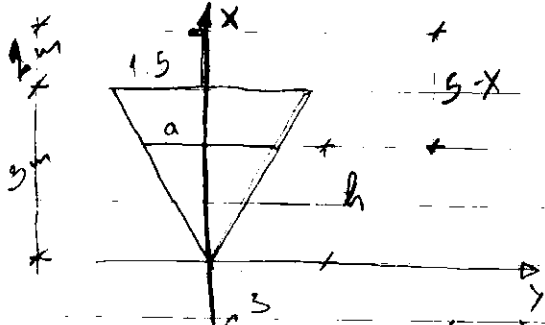
$$\Delta V = 2a \cdot 8 \Delta x = 8(3-x) \Delta x; \Delta u = 8000(3-x) \Delta x$$

$$W = \int_0^3 8 \cdot 8000 (3-x) (x+2) dx = 1.0524 \cdot 10^6 \text{ J}$$

$$W = \int_0^3 8 \cdot 8000 (3-x) (x+2) dx = 4.7 \cdot 10^5 \text{ J}$$

$$D = 0.971$$

$$h = 3 - D = 2 \text{ m}$$



$$\frac{3}{1.5} = \frac{h}{a}$$

$$a = \frac{1}{2}x$$

$$\Delta m = 1000 \Delta V; \Delta V = 2a \cdot 8 = 8x$$

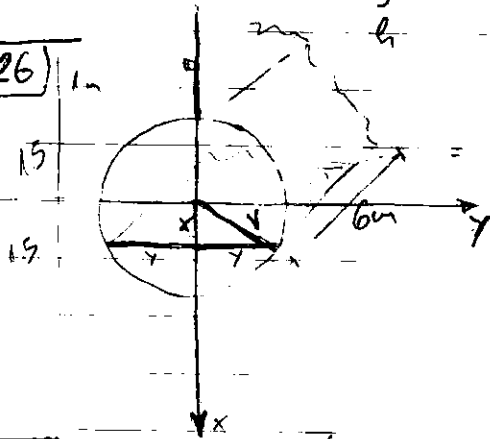
$$\Delta m = 8000x; W_i = g \cdot \Delta m (5-x)$$

$$W = \int_0^5 g \cdot 8000x (5-x) dx = 1.06 \cdot 10^6 \text{ J}$$

$$W_0 = 4.7 \cdot 10^5 = \int_0^3 9.8 \cdot 8000x (5-x) dx$$

$$L \approx 2$$

[26]



$$\Delta m = 920 \cdot \Delta V; \Delta V = 2 \cdot \sqrt{r^2 - x^2} \cdot 6 \cdot \Delta x$$

$$\Delta m = 2012 \Delta x \sqrt{(1.5)^2 - x^2}$$

$$W_i = 9.8 \cdot \Delta m \cdot (2.5 + x)$$

$$W = \int_0^{1.5} 920 \cdot 9.8 \cdot 12 \cdot \sqrt{(1.5)^2 - x^2} \cdot (2.5 + x) dx$$

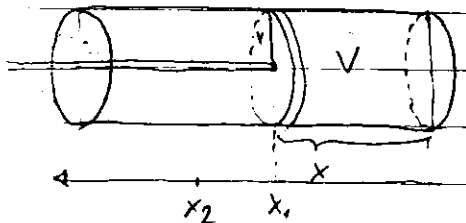
$$W \approx 6 \cdot 10^5 \text{ J}$$

[27] - Pressure at any given time is function of volume
 $P = P(V)$

- Force exerted by the gas is: $F = \pi r^2 P$

- Show that work done by the gas for extension of volume from V_1 to V_2 is:

$$W = \int_{V_1}^{V_2} P dV$$



$$\Delta W = \Delta F \cdot \Delta x = \frac{\pi r^2 \Delta x \cdot P(\Delta V)}{\Delta V}$$

$$\Delta F = \pi r^2 P(\Delta V)$$

$$W = \int_{V_1}^{V_2} P(V) dV$$

$$W = \int_{x_1}^{x_2} F(x) dx = \int_{x_1}^{x_2} \pi r^2 P(V) dx = \int_{V_1}^{V_2} P(V) dV \Rightarrow$$

$\left. \begin{array}{l} V = \pi r^2 x \\ dV = \pi r^2 dx \\ x = x_1 \quad V = V_1 = \pi r^2 x_1 \\ x = x_2 \quad V = V_2 = \pi r^2 x_2 \end{array} \right\} \int_{\pi r^2 x_1}^{\pi r^2 x_2} P(V) dV \Rightarrow$

$$W = \int_{V_1}^{V_2} P(V) dV$$

[28] Steam Engine $P \cdot V^{1.4} = k$

- ENGINE STARTS AT $P_0 = 160 \text{ lb/in}^2$ $V_0 = 100 \text{ in}^3$

- $V_1 = 800 \text{ in}^3$

$$W = \int_{V_0}^{V_1} P(V) dV$$

$$1.4 = 1 + \frac{1}{5} = \frac{7}{5}$$

$$k = 160 \frac{\text{lb}}{\text{in}^2} \cdot (100 \text{ in}^2)^{7/5} = 160 \cdot 100^{7/5} [\text{lb} \cdot \text{in}^{14/5}] = 1.01 \cdot 10^5 [\text{lb} \cdot \text{in}^4]$$

$$P(V) = \frac{k}{V^{7/5}}$$

$$W = \int_{100}^{800} \frac{1.01 \cdot 10^5}{V^{7/5}} dV = 22.588 [\text{in} \cdot \text{lb}]$$

$$1 \text{ foot} = 12 \text{ inch}$$

$$W = \frac{22.588}{12} [\text{ft} \cdot \text{lb}] = \underline{\underline{1.882 [\text{ft} \cdot \text{lb}]}}$$

$$P_0 = 160 \text{ lb/in}^2 = \left| 1 \text{ in} = \frac{1}{12} \text{ ft} \right| = 160 \cdot 144 \text{ lb/ft}^2$$

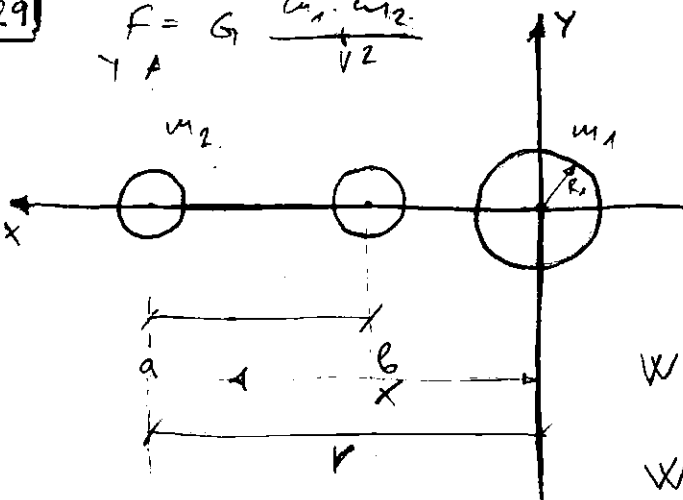
$$V_0 = 100 \text{ in}^3 = \left| 1 \text{ in} = \frac{1}{12} \text{ ft} \right| = \frac{100}{1728} \text{ ft}^3 \quad V_1 = \frac{800}{1728} \text{ ft}^3$$

$$k = P_0 \cdot V_0^{7/5} = 160 \cdot 144 \cdot \left(\frac{100}{1728} \right)^{7/5} = 426,502$$

$$W = \int_{\frac{100}{1728}}^{\frac{800}{1728}} \frac{426,502}{V^{7/5}} dV = \underline{\underline{1.88242 [\text{ft} \cdot \text{lb}]}}$$

29

$$F = G \frac{m_1 \cdot m_2}{r^2}$$



$$W = \int_b^a F(x) dx$$

ПРЕТОСТАВИ
КАКО ВА ТРОМ
ОР ЗА СОВЛАГА
ГРЕЈ ТАКОЈАТА
ФИЈА, ОД
НОТИЦА Б ЈЕ
ИЗРЕШЕ ВО 29

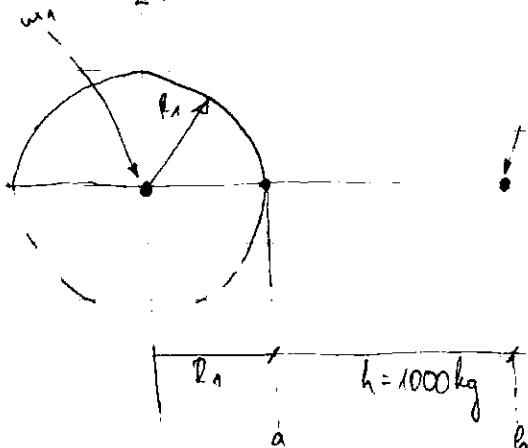
$$W = \int_b^a G \frac{m_1 m_2}{x^2} dx$$

$$W = G m_1 m_2 \left. \frac{x^{-2+1}}{-2+1} \right|_b^a = G m_1 m_2 \left. \frac{-1}{x} \right|_b^a$$

$$W = G m_1 m_2 \left(\frac{1}{b} - \frac{1}{a} \right) = \frac{G m_1 m_2 (a-b)}{ab}$$

30

W=? TO LAUNCH 1000kg satellite TO 1000km HIGH ORBIT
 $m_1 = 5.98 \cdot 10^{24} \text{ kg}$; $R_1 = 6.37 \cdot 10^6$; $G = 6.67 \cdot 10^{-11} \text{ N} \frac{\text{m}^2}{\text{kg}^2}$



m_2

$$F = G \frac{m_1 m_2}{r^2}$$

$$W = \int_a^b G \frac{m_1 m_2}{x^2} dx = G m_1 m_2 \left. \frac{1}{x} \right|_a^b$$

$$W = G m_1 m_2 \left(\frac{1}{a} - \frac{1}{b} \right)$$

$$a = R_1 = 6.37 \cdot 10^6 \text{ m}; \quad b = a - 10^6 = 7.37 \cdot 10^6 \text{ m}$$

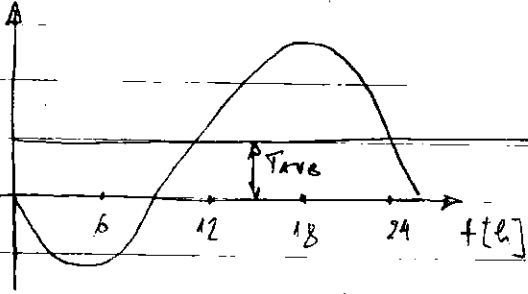
$$W = \frac{6.67 \cdot 10^{-11} \cdot 5.98 \cdot 10^{24} \cdot 10^3}{G} \cdot \left(\frac{1}{6.37 \cdot 10^6} - \frac{1}{7.37 \cdot 10^6} \right)$$

$$W = 8.496 \cdot 10^3 \text{ J} \approx 8.5 \text{ GJ}$$

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6.5 AVERAGE VALUE OF A FUNCTION

$$y_{ave} = \frac{y_1 + y_2 + \dots + y_n}{n}$$



$$y = f(x) \quad a \leq x \leq b$$

$$\Delta x = \frac{b-a}{n} \quad ; \quad n = \frac{b-a}{\Delta x}$$

$$y_{ave} = \frac{f(x_1^*) + f(x_2^*) + \dots + f(x_n^*)}{n}$$

$$y_{ave} = \frac{1}{b-a} (f(x_1^*) + f(x_2^*) + \dots + f(x_n^*)) \Delta x$$

$$y_{ave} = \frac{1}{b-a} \sum_{i=1}^n f(x_i^*) \Delta x$$

$$\lim_{n \rightarrow \infty} \frac{1}{b-a} \sum_{i=1}^n f(x_i^*) \Delta x = \frac{1}{b-a} \int_a^b f(x) dx$$

$$f_{ave} = \frac{1}{b-a} \int_a^b f(x) dx$$

$$f'(c) = \frac{f(b) - f(a)}{b-a}$$

ex.1 $f(x) = 1+x^2 \quad x = [1, 2]$

you solve problem for derivatives

MEAN VALUE THEOREM FOR INTEGRALS

If f is continuous on interval $[a, b]$, then there exist number c in $[a, b]$ such that:

$$\int_a^b f(x) dx = (b-a) f(c) \quad ; \quad \boxed{f(c) = f_{ave}(f)}$$

ex.2 $f(x) = 1+x^2 \quad \int_1^2 f(x) dx = f(c)(2-1) \quad c = ?$

$f(c) = f_{ave} = 2 \Rightarrow 1+c^2 = 2 \quad \boxed{c = 1}$

ex.3 $\frac{ds}{dt} = s(t) \rightarrow s(t_1) = s(t_2)$ - AVERAGE VELOCITIES OF THE CAR

$$v_{ave} = \frac{1}{t_2-t_1} \int_{t_1}^{t_2} v(t) dt = \frac{1}{t_2-t_1} \int_{t_1}^{t_2} s'(t) dt = \frac{1}{t_2-t_1} [s(t_2) - s(t_1)]$$

Exercises

2 $f(x) = \frac{1}{x} \quad [1, 4] \quad f_{ave} = \frac{1}{4-1} \int_1^4 \frac{1}{x} dx$

$$f_{ave} = \frac{1}{3} \ln(x) \Big|_1^4 = \frac{1}{3} [\ln 4 - \ln 1] = \frac{2}{3} \ln 2$$

5 $f(t) = t e^{t^2} \quad [0, 5] \quad f_{ave} = \frac{1}{5} \int_0^5 t e^{t^2} dt$

$$\int t e^{t^2} dt = \frac{1}{2} \int e^{u} d(u) = \frac{1}{2} e^u = \frac{1}{2} e^{t^2}$$

$$\int t e^{-t^2} dt = \left| \begin{array}{l} u = e^{-t^2} \\ \frac{du}{dt} = -2t e^{-t^2} \\ t e^{-t^2} du = -\frac{du}{2} \end{array} \right| = -\frac{1}{2} \int du = -\frac{1}{2} e^{-t^2}$$

$$f_{avg} = \frac{1}{5} \left(-\frac{1}{2} \right) e^{-t^2} \Big|_0^5 = -\frac{1}{10} (e^{-25} - 1) = \frac{1}{10} (1 - e^{-25})$$

7) $h(x) = \cos^4(x) \sin(x)$; $[0, \pi]$

$$\frac{1}{\pi} \int_0^{\pi} \cos^4(x) \sin(x) dx = -\frac{1}{\pi} \int_0^{\pi} \cos^4(x) \cos(x) dx = -\frac{1}{\pi} \left[\frac{\cos^5(x)}{5} \right]_0^{\pi}$$

$$= -\frac{1}{5\pi} (-1 - 1) = \frac{2}{5\pi}$$

11) $2 \sin(x) - \sin(2x) = \frac{4}{\pi}$

$$\left[\frac{1}{\pi} \int_0^{\pi} 2 \sin(x) - \sin(2x) dx = \frac{4}{\pi} \right]$$

$$2 \sin(x) - 2 \sin(x) \cos(x) = \frac{4}{\pi}$$

$$\sin(x) (1 - \cos(x)) = \frac{2}{\pi}$$

$$\sqrt{1 - \cos^2(x)} (1 - \cos(x)) = \frac{2}{\pi}$$

$$(1 - u^2)(1 - u)^2 = \frac{4}{\pi^2}$$

$$(1 - u)(1 + u)(1 - u)^2 = \frac{4}{\pi^2}$$

$$(1 + u)(1 - u)^3 = \frac{4}{\pi^2}$$

$$(1 - u^2)(1 - 2u + u^2) = \frac{4}{\pi^2}$$

$$1 - 2u + u^2 - u^2 + 2u^3 - u^4 = \frac{4}{\pi^2}$$

$$u^4 - 2u^3 + 2u - \frac{4}{\pi^2} - 1 = 0$$

$$u = [0.95, 0.25]$$

$$\left[\begin{array}{l} \cos(x) = -0.95 \Rightarrow c = 2.81 \\ \cos(x) = 0.92 \Rightarrow c = 1.24 \end{array} \right]$$

13) $\int_1^3 f(x) dx = 8$

$$\frac{1}{b-a} \int_a^b f(x) dx = \frac{f(c)}{b-a}$$

$$\int_1^3 f(x) = (3-1) f(c)$$

$$f(c) = 4 \Rightarrow \int_1^3 f(x) = 2 \cdot 4 = 8$$

$$f(x) = 4 \text{ for } [x=c] \quad f(c) = f_{avg}$$

14) $b = ?$ $f_{avg} = ?$ $f(x) = 2 + 6x - x^2$ $[0, b]$

$$\frac{1}{b-0} \int_0^b f(x) dx = \frac{1}{b} \int_0^b (2 + 6x - x^2) dx = \frac{1}{b} (2b + 3b^2 - \frac{b^3}{3})$$

$$f_{avg} = 2 + 3b - \frac{b^2}{3}$$

$$b^2 - 3b + 2 + 3 = 0 \quad b^2 - 3b + 1 = 0$$

$$b_{1,2} = \frac{3 \pm \sqrt{9-4}}{2} = \frac{3}{2} \pm \frac{1}{2}\sqrt{5}$$

15	x	20	25	30	35	40	45	50
	f(x)	42	38	31	29	35	48	60

$$f_{\text{AVG}} = \frac{1}{b-a} \sum_{i=1}^n f(x_i) \Delta x$$

$$\Delta x = \frac{b-a}{n} = \frac{50-20}{3} = \frac{30}{3} = 10$$

$$x_i = a + \frac{(2i-1)\Delta x}{2} \quad b=20; \quad x_1 = 20 + \frac{2-1}{2} \cdot 10 = \underline{25}$$

$$x_2 = 20 + \frac{4-1}{2} \Delta x = 20 + 15 = \underline{35}; \quad x_3 = 20 + \frac{6-1}{2} \cdot 10 = \underline{45}$$

$$f_{\text{AVG}} = \frac{1}{30} \sum_{i=1}^3 f(x_i) \Delta x = \frac{1}{30} [38 + 29 + 48] = \frac{1}{30} \cdot 115$$

$$f_{\text{AVG}} = 38.333$$

20 $s = \frac{1}{2} g t^2$; velocity after time T is v_T

$$\int v(t) dt = s(t)$$

$$v_{\text{ave}} = \frac{1}{T} \int_0^T v(t) dt = \frac{1}{T} \int_0^T s'(t) dt = \frac{1}{T} \int_0^T \frac{1}{2} g \cdot 2t dt$$

$$v_{\text{ave}} = \frac{1}{T} g \int_0^T t dt = \left. \frac{1}{T} g \frac{t^2}{2} \right|_0^T = \frac{1}{T} g \frac{T^2}{2}$$

$$v = \frac{ds}{dt} = g \cdot t \quad (v_T = g \cdot T) \quad v_{\text{ave}} = \frac{gT}{2} = \frac{v_T}{2}$$

$$a = \frac{\Delta v}{\Delta t} = \frac{\frac{1}{2} g T^2 - 0}{T - 0} = \frac{1}{2} g T = v_{\text{avg}}$$

$$s_{\text{avg}} = \frac{1}{T} \int_0^T \frac{1}{2} g t^2 dt = \left. \frac{1}{2T} g \frac{t^3}{3} \right|_0^T = \frac{g T^2}{6}$$

$$s = \frac{g t^2}{2} = \frac{1}{2g} (g t)^2 = \frac{v^2}{2g}$$

$$2gs = v^2$$

$$v = \sqrt{2gs}$$

$$v_{\text{avg}} = \frac{1}{s(T) - s(0)} \int_0^{s(T)} v(s) ds = \frac{1}{\frac{g T^2}{2}} \int_0^{\frac{g T^2}{2}} \sqrt{2gs} ds = \frac{2}{g T^2} \sqrt{2g} \left. \frac{s^{\frac{1}{2}+1}}{\frac{1}{2}+1} \right|_0^{\frac{g T^2}{2}}$$

$$\left. \begin{array}{l} s(0) = 0 \\ s(T) = \frac{g T^2}{2} \end{array} \right| = \frac{2}{g T^2} \sqrt{2g} \frac{(g \frac{T^2}{2})^{\frac{3}{2}}}{\frac{3}{2}} = \frac{4}{g T^2} \sqrt{2g} \frac{\sqrt{g^3} \frac{T^3}{\sqrt{2}}}{3}$$

$$V_{avg} = \frac{2A}{\pi R^2} \frac{\sqrt{2gH} T^2}{3 \times \sqrt{2}} = \frac{2}{3\sqrt{2}} \frac{\sqrt{2} (gH)^{1/2} T}{3\sqrt{2}} = \frac{2}{3} gT = \frac{2}{3} V_T$$

(21) $T = 5 \text{ sec} \Rightarrow$ DURATION OF FULL RESPIRATORY CYCLE

$0.5 \text{ L/sec} \Rightarrow$ MAXIMUM RATE OF AIR FLOW

$f(t) = 0.5 \sin(2\pi t/5)$ RATE OF AIR FLOW

$$V(t) = \int_0^t f(t) dt = \int_0^t 0.5 \sin(2\pi t/5) dt = 0.5 \int_0^t \sin(2\pi t/5) dt$$

$$= \left. \begin{matrix} u = 2\pi t/5 \\ du = \frac{2\pi}{5} dt \end{matrix} \right|_0^t = \left. \begin{matrix} u=0 \\ u = \frac{2\pi t}{5} \end{matrix} \right|_0^t = -0.5 \left(\frac{5}{2\pi} \right) \cos(u) \Big|_0^{\frac{2\pi t}{5}}$$

$$V(t) = 0.5 \cos(u) \Big|_0^{\frac{2\pi t}{5}} = \frac{0.5}{2\pi} (1 - \cos \frac{2\pi t}{5})$$

$$V(T) = \frac{0.5}{2\pi} (1 - \cos \frac{2\pi \cdot 5}{5}) = \frac{2 \cdot 0.5}{2\pi} = \frac{1}{\pi} \text{ L}$$

~~$V_{avg} = \frac{1}{T} \int_0^T \frac{0.5 \sin(2\pi t/5)}{2\pi} dt = \frac{1}{T} \cdot \frac{0.5}{2\pi} \left(-\cos \frac{2\pi t}{5} \right) \Big|_0^T = \frac{0.5}{2\pi T} (1 - \cos \frac{2\pi T}{5})$~~

~~$V_{avg} = \frac{0.5}{2\pi T} (1 + 1) = \frac{1}{2\pi T} = 0.46 \text{ L}$~~

$$V(t) = \frac{0.5}{2\pi} (1 - \cos \frac{2\pi t}{5})$$

$$V_{avg} = \frac{1}{T} \int_0^T V(t) dt = \frac{1.25}{2\pi T} \int_0^T (1 - \cos \frac{2\pi t}{5}) dt = \frac{1.25}{2\pi T} \left(t + \frac{5}{2\pi} \sin \frac{2\pi t}{5} \right) \Big|_0^T$$

$$V_{avg} = \frac{1.25}{\pi} \left(T - \frac{5}{2\pi} \sin \frac{2\pi T}{5} \right) = \frac{1.25}{\pi} \left(1 - \frac{5}{2\pi} \sin \frac{2\pi T}{5} \right)$$

if $T = 5 \text{ sec} \Rightarrow V_{avg} = \frac{1.25}{\pi} \left(1 - \frac{5}{2\pi} \cdot \frac{\sin(2\pi)}{5} \right) = 0.5 \text{ L} \cdot \frac{2.5}{\pi}$

$$\rightarrow V_{avg} = \frac{1.25}{\pi} \left(1 - \frac{5}{2\pi} \sin \frac{2\pi T}{5} \right) \quad \boxed{V_{avg} = \frac{1.25}{\pi} \text{ L} = 0.398 \text{ L}}$$

(22) $v(r) = \frac{\gamma}{4\eta l} (R^2 - r^2)$ velocity of blood that flows in blood vessel with length l and radius R !

$$V_{avg} = \frac{1}{R} \int_0^R \frac{P}{4\eta l} (R^2 - r^2) dr = \frac{PR^2}{6\eta l} \quad ; \quad V_{max} = \frac{PR^2}{4\eta l}$$

$$V_{avg} = \frac{4}{3} \frac{PR^2}{6\eta l} = \frac{2}{3} \frac{PR^2}{4\eta l} = \frac{2}{3} V_{max}$$

[23]

$$\int_a^b f(t) dt = f'(c) (b-a)$$

$$f'(c) = \frac{f(b) - f(a)}{b-a}$$

mean value theorem
for integrals

mean value theorem

$$F'(x) = f(x)$$

$$F(x) = \int_a^x f(t) dt$$

$$F'(c) =$$

$$\frac{F(b) - F(a)}{b-a}$$

$$f(c) = \frac{\int_a^b f(t) dt - \int_a^a f(t) dt}{b-a}$$

$$\int_a^b f(t) dt = (b-a)f(c)$$

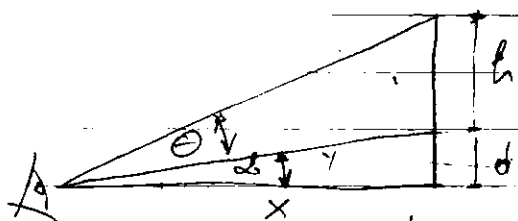
[24] $f_{avg}[a, b]$ - average of f in interval $[a, b]$
 $[a < c < b]$

show: $f_{avg}[a, b] = \frac{c-a}{b-a} f_{avg}[a, c] + \frac{b-c}{b-a} f_{avg}[c, b]$

$$\begin{aligned} f_{avg}[a, b] &= \frac{1}{b-a} \int_a^b f(t) dt = \frac{1}{b-a} \left[\int_a^c f(t) dt + \int_c^b f(t) dt \right] \\ &= \frac{1}{b-a} \left[\frac{c-a}{c-a} \int_a^c f(t) dt + \frac{b-c}{b-c} \int_c^b f(t) dt \right] \\ &= \frac{c-a}{b-a} f_{avg}[a, c] + \frac{b-c}{b-a} f_{avg}[c, b] \end{aligned}$$

APPLIED PROJECT: Where to sit at the Movies

[58] ch 4.7



$$x = ? \quad \theta = \theta_{max}$$

$$r = \sqrt{d^2 + x^2}$$

$$\tan \alpha = \frac{d}{x}$$

$$\alpha = \arctan \frac{d}{x}$$

$$\tan(\theta + \alpha) = \frac{h+d}{x}$$

$$\frac{\tan \theta + \tan \alpha}{1 - \tan \theta \tan \alpha} = \frac{h+d}{x}$$

$$\tan \theta + \tan \alpha = \frac{h+d}{x} (1 - \tan \theta \tan \alpha) ; \tan \theta + \frac{d}{x} = \frac{h+d}{x} (1 - \frac{d}{x} \tan \theta)$$

$$\operatorname{tg} \theta + \frac{d}{x} = \frac{h+d}{x} - \frac{d(h+d)}{x^2} \operatorname{tg}(\theta)$$

$$\operatorname{tg} \theta \left[1 + \frac{d(h+d)}{x^2} \right] = \frac{h+d}{x} - \frac{d}{x}$$

$$\operatorname{tg} \theta \left[\frac{x^2 + dh + d^2}{x^2} \right] = \frac{hx}{x^2} \quad \operatorname{tg} \theta = \frac{hx}{x^2 + dh + d^2}$$

$$(\operatorname{tg} \theta)' = \left(\frac{\sin \theta}{\cos \theta} \right)' = \frac{\cos \theta \cdot \cos \theta - \sin \theta \cdot (-\sin \theta)}{\cos^2 \theta} = \frac{1}{\cos^2 \theta}$$

$$\theta(x) = \operatorname{arctg} \frac{hx}{x^2 + dh + d^2}$$

$$\theta'(x) = \frac{1}{1 + \mu^2} \frac{d\mu}{dx}$$

$$\gamma(x) = \operatorname{arctg} \gamma(x)$$

$$\lambda = \operatorname{tg} \gamma \quad \left| \frac{d}{dx} \right| \Rightarrow 1 = \frac{1}{\cos^2 \gamma} \frac{d\gamma}{dx}$$

$$1 = \left(\frac{\sin^2(\gamma) + \cos^2(\gamma)}{\cos^2(\gamma)} \right) \frac{d\gamma}{dx} \Rightarrow 1 = \left(\frac{1}{\cos^2(\gamma)} + 1 \right) \frac{d\gamma}{dx}$$

$$\boxed{\gamma'(x) = \frac{1}{1 + x^2}}$$

$$\boxed{\theta'(x) = 0}$$

$$\frac{1}{1 + \frac{hx}{x^2 + dh + d^2}} \cdot \left(\frac{hx}{x^2 + dh + d^2} \right)' = 0$$

$$\frac{x^2 + dh + d^2}{x^2 + dh + d^2 + hx} \cdot \frac{h(x^2 + dh + d^2) - hx(2x)}{(x^2 + dh + d^2)^2} = 0$$

$$(x^2 + dh + d^2) (hx^2 + dh^2 + d^2h - 2hx^2) = 0$$

$$(x^2 + dh + d^2) (hx^2 - dh^2 - d^2h) = 0$$

$$x^2 + dh + d^2 = 0 \quad ?? \quad \text{no}$$

$$hx^2 - dh^2 - d^2h = 0$$

$$x^2 = d^2 + dh$$

$$\boxed{x = \sqrt{d^2 + dh}}$$

$$\theta(\mu) = \operatorname{arctg}(\mu)$$

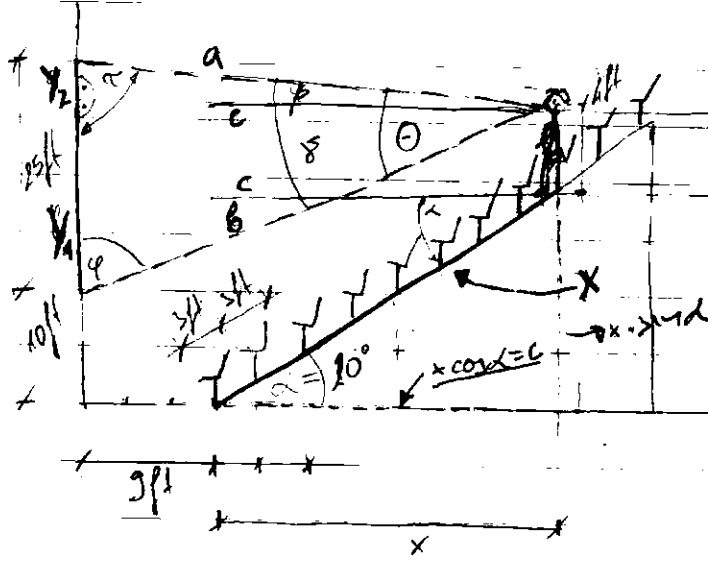
$$\frac{d\theta(\mu)}{dx} = \frac{d\theta(\mu)}{d\mu} \frac{d\mu}{dx} \quad \text{chain rule}$$

MOZE I VAKA:

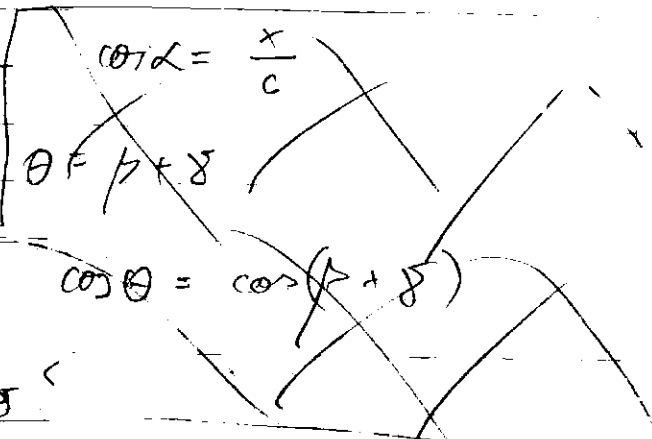
$$\theta = \operatorname{arctg} \frac{h+d}{x} - \operatorname{arctg} \frac{d}{x}; \quad \frac{d\theta}{dx} = \frac{1}{1 + \left(\frac{h+d}{x}\right)^2} \left(-\frac{h+d}{x^2} \right) - \frac{1}{1 + \left(\frac{d}{x}\right)^2} \left(-\frac{d}{x^2} \right)$$

$$\frac{d\theta}{dx} = 0 \Rightarrow$$

$$\boxed{x = \sqrt{d^2 + dh} = \sqrt{d(d+h)}}$$



$\alpha = 20^\circ$; $0 \leq x \leq 60$ ft
 NUMBER OF POINTS = 21
 $\theta = \arccos\left(\frac{a^2 + b^2 - 625}{2ab}\right)$
 $\cos \theta = \frac{a^2 + b^2 - 625}{2ab}$



$\frac{9}{g} = \frac{a}{x+9}$ $\frac{1}{g} \delta = \frac{b}{x+g}$

$\cos \theta = \cos \phi \cdot \cos \delta - \sin \phi \cdot \sin \delta$

$c = x \cdot \cos(\alpha)$; $\theta = \phi + \delta$

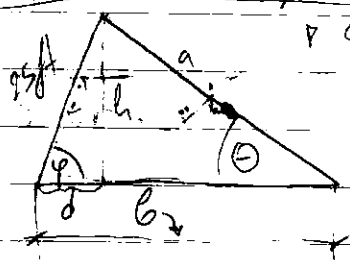
$a^2 = (g + x \cos \alpha)^2 + (31 - x \sin \alpha)^2$
 $b^2 = (g + x \cos \alpha)^2 + (x \sin \alpha - 6)^2$

$y_2 = 10 + 25 - 4 - x \sin \alpha = 31 - x \sin \alpha$
 $y_1 = 25 - y_2 = 25 - 31 + x \sin \alpha = x \sin \alpha - 6$

$a^2 = (g+c)^2 + y_2^2 = (g+x \cos \alpha)^2 + (31-x \sin \alpha)^2$
 $b^2 = (g+c)^2 + y_1^2 = (g+x \cos \alpha)^2 + (x \sin \alpha - 6)^2$

$\theta = \phi + \delta$; $\cos \phi = \left(\frac{a}{c+g}\right)^{-1} = \left(\frac{a}{x \cos \alpha + g}\right)^{-1}$ $\sin \phi = \left(\frac{a}{31-x \sin \alpha}\right)^{-1}$
 $\cos \delta = \frac{b}{x \cos \alpha + g}$ $\cos \theta = \cos \phi \cdot \cos \delta - \sin \phi \cdot \sin \delta$

$\cos \theta = \left(\frac{a \cdot b}{(x \cos \alpha + g)^2}\right)^{-1} - \left(\frac{a \cdot b}{(31-x \sin \alpha)(x \sin \alpha - 6)}\right)^{-1} = \frac{a \cdot b \cdot (31-x \sin \alpha)(x \sin \alpha - 6) - (x \cos \alpha + g)^2}{(x \cos \alpha + g)^2 (31-x \sin \alpha)(x \sin \alpha - 6)}$



$\frac{b \cdot h}{2} = \frac{(x \cos \alpha + g) \cdot 25}{2}$ $h = \frac{25(x \cos \alpha + g)}{b}$

$\frac{h}{25} = \cos \phi$ $h = 25 \cos \phi$

$\cos \theta = \frac{(x \cos \alpha + g)^2}{a \cdot b} - \frac{(31-x \sin \alpha)(x \sin \alpha - 6)}{a \cdot b}$

$$\sin \theta = \frac{y_1}{b} = \frac{25 - 72}{b} = \frac{25 - 31 + x \sin \alpha}{b} = \frac{x \sin \alpha - 6}{b}$$

$$\cos \theta = \frac{(x \cos \alpha + 9)^2 - (31 + x \sin \alpha)^2 + 186 - x^2 \sin^2 \alpha + 6x \sin \alpha}{ab}$$

$$\cos \theta = \frac{(x \cos \alpha + 9)^2 - 37x \sin \alpha + x^2 \sin^2 \alpha + 186}{ab}$$

$$\begin{aligned} a^2 + b^2 &= 2(9 + x \cos \alpha)^2 + 961 - 2 \cdot 31 \cdot x \sin \alpha - x^2 \sin^2 \alpha \\ &+ x^2 \sin^2 \alpha - 12x \sin \alpha + 36 = 2(9 + x \cos \alpha)^2 + 997 - 74x \sin \alpha \\ &= 2(9 + x \cos \alpha)^2 + 372 - 2 \cdot 37 \cdot x \sin \alpha + 2x^2 \sin^2 \alpha + 625 \\ &= 2[(9 + x \cos \alpha)^2 + 186 - 37x \sin \alpha + x^2 \sin^2 \alpha] + 625 \end{aligned}$$

$$\cos \theta = \frac{a^2 + b^2 - 625}{2ab}$$

$$\cos \theta = \frac{2(9 + x \cos \alpha)^2 + 372 - 2 \cdot 37 \cdot x \sin \alpha + 2x^2 \sin^2 \alpha + 625 - 625}{2ab}$$

$$\theta = \arccos \frac{a^2 + b^2 - 625}{2ab}$$

7. TECHNIQUES OF INTEGRATION

$$\begin{aligned} \int \sec x \cdot \frac{1}{\cos x} dx &= \int \frac{1}{\cos^2 x} dx = - \int \frac{d(\cos x)}{\cos^2 x} = - \frac{\cos^{-2}(x)}{-2+1} \\ &= \frac{1}{\cos(x)} = \sec(x) + C \end{aligned}$$

$$I = \int \frac{1}{x^2 + a^2} dx = \frac{1}{a} \arctan \left(\frac{x}{a} \right) + C$$

$$y = \arctan \frac{x}{a} \quad x = a \tan y \quad \frac{dx}{dy} = \frac{a \sec^2 y + \cos^2 y}{\cos^2 y} \cdot \frac{dy}{dx} = (1 + \tan^2 y) \frac{dy}{dx}$$

$$1 = (1 + \tan^2 y) \frac{dy}{dx} \quad \frac{dy}{dx} = \frac{1}{1 + x^2}$$

$$I = \int \frac{x}{a} = u = \frac{dx}{a} = du \quad \int \frac{1}{a} \frac{1}{\left(\frac{x}{a}\right)^2 + 1} d\left(\frac{x}{a}\right) = \frac{1}{a} \int \frac{1}{\left(\frac{x}{a}\right)^2 + 1} d\left(\frac{x}{a}\right)$$

$$I = \frac{1}{a} \arctan \left(\frac{x}{a} \right) + C$$

$$y = \arcsin \frac{x}{a} \quad x = a \sin y \quad 1 = a \cos y \frac{dy}{dx} \quad \frac{dy}{dx} = \frac{1}{a \cos y}$$

$$\frac{dy}{dx} = \frac{1}{a \cos y} = \frac{1}{\sqrt{a^2 - x^2}} = \frac{1}{\sqrt{a^2 - x^2}}$$

$$\int \frac{1}{\sqrt{a^2 - x^2}} dx = \arcsin \left(\frac{x}{a} \right) + C$$

$$\int \frac{1}{\sqrt{a^2 - x^2}} dx = \left| \frac{x}{a} = u \quad \frac{dx}{a} = du \right| = \int \frac{1}{a} \frac{1}{\sqrt{1 - \frac{x^2}{a^2}}} d\left(\frac{x}{a}\right) = \frac{1}{a} \arcsin \left(\frac{x}{a} \right) + C$$

7.1 Integration by Parts

$$\frac{d}{dx} f(x)g(x) = f'(x)g(x) + f(x)g'(x) \quad | \int$$

$$\int [f'(x)g(x) + f(x)g'(x)] dx = f(x)g(x)$$

$$\int f(x)g'(x) dx = f(x)g(x) - \int f'(x)g(x) dx$$

$$u = f(x) \quad v = g(x)$$

$$du = f'(x) dx \quad dv = g'(x) dx$$

$$\int u dv = uv - \int v du$$

Ex 1 $I = \int x \sin x dx = ?$

$$u = x \rightarrow du = dx$$

$$v = -\cos x \rightarrow dv = \sin x dx$$

$$I = -x \cdot \cos(x) + \int \cos x dx = -x \cos x + \sin x = \sin x - x \cos x$$

$$\left. \begin{aligned} f(x) &= x & f'(x) &= 1 \\ g'(x) &= \sin(x) & g(x) &= -\cos(x) \end{aligned} \right\} \rightarrow$$

$$I = f(x)g'(x) - \int f'(x)g(x) dx = -x \cos(x) + \int 1 \cdot \cos(x) dx = \sin(x) - x \cos(x) + C$$

$$\frac{dI(x)}{dx} = \cos(x) - [\cos(x) - x \sin(x)] = \cancel{\cos(x)} - \cancel{\cos(x)} + \underline{x \sin(x)}$$

Ex 2 $\int \ln(x) dx = \left| \begin{array}{l} u = \ln(x) \\ du = \frac{dx}{x} \\ v = x \\ dv = dx \end{array} \right| = x \cdot \ln(x) - \int \frac{dx}{x} = x \ln(x) - x + C$

Ex 3 $I = \int t^2 e^t dt = \left| \begin{array}{l} u = t^2 \quad du = 2t dt \\ dv = e^t dt \quad v = e^t \end{array} \right| = t^2 \cdot e^t - \int e^t \cdot 2t dt$

$$I' = \int e^t t dt = \left| \begin{array}{l} u = t \quad du = dt \\ dv = e^t dt \quad v = e^t \end{array} \right| = t e^t - \int e^t dt = t e^t - e^t$$

$$I = t^2 e^t - 2[t e^t - e^t] = t^2 e^t - 2t e^t + 2e^t + C$$

Ex 4 $I = \int e^x \sin(x) dx = \left| \begin{array}{l} u = \sin(x) \quad du = \cos(x) dx \\ dv = e^x dx \quad v = e^x \end{array} \right| = \sin(x) e^x - \int e^x \cos(x) dx$

$$I = \sin(x) e^x - \int e^x \cos(x) dx = \left| \begin{array}{l} u = \cos(x) \quad du = -\sin(x) dx \\ dv = e^x dx \quad v = e^x \end{array} \right|$$

$$I_1 = \cos(x) e^x + \int e^x \sin(x) dx$$

$$I = \sin(x) e^x - \cos(x) e^x - \int e^x \sin(x) dx \quad 2I = \sin(x) e^x - \cos(x) e^x$$

$$I = \frac{e^x}{2} (\sin(x) - \cos(x)) + C$$

$$I = \int e^x \left(\frac{1}{2j} (e^{+jx} - e^{-jx}) \right) dx = \frac{1}{2j} \left(\int e^{x(1+j)} dx - \int e^{x(1-j)} dx \right)$$

$$I = \frac{1}{2j} \left(\frac{1}{1+j} e^{x(1+j)} - \frac{1}{1-j} e^{x(1-j)} \right) = \frac{e^x}{2j} \left(\frac{e^{ix}}{1+j} - \frac{e^{-ix}}{1-j} \right)$$

$$= \frac{e^x}{2j} \frac{(1-j)e^{ix} - (1+j)e^{-ix}}{1-j^2} = \frac{e^x}{4j} (e^{ix} - j e^{ix} - e^{-ix} - j e^{-ix}) =$$

$$= \frac{e^x}{2 \cdot 2j} \left[(e^{ix} - e^{-ix}) - j(e^{ix} + e^{-ix}) \right] = \frac{e^x}{2} \left[\underbrace{\frac{e^{ix} - e^{-ix}}{2j}}_{\sin x} - \underbrace{\frac{e^{ix} + e^{-ix}}{2}}_{\cos x} \right]$$

$$I = \frac{e^x}{2} (\sin(x) - \cos(x))$$

$f(x) = F'(x)$ $f'(x) = (e^x \sin(x))' = e^x \cdot \sin(x) + \cos(x) e^x$
 $x=0$ $f'(0) = 1 \cdot 0 + 1 \cdot 1 = 1 > 0 \Rightarrow F(0) = \text{minimum}$

Integration by parts of definite integrals

$$\int_a^b f(x) g'(x) dx = f(x) g(x) \Big|_a^b - \int_a^b g(x) f'(x) dx$$

Ex. 5 $I = \int_0^1 \tan^{-1}(x) dx = \int_0^1 \arctan(x) dx = \left| \begin{array}{l} u = \arctan(x) \quad du = \frac{dx}{1+x^2} \\ dv = dx \quad v = x \end{array} \right.$

$$I = x \arctan(x) \Big|_0^1 - \int_0^1 \frac{x dx}{1+x^2} = \left(1 \cdot \frac{\pi}{4} - 0 \right) - \frac{1}{2} \int_0^1 \frac{d(1+x^2)}{1+x^2} = \frac{\pi}{4} - \frac{1}{2} \ln|1+x^2| \Big|_0^1$$

$$I = \frac{\pi}{4} - \frac{1}{2} (\ln 2 - \ln 1) = \frac{\pi}{4} - \frac{1}{2} \ln 2 = \frac{1}{2} \left(\frac{\pi}{2} - \ln 2 \right)$$

Ex. 6 $I = \int \sin^n(x) dx = -\frac{1}{n} \cos(x) \sin^{n-1}(x) + \frac{n-1}{n} \int \sin^{n-2}(x) dx$

$$I = \int \sin^{n-1}(x) \sin(x) dx = \left| \begin{array}{l} du = \sin^{n-1}(x) dx \\ v = \int \sin^{n-1}(x) dx = \left| \begin{array}{l} q = \sin(x) \\ dq = \cos(x) dx \end{array} \right. \end{array} \right.$$

$$v = \int \sin(x) dx = -\cos(x) \quad u = \sin^{n-1}(x) \quad du = (n-1) \sin^{n-2}(x) \cdot \cos(x) dx$$

$$\rightarrow v = \int \frac{2^{n-1} \frac{dq}{\cos x}}{\cos x} = \int \frac{2^{n-1}}{\sqrt{1-q^2}} \frac{dq}{2}$$

$u = \sin^n(x) \quad ; \quad du = n \sin^{n-1}(x) \cdot \cos(x) dx$
 $dv = dx \quad ; \quad v = x$

$$I = \int \sin^n(x) dx = \int u dv = \sin^n(x) \cdot x + \int x \cdot n \sin^{n-1}(x) \cos(x) dx$$

$$I = \int \sin^n(x) dx$$

$$\int \sin^n(x) dx = -\frac{1}{n} \cos(x) \sin^{n-1}(x) + \frac{n-1}{n} \int \sin^{n-2}(x) dx$$

$$(1+z)^n = \sum_{k=0}^{\infty} \binom{n}{k} z^k$$

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots + \frac{x^n}{n!}$$

$$(a+b)^n = a^n \left(1 + \frac{b}{a}\right)^n = a^n \sum_{k=0}^n \binom{n}{k} \left(\frac{b}{a}\right)^k = \sum_{k=0}^n \binom{n}{k} a^{n-k} b^k$$

$$I = \int \sin^{n-1}(x) \sin(x) dx \quad \left\{ \begin{array}{l} \textcircled{1} u = \sin(x) \quad du = \cos(x) dx \\ dv = \sin^{n-1}(x) dx \quad v = \int \sin^{n-1}(x) dx \end{array} \right.$$

$$I = \sin(x) \int \sin^{n-1}(x) dx - \int \cos(x) \left(\int \sin^{n-1}(x) dx \right) dx \quad (?)$$

$$\textcircled{2} u = \sin^{n-1}(x) \quad du = (n-1) \sin^{n-2}(x) \cdot \cos(x) dx$$

$$dv = \sin(x) dx \quad v = -\cos(x)$$

$$I = -\sin^{n-1}(x) \cdot \cos(x) + \int \cos(x) \cdot (n-1) \sin^{n-2}(x) \cos(x) dx \quad (*)$$

$$\textcircled{3} u = \sin^n(x) \quad du = n \sin^{n-1}(x) \cdot \cos(x) dx$$

$$dv = dx \quad v = x$$

$$I = x \sin^n(x) - \int x \cdot n \sin^{n-1}(x) \cos(x) dx \quad (?)$$

$$I_n = \int (n-1) \cos^2(x) \sin^{n-2}(x) dx = (n-1) \int \frac{\cos^2(x) \sin^n(x)}{\sin^2(x)} dx$$

$$y = \cot^2(x) \quad \frac{dy}{dx} = -\frac{1}{\sin^2(x)} \quad \left(\frac{\cos(x)}{\sin(x)} \right) = \frac{\cos^2(x)}{\sin^2(x)} = \frac{\cos^2(x) \sin^n(x)}{\sin^2(x)}$$

$$v = \int \cot^2(x) dx = \int \frac{\cos^2(x)}{\sin^2(x)} dx = \int \frac{1 - \sin^2(x)}{\sin^2(x)} dx = \int \frac{dx}{\sin^2(x)} - x = -\cot(x) - x$$

$$u = \sin^n(x) \quad du = n \sin^{n-1}(x) \cos(x) dx$$

$$\frac{I_n}{n-1} = \sin^n(x) \cdot \left(\frac{\cos^2(x)}{\sin^2(x)} - x \right) + \int \left(\frac{\cos(x)}{\sin(x)} + x \right) n \sin^{n-1}(x) \cos(x) dx$$

$$\frac{I_n}{n-1} = \sin^n(x) (\cot^2(x) - x) + \int x \sin^{n-1}(x) \cos(x) dx + n \int \cos^2(x) \sin^{n-2}(x) dx$$

$$\frac{I_n}{n-1} - \frac{n I_n}{n-1} = \frac{(1-n) I_n}{n-1} = -I_n = \sin^n(x) (\cot^2(x) - x) + \int x \sin^{n-1}(x) \cos(x) dx + \frac{I_n}{n-1}$$

$$\frac{I_2}{2} = \int x \sin^{n-1}(x) \cos(x) dx = \left\{ \begin{array}{l} u = \sin^{n-1}(x) \quad du = (n-1) \sin^{n-2}(x) dx \\ dv = x \cos(x) dx \quad v = \int x \cos(x) dx = (\cos(x) + x) \sin(x) \end{array} \right.$$

$$I_2 = \sin^{n-1}(x) (\cos(x) + x \sin(x)) - (n-1) \int [\cos(x) + x \sin(x)] \sin^{n-2}(x) dx \quad (?)$$

$$I_2 = \sin^{n-1}(x) (\cos(x) + x \sin(x)) - (n-1) \int \cos(x) \sin^{n-2}(x) dx - (n-1) \int x \sin^{n-1}(x) dx$$

$$I = -\sin^{n-1}(x) \cos(x) + \int (n-1) \sin^{n-2}(x) \cos^2(x) dx = \left| \cos^2(x) = 1 - \sin^2(x) \right|$$

$$= -\sin^{n-1}(x) \cos(x) + \int (n-1) \sin^{n-2}(x) dx - (n-1) \int \sin^n(x) dx$$

$$I + (n-1)I = I + 4I - 2I = 4I = -\sin^{n-1}(x) \cos(x) + (n-1) \int \sin^{n-2}(x) dx$$

$$I = -\frac{1}{n} \sin^{n-1}(x) \cos(x) + \frac{n-1}{n} \int \sin^{n-2}(x) dx \quad \text{REDUCTION FORMULA}$$

$$\text{Ex. 1 } I = \int x \ln x dx = \left| \begin{array}{l} u = \ln x \quad du = \frac{1}{x} dx \\ dv = x dx \quad v = \frac{x^2}{2} \end{array} \right| = \frac{x^2}{2} \ln x - \int \frac{x^2}{2} \cdot \frac{1}{x} dx$$

$$I = \frac{x^2}{2} \ln(x) - \frac{1}{2} \int x dx = \frac{x^2}{2} \ln(x) - \frac{x^2}{4} = \frac{x^2}{2} \left(\ln(x) - \frac{1}{2} \right)$$

$$\text{Ex. 2 } I = \int \theta \sec^2 \theta d\theta = \left| \begin{array}{l} u = \sec^2 \theta \quad du = \left(\frac{1}{\cos^3 \theta} \right)' d\theta = -2 \cos^{-3} \theta (-\sin \theta) \\ dv = \sec^2 \theta d\theta \quad v = \int \sec^2 \theta d\theta = \tan \theta \\ u = \theta \quad du = d\theta \end{array} \right|$$

$$I = \theta \cdot \tan \theta - \int \tan \theta d\theta = \theta \tan \theta - \int \frac{\sin \theta}{\cos \theta} d\theta = \theta \tan \theta + \int \frac{d(\cos \theta)}{\cos \theta}$$

$$I = \theta \tan \theta + \ln |\cos \theta|$$

$$\text{Ex. 5 } \int x e^{x/2} dx = \left| \begin{array}{l} u = x \quad du = dx \\ dv = e^{x/2} dx \quad v = \int e^{x/2} dx = 2e^{x/2} \end{array} \right|$$

$$2 \cdot x e^{x/2} - \int 2 e^{x/2} dx = 2x e^{x/2} - 4 e^{x/2} = 2e^{x/2} (x - 2) + C$$

$$\text{Ex. 7 } I = \int x^2 \sin(\pi x) dx = \left| \begin{array}{l} u = x^2 \quad du = 2x dx \\ v = \int \sin(\pi x) dx = \frac{1}{\pi} (-\cos(\pi x)) \end{array} \right|$$

$$I = -\frac{x^2}{\pi} \cos(\pi x) + \frac{2}{\pi} \int x \cdot \cos(\pi x) dx$$

$$I_1 = \left| \begin{array}{l} u = x \quad du = dx \\ dv = \cos(\pi x) dx \quad v = \int \cos(\pi x) dx = \frac{1}{\pi} \sin(\pi x) \end{array} \right|$$

$$I_1 = \frac{x}{\pi} x \sin(\pi x) - \frac{1}{\pi} \int \sin(\pi x) dx = \frac{1}{\pi} x \sin(\pi x) + \frac{1}{\pi^2} \cos(\pi x)$$

$$I = -\frac{x^2}{\pi} \cos(\pi x) + \frac{2}{\pi} \left(\frac{1}{\pi} x \sin(\pi x) + \frac{1}{\pi^2} \cos(\pi x) \right)$$

$$I = \frac{1}{\pi} \left(-x^2 \cos(\pi x) + \frac{2}{\pi} x \sin(\pi x) + \frac{2}{\pi^2} \cos(\pi x) \right) + C$$

Ex. 9 $I = \int \ln(2x+1) dx = \left| \begin{array}{l} u = \ln(2x+1) \\ du = \frac{2}{2x+1} dx \\ v = x \end{array} \right|$

$= x \ln(2x+1) - \int \frac{2x}{2x+1} dx$

$I_1 = \int \frac{2x+1}{2x+1} dx - \int \frac{dx}{2x+1} = x - \frac{1}{2} \int \frac{d(2x+1)}{2x+1} = x - \frac{1}{2} \ln(2x+1)$

$I = x \ln(2x+1) - x + \frac{1}{2} \ln(2x+1) = \frac{1}{2} \ln(2x+1)(2x+1) - x + C$

Ex. 11 $I = \int \arctg(4t) dt = \left| \begin{array}{l} u = \arctg(4t) \\ du = \frac{4}{1+16t^2} dt \\ v = t \end{array} \right|$

$I = t \arctg(4t) - 4 \int \frac{t dt}{1+16t^2} = t \arctg(4t) - \frac{1}{32} \ln(16t^2+1)$

$I_1 = \frac{1}{32} \int \frac{d(16t^2+1)}{1+16t^2} = \frac{1}{32} \ln(1+16t^2)$

$+ t \arctg(4t) - \frac{1}{32} \ln(16t^2+1) + C$

Ex. 13 $I = \int \ln^2(x) dx \left| \begin{array}{l} u = \ln^2(x) \\ du = 2 \frac{\ln(x)}{x} dx \\ v = x \end{array} \right|$

$I = x \ln^2(x) - \int x \cdot 2 \frac{\ln(x)}{x} dx = x \ln^2(x) - 2 \int \ln(x) dx$

~~$I = x \ln^2(x) - 2(x \ln(x) - x) = x \ln^2(x) - 2x \ln(x) + 2x$~~

$I_1 = \int \ln(x) dx = \left| \begin{array}{l} u = \ln(x) \\ du = \frac{1}{x} dx \\ v = x \end{array} \right| = x \ln(x) - \int \frac{dx}{x} = x \ln(x) - x$

$I = x \ln^2(x) - 2(x \ln(x) - x) = x \ln^2(x) - 2x \ln(x) + 2x$

Ex. 15 $I = \int e^{2\theta} \sin(3\theta) d\theta \left| \begin{array}{l} u = \sin(3\theta) \\ du = 3 \cos(3\theta) d\theta \\ v = \int e^{2\theta} d\theta = \frac{1}{2} e^{2\theta} \end{array} \right|$

$I = \frac{1}{2} e^{2\theta} \sin(3\theta) - \frac{1}{2} \int e^{2\theta} \cdot 3 \cos(3\theta) d\theta = \frac{1}{2} e^{2\theta} \sin(3\theta) - \frac{3}{2} \int e^{2\theta} \cos(3\theta) d\theta$

$I_1 = \left| \begin{array}{l} u = \cos(3\theta) \\ du = -3 \sin(3\theta) d\theta \\ v = \int e^{2\theta} d\theta = \frac{1}{2} e^{2\theta} \end{array} \right| = \frac{1}{2} e^{2\theta} \cos(3\theta) + \frac{3}{2} \int e^{2\theta} \sin(3\theta) d\theta$

$I = \frac{1}{2} e^{2\theta} \sin(3\theta) - \frac{3}{2} \left(\frac{1}{2} e^{2\theta} \cos(3\theta) - \frac{3}{4} I \right)$

$I = \frac{2}{13} e^{2\theta} \sin(3\theta) - \frac{3}{13} e^{2\theta} \cos(3\theta)$

$$\boxed{\text{ex. 17}} \int \sinh(x) dx = \frac{1}{2} \int (e^x - e^{-x}) dx = \frac{1}{2} (e^x + e^{-x}) = \cosh(x)$$

$$I = \int \gamma \sinh \gamma dy = \left| \begin{array}{l} u = \gamma \quad du = d\gamma \\ v = \int \sinh \gamma d\gamma = \cosh(\gamma) \end{array} \right| = \gamma \cosh(\gamma) - \int \cosh(\gamma) d\gamma$$

$$\boxed{I = \gamma \cosh(\gamma) - \sinh(\gamma)}$$

$$\boxed{\text{ex. 22}} I = \int \sqrt{t} \ln(t) dt = \left| \begin{array}{l} u = \ln(t) \\ du = \frac{1}{t} dt \end{array} \right| \quad v = \int \sqrt{t} dt = \frac{1}{\frac{3}{2}} \cdot \sqrt{t}^{\frac{3}{2}} = \frac{2\sqrt{t}}{3}$$

$$I = \frac{2\sqrt{t} \ln(t)}{3} \Big|_1^4 - \int \frac{2\sqrt{t}}{3} \frac{1}{t} dt = \left(\frac{2 \cdot 4 \cdot 2 \ln 4}{3} - \frac{2 \cdot 1}{3} \right) - \frac{2}{3} \int \sqrt{t} dt =$$

$$= \frac{14}{3} - \frac{2}{3} \left(\frac{2}{3} t^{\frac{3}{2}} \Big|_1^4 \right) = \frac{2}{3} \left(7 - \frac{2}{3} (4 \cdot 2 - 1) \right) = \frac{2}{3} \left(7 - \frac{14}{3} \right) = \frac{2}{3} \left(\frac{21}{3} - \frac{14}{3} \right) = \frac{2}{3} \cdot \frac{7}{3} = \frac{14}{9}$$

$$\boxed{I = \frac{14}{9}}$$

$$I = \frac{32}{3} \ln(2) - \frac{2}{3} - \frac{28}{9} = \frac{32}{3} \ln(2) - \frac{28}{9}$$

$$\boxed{\text{ex. 25}} I = \int_0^{\frac{1}{2}} \arccos(x) dx$$

$$u = \arccos(x)$$

$$dv = dx$$

$$du = -\frac{1}{\sqrt{1-x^2}} dx$$

$$v = x$$

$$\gamma = \arccos x; \quad x = \cos \gamma; \quad 1 = -\sin(\gamma) \frac{d\gamma}{dx} \Rightarrow \frac{d\gamma}{dx} = -\frac{1}{\sin \gamma} = -\frac{1}{\sqrt{1-x^2}}$$

$$I = x \cdot \arccos(x) \Big|_0^{\frac{1}{2}} + \int_0^{\frac{1}{2}} \frac{x dx}{\sqrt{1-x^2}} = \frac{1}{2} \cdot \frac{\pi}{3} - 0 + \frac{(-1)}{2} \int_0^{\frac{1}{2}} \frac{d(1-x^2)}{\sqrt{1-x^2}}$$

$$I = \frac{\pi}{6} - \frac{1}{2} \left(\sqrt{1-x^2} \right) \Big|_0^{\frac{1}{2}} = \frac{\pi}{6} - \frac{1}{2} \left(\sqrt{1-\frac{1}{4}} - \sqrt{1} \right) = \frac{\pi}{6} - \frac{1}{2} \left(\frac{\sqrt{3}}{2} - 1 \right)$$

$$= \frac{\pi}{6} - \frac{1}{2} \left(\frac{\sqrt{3}}{4} - 1 \right) = \frac{\pi}{6} - \frac{\sqrt{3}}{4} + \frac{1}{2} = \frac{\pi}{6} - \frac{\sqrt{3}}{4} + \frac{2}{4} = \frac{\pi}{6} - \frac{\sqrt{3}-2}{4}$$

$$\boxed{I = \frac{\pi}{6} - \frac{\sqrt{3}}{4} + \frac{1}{2}}$$

$$\boxed{\text{ex. 29}} I = \int \cos(\ln x) dx$$

$$u = \cos(\ln x)$$

$$dv = dx$$

$$du = -\sin(\ln x) \cdot \frac{1}{x} dx$$

$$v = x$$

$$I = x \cdot \cos(\ln x) + \int \sin(\ln x) dx$$

$$\left(\begin{array}{l} u = \sin(\ln x) \\ du = \cos(\ln x) \cdot \frac{1}{x} dx \\ v = x \end{array} \right) \quad \frac{dv}{dx} = dx$$

$$I_1 = x \sin(\ln x) - \int \cos(\ln x) dx = x \sin(\ln x) - I$$

$$I = x \cos(\ln x) + x \sin(\ln x) - I \Rightarrow I = \frac{x}{2} (\cos(\ln x) + \sin(\ln x))$$

ALTERNATIVE:

$$I = \int \cos(\ln x) dx \quad w = \ln x \quad dw = \frac{dx}{x} \quad x = e^w \quad dw = e^{-w} dx$$

$$\frac{dx}{x} = e^{-w} dw$$

$$I = \int e^{-w} \cos(w) dw = \int \left. \begin{array}{l} u = \cos w \\ du = -\sin(w) dw \\ v = e^{-w} \\ dv = -e^{-w} dw \end{array} \right| =$$

$$= e^{-w} \cos w + \int e^{-w} \sin(w) dw$$

$$I_1 = e^{-w} \sin w - \int e^{-w} \cos w dw \quad ; \quad I = e^{-w} \cos w + e^{-w} \sin w - I$$

$$I = \frac{e^{-w}}{2} \cos w + \frac{e^{-w}}{2} \sin w = \frac{x}{2} (\cos(\ln x) + \sin(\ln x))$$

EXC. 30 $I = \int_0^1 \frac{r^3}{\sqrt{4+r^2}} dr$ $\left. \begin{array}{l} u = r^3 \quad du = 3r^2 dr \\ v = \int \frac{dr}{\sqrt{4+r^2}} = \frac{1}{2} \cdot ar \end{array} \right\} \#$

$$u = \frac{r^3}{\sqrt{4+r^2}} \quad \frac{du}{dr} = \frac{3r^2 \sqrt{4+r^2} - r^3 \cdot \frac{1}{2} (4+r^2)^{-\frac{1}{2}}}{4+r^2}$$

$$= \frac{6r^2(4+r^2) - r^3}{(4+r^2)\sqrt{4+r^2}}$$

$$u = r^2 \quad du = 2r dr$$

$$v = \int \frac{r dr}{\sqrt{4+r^2}} = \frac{1}{2} \int \frac{d(4+r^2)}{\sqrt{4+r^2}} = \frac{1}{2} \cdot \frac{1}{-\frac{1}{2}+1} \cdot \sqrt{4+r^2} = \sqrt{4+r^2}$$

$$I = r^2 \sqrt{4+r^2} \Big|_0^1 - 2 \int_0^1 \sqrt{4+r^2} r dr = 1 \cdot \sqrt{5} - \int_0^1 \sqrt{4+r^2} d(4+r^2)$$

$$I = \sqrt{5} - \frac{2}{3} (4+r^2) \sqrt{4+r^2} \Big|_0^1 = \sqrt{5} - \frac{2}{3} (5 \cdot \sqrt{5} - 4 \cdot 2) = \sqrt{5} - \frac{10}{3} \sqrt{5} + \frac{16}{3}$$

$$I = \frac{3-10}{3} \sqrt{5} + \frac{16}{3} = \frac{16}{3} - \frac{7}{3} \sqrt{5}$$

EXC. 31 $I = \int x^4 (\ln x)^2 dx$ $\left. \begin{array}{l} u = x^4 \quad du = 4x^3 dx \\ v = \int \ln^2(x) dx = I_1 \end{array} \right\}$

$$I_1 = \int \ln^2(x) dx \quad \left. \begin{array}{l} u = \ln^2(x) \\ du = 2 \ln(x) \cdot \frac{1}{x} dx \\ v = x \end{array} \right\} = x \ln^2(x) - 2 \int \ln(x) dx$$

$$\int \ln(x) dx = \int \left. \begin{array}{l} u = \ln x \\ du = \frac{1}{x} dx \\ v = x \end{array} \right\} = x \ln(x) - \int x \frac{dx}{x} = x \ln(x) - x$$

$$I_1 = x \ln^2(x) - 2x \ln(x) + 2x = v$$

$$I = x^4 (x \ln^2(x) - 2x \ln(x) + 2x) - \int 4x^3 (x \ln^2(x) - 2x \ln(x) + 2x) dx$$

$$4I = \left(x^5 \ln^2(x) - 2x^5 \ln(x) + 2x^5 \right) \Big|_1^2 + \underbrace{6 \int x^4 \ln x dx}_{I_2} - \underbrace{6 \int x^4 dx}_{6 \cdot \frac{x^5}{5} \Big|_1^2}$$

$$I_2 = \int x^4 \ln x \, dx = \left| \begin{array}{l} v = \ln x \quad v' = \frac{1}{x} \\ dv = \frac{1}{x} dx \quad v = \frac{x^5}{5} \end{array} \right| = \frac{x^5}{5} \ln x - \int \frac{x^4}{5} \frac{1}{x} dx$$

$$I_2 = \frac{x^5}{5} \ln(x) - \frac{1}{5} \int x^4 dx = \frac{x^5}{5} \ln(x) - \frac{x^5}{25} = \frac{x^5}{5} \left(\ln(x) - \frac{1}{5} \right) \Big|_1^2$$

$$4I = x^5 \left(\ln^2(x) - 2 \ln(x) + 2 \right) \Big|_1^2 + \frac{6x^5}{5} \left(\ln(x) - \frac{1}{5} \right) \Big|_1^2 - \frac{6x^5}{5} \Big|_1^2$$

$$I = \frac{x^5}{4} \left(\ln^2(x) - 2 \ln(x) + 2 \right) \Big|_1^2 + \frac{3x^5}{2 \cdot 5} \left(\ln(x) - \frac{6}{5} \right) \Big|_1^2$$

$$I = \frac{x^5}{2} \left(\frac{1}{2} \ln^2(x) - \ln(x) + 1 - \frac{3}{5} \ln(x) + \frac{18}{25} \right) \Big|_1^2$$

$$I = \frac{x^5}{2} \left(\frac{1}{2} \ln^2(x) - \frac{2}{5} \ln(x) + \frac{7}{25} \right) \Big|_1^2$$

$$I = \frac{32}{2} \left(\frac{1}{2} \ln^2(2) - \frac{2}{5} \ln(2) + \frac{7}{25} \right) - \frac{1}{2} \left(0 - 0 + \frac{7}{25} \right)$$

$$I = 8 \ln^2(2) - \frac{32}{5} \ln(2) + \frac{112}{25} - \frac{7}{50} = 8 \ln^2(2) - \frac{32}{5} \ln(2) + \frac{49}{50}$$

ALTERNATIVE

$$I = \int_1^2 x^4 \ln^2(x) \, dx \quad u = \ln^2(x) \quad du = 2 \frac{\ln(x)}{x} dx$$

$$v = \int x^4 dx = \frac{x^5}{5}$$

$$I = \frac{x^5}{5} \ln^2(x) \Big|_1^2 - \frac{1}{5} \int x^5 \ln(x) dx = \frac{32}{5} \ln^2(2) - \frac{2}{5} \int x^4 \ln(x) dx$$

$$I_1 = \left| \begin{array}{l} v = \ln(x) \quad v' = \frac{1}{x} \\ dv = \frac{1}{x} dx \quad v = \frac{x^5}{5} \end{array} \right| = \frac{x^5}{5} \ln(x) - \int \frac{x^4}{5} \frac{1}{x} dx = \frac{x^5}{5} \ln(x) - \frac{x^5}{25}$$

$$I = \frac{32}{5} \ln^2(2) - \frac{2}{5} \left(\frac{x^5}{5} \ln(x) - \frac{x^5}{25} \right) \Big|_1^2 = \frac{32}{5} \ln^2(2) - \frac{2x^5}{25} \left(\ln(x) - \frac{1}{5} \right) \Big|_1^2$$

$$= \frac{32}{5} \ln^2(2) - \frac{2 \cdot 32}{25} \left(\ln(2) - \frac{1}{5} \right) + \frac{2}{25} \left(0 - \frac{1}{5} \right)$$

$$= \frac{32}{5} \ln^2(2) - \frac{64}{25} \ln(2) + \frac{64}{125} - \frac{2}{125} = \frac{32}{5} \ln^2(2) - \frac{64}{25} \ln(2) + \frac{62}{125}$$

$$\boxed{32} \quad I = \int_0^t e^s \sin(t-s) \, ds \quad u = \sin(t-s) \quad du = -\cos(t-s) \, ds \quad v = \int e^s ds = e^s$$

$$I = e^s \sin(t-s) \Big|_0^t + \int_0^t \cos(t-s) e^s \, ds = (e^t \cdot 0 - e^0 \cdot \sin t) + \int_0^t e^s \cos(t-s) \, ds$$

$$I_1 = \left| \begin{array}{l} v = \cos(t-s) \quad v' = \sin(t-s) \\ dv = -\sin(t-s) \, ds \quad v = e^s \end{array} \right| = e^s \cos(t-s) \Big|_0^t - \int_0^t e^s \sin(t-s) \, ds$$

$$2I = -\sin t + e^s \cos(t-s) \Big|_0^t = \sin t + (e^t - 1) \cos t = e^t - \sin t - \cos t$$

$$I = \frac{1}{2} (e^t - \sin t - \cos t)$$

Exc. 33 $I = \int \sin \sqrt{x} dx$ $w = \sqrt{x}$
 $\frac{dw}{dx} = \frac{1}{2} \frac{1}{\sqrt{x}} dx = \frac{1}{2w} dx$

$dx = 2w dw$; $I = \int 2w \sin w dw = 2 \int w \sin w dw$

$u = w$ $du = dw$ $v = \int \sin w dw = -\cos w$
 $I = 2 [-w \cos w + \int \cos w dw] = -2w \cos w + 2 \sin w \Rightarrow$
 $I = 2 \sin \sqrt{x} - 2\sqrt{x} \cos \sqrt{x}$

Exc. 35 $I = \int_{\sqrt{\pi/2}}^{\sqrt{\pi}} \theta^3 \cos(\theta^2) d\theta$ $w = \theta^2$ $\theta = \sqrt{w}$
 $dw = 2\theta d\theta = 2\sqrt{w} d\theta$
 $d\theta = dw / 2\sqrt{w}$

$I = \int \frac{\sqrt{w^3} \cos(w) dw}{2\sqrt{w}} = \frac{1}{2} \int w \cos(w) dw = \left| \begin{matrix} u = w & du = dw \\ v = \sin w \end{matrix} \right|$

$I = \frac{1}{2} (w \sin w - \int \sin w dw) = \frac{1}{2} (w \sin w + \cos w)$

$I = \frac{1}{2} (\theta^2 \sin \theta^2 - \cos(\theta^2)) \Big|_{\sqrt{\pi/2}}^{\sqrt{\pi}} = \frac{1}{2} (\pi \sin \pi + \cos \pi) - \frac{1}{2} (\frac{\pi}{2} \sin \frac{\pi}{2} + \cos \frac{\pi}{2})$

$I = \frac{1}{2} (-1) - \frac{1}{2} (\frac{\pi}{2} \cdot 1 - 0) \quad \boxed{I = -\frac{1}{2} - \frac{\pi}{4}}$?

$\theta = \sqrt{\frac{\pi}{2}} \quad w = \theta^2 = \frac{\pi}{2}$; $\theta = \sqrt{\pi} \quad w = \theta^2 = \pi$

$I = \frac{1}{2} (w \sin w - \cos w) \Big|_{\pi/2}^{\pi} = \frac{1}{2} (\pi \sin \pi + \cos \pi) - \frac{1}{2} (\frac{\pi}{2} \sin \frac{\pi}{2} + \cos \frac{\pi}{2})$

$I = -\frac{1}{2} - \frac{\pi}{4}$

Exc. 38 $I = \int \frac{x^{3/2} \ln(x)}{x} dx = \int x^{1/2} \ln(x) dx$ $u = \ln(x)$ $v = \int x^{1/2} dx = \frac{2}{3} x^{3/2}$
 $du = \frac{1}{x} dx$

$I = \frac{2}{3} x^{3/2} \ln(x) - \frac{2}{3} \int x^{3/2} \cdot \frac{1}{x} dx = \frac{2}{3} x^{3/2} \ln(x) - \frac{2}{3} \cdot \frac{2}{5} x^{5/2}$

$I = \frac{2}{3} x^{3/2} (\ln(x) - \frac{2}{5})$

$f'(x) = \frac{3}{2} x^{1/2} \ln(x) + x^{3/2} \frac{1}{x} = \frac{3}{2} \sqrt{x} \ln(x) + \sqrt{x}$ $f'(1) = 1 > 0$ Minimum
 $\int f'(x) dx = f(x)$ $f'(x) = F''(x)$ $f''(x) = F'''(x)$

Exc. 40 $I = \int x^3 e^{x^2} dx = \int \frac{1}{2} w e^w \frac{dw}{\sqrt{w}}$ $x^2 = w$ $x = \sqrt{w}$
 $2x dx = dw$ $2\sqrt{w} dx = dw$ $dx = \frac{dw}{2\sqrt{w}}$

$I = \int \frac{w e^w}{2\sqrt{w}} \frac{dw}{\sqrt{w}} = \frac{1}{2} \int w e^w dw = \left| \begin{matrix} u = w & du = dw \\ v = \int e^w dw = e^w \end{matrix} \right|$

$I = \frac{1}{2} [w e^w - e^w] = \frac{e^w}{2} (w - 1) = \frac{e^{x^2}}{2} (x^2 - 1)$

Ex 41 $\int \sin^n(x) dx = -\frac{1}{n} \sin^{n-1}(x) \cos(x) + \frac{n-1}{n} \int \sin^{n-2}(x) dx$

① $I = \int \sin^2(x) dx = -\frac{1}{2} \sin(x) \cos(x) + \frac{1}{2} \int \sin^0(x) dx = \frac{x}{2} - \frac{1}{2} \sin(x) \cos(x)$
 $\sin(2x) = 2 \sin x \cos x \quad \sin x \cos x = \frac{\sin(2x)}{2}$

$I = \frac{x}{2} - \frac{1}{4} \sin(2x)$ $\frac{x}{2} - \frac{1}{4} \sin(2x)$

② $\int \sin^4(x) dx = -\frac{1}{4} \sin^3(x) \cos(x) + \frac{3}{4} \int \sin^2(x) dx$
 $I = -\frac{1}{4} \sin^3(x) \cos(x) + \frac{3x}{8} - \frac{3}{16} \sin(2x) + C$

Ex 42 $\int \cos^n(x) dx = \frac{1}{n} \cos^{n-1}(x) \sin(x) + \frac{n-1}{n} \int \cos^{n-2}(x) dx$

$I = \int \cos^{n-1}(x) \cos(x) dx; \quad u = \cos^{-1}(x); \quad du = -\cos^{-2}(x) \sin(x) dx$
 $v = \int \cos(x) dx = \sin(x)$

$I = \sin(x) \cos^{n-1}(x) + (n-1) \int \cos^{n-2}(x) \sin^2(x) dx = \sin(x) \cos^{n-1}(x) + \int \cos^{n-2}(x) dx - I$

$I + (n-1)I = I + nI = \sin(x) \cos^{n-1}(x) + (n-1) \int \cos^{n-2}(x) dx$

$I = \frac{1}{n} \sin(x) \cos^{n-1}(x) + \frac{n-1}{n} \int \cos^{n-2}(x) dx$

③ $\int \cos^2(x) dx = \frac{1}{2} \cos(x) \sin(x) + \frac{1}{2} \int dx = \frac{1}{2} x + \frac{1}{2} \cos(x) \sin(x)$

$= \frac{1}{2} x + \frac{1}{4} \sin(2x)$

④ $I = \int \cos^4(x) dx = \frac{1}{4} \cos^3(x) \sin(x) + \frac{3}{4} \int \cos^2(x) dx$

$I = \frac{1}{4} \cos(x) \sin(x) + \frac{3}{8} x + \frac{3}{16} \sin(2x) + C$

Ex 43

$\int \sin^n(x) dx = -\frac{1}{n} \sin^{n-1}(x) \cos(x) + \frac{n-1}{n} \int \sin^{n-2}(x) dx$

SHOW THAT: $\int_0^{\pi/2} \sin^n(x) dx = \frac{n-1}{n} \int_0^{\pi/2} \sin^{n-2}(x) dx$

$I = \int_0^{\pi/2} \sin^n(x) dx = -\frac{1}{n} \sin^{n-1}(x) \cos(x) \Big|_0^{\pi/2} + \frac{n-1}{n} \int_0^{\pi/2} \sin^{n-2}(x) dx$

$I = -\frac{1}{n} (1^{n-1} \cdot 0 - 0 \cdot 1) = 0 \quad \Rightarrow \quad I = \frac{n-1}{n} \int_0^{\pi/2} \sin^{n-2}(x) dx$

$I = \int_0^{\pi/2} \sin^n(x) dx = \int \frac{u = \sin^{-1}(x)}{du = (n-1) \sin^{n-2}(x) \cos(x) dx} \quad dv = \sin(x) dx = -\cos(x) \Big|_0^{\pi/2}$

$I = -\sin^{n-1}(x) \cos(x) \Big|_0^{\pi/2} + (n-1) \int_0^{\pi/2} \cos^2(x) \sin^{n-2}(x) dx = (n-1) \int_0^{\pi/2} \sin^{n-2}(x) dx - (n-1) \int_0^{\pi/2} \sin^n(x) dx$

$I + (n-1)I = I + nI = I \Rightarrow I = \frac{n-1}{n} \int_0^{\pi/2} \sin^{n-2}(x) dx$

⑤ $I = \int_0^{\pi/2} \sin^3(x) dx = \frac{3-1}{3} \int_0^{\pi/2} \sin(x) dx = -\frac{2}{3} \cos(x) \Big|_0^{\pi/2} = -\frac{2}{3} (0 - 1) = \frac{2}{3}$

$$I = \int_0^{\pi/2} \sin^4(x) dx = \frac{4-1}{4} \int_0^{\pi/2} \sin^{4-2}(x) dx + \int_0^{\pi/2} \sin^3(x) dx = \frac{2}{3}$$

$$I_2 = \int_0^{\pi/2} \sin^6(x) dx = \frac{4}{5} \int_0^{\pi/2} \sin^4(x) dx = \frac{4}{5} \cdot \frac{2}{3} = \frac{8}{15}$$

$$I_3 = \int_0^{\pi/2} \sin^8(x) dx = \frac{7-1}{7} \int_0^{\pi/2} \sin^6(x) dx = \frac{6}{7} \cdot \frac{4}{5} \cdot \frac{2}{3}$$

$$I_n = \frac{2}{3} \cdot \frac{4}{5} \cdot \frac{6}{7} \cdot \frac{n-1}{n} \quad n = 3, 5, 7, \dots, 2k+1$$

$$\text{ex: } \int_0^{\pi/2} \sin^{2k+1}(x) dx = \frac{2}{3} \cdot \frac{4}{5} \cdot \frac{6}{7} \cdot \dots \cdot \frac{2k}{2k+1}$$

$$\int_0^{\pi/2} \sin^{2k}(x) dx = \frac{2k-1}{2k} \int_0^{\pi/2} \sin^{2k-2}(x) dx = \frac{2k-2}{2k-1} \int_0^{\pi/2} \sin^{2k-4}(x) dx$$

$$= \frac{2k-2}{2k-1} \cdot \frac{2k-4}{2k-3} \cdot \frac{4}{5} \cdot \frac{2}{3}$$

$$\boxed{44} \int_0^{\pi/2} \sin^{2n}(x) dx = \frac{1 \cdot 3 \cdot 5 \cdot \dots \cdot (2n-1)}{2 \cdot 4 \cdot 6 \cdot \dots \cdot 2n} \cdot \frac{\pi}{2}$$

$$\int_0^{\pi/2} \sin^2(x) dx = \frac{1}{2} \int_0^{\pi/2} \sin^0(x) dx = \frac{1}{2} \cdot \frac{\pi}{2}$$

$$\int_0^{\pi/2} \sin^4(x) dx = \frac{3}{4} \int_0^{\pi/2} \sin^2(x) dx = \frac{3}{4} \cdot \frac{1}{2} \cdot \frac{\pi}{2}$$

$$\int_0^{\pi/2} \sin^{2k}(x) dx = \frac{2k-1}{2k} \int_0^{\pi/2} \sin^{2k-2}(x) dx = \frac{2k-1}{2k} \cdot \frac{2k-3}{2k-2} \cdot \frac{3}{4} \cdot \frac{1}{2} \cdot \frac{\pi}{2}$$

$n = 1, 2, \dots, k$

let $n = k+1$

$$\int_0^{\pi/2} \sin^{2n}(x) dx = \int_0^{\pi/2} \sin^{2(k+1)}(x) dx = \frac{2k+1}{2k+2} \int_0^{\pi/2} \sin^{2k}(x) dx$$

$$= \frac{1}{2} \cdot \frac{3}{4} \cdot \frac{5}{6} \cdot \dots \cdot \frac{2k-1}{2k} \cdot \frac{2k+1}{2k+2} \Rightarrow \text{HOLDS FOR } n = k+1 \text{ BY INDUCTION}$$

IT HOLDS FOR ANY $n \geq 1$

$$\boxed{45} I = \int \ln^4(x) dx = x \ln^4(x) - 4 \int \ln^3(x) dx$$

$$u = \ln^4(x) \quad du = 4 \cdot \ln^3(x) \cdot \frac{1}{x} dx \quad dv = dx \quad v = x$$

$$I = x \cdot \ln^4(x) - 4 \int \ln^3(x) \cdot \frac{1}{x} \cdot x dx = x \ln^4(x) - 4 \int \ln^3(x) dx$$

$$\boxed{46} I = \int x^n e^x dx = x^n e^x - n \int x^{n-1} e^x dx$$

$$u = x^n \quad du = n x^{n-1} dx \quad v = \int e^x dx = e^x$$

$$I = x^n e^x - n \int x^{n-1} e^x dx$$

$$\boxed{47} I = \int (x^2 + a^2)^n dx = \frac{x(x^2 + a^2)^n}{2n+1} + \frac{2na^2}{2n+1} \int (x^2 + a^2)^{n-1} dx \quad n \neq -\frac{1}{2}$$

$$u = (x^2 + a^2)^n \quad du = n(x^2 + a^2)^{n-1} \cdot 2x dx \quad v = \int dx = x$$

$$I = x(x^2 + a^2)^n - 2 \int n(x^2 + a^2)^{n-1} \cdot x^2 dx$$

$$I = \int (x^2+a^2)^n - 2n \int (x^2+a^2)^{n-1} (x^2+a^2) dx + 2n \cdot a^2 \int (x^2+a^2)^{n-1} dx$$

$$I = \int (x^2+a^2)^n - 2n \cdot I + 2na^2 \int (x^2+a^2)^{n-1} dx$$

$$(2n+1)I = \int (x^2+a^2)^n + 2na^2 \int (x^2+a^2)^{n-1} dx$$

$$I = \frac{\int (x^2+a^2)^n}{2n+1} + \frac{2na^2}{(2n+1)} \int (x^2+a^2)^{n-1} dx \quad 2n+1 \neq 0 \quad n \neq -\frac{1}{2}$$

$$\boxed{48} I = \int \sec^n(x) dx = \frac{\tan(x) \sec^{n-2}(x)}{n-1} + \frac{n-2}{n-1} \int \sec^{n-2}(x) dx$$

$$u = \sec^n(x) \quad du = n \sec^{n-1}(x) \cdot (-1) \cos^{-1}(x) \cdot (-\sin(x)) dx$$

$$du = n \cdot \frac{1}{\cos^n(x)} \cdot \frac{1}{\cos^2(x)} \cdot \sin(x) dx = \frac{n}{\cos^n(x)} \cdot \tan(x) dx$$

$$du = dx \Rightarrow u = x \quad ??$$

$$u = \sec^{n-2}(x) \quad du = (n-2) \sec^{n-3}(x) \cdot (-1) \cos^{-2}(x) \cdot (-\sin(x)) dx$$

$$du = \sec^2(x) dx \quad u = \int \sec^2(x) dx = \tan(x)$$

$$du = (n-2) \sec^{n-3}(x) \sec(x) \cdot \tan(x) dx = (n-2) \sec^{n-2}(x) \tan(x) dx$$

$$I = \tan(x) \sec^{n-2}(x) - (n-2) \int \sec^{n-2}(x) \tan^2(x) dx$$

$$I_2 = \int \sec^{n-2}(x) \frac{\sin^2(x)}{\cos^2(x)} dx = \int \sec^{n-2}(x) \frac{1-\cos^2(x)}{\cos^2(x)} dx$$

$$I_2 = \int \sec^{n-2}(x) \cdot \frac{1}{\cos^2(x)} dx - \int \sec^{n-2}(x) dx = \int \sec^n(x) dx - \int \sec^{n-2}(x) dx$$

$$I = \tan(x) \sec^{n-2}(x) - (n-1)I + (n-2) \int \sec^{n-2}(x) dx \quad I + 4I - 2I = (n-1)I$$

$$\boxed{I = \frac{\tan(x) \sec^{n-2}(x)}{(n-1)} + \frac{(n-2)}{(n-1)} \int \sec^{n-2}(x) dx} \quad (n \neq 1)$$

$$\boxed{49} I = \int \ln^3(x) dx \quad \int \ln^n(x) dx = x \ln^n(x) - n \int \ln^{n-1}(x) dx$$

$$I = x \cdot \ln^3(x) - 3 \int \ln^2(x) dx \quad I_1 = \left| \begin{array}{l} u = \ln^2(x) \quad du = 2\ln(x) \cdot \frac{1}{x} dx \\ dv = dx \quad v = \int dx = x \end{array} \right|$$

$$I_1 = x \ln^2(x) - 2 \int \ln(x) \cdot \frac{1}{x} \cdot x dx = x \ln^2(x) - 2 \int \ln(x) dx = x \ln^2(x) - 2(x \ln(x) - x)$$

$$\boxed{I_1 = x \ln^2(x) - 2x \ln(x) + 2x}$$

$$I = x \ln^3(x) - 3(x \ln^2(x) - 2x \ln(x) + 2x) = x \ln^3(x) - 3x \ln^2(x) + 6x \ln(x) - 6x$$

$$\boxed{50} I = \int x^4 e^x dx \quad \int x^n e^x dx = x^n e^x - n \int x^{n-1} e^x dx$$

$$I = x^4 e^x - 4 \int x^3 e^x dx = x^4 e^x - 4 [x^3 e^x - 3 \int x^2 e^x dx]; \quad I_1 = x^2 e^x - 2 \int x e^x dx$$

$$I_1 = x^2 e^x - 2(x e^x - e^x); \quad I = x^4 e^x - 4(x^3 e^x - 3(x^2 e^x - 2(x e^x - e^x))) = x^4 e^x - 4x^3 e^x + 12x^2 e^x - 24x e^x + 14e^x$$

$$\boxed{51} \quad y = x e^{-0.4x} \quad y=0, x=5$$

$$A = \int_0^5 x e^{-0.4x} dx \Rightarrow I = \int x e^{cx} dx = \frac{1}{c^2} \int cx e^{cx} dx$$

$$= \frac{1}{c^2} \int u e^u du = \frac{1}{c^2} (u e^u - e^u) = \left| \begin{matrix} u=cx \\ c=-0.4 \end{matrix} \right| =$$

$$= \frac{1}{(0.4)^2} (-0.4x e^{-0.4x} - e^{-0.4x}) \Big|_0^5 = -\frac{1}{0.16} (0.4x+1) e^{-0.4x} \Big|_0^5$$

$$= -\frac{1}{0.16} [(2+1)e^{-2} - (0+1)e^0] = -\frac{1}{0.16} (3 \cdot e^{-2} - 1) = \frac{1}{0.16} (1 - 3e^{-2})$$

$$\boxed{A = 6.25 - 18.75 e^{-2}}$$

$$\boxed{A = \frac{25}{4} - \frac{75}{4} e^{-2}}$$

$$\boxed{52} \quad y_1 = 5 \ln x \quad y_2 = x \ln x \quad A = \int_1^5 (5 \ln x - x \ln x) dx$$

$$A = 5 \int_1^5 \ln x dx - \int_1^5 x \ln x dx$$

$$I_1 = \int \ln x dx = \left| \begin{matrix} u = \ln x & du = \frac{1}{x} dx \\ v = x \end{matrix} \right| = x \ln x - x$$

$$\int \ln^2(x) dx = x \cdot \ln^2(x) - 2 \int \ln(x) dx$$

$$I_2 = \int \ln^2(x) dx = x \cdot \ln^2(x) - 2 \int \ln(x) dx = x \ln^2(x) - 2(x \ln x - x)$$

$$A = 5 \left(x \ln x - x \right) \Big|_1^5 + \left(x \ln^2(x) + 2x \ln x - 2x \right) \Big|_1^5$$

$$A = \left(x \ln^2(x) + 7x \ln(x) - 7x \right) \Big|_1^5 = \left(-5 \ln^2(5) + 7 \cdot 5 \ln(5) - 35 \right) - (0 + 0 - 7) = -5 \ln^2(5) + 35 \ln(5) - 28$$

$$I_2 = \int x \ln x dx = \left| \begin{matrix} u = \ln x & du = \frac{1}{x} dx \\ v = \int x dx = \frac{x^2}{2} \end{matrix} \right| = \frac{x^2}{2} \ln(x) - \int \frac{x}{2} dx$$

$$I_2 = \frac{x^2}{2} \ln(x) - \frac{x^2}{4}$$

$$A = 5 \left(x \ln x - x \right) \Big|_1^5 + \left(\frac{x^2}{2} \ln(x) + \frac{x^2}{4} \right) \Big|_1^5 =$$

$$= 5 [5 \ln 5 - 5 + 1] + \left(\frac{25}{4} - \frac{25}{2} \ln(5) - \frac{1}{4} + 0 \right) =$$

$$= 25 \ln 5 - 20 + \frac{24}{4} - \frac{25}{2} \ln(5) = \frac{50 - 25 \ln(5) - 20 + 24}{2}$$

$$A = \frac{25}{2} \ln(5) - \frac{56}{4} = \frac{25}{2} \ln(5) - 14$$

53 & 54 $A = \int_0^{x_1} (\arctan(x) - x \sin(x)) dx + \int_{x_1}^{x_2} (x \sin(x) - \arctan(x)) dx$
check
max &
min
6

$$I_1 = \int x \sin(x) dx = \left| \begin{array}{l} u = x \quad du = dx \\ v = \int \sin(x) dx = -\cos(x) \end{array} \right| = -x \cos(x) + \int \cos(x) dx = \sin(x) - x \cos(x)$$

$$I_2 = \int \arctan(x) dx = \left| \begin{array}{l} u = \arctan(x) \\ du = \frac{1}{1+x^2} dx \end{array} \right| = x \arctan(x) - \int \frac{x dx}{1+x^2}$$

$$I_2 = x \arctan(x) - \frac{1}{2} \int \frac{d(x^2+1)}{1+x^2} = x \arctan(x) - \frac{1}{2} \ln|1+x^2|$$

$$A = (x \arctan(x) - \frac{1}{2} \ln(1+x^2)) \Big|_0^{x_1} - (\sin(x) - x \cos(x)) \Big|_0^{x_1} + (\sin(x) - x \cos(x)) \Big|_{x_1}^{x_2} - (x \arctan(x) - \frac{1}{2} \ln(1+x^2)) \Big|_{x_1}^{x_2}$$

$$I_3 = \int \arctan(3x) dx = \frac{1}{3} \int \arctan(u) du = \frac{1}{3} (x \arctan(3x) - \frac{1}{2} \ln(1+9x^2))$$

$$I_3 = x \arctan(3x) - \frac{1}{6} \ln(9x^2+1)$$

55 Use method of cylindrical shells to find volume

$$y = \cos(\pi x/2); \quad y=0 \quad 0 \leq x \leq 1$$

$$V = \int_0^1 2\pi x \cdot \cos(\pi x/2) dx = \left| \begin{array}{l} u = 2\pi x \quad du = 2\pi dx \\ v = \int \cos(\frac{\pi x}{2}) dx = \frac{2}{\pi} \sin(\frac{\pi x}{2}) \end{array} \right|$$

$$V = 2\pi x \cdot \frac{2}{\pi} \sin(\frac{\pi x}{2}) \Big|_0^1 - \int_0^1 \frac{2}{\pi} \sin(\frac{\pi x}{2}) \cdot 2\pi dx$$

$$V = 4x \sin(\frac{\pi x}{2}) \Big|_0^1 + 4 \cos(\frac{\pi x}{2}) \cdot \frac{2}{\pi} \Big|_0^1 = \left[4x \sin(\frac{\pi x}{2}) + \frac{8}{\pi} \cos(\frac{\pi x}{2}) \right] \Big|_0^1$$

$$V = \left(4 \sin \frac{\pi}{2} + \frac{8}{\pi} \cos \frac{\pi}{2} \right) - \left(-4 \sin(0) + \frac{8}{\pi} \cos(0) \right)$$

$$V = 4 - \frac{8}{\pi}$$

57 $y = e^{-x}; \quad y=0; \quad x=-1, x=0$ ABOUT $x=1$

$$V = \int_{-1}^0 2\pi(1-x)e^{-x} dx = 2\pi \int_{-1}^0 e^{-x} dx - 2\pi \int_{-1}^0 x e^{-x} dx$$

$$I_1 = \int x e^{-x} dx = \left| \begin{array}{l} u = x \quad du = dx \\ v = \int e^{-x} dx = -e^{-x} \end{array} \right| = -x e^{-x} + \int e^{-x} dx = -x e^{-x} - e^{-x}$$

$$V = \left[-2\pi e^{-x} - 2\pi(-x e^{-x} - e^{-x}) \right] \Big|_{-1}^0 = 2\pi (x e^{-x} + e^{-x}) \Big|_{-1}^0 = 2\pi (x e^{-x} + e^{-x}) \Big|_{-1}^0$$

$$V = 2\pi e^{-x} \cdot x \Big|_{-1}^0 = (0 - 2\pi e^1 (-1)) = 2\pi e$$

58) $y = e^x$; $x = 0$; $y = \pi$; about x -axis

$x = \frac{1}{\pi} \ln y$

$$V = \int_1^{\pi} 2\pi y \ln y \, dy = \left| \begin{array}{l} u = \ln y \quad du = \frac{1}{y} dy \\ v = \int y \, dy = \frac{y^2}{2} \end{array} \right| = \pi \left(\frac{y^2}{2} \ln y - \frac{1}{2} \int y \, dy \right)$$

$$V = 2\pi \left(\frac{y^2}{2} \ln y - \frac{y^2}{4} \right) = \left(\pi y^2 \ln y - \frac{\pi}{2} y^2 \right) \Big|_1^{\pi}$$

$$V = \pi \cdot \pi^2 \ln \pi - \frac{\pi}{2} \pi^2 - \pi \cdot 0 + \frac{\pi}{2} = \pi^3 \ln \pi - \frac{\pi^3}{2} + \frac{\pi}{2}$$

$e^x = \pi \quad x_1 = \ln \pi$

59) $f(x) = x^2 \ln(x)$ $f_{ave} = ?$ $[1, 3]$

$$f_{ave} = \frac{1}{3-1} \int_1^3 x^2 \ln(x) \, dx = \left| \begin{array}{l} u = \ln(x) \quad du = \frac{1}{x} dx \\ v = \frac{x^3}{3} \end{array} \right| =$$

$$= \frac{1}{2} \left(\frac{x^3}{3} \ln(x) - \int \frac{x^2}{3} \, dx \right) = \frac{1}{2} \left(\frac{x^3}{3} \ln(x) - \frac{x^3}{9} \right) \Big|_1^3$$

$$f_{ave} = \frac{27}{6} \ln(3) - \frac{27}{18} - \frac{1}{6} \ln(1) + \frac{1}{18} = \frac{27}{6} \ln(3) - \frac{26}{18}$$

$$f_{ave} = \frac{9}{2} \ln(3) - \frac{13}{9}$$

60) m - initial mass of the rocket

r - RATE of consumption of fuel

v_e - exhaust gases are ejected with this velocity (relative to rocket)

VELOCITIES OF THE ROCKET AT TIME t IS:

$$v(t) = -gt - v_e \ln\left(\frac{m-rt}{m}\right)$$

$g = 9.8 \frac{m}{s^2}$; $m = 30,000 \text{ kg}$; $r = 160 \text{ kg/s}$; $v_e = 2000 \text{ m/s}$

$h = ?$ - ONE MINUTE AFTER LIFT OFF

$$v(t) = \frac{dh}{dt} \quad ; \quad h = \int v(t) \, dt = \int_0^T -gt - v_e \ln\left(\frac{m-rt}{m}\right) \, dt$$

$$h = -g \frac{t^2}{2} \Big|_0^T - v_e \int_0^T \ln\left(\frac{m-rt}{m}\right) \, dt$$

$$I_1 = \int_0^T \ln\left(\frac{m-rt}{m}\right) \, dt \quad \left| \begin{array}{l} u = \frac{m-rt}{m} \quad du = -\frac{r}{m} dt \\ t=0 \quad u=1 \quad t=T \quad u = \frac{m-rT}{m} \end{array} \right| = -\frac{m}{r} \int_1^{\frac{m-rT}{m}} \ln u \, du = \left| \begin{array}{l} \int \ln u \, du = u \ln u - u \\ du = \frac{1}{u} du \\ v = \frac{1}{u} \end{array} \right|$$

$$= -\frac{m}{r} \left(u \ln u - u \right) \Big|_1^{\frac{m-rT}{m}} = -\frac{m}{r} \frac{m-rT}{m} \left(\ln \frac{m-rT}{m} - 1 \right) + \frac{m}{r} (1 - 1)$$

$$I_1 = -\frac{m-rT}{r} \left(\ln \frac{m-rT}{m} - 1 \right) - \frac{m}{r}$$

$$h = -g \frac{T^2}{2} + \sigma_e \left[\frac{u-rT}{r} \ln \left(\frac{u-rT}{u} \right) - \frac{u-rT}{r} + \frac{u}{r} \right]$$

$$h = -g \frac{T^2}{2} + \sigma_e \left[\frac{rT}{r} + \frac{u-rT}{r} \ln \left(\frac{u-rT}{u} \right) \right]$$

$$h = -g \frac{T^2}{2} + \sigma_e \left[T + \frac{u-rT}{r} \ln \left(\frac{u-rT}{u} \right) \right]$$

61) $v(t) = t^2 e^{-t}$ $s(t) = \int_0^t x^2 e^{-x} dx = \left| \begin{array}{l} u = x^2 \\ du = 2x dx \\ v = -e^{-x} \\ dv = dx \end{array} \right|$

$$s(t) = -x^2 \cdot e^{-x} \Big|_0^t + 2 \int_0^t x e^{-x} dx = \left| \begin{array}{l} v = x \\ dv = dx \\ v = -e^{-x} \end{array} \right|$$

$$= -x^2 \cdot e^{-x} \Big|_0^t + 2 \left(-x e^{-x} - e^{-x} \right) \Big|_0^t = \left(-x^2 e^{-x} - 2x e^{-x} - 2e^{-x} \right) \Big|_0^t$$

$$s(t) = -e^{-x} (x^2 + 2x + 2) \Big|_0^t = -e^{-t} (t^2 + 2t + 2) + (2) = \underline{2 - (t^2 + 2t + 2)e^{-t}}$$

62) If $f(0) = g(0) = 0$ f'' , g'' are continuous show that:

$$\int_0^a f(x) g''(x) dx = f(a) g'(a) - f'(a) g(a) + \int_0^a f''(x) g(x) dx$$

$$\frac{d}{dx} f(x) g(x) = f'(x) g(x) + f(x) g'(x) \quad | \int$$

$$f(x) g'(x) = \int f'(x) g(x) dx + \int f(x) g''(x) dx$$

$$\int f(x) g''(x) dx = f(x) g'(x) - \int f'(x) g(x) dx$$

$$\frac{d^2}{dx^2} f(x) g(x) = \left(f'(x) g(x) + f(x) g''(x) \right)' = \underline{f''(x) g(x) + g'(x) f'(x)}$$

$$+ \underline{f''(x) g'(x) - f'(x) g''(x)} \quad | \int$$

$$f'(x) g(x) + f(x) g'(x) = \int f''(x) g(x) dx + 2 \int g'(x) f(x) dx + \int f(x) g''(x) dx$$

$$\int f(x) g''(x) dx = f'(x) g(x) + f(x) g'(x) - 2 \int g'(x) f(x) dx - \int f''(x) g(x) dx$$

$$\int_0^a f(x) g''(x) dx = f'(a) g(a) + f(a) g'(a) - 2 \int_0^a g'(x) f(x) dx - \int_0^a f''(x) g(x) dx$$

Proof: $I = \int_0^a f(x) g''(x) dx = f(a)g'(a) - f(0)g'(0) + \int_0^a f''(x)g(x) dx$ $f(0)=g(0) \Rightarrow$

$u = f(x) \quad du = f'(x) dx \quad dv = g''(x) dx \quad v = \int g''(x) dx = g'(x)$

$I = f(x)g'(x) \Big|_0^a - \int_0^a g'(x) f'(x) dx$

$I_1 = \left| \begin{array}{l} u = f(x) \quad du = f'(x) dx \\ v = \int g'(x) dx = g(x) \end{array} \right| = g(x) f'(x) - \int g(x) f''(x) dx$

$I = f(x)g'(x) \Big|_0^a - g(x) \cdot f'(x) \Big|_0^a + \int_0^a g(x) f''(x) dx$

$f(0)=g(0)=0 \Rightarrow \boxed{I = f(a)g'(a) - f'(a)g(a) + \int_0^a f''(x)g(x) dx}$

$\boxed{\int f(x)g''(x) dx = f(x)g'(x) - f'(x)g(x) + \int g(x)f''(x) dx} \quad (*)$

[63] $f(1)=2; f(4)=7; f'(1)=5; f'(4)=3; f''$ is continuous

$I = \int_1^4 x f''(x) dx = \int_1^4 x f''(x) dx - \int_1^4 x f''(x) dx = \left| \begin{array}{l} f(x)=x \\ g(x)=f'(x) \end{array} \right|$

$= 4 \cdot f'(4) - (x)' \cdot f(x) \Big|_{x=4} + \int_1^4 (x)'' f'(x) dx - \left(1 \cdot f'(1) - (x)' \cdot f(1) \right)$

$+ \int_1^4 (x)'' f(x) dx = 4 \cdot f'(4) - 1 \cdot f(4) - f'(1) + f(1) =$

$= 4 \cdot 3 - 1 \cdot 7 - 5 + 2 = 12 - 7 - 5 + 2 = 2$

$(*) \Rightarrow \int_1^4 x f''(x) dx = (x \cdot f'(x) - x' \cdot f(x)) \Big|_1^4 + \int_1^4 (x)'' \cdot f(x) dx$

$= 4 \cdot f'(4) - 1 \cdot f(4) - (1 \cdot f'(1) - 1 \cdot f(1)) = 4 \cdot f'(4) - 1 \cdot f(4) - f'(1) + f(1)$

$= 4 \cdot 3 - 7 - 5 + 2 = 2$

ALT: $I = \int_1^4 x f''(x) dx; \quad u=x \quad du=dx; \quad v = \int f''(x) dx = f'(x)$

$I = x \cdot f'(x) \Big|_1^4 - \int_1^4 f'(x) dx = 4 \cdot f'(4) - 1 \cdot f'(1) - f(4) + f(1)$

$I = 4 \cdot 3 - 1 \cdot 5 - 7 + 2 = 2$

64) ① $\int f(x) dx = \left| \begin{matrix} u = f(x) & du = f'(x) dx \\ dv = dx & v = x \end{matrix} \right| = x \cdot f(x) - \int x f'(x) dx$

② $\int_a^b f(x) dx = b f(b) - a f(a) - \int_a^b g(y) dy$

$y = f(x); \quad x = g(y);$

$\frac{dy}{dx} = \frac{df(x)}{dx} \frac{dx}{dy} \Rightarrow dy = f'(x) dx$

$\int_a^b f(x) dx = x \cdot f(x) \Big|_a^b - \int_a^b x f'(x) dx = b \cdot f(b) - a f(a) - \int_a^b x f'(x) dx$

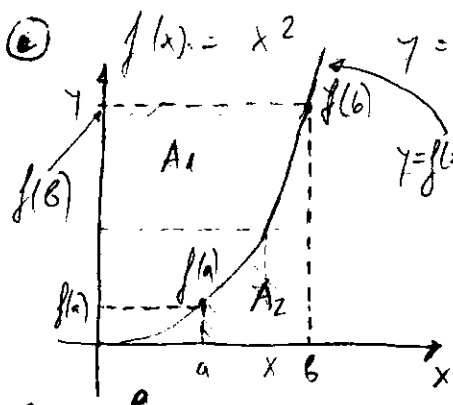
$= \int_a^b \frac{x = g(y)}{dx = g'(y) dy} \cdot \frac{f'(x) = (y)'}{x = g(y)} = b f(b) - a f(a) - \int_a^b g(y) \cdot f'(g(y)) dy$

$y = f(b) \quad \leftarrow x = b \quad g(y) = b$

$g'(y) = \frac{dg(y)}{dy} = \frac{d(x)}{dx} = 1 \quad f'(x) = \frac{df(x)}{dx} = \frac{d(y)}{dy}$

$\Rightarrow x = g(y); \quad dy = f'(x) dx \quad x = a \Rightarrow y = f(a); \quad x = b \Rightarrow y = f(b)$

$\int_a^b f(x) dx = b f(b) - a f(a) - \int_a^b g(y) \cdot dy$



$f(x) = x^2 \quad y = x^2 \Rightarrow x = \sqrt{y}$

$A_1 + A_2 = b \cdot f(b) - a f(a)$

$A_2 = b \cdot f(b) - a f(a) - A_1$

$A_1 = \int_a^b g(y) dy$

③ $I = \int \ln(x) dx$

$f(x) = \ln(x); \quad y = \ln(x); \quad x = e^y; \quad g(y) = e^y$

$\int = e \cdot \ln(e) - 1 \cdot \ln(1) - \int_0^1 e^y dy = e \ln(e) - e^y \Big|_0^1 = e \ln e - e + 1$

$\int = e - e + 1 = 1$

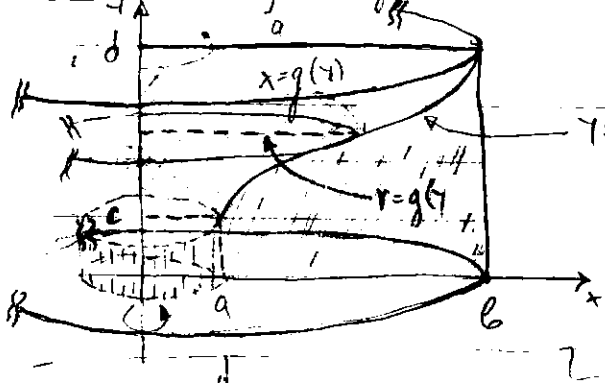
ANSWER: e

$\int \ln(x) dx = \left| \begin{matrix} u = \ln(x) \\ dv = \frac{1}{x} dx \end{matrix} \right| = x \ln(x) - \int x \cdot \frac{dx}{x} =$

$= e \ln e - 1 \cdot \ln 1 - x \Big|_1^e = e - e + 1 = 1$

65

$$V = \int_0^d 2\pi x f(x) dx \quad ; \quad V = \pi b^2 d - \pi a^2 c - \int_c^d \pi g^2(\gamma) d\gamma$$



$$V = V_{cyl1} - V_{cyl2} - V_g = \pi b^2 d - \pi a^2 c - \int_c^d \pi g^2(\gamma) d\gamma$$

$\boxed{\gamma = f(x)} \quad \boxed{g(\gamma) = x}$

$$I_1 = \int_c^d \pi g^2(\gamma) d\gamma \quad \begin{matrix} \gamma = f(x) & d\gamma = f'(x) dx \\ x = g(\gamma) & \frac{dx}{d\gamma} = g'(\gamma) & d\gamma = \frac{1}{g'(\gamma)} dx \end{matrix}$$

$$I_1 = \int_c^d \pi \cdot x^2 \cdot \frac{1}{x'} dx = \int_c^d \pi x^2 dx$$

$$I_1 = \int_c^d \pi g^2(\gamma) d\gamma = \left| \begin{matrix} u = g^2(\gamma) \\ du = 2g(\gamma)g'(\gamma)d\gamma \\ dv = \pi d\gamma \\ v = \pi\gamma \end{matrix} \right| = \pi\gamma \cdot g^2(\gamma) \Big|_c^d - \int_c^d 2\pi\gamma g(\gamma)g'(\gamma) d\gamma$$

$$I_1 = \pi d \cdot g^2(d) - \pi c \cdot g^2(c) - \int_c^d 2\pi\gamma g(\gamma)g'(\gamma) d\gamma = \pi b^2 d - \pi a^2 c - \int_c^d 2\pi\gamma g(\gamma)g'(\gamma) d\gamma$$

$$(*) V = \pi b^2 d - \pi a^2 c - \int_c^d 2\pi\gamma g(\gamma)g'(\gamma) d\gamma = \int_c^d 2\pi\gamma g(\gamma)g'(\gamma) d\gamma$$

$$V = \int_c^d 2\pi\gamma g(\gamma)g'(\gamma) d\gamma \quad \begin{matrix} x = g(\gamma) \\ dx = g'(\gamma) d\gamma \end{matrix} \quad \begin{matrix} \gamma = c \quad x = g(c) \\ \gamma = d \quad x = g(d) \end{matrix}$$

$$V = \int_{g(c)}^{g(d)} 2\pi f(x) \cdot x \cdot g'(\gamma) d\gamma = \int_a^b 2\pi x f(x) dx$$

NOTE: $I_1 = \int_c^d \pi g^2(\gamma) d\gamma = \left| \begin{matrix} \gamma = f(x) & d\gamma = f'(x) dx \\ g(\gamma) = x & \begin{matrix} \gamma = c & x = g(c) \\ \gamma = d & x = g(d) \end{matrix} \end{matrix} \right| = \int_a^b \pi x^2 f(x) dx$

$$I_1 = \int_a^b \pi x^2 f(x) dx = \left| \begin{matrix} u = x^2 & du = 2x dx \\ dv = f(x) dx & v = f(x) \end{matrix} \right| = \pi \left[x^2 f(x) - \int 2x f(x) dx \right]$$

$$= \pi b^2 f(b) - \pi a^2 f(a) - \int_a^b 2\pi x f(x) dx = \pi b^2 d - \pi a^2 c - \int_a^b 2\pi x f(x) dx$$

$$V = \pi b^2 d - \pi a^2 c - \int_a^b 2\pi x f(x) dx = \int_a^b 2\pi x f(x) dx$$

$$\boxed{66} \quad I_n = \int_0^{\pi/2} \sin^n(x) dx = \frac{n-1}{n} \int_0^{\pi/2} \sin^{n-2}(x) dx$$

$$\int \sin^n(x) dx = -\frac{1}{n} \sin^{n-1}(x) \cdot \cos(x) + \int \sin^{n-2}(x) dx$$

$$k=2n+1 \quad \int_0^{\pi/2} \sin^{2n+1}(x) dx = \frac{2 \cdot 4 \cdot 6 \cdots 2n}{3 \cdot 5 \cdot 7 \cdots 2n+1} \cdot \frac{2 \cdot 4}{2 \cdot 5} = \frac{8}{15} = 0.533$$

$$\int_0^{\pi/2} \sin^{2n}(x) dx = \frac{1 \cdot 3 \cdot 5 \cdots 2n-1}{2 \cdot 4 \cdot 6 \cdots 2n} \cdot \frac{\pi}{2} \quad \frac{1 \cdot 3}{2 \cdot 4} = \frac{3}{8} = 0.375$$

$$(a) \quad I_{2n+2} \leq I_{2n+1} \leq I_{2n}$$

$$I_{2n} = \frac{1 \cdot 3 \cdot 5 \cdots 2n-1}{2 \cdot 4 \cdot 6 \cdots 2n} \cdot \frac{\pi}{2} \quad I_{2n+1} = \frac{2 \cdot 4 \cdot 6 \cdots 2n}{3 \cdot 5 \cdot 7 \cdots 2n+1}$$

$$I_{2n+2} = \frac{1 \cdot 3 \cdot 5 \cdots 2n+1}{2 \cdot 4 \cdot 6 \cdots 2n+2} \cdot \frac{\pi}{2}$$

$$\frac{I_{2n}}{I_{2n+2}} = \frac{\frac{1 \cdot 3 \cdot 5 \cdots 2n-1}{2 \cdot 4 \cdot 6 \cdots 2n} \cdot \frac{\pi}{2}}{\frac{1 \cdot 3 \cdot 5 \cdots 2n-1 \cdot 2n+1}{2 \cdot 4 \cdot 6 \cdots 2n \cdot 2n+2} \cdot \frac{\pi}{2}} = \frac{2n+2}{2n+1} > 1$$

$$(1) \quad I_{2n} = \frac{2n+2}{2n+1} \cdot I_{2n+2}$$

$$I_{2n} > I_{2n+2}$$

$$I_{2n+1} = \frac{1}{\frac{3 \cdot 5 \cdot 7 \cdots 2n-1 \cdot 2n+1}{2 \cdot 4 \cdot 6 \cdots 2n \cdot 2n+2}}$$

$$= \frac{1}{(2n+1) I_{2n} \cdot \frac{\pi}{2}}$$

$$(2) \quad I_{2n+1} = \frac{1}{(2n+1) I_{2n} \cdot \frac{\pi}{2}}$$

$$I_{2n+2} = \frac{1 \cdot \frac{2}{\pi} \cdot I_{2n}}{\frac{2 \cdot 4 \cdot 6 \cdots 2n \cdot (2n+2)}{1 \cdot 3 \cdot 5 \cdots (2n-1) \cdot (2n+1)}} \cdot \frac{\pi}{2} = \frac{1}{(2n+2) I_{2n+1}}$$

$$= \frac{1}{(2n+2) I_{2n+1}} \cdot \frac{\pi}{2}$$

$$(3) \quad I_{2n+1} = \frac{1}{2 (2n+2) I_{2n+2}}$$

$$(1), (3) \quad I_{2n+2} = \frac{2n+1}{2n+2} I_{2n}$$

$$I_{2n} - I_{2n+1} = I_{2n} - \frac{1}{(2n+1) I_{2n} \cdot \frac{\pi}{2}} = \frac{(2n+1) I_{2n}^2 - \frac{\pi}{2}}{(2n+1) I_{2n}}$$

$$(2) \quad 2n \cdot I_{2n+1} + I_{2n+1} = \frac{1}{I_{2n}} \cdot \frac{\pi}{2}$$

$$\frac{I_{2n}}{I_{2n+1}} = \frac{\frac{1 \cdot 3 \cdot 5 \cdots 2n-1}{2 \cdot 4 \cdot 6 \cdots 2n} \cdot \frac{\pi}{2}}{\frac{2 \cdot 4 \cdot 6 \cdots 2n}{3 \cdot 5 \cdot 7 \cdots 2n-1 \cdot 2n+1}} = (2n+1) I_{2n} \cdot \frac{2}{\pi}$$

$$(2), (3) \quad I_{2n+1} = \frac{1}{(2n+1)I_{2n}} \cdot \frac{\pi}{2}$$

$$I_{2n+2} = \frac{1}{(2n+2)I_{2n+1}} \cdot \frac{\pi}{2}$$

$$I_{2n} > I_{2n+2} = \frac{1}{(2n+2)I_{2n+1}} \cdot \frac{\pi}{2}$$

$$I_{2n} = \frac{1 \cdot 3 \cdot 5 \cdots (2n-1)}{2 \cdot 4 \cdot 6 \cdots 2n} \cdot \frac{\pi}{2}$$

$$I_{2n+1} = \frac{2 \cdot 4 \cdot 6 \cdots 2n}{3 \cdot 5 \cdot 7 \cdots (2n+1)}$$

$$I_{2n+1} = \int_0^{\pi/2} \sin^{2n+1}(x) dx = \frac{2n+1-1}{2n+1} \int_0^{\pi/2} \sin^{2n-1}(x) dx = \frac{2n}{2n+1} \int_0^{\pi/2} \sin^{2n}(x) dx$$

$$I_{2n+2} = \int_0^{\pi/2} \sin^{2n+2}(x) dx = \frac{2n+2-1}{2n+2} \int_0^{\pi/2} \sin^{2n}(x) dx$$

$$I_{2n+2} = \frac{2n+1}{2n+2} I_{2n}$$

$$I_{2n+1} = \int_0^{\pi/2} \sin^{2n+1}(x) dx$$

$$0 \leq x \leq \frac{\pi}{2} \quad 0 \leq \sin(x) \leq 1 \quad \Rightarrow$$

$$(a) \quad \sin^{2n+2}(x) \leq \sin^{2n+1}(x) \leq \sin^{2n}(x)$$

$$(b) \quad \frac{I_{2n+2}}{I_{2n}} = \frac{1 \cdot 3 \cdot 5 \cdots (2n+1)(2n+1)}{2 \cdot 4 \cdot 6 \cdots 2n(2n+2)} \cdot \frac{\pi}{2} = \frac{2n+1}{2n+2}$$

$$(c) \quad \frac{2n+1}{2n+2} \leq \frac{I_{2n+1}}{I_{2n}} \leq 1$$

$$I_{2n+2} \leq I_{2n+1} \leq I_{2n} \quad \frac{2n+1}{2n+2} I_{2n} \leq I_{2n+1} \leq I_{2n} \quad \Big/ I_{2n}$$

$$\frac{2n+1}{2n+2} \leq \frac{I_{2n+1}}{I_{2n}} \leq 1$$

$$\lim_{n \rightarrow \infty} \frac{I_{2n+1}}{I_{2n}} = \lim_{n \rightarrow \infty} \frac{2n+1}{2n+2} = \frac{2}{2} = 1$$

SQUEEZE THEOREM
 $\lim_{n \rightarrow \infty} \frac{I_{2n+1}}{I_{2n}} = 1$

$$(c) \lim_{n \rightarrow \infty} \left(\frac{2}{1} \cdot \frac{2}{3} \cdot \frac{4}{3} \cdot \frac{4}{5} \cdot \frac{6}{5} \cdot \frac{6}{7} \dots \frac{2n}{2n-1} \cdot \frac{2n}{2n+1} \right) = \frac{\pi}{2}$$

$$I_{2n+1} = \frac{2 \cdot 4 \cdot 6 \cdot 8 \dots 2n}{1 \cdot 3 \cdot 5 \cdot 7 \dots 2n+1} \quad I_{2n} = \frac{1 \cdot 3 \cdot 5 \dots 2n-1}{2 \cdot 4 \cdot 6 \dots 2n} \cdot \frac{\pi}{2}$$

$$\frac{I_{2n+1}}{I_{2n}} = \left(\frac{2}{1} \cdot \frac{2}{3} \cdot \frac{4}{3} \cdot \frac{4}{5} \cdot \frac{6}{5} \cdot \frac{6}{7} \dots \frac{2n}{2n-1} \cdot \frac{2n}{2n+1} \right) \cdot \frac{\pi}{2}$$

$$\lim_{n \rightarrow \infty} \frac{I_{2n+1}}{I_{2n}} = \frac{\pi}{2} \quad \lim_{n \rightarrow \infty} \left(\frac{2}{1} \cdot \frac{2}{3} \cdot \frac{4}{3} \cdot \frac{4}{5} \cdot \frac{6}{5} \cdot \frac{6}{7} \dots \frac{2n}{2n-1} \cdot \frac{2n}{2n+1} \right) = \frac{\pi}{2}$$

$$\boxed{\frac{\pi}{2}} = \frac{\pi}{2} \quad \left[\frac{\pi}{2} = \frac{2}{1} \cdot \frac{2}{3} \cdot \frac{4}{3} \cdot \frac{4}{5} \cdot \frac{6}{5} \cdot \frac{6}{7} \dots \right] \text{ Wallis' Product}$$

$$(c) \frac{\text{width}}{\text{height}} = \frac{1}{1} \cdot \frac{2}{1} \cdot \frac{2}{3} = \frac{2}{1} \cdot \frac{2}{3} \cdot \frac{5}{2} = \frac{5}{3} = \frac{2}{3} \cdot \frac{5}{2} \cdot \frac{5}{2} = \frac{5}{4}$$

$$k=1 \quad \frac{a}{b} = \frac{1}{1} = 1$$

$$k=2 \quad \frac{a}{b} = \frac{1+1}{1} = \frac{2}{1} = 2 \quad \frac{2n}{2n-1} = \frac{4}{3} \quad n=1$$

$$k=3 \quad \frac{a}{b} = \frac{2}{1} \cdot \frac{2}{3} = \frac{4}{3} = 1.33 \quad n=1$$

$$k=4 \quad \frac{a}{b} = \frac{2}{1} \cdot \frac{2}{3} = \frac{8}{3} = \frac{16}{9} = 1.66 \quad n=2 \quad k=2n=4$$

$$k=5 \quad \frac{a}{b} = \frac{5/2}{2} = \frac{5/2}{2} = \frac{5/2}{4} = \frac{5}{8} = \frac{25}{16} = 1.56 \quad n=2$$

$$k=6 \quad \frac{a}{b} = \frac{5/2 + 1/4}{2} = \frac{9/4}{2} = \frac{9}{8} = \frac{95+20}{38} = \frac{115}{38} = \frac{515}{361} = 1.593 \quad n=3$$

$$k=7 \quad \frac{a}{b} = \frac{115/38}{10} = \frac{115}{380} = \frac{115}{380} = \frac{115}{380} = 1.356 \quad n=3$$

$$\frac{a_n}{b_n} = \frac{a_{n-1}}{b_{n-1}} + \frac{1}{a_{n-1}}$$

$$\frac{a_n}{b_n} = \frac{a_{n-1}}{b_{n-1}} + \frac{1}{a_{n-1}}$$

$$\frac{a_n}{b_n} = \frac{a_{n-1}}{b_{n-1}} + \frac{1}{a_{n-1}}$$

$$\frac{a_n}{b_n} = \frac{a_{n-1}}{b_{n-1}} + \frac{1}{a_{n-1}}$$

$n=1$
 $k=2n$ step

$$\text{Area} = 2n$$

$$\frac{a}{b} = \frac{1 + \frac{2n}{2n-1}}{1} = \frac{2}{1} = 2$$

$$\text{Area} = 2n = 2$$

$$\frac{1 + \frac{2}{1}}{\frac{3}{2}} = \frac{2}{1} = 2$$

$$\text{ratio}\left(\frac{a}{b}\right) = \frac{2n}{2n-1}$$

$$k=2n+1=3 \quad \frac{a}{b} = \frac{2}{1 + \frac{2n+1}{2n}} = \frac{2}{\frac{3}{2}} = \frac{4}{3}$$

$$\text{ratio}\left(\frac{a}{b}\right) = \frac{2n}{2n+1}$$

$$\text{ratio}\left(\frac{a}{b}\right)_{2n} \cdot \text{ratio}\left(\frac{a}{b}\right)_{2n+1} = \frac{2n}{2n-1} \cdot \frac{2n}{2n+1} \rightarrow \lim_{n \rightarrow \infty} \frac{2}{1} \cdot \frac{2}{3} \cdot \frac{4}{3} \dots = \frac{\pi}{2}$$

$n=2$

$$k=2n \quad k=4$$

$$\frac{a}{b} = \frac{2 \cdot \frac{2n+1}{2n+1}}{\frac{3}{2}} = \frac{2 \cdot \frac{5}{4+0}}{\frac{3}{2}} = \frac{5}{3}$$

$$k=2n+1 \quad k=5$$

$$\frac{a}{b} = \frac{\frac{5}{2}}{\frac{3}{2} \cdot \frac{2n+1}{2n-1}} = \frac{5/2}{\frac{3}{2} \cdot \frac{4}{3}} = \frac{5}{4}$$

$$\frac{5 \cdot 7}{2 \cdot 6} = \frac{35}{12} = \frac{35}{24}$$

$n=3$

$$k=2n \quad k=6$$

$$\frac{a}{b} = \frac{5/2 \cdot \frac{2n}{2n-1}}{\frac{3}{2} \cdot \frac{6}{5}} = \frac{3}{2}$$

$$\frac{5}{2} + \frac{1}{4} = \frac{11}{8} \quad \frac{5}{2} \cdot x = \frac{11}{8} \quad x = \frac{11}{5} = 2.2 \quad (?)$$

$$\frac{5}{2} + \frac{5 \cdot 2n}{2 \cdot 2n-1} = \frac{5}{2} + \frac{5 \cdot 6}{2 \cdot 5} = \frac{5}{2} + 3$$

$$\frac{a}{b} = \frac{a_n}{b_n + 4b_n}$$

$$a_n \cdot a_n = 1 \quad a_n = \frac{1}{a_n}$$

$$\frac{a}{b} = \frac{a_n}{b_n + \frac{1}{a_n}} = \frac{a_n^2}{a_n \cdot b_n + 1}$$

$$1.5 \cdot x = 1 \quad x = \frac{1}{1.5} = \frac{2}{3}$$

EXAMPLE: $k=3$ $a_k=2$ $b_{k-1}=1$ $\left(\frac{a}{b}\right) = \frac{4}{2 \cdot 1 + 1} = \frac{4}{3}$

$$k=5 \quad \left(\frac{a}{b}\right) = \frac{a_5^2}{a_5 \cdot b_4 + 1} = \frac{\left(\frac{5}{2}\right)^2}{\frac{5}{2} \cdot \frac{5}{2} + 1} = \frac{25}{19}$$

$$k=7 \quad \frac{a_7}{b_7} = \frac{a_7^2}{a_7 \cdot b_6 + 1} = \frac{\left(\frac{115}{38}\right)^2}{\frac{115}{38} \cdot \frac{19}{10} + 1} = \frac{\left(\frac{115}{38}\right)^2}{\frac{2185 + 380}{380}} = \frac{\left(\frac{115}{38}\right)^2}{\frac{2565}{380}}$$

$$\frac{a_7}{b_7} = 1.35683$$

$$k=2 \quad \frac{a_n}{b_n} = \frac{a_{n-1} + \frac{1}{b_n}}{b_n \cdot a_{n-1} + 1} = \frac{1 \cdot 1 + 1}{1^2} = 2$$

$$k=4 \quad \frac{a_4}{b_4} = \frac{a_3 \cdot b_4 + 1}{b_4} = \frac{2 \cdot \frac{3}{2} + 1}{\frac{3}{2}} = \frac{4}{\frac{3}{2}} = \frac{8}{3}$$

$$\frac{2 + \frac{2}{3}}{\frac{3}{2}} = \frac{\frac{6+2}{3}}{\frac{3}{2}} = \frac{16}{9}$$

$$k=4 \quad \frac{a}{b} = \frac{2 \cdot \frac{24}{24-1}}{\frac{3}{2}} = \frac{2 \cdot \frac{4}{3}}{\frac{3}{2}} = \frac{\frac{8}{3}}{\frac{3}{2}} = \frac{16}{9}$$

$$\frac{1}{9k}$$

MARKAZ

$$k=1 \quad \frac{a}{b} = \frac{1}{1}, \quad k=2 \quad \frac{a}{b} = \frac{1+1}{1} = 2; \quad k=3 \Rightarrow \frac{a}{b} = \frac{2}{1 + \frac{1}{2}} = \frac{2}{\frac{3}{2}} = \frac{4}{3}$$

$$k=4 \quad \frac{a}{b} = \frac{2 + \frac{1}{\frac{3}{2}}}{\frac{3}{2}} = \frac{2 + \frac{2}{3}}{\frac{3}{2}} = \frac{\frac{8}{3}}{\frac{3}{2}} = \frac{16}{9}; \quad k=5 \quad \frac{a}{b} = \frac{\frac{8}{3}}{\frac{3}{2} + \frac{3}{8}} = \frac{\frac{8}{3}}{\frac{15}{8}} = \frac{64}{45}$$

$$k=6 \quad \frac{a}{b} = \frac{\frac{8}{3} + \frac{8}{15}}{\frac{15}{8}} = \frac{\frac{48}{15}}{\frac{15}{8}} = \frac{384}{225}; \quad k=7 \quad \frac{a}{b} = \frac{\frac{48}{15}}{\frac{15}{8} + \frac{15}{48}} = \frac{\frac{48}{15}}{\frac{109}{48}} = \frac{488}{175}$$

$$k=5 \quad k=2u+1; u=2;$$

$$\frac{a_u}{b_{u-1}} = \frac{8/3}{\frac{2u+1}{2} \cdot \frac{5}{4}} = \frac{8/3}{\frac{15}{8}} = \frac{64}{45}$$

~~$$\frac{a_n}{b_{n-1}} = \frac{8 \cdot 5}{3 \cdot 15} = \frac{40}{45}$$~~

$$k=6 \quad k=2u; u=3$$

$$\frac{a_{u-1}}{b_u} = \frac{8/3 \cdot \frac{6}{5}}{\frac{15}{8}} = \frac{48}{15} = \frac{384}{225}$$

$$k=7 \quad k=2u+1; u=3$$

$$\frac{a_u}{b_{u-1}} = \frac{\frac{48}{15}}{\frac{15}{8} \cdot \frac{7}{6}} = \frac{488}{175}$$

$$k=2 \quad \frac{2u}{2u-1} = \frac{2}{1}$$

$$k=3 \quad \frac{2u+1}{2u} = \frac{3}{2}; \quad k=4 \quad \frac{2u}{2u-1} = \frac{4}{3}$$

$$\frac{2}{1} \cdot \frac{2}{3} \cdot \frac{4}{3} \cdot \frac{4}{5} \cdot \frac{6}{5} \cdot \frac{6}{7} \dots \quad \lim_{u \rightarrow \infty} \frac{u}{2} = \frac{u}{2}$$

$$\frac{a_5}{b_5} = \frac{4}{5}$$

$$\frac{a_7}{b_6} = \frac{\frac{48}{15} \cdot \frac{6}{7}}{\frac{48}{15}} = \frac{6}{7}$$

[CRC] [1100110]

$$M = x^6 + x^5 + x^2 + x$$

$$1101$$

$$P = x^3 + x^2 + 1 \quad v=3$$

$$T = M \cdot x^3 / P$$

$$7+4-1=10$$

$$R = \frac{T}{Q \cdot P}$$

$$Q = x^6 + x^7 x$$

LINEAR BLOCK CODES

$X_{in} = [x_{in1}, x_{in2}, \dots, x_{ink}]$ INPUT VECTOR INTO ENCODER

$C_{out} = [C_{out1}, C_{out2}, \dots, C_{outn}]$ OUTPUT OF THE ENCODER

$$C_{out} = X_{in} G$$

$$G = \begin{bmatrix} g_{11} & g_{12} & \dots & g_{1n} \\ g_{21} & g_{22} & \dots & g_{2n} \\ g_{k1} & g_{k2} & \dots & g_{kn} \end{bmatrix}$$

\Rightarrow G-GENERATOR MATRIX

$$C_{outj} = x_{in1} g_{1j} + x_{in2} g_{2j} + \dots + x_{ink} g_{kj}$$

$$G = [I_k | P] = \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & \dots & 0 & p_{11} & p_{12} & \dots & p_{1n-k} \\ 0 & 1 & 0 & & 0 & p_{21} & p_{22} & & p_{2n-k} \\ \vdots & \vdots & \vdots & & \vdots & \vdots & \vdots & & \vdots \\ 0 & 0 & 0 & \dots & 1 & p_{k1} & p_{k2} & & p_{kn-k} \end{array} \right] \quad k$$

① HAMMING CODE

$$(n, k) = (2^m - 1, 2^m - 1 - m)$$

$m=3$ $2^3 - 1 = 8 - 1 = 7$; $2^3 - 1 - 3 = 8 - 4 = 4$

$(n, k) = (7, 4)$ CODE \Rightarrow

$$C_{out} H' = 0$$

H - PARITY CHECK MATRIX

\Downarrow ALL ZERO ROW VECTOR WITH $n-k$ ELEMENTS

$G \cdot H' = 0 \Rightarrow k \times (n-k)$ 0 MATRIX

ex:

$$G = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 & 1 \end{bmatrix} = [I_4 | P]$$

$C_{out5} = x_{in1} + x_{in2} + x_{in3}$

$C_{out6} = x_{in2} + x_{in3} + x_{in4}$

$C_{out7} = x_{in1} + x_{in2} + x_{in4}$

$$C_{out} = [x_{in1}, x_{in2}, x_{in3}, x_{in4}, C_{out5}, C_{out6}, C_{out7}]$$

$$H = \begin{bmatrix} 1 & 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 1 & 0 & 0 & 1 \end{bmatrix}$$

$$H = \left[\begin{array}{c|c} -P' & I_{n-k} \end{array} \right]$$

$C_{out} H'$

$x_{in1} + x_{in2} + x_{in3} + C_{out5} = 0$

$x_{in2} + x_{in3} + x_{in4} + C_{out6} = 0$

$x_{in1} + x_{in2} + x_{in4} + C_{out7} = 0$

$\Rightarrow n = 2^m - 1$

$m = n - k = 3$ element

HAMMING CODE

DATA = 1011

$n = 2^m - 1, m = 3$ $n = 2^3 - 1 = 7$

$k = 4$

$k = n - m = 2^m - 1 - m = 2^3 - 1 - 3 = 4$

$msg = 1011$

$[L, g, u, k] = \text{Langer}(u)$

$code = [1011] \begin{bmatrix} 1 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 0 & 0 & 1 \end{bmatrix} = [P | I_k]$

$1+1+1, 1+0+1+0, 0+0+1+1, 1, 0, 1, 1$

$[1, 0, 0, 1, 0, 1, 1]$

$\begin{array}{r} 83 \\ - 75 \\ \hline 8 \\ \hline 93 \\ - 88 \\ \hline 5 \end{array}$

$H = [I_{n-k} | P^T] = \begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 & 1 & 1 \end{bmatrix}$

The Binary primitive polynomial used to produce Hamming code is default primitive polynomial GF(2³)

$pol = \text{gfprimd}(2, 3)$
 $pol = [2, 1, 1]$

$(2 + x + x^2)$

$\text{gfprimd}(3, 2) = [1, 1, 0, 1]$

$2^3 + 2 + 1 = 11 = \text{prim poly}(3)$
 $D^3 + D^1 + 1$

	0	1	2
0	0	1	2
1	1	2	0
2	2	0	1

Channels and Propagation

- (a) Channel - Physical Layer
 - transmission & reception
 - decode & forward

(b) Propagation is

(c) propagation delay

DEL TO THE RECEIVER
 WITH ANTENNA
 AT THE TRANSMITTER

VERSITY - ~~REPLY~~ IS A REPLY TO

PROBLEM PATENT TOGETHER WITH "DIVERSE"

FAKLEIGH FIDING SE KOBISTI
 KOST NEMA LOS (line of sight),
 + RIGIAN PASTRODENA KOST VIA LEX

• Gain $G = \frac{\text{SISTEM NA HOC...}}{\text{...}}$

$\frac{P_t}{4\pi r^2}$

• Effective Area Propagasi : $A = \frac{\lambda^2 G}{4\pi}$

ФУНДАМЕНТАЛНА МОЌНОСТ:

$$P = W \cdot A$$

$$P_R = \frac{P_T G_T}{4\pi d^2} A = \frac{P_T G_T}{4\pi d^2} \frac{\lambda^2 G_R}{4\pi}$$

$$\boxed{\frac{P_R}{P_T} = G_T G_R \left(\frac{\lambda}{4\pi d} \right)^2} / \log$$

$$\frac{P_T}{P_R} = \frac{1}{G_T G_R \left(\frac{4\pi d}{\lambda} \right)^2} / \log$$

ФУНДАМЕНТАЛНА
РАВЕНКА ЗА
СМЕРЕНОСТ ВО
СЛОБДЕН ПРОСТОР

$$\begin{aligned} 10 \log \frac{P_T}{P_R} &= -10 \log(G_T) - 10 \log(G_R) + 10 \log \left(\frac{4\pi d \cdot c}{c \cdot \lambda} \right)^2 \\ &= -10 \log(G_T) - 10 \log(G_R) + 20 \log \left(\frac{4\pi d}{c} \right) + 20 \log \left(\frac{c}{\lambda} \right) \\ &= -10 \log(G_T) - 10 \log(G_R) + 20 \log(f) + 20 \log d + 20 \log \frac{4\pi}{c} \\ &\quad - 147.56 \text{ dB} \end{aligned}$$

ПОТРОШНА АНЕНА

$$\begin{aligned} L_b(\text{dB}) &= 20 \log(f_{\text{MHz}}) + 20 \log(d_{\text{km}}) + 20 \log 10^6 + 20 \log 10^3 \\ -147.56 &= 32.44 \text{ dB} + 20 \log(f_{\text{MHz}}) + 20 \log(d_{\text{km}}) \end{aligned}$$

$$SUR = \frac{P_R}{kTB} = \frac{P_T G_T G_R}{kTB} \left(\frac{c}{4\pi f d} \right)^2$$

• ГУСТИНА НА МОЌНОСТ:

$$W = \frac{|\vec{E}|^2}{Z_W}$$

$Z_W = \text{ВАЗРОВА МИСРА} = R$

$$Z_W = \sqrt{\frac{\mu_0}{\epsilon_0}} = 120\pi \Omega$$

$$W = \frac{E^2}{120\pi}$$

$$\frac{P_T G_T}{4\pi d^2}$$

$$= \frac{E^2}{120\pi}$$

$$= \frac{E^2}{120\pi}$$

$$\boxed{E = \sqrt{\frac{30 P_T G_T}{d}}}$$

$$P_R = W \cdot A = \frac{E^2}{120\pi} \cdot \frac{\lambda^2 G_R}{4\pi} = \left(\frac{E \lambda}{2\pi} \right)^2 \frac{G_R}{120} \sim E^2$$

• ФАЗНА НАЗНАЧА

$$\Delta \phi = \frac{2\pi \Delta R}{\lambda} = \frac{4\pi L_T L_R}{\lambda d}$$

РЕФЛЕКТИРАЊЕ

$$E = E_0 [1 + \rho e^{-j2\phi}] = E_0 [1 + |\rho| e^{-j(\theta + \phi)}] \quad \text{FOLE VO PRIBLYNKOT}$$

$$\rho \approx \frac{\sin \phi - \sqrt{(\epsilon_r - 1) - \cos^2 \phi}}{\sin \phi + \sqrt{(\epsilon_r - 1) - \cos^2 \phi}} = \frac{-(\epsilon_r - 1) - 1}{(\epsilon_r - 1) - 1} = -1$$

$$E = E_0 [1 - e^{-j2\phi}] \quad |E| = |E_0| \sqrt{(1 - \cos 2\phi)^2 + \sin^2 2\phi} = \text{PROVEJVA}$$

$$= |E_0| \sqrt{4 \sin^2 \frac{2\phi}{2}} = |E_0| \cdot 2 \sin \frac{2\phi}{2}$$

$$e^{-j2\phi} = (\cos 2\phi) - j \sin 2\phi \quad |1 - e^{-j2\phi}| = \sqrt{(1 - \cos 2\phi)^2 + \sin^2 2\phi} =$$

$$1 - 2 \cos 2\phi + \cos^2 2\phi + \sin^2 2\phi = \sqrt{1 - 2 \cos 2\phi + 1} =$$

$$= 2(1 - \cos 2\phi) = 4 \sin^2 \phi$$

$$\cos 2\phi = \cos \left(2 \cdot \frac{2\pi h_T h_R}{\lambda \cdot d} \right) = \cos \left(\frac{4\pi h_T h_R}{\lambda \cdot d} \right) =$$

$$= \cos \left(\frac{4\pi}{\lambda} \right) = 2 \cos^2 \left(\frac{2\pi}{\lambda} \right) - 1$$

$$4 \sin^2 \phi = 2 \left(1 - \cos^2 \left(\frac{2\pi}{\lambda} \right) + \sin^2 \left(\frac{2\pi}{\lambda} \right) \right) = 2 \left(\cos^2 \left(\frac{2\pi}{\lambda} \right) + \sin^2 \left(\frac{2\pi}{\lambda} \right) - \cos^2 \left(\frac{2\pi}{\lambda} \right) + \sin^2 \left(\frac{2\pi}{\lambda} \right) \right) = 4 \sin^2 \left(\frac{2\pi}{\lambda} \right)$$

IN NA PROJEKCIJI
KOTI PISANA

$$\Delta z = z_2 - z_1 \approx \frac{2 h_T \cdot h_R}{d}$$

$$\Delta \phi = \frac{2\pi \Delta z}{\lambda} = \frac{4\pi h_T \cdot h_R}{\lambda \cdot d}$$

$$P_R \sim 4 |E_0|^2 \cdot \sin^2 \left(\frac{2\pi h_T \cdot h_R}{\lambda \cdot d} \right) \stackrel{\oplus}{=} 4 P_T G_T G_R \left(\frac{\lambda}{4\pi d} \right)^2 \cdot \sin^2 \left(\frac{2\pi h_T \cdot h_R}{\lambda \cdot d} \right)$$

$$|d \gg h_T \quad d \gg h_R| = 4 G_T G_R P_T \left(\frac{\lambda}{4\pi d} \right)^2 \cdot \frac{(2\pi h_T h_R)^2}{\lambda^2 d^2} = 4 G_T G_R \frac{1}{\lambda^2 d^2} \frac{4\pi^2 h_T^2 h_R^2}{\lambda^2 d^2}$$

$$P_R = P_T G_T G_R \frac{h_T^2 h_R^2}{d^4} = P_T G_T G_R \left(\frac{h_T h_R}{d^2} \right)^2 = P_T G_T G_R \left(\frac{h_T h_R}{d^2} \right)^2$$

$$\boxed{\frac{P_R}{P_T} = G_T G_R \left(\frac{h_T h_R}{d^2} \right)^2}$$

PRVENICA NA ZADIVAGANJA NAD
LAMPNA TOVLISINA;

• VIZITANE NA NEKAMNITE

$$\Delta L = 2 \delta \sin \phi$$

$$\Delta \theta = \frac{2\pi}{\lambda} \cdot \Delta L = \frac{4\pi \delta}{\lambda} \sin \phi$$

RAYLEIGH-ON KRITERIUM: $d_r \geq \frac{\lambda}{8 \sin \phi}$

$$\Delta \theta \geq \frac{\pi}{2} \quad \frac{4\pi \delta}{\lambda} \sin \phi \geq \frac{\pi}{2} \quad d_r \geq \frac{\lambda}{8 \sin \phi} = \frac{\lambda}{8 \sin \phi}$$

STANDARDNA DEVIACIJA NA TEREŠNA NEKAVNOST:

$$c = \frac{496 \sin \varphi}{\lambda} \approx \frac{496 \cdot \varphi}{\lambda}$$

$c < 0,1 \Rightarrow$ POJKOVATA E MALA

$c > 10 \Rightarrow$ POJKOVATA E NEKAVNA

MULTIPLE INTEGRALS

$$\sum_{i=1}^n f(x_i^*) \Delta x \quad \int_a^b f(x) dx = \lim_{n \rightarrow \infty} \sum_{i=1}^n f(x_i^*) \Delta x$$

Volumes and double integrals
 $z = f(x,y)$ $R = [a,b] \times [c,d] = \{(x,y) \in \mathbb{R}^2, a \leq x \leq b, c \leq y \leq d\}$

$$S = \{(x,y,z) \in \mathbb{R}^3 \mid 0 \leq z \leq f(x,y), (x,y) \in R\}$$

$$[a,b] \quad [x_{i-1}, x_i], \quad \Delta x = \frac{b-a}{n}$$

$$[c,d] \quad [y_{j-1}, y_j], \quad \Delta y = \frac{d-c}{m}$$

Volume of the column (ij)

$$f(x_{ij}^*, y_{ij}^*) \Delta A \quad ; \quad V = \sum_{i=1}^m \sum_{j=1}^n f(x_{ij}^*, y_{ij}^*) \Delta A$$

$$V = \lim_{m,n \rightarrow \infty} \sum_{i=1}^m \sum_{j=1}^n f(x_{ij}^*, y_{ij}^*) \Delta A$$

$$\iint_R f(x,y) dA = \lim_{m,n \rightarrow \infty} \sum_{i=1}^m \sum_{j=1}^n f(x_{ij}^*, y_{ij}^*) \Delta A$$

726
1006
1325
848
1005

$$\iint_R f(x,y) dA = \lim_{m,n \rightarrow \infty} \sum_{i=1}^m \sum_{j=1}^n f(x_{ij}^*, y_{ij}^*) \Delta A$$

$$V = \iint_R f(x,y) dA$$

EX 1 $R = [0,2] \times [0,2]$ $V = ?$

$$z = 16 - x^2 - 2y^2$$

$m = 2 \quad \Delta x = 1$
 $n = 2 \quad \Delta y = 1$

$$V = \sum_{i=1}^2 \sum_{j=1}^2 f(x_i, y_j) \Delta A = f(1,1) \Delta A + f(1,2) \Delta A +$$

$$+ f(2,1) \Delta A + f(2,2) \Delta A = 13 \cdot 1 + 7 \cdot 1 + 10 \cdot 1 + 4 \cdot 1 = 20 + 14 = 34$$

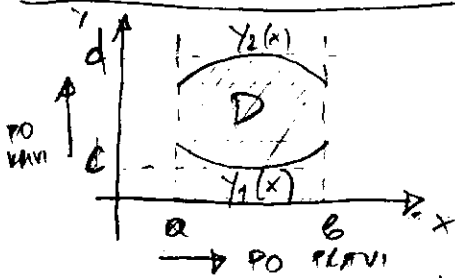
Ex 2) $R = \{(x, y) \mid -1 \leq x \leq 1, -2 \leq y \leq 2\}$ $\iint_R \sqrt{1-x^2} dA$

$V = \frac{R^2 \pi}{2} \cdot (2-2) = \frac{\pi}{2} \cdot 4 = 2\pi$

Ex 1) $V = \int_0^2 \int_0^2 (16 - x^2 - 2y) dx dy = \int_0^2 \left(16y - x^2 y - 2 \frac{y^2}{2} \right) \Big|_0^2 dy =$
 $= \int_0^2 dx \left[(2 \cdot 16 - 2x^2 - 2 \cdot 2/2) - (0 - 0 - 0) \right] = \int_0^2 (32 - 2x^2 - 16/2) dx$
 $= \int_0^2 \left(\frac{32-16}{2} - 2x^2 \right) dx = \left(\frac{80}{3} x - 2 \frac{x^3}{3} \right) \Big|_0^2 = \frac{160}{3} - \frac{16}{3} = \frac{144}{3}$

$V = 48$

REŠENJE DVOJNE INTEGRALI OD ELEKTROMAGNETIKA



$V = \iint_D f(x, y) dx dy$ $D = \{(x, y) \mid a \leq x \leq b, y_1(x) \leq y \leq y_2(x)\}$

$V = \int_a^b dx \int_{y_1(x)}^{y_2(x)} f(x, y) dy = \int_c^d dy \int_{x_1(y)}^{x_2(y)} f(x, y) dx$

SMENA NA PROMENLIVI
 $x = x(u, v)$
 $y = y(u, v)$

KAZ DVOJNE INTEGRAL:

$\begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = J$

$u = \rho$
 $v = \varphi$

$\iint_D f(x, y) dx dy = \iint_{D_1} f(x(u, v)) |J| du dv$

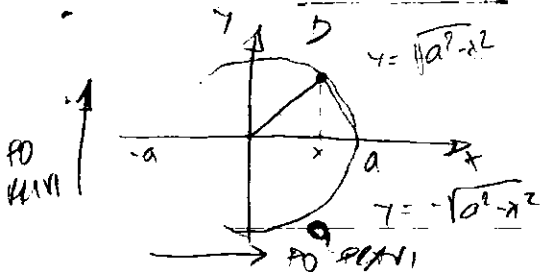
PRIMER: $x = \rho \cdot \cos \varphi$
 $y = \rho \cdot \sin \varphi$

$\begin{vmatrix} \cos \varphi & -\rho \sin \varphi \\ \sin \varphi & \rho \cos \varphi \end{vmatrix} = J$

$J = \rho \cdot \cos^2 \varphi + \rho \sin^2 \varphi = \rho (\cos^2 \varphi + \sin^2 \varphi) = \rho$

$\iint_D f(x, y) dx dy = \iint_{D_1} f(\rho \cos \varphi, \rho \sin \varphi) \rho \cdot d\rho \cdot d\varphi$

PRIMER: $\iint_D \sqrt{x^2 + y^2} dx dy$ $D: x^2 + y^2 \leq a^2$



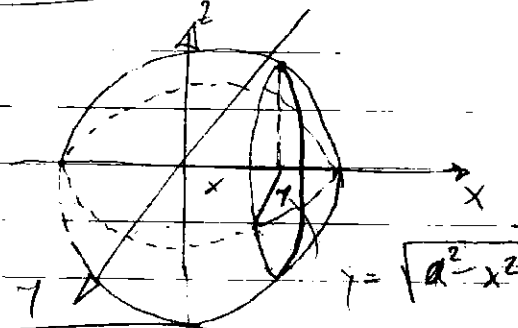
$\iint_D \sqrt{x^2 + y^2} dx dy = \int_{-\pi}^{\pi} d\varphi \int_0^a \sqrt{\rho^2} \rho \cdot d\rho$

$$\left. \begin{aligned} x &= \rho \cos \varphi \\ y &= \rho \sin \varphi \end{aligned} \right\} \Rightarrow \rho = \rho \quad V = \iiint_D f(x, y) dx dy = \int_0^{2\pi} \int_0^a f(\rho \cos \varphi, \rho \sin \varphi) \rho d\rho d\varphi$$

$$V = \int_0^{2\pi} \int_0^a \rho^2 (\cos^2 \varphi + \sin^2 \varphi) d\rho = \int_0^{2\pi} d\varphi \int_0^a \rho^2 d\rho = \int_0^{2\pi} \frac{\rho^3}{3} d\varphi$$

$$V = \frac{2a^3\pi}{3}$$

ТОЧКА:



$$V = \frac{4\pi a^3}{3}$$

$$\begin{aligned} V &= \int_{-a}^a \pi x^2 dx = 2 \int_0^a (\pi (a^2 - x^2)) dx \\ &= 2\pi \left[a^2 x - \frac{x^3}{3} \right] \Big|_0^a = \\ &= 2\pi \left[0^3 - \frac{a^3}{3} \right] = 2\pi \frac{2a^3}{3} \end{aligned}$$

ТРОЈНИ ИНТЕГРАЛИ

$$\iiint_V f(x, y, z) dx dy dz = \iint_D dx dy \int_{z_1(x, y)}^{z_2(x, y)} dz$$

$$\iiint_V f(x, y, z) dx dy dz = \iiint_{V_1} f(x(\mu, \nu, \omega), y(\mu, \nu, \omega), z(\mu, \nu, \omega)) |J| d\mu d\nu d\omega$$

ЦИЛИНДРИЧНИ КООРДИНАТИ

$$x = \rho \cos \varphi; \quad y = \rho \sin \varphi; \quad z = z$$

$$\begin{cases} \rho = \rho \\ \varphi = \varphi \\ z = z \end{cases}$$

$$\iiint_V f(x, y, z) dx dy dz = \iiint_{V_1} f(\rho \cos \varphi, \rho \sin \varphi, z) \rho d\rho d\varphi dz$$

$$J = \begin{vmatrix} \frac{\partial x}{\partial \mu} & \frac{\partial x}{\partial \nu} & \frac{\partial x}{\partial \omega} \\ \frac{\partial y}{\partial \mu} & \frac{\partial y}{\partial \nu} & \frac{\partial y}{\partial \omega} \\ \frac{\partial z}{\partial \mu} & \frac{\partial z}{\partial \nu} & \frac{\partial z}{\partial \omega} \end{vmatrix}$$

$$\begin{aligned} \begin{bmatrix} 9 & 8 & 4 \\ 0 & 1 & 3 \\ 0 & 0 & 6 \end{bmatrix} &= 9 \cdot \begin{vmatrix} 1 & 3 \\ 0 & 6 \end{vmatrix} - 8 \cdot \begin{vmatrix} 0 & 3 \\ 0 & 6 \end{vmatrix} \\ &+ 4 \cdot \begin{vmatrix} 0 & 1 \\ 0 & 0 \end{vmatrix} = 9(6-0) = \\ &= 54 \end{aligned}$$

РЕЗУЛТАТ

$$J = \begin{vmatrix} \cos \varphi & -\rho \sin \varphi & 0 \\ \sin \varphi & \rho \cos \varphi & 0 \\ 0 & 0 & 1 \end{vmatrix}$$

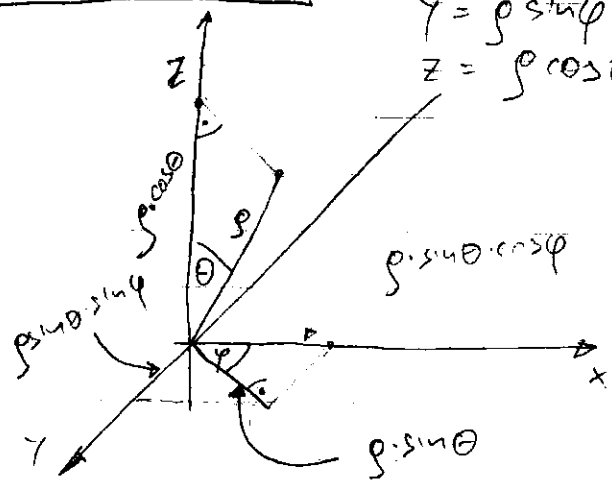
$$= \cos \varphi \begin{vmatrix} \rho \cos \varphi & 0 \\ 0 & 1 \end{vmatrix} + \rho \sin \varphi \begin{vmatrix} \sin \varphi & 0 \\ 0 & 1 \end{vmatrix} =$$

$$= \cos \varphi (\rho \cos \varphi) + \rho \sin \varphi (\rho \sin \varphi) = \rho (\cos^2 \varphi + \sin^2 \varphi) = \rho$$

SPERIČNI KOORDINATI

$$\begin{aligned} x &= \rho \cos \varphi \cdot \sin \theta \\ y &= \rho \sin \varphi \cdot \sin \theta \\ z &= \rho \cos \theta \end{aligned}$$

$$\begin{aligned} 0 \leq \varphi &\leq 2\pi \\ 0 \leq \theta &\leq \pi \end{aligned}$$



$$J = \begin{vmatrix} \frac{\partial x}{\partial \rho} & \frac{\partial x}{\partial \varphi} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial \rho} & \frac{\partial y}{\partial \varphi} & \frac{\partial y}{\partial \theta} \\ \frac{\partial z}{\partial \rho} & \frac{\partial z}{\partial \varphi} & \frac{\partial z}{\partial \theta} \end{vmatrix}$$

$$J = \begin{vmatrix} \cos \varphi \sin \theta & -\rho \sin \varphi \sin \theta & \rho \cos \varphi \cos \theta \\ \sin \varphi \sin \theta & \rho \cos \varphi \sin \theta & \rho \sin \varphi \cos \theta \\ \cos \theta & 0 & -\rho \sin \theta \end{vmatrix} = -\sin \theta \cdot \rho^2$$

$|J| = \rho^2 \sin \theta$

$$I = \iiint_V f(x, y, z) dx dy dz =$$

$$= \iiint_V f(\rho \cos \varphi \sin \theta, \rho \sin \varphi \sin \theta, \rho \cos \theta) \rho^2 \sin \theta \cdot d\rho d\varphi d\theta$$

ARC LENGTH

(PRISMERJUVANJE NA DLŽINA NA PAVNUKKA KURVA SO KURVOLINISKI INTEGRAL OD 1. RED)

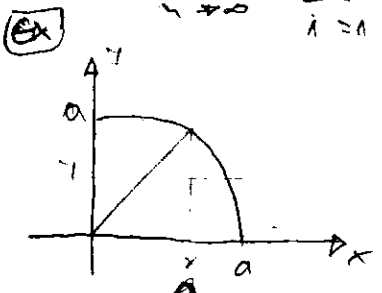
$$L = \lim_{n \rightarrow \infty} \sum_{i=1}^n |P_{i-1}P_i|$$

$$|P_{i-1}P_i| = \sqrt{(x_i - x_{i-1})^2 + (y_i - y_{i-1})^2} = \sqrt{\Delta x^2 + \Delta y^2}$$

$$f(x_i) - f(x_{i-1}) = f'(x_i^*) (x_i - x_{i-1}); \quad \Delta y = f'(x_i^*) \Delta x$$

$$|P_{i-1}P_i| = \Delta x \sqrt{1 + \frac{\Delta y^2}{\Delta x^2}} = \Delta x \sqrt{1 + [f'(x_i^*)]^2}$$

$$L = \lim_{n \rightarrow \infty} \sum_{i=1}^n \Delta x \sqrt{1 + [f'(x_i^*)]^2} \quad \boxed{L = \int_a^b \sqrt{1 + f'(x)^2} dx}$$



$$f(x) = \sqrt{a^2 - x^2} \quad f'(x) = \frac{1}{2} \frac{1}{\sqrt{a^2 - x^2}} (-2x)$$

$$f'(x) = -\frac{x}{\sqrt{a^2 - x^2}}$$

$$L = \int_0^a \sqrt{\frac{a^2 - x^2 + x^2}{a^2 - x^2}} dx = a \int_0^a \frac{dx}{\sqrt{a^2 - x^2}} = \left. \frac{a \arcsin(\frac{x}{a})}{\sqrt{1 - (\frac{x}{a})^2}} \right|_0^a$$

$$y = \arcsin(\frac{x}{a}) \quad x = a \sin y \quad 1 = \cos y \cdot \frac{dy}{dx} \Rightarrow \frac{dy}{dx} = \frac{1}{\sqrt{1 - \sin^2 y}} = \frac{1}{\sqrt{1 - \frac{x^2}{a^2}}}$$

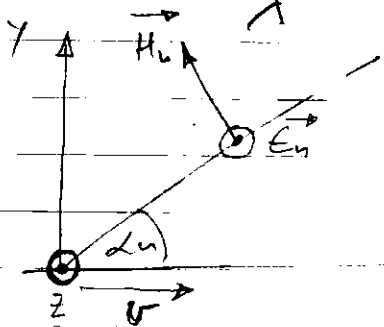
$$L = a \cdot \arcsin\left(\frac{x}{a}\right) \Big|_0^a = a \left(\arcsin\left(\frac{a}{a}\right) - \arcsin\left(\frac{0}{a}\right) \right) = \left(\frac{a\pi}{2} \right)$$

$$L_{\text{arc}} = 4 \cdot L = 4 \cdot \frac{a\pi}{2} = 2a\pi \quad [9 + 7^2 = 7 + 49 = 58]$$

$$\Delta\phi = \frac{2\pi \Delta L}{\lambda} = \frac{2\pi d \cos\theta}{\lambda} \quad \omega = \frac{\Delta\phi}{\Delta t} \quad f = \frac{\omega}{2\pi} = \frac{\Delta\phi}{2\pi \Delta t}$$

$$f = \frac{\frac{2\pi d \cos\theta}{\lambda}}{2\pi \Delta t} = \left(\frac{d}{\lambda} \right) \cdot \cos\theta = f_{\text{max}} \cos\theta \quad \boxed{f = \frac{v}{\lambda} \cdot \cos\theta}$$

$$\omega_{\text{dir}} = \frac{2\pi v}{\lambda} \cos(\alpha_{\text{dir}}) = \omega_{\text{max}} \cos(\alpha_{\text{dir}})$$



$$\vec{E} = E_z \hat{e}_z$$

$$E_z = \sum_{n=1}^N E_n = E_0 \sum_{n=1}^N C_n \cos(\omega t + \phi_n)$$

$$E_z = E_0 \sum_{n=1}^N C_n \cos(\omega t + \omega_{\text{dir}} t + \phi_n)$$

$C_n \rightarrow$ СЛУЧАЙНАЯ ФАЗА НА n -ТА УПАДНА КОМПОНЕНТА
 $E_0 C_n \rightarrow$ АМПЛИТУДА НА n -ТА УПАДНА КОМПОНЕНТА

$$\sum_{n=1}^N C_n^2 = 1$$

$$\overline{E^2} = \overline{\left(\sum E_n \right)^2}$$

ДИФРАКЦИОННОЕ РАДИО

$$r(r, \theta) = \frac{v}{2\pi G^2} e^{-\frac{r^2 + r_s^2 - 2rr_s \cos\theta}{2G^2}}$$

$$r_r(r) = \int r(r, \theta) dr$$

$$r_r(r) = \frac{v}{6\pi G^2} e^{-\frac{r^2 + r_s^2}{2G^2}} I_0\left(\frac{rr_s}{G^2}\right)$$

$$E_z(t) = T_c(t) \cdot \cos(\omega t) - T_s(t) \sin(\omega t)$$

$$T_c(t) = E_0 \sum_{n=1}^N C_n \cos(\omega_{\text{dir}} t + \phi_n)$$

$$T_s(t) = E_0 \sum_{n=1}^N C_n \sin(\omega_{\text{dir}} t + \phi_n)$$

ЭКОНОМИЧНИ
 СЛУЧАЙНИ ПРОЦЕСИ

$$\overline{T_c(t)} = \overline{T_s(t)} = 0$$

$$\overline{T_c^2} = \overline{T_s^2} = \overline{|E_z|^2} = \frac{E_0^2}{2}$$

РАСЧЕТЫ НА ПРАКТИКЕ

$$E_z(t) = R(t) \cos[\omega t - \phi(t)]$$

$$E_z(t) = \frac{T_c}{2} (e^{j\omega t} - e^{-j\omega t}) - \frac{T_s}{2} (e^{j\omega t} + e^{-j\omega t})$$

$$= e^{j\omega t} \frac{1}{2} (T_c - T_s) - e^{-j\omega t} \frac{1}{2} (T_c + T_s)$$

$$E_z(t) = T_c(t) \cdot \cos(\omega_c t) - T_s(t) \cdot \sin(\omega_c t)$$

$$T_c(t) = R(t) \cdot \cos \varphi(t) \quad T_s(t) = R(t) \cdot \sin \varphi(t)$$

$$E_z(t) = R(t) \cdot \cos \varphi(t) \cos(\omega_c t) - R(t) \sin \varphi(t) \sin(\omega_c t)$$

$$E_z(t) = R(t) \cdot \cos(\omega_c t + \varphi(t))$$

$$T_c^2(t) + T_s^2(t) = R^2(t) [\cos^2 \varphi(t) + \sin^2 \varphi(t)]$$

$$R(t) = \sqrt{T_c^2(t) + T_s^2(t)}$$

$$\frac{T_s}{T_c} = \tan \varphi(t)$$

$$\varphi(t) = \arctan \frac{T_s(t)}{T_c(t)}$$

SUMA OD DVA ILI TOVIŠE SLUČAJNI VECI
SO PORAZA GUSTINA NA VEŠTAČENSTVO

$$\xi_1, \xi_2, \dots, \xi_n \quad \xi_1 + \xi_2 + \dots + \xi_n \Rightarrow \text{GAUSOVA ZAKONODAVNA} \\ \text{ZAKON AVO } n \rightarrow \infty$$

$$P_{\xi}(\vec{x}) = \frac{1}{(2\pi)^{n/2}} e^{-\frac{\vec{x} \cdot \vec{x}}{2\sigma^2}} \quad \mu = \sum \mu_i \quad \sigma^2 = \sum \sigma_i^2$$

NEKA: $n=2$

$\xi_1, \xi_2 \quad P_{\xi}(x, y)$ } SLUČAJNI VECI NEZAVISNI I NIVIA
ZAKONODAVNA F.Z.A. NA VEŠTAČENSTVO

$$y = \xi + \eta \quad z = x + y$$

VOVEDUVANJE NA POMOSNA NUMERLIVA ZA DA SE
NADE I JI

$$\xi' = \xi \quad z = x + y \quad x' = x$$

$$\begin{matrix} \text{INV. F.Z.A.} \\ \downarrow \\ \text{INV. F.Z.A.} \end{matrix} \quad y = z - x \quad x = x'$$

$$J = \begin{vmatrix} \frac{\partial z}{\partial x} & \frac{\partial z}{\partial y} \\ \frac{\partial x'}{\partial x} & \frac{\partial x'}{\partial y} \end{vmatrix} = \begin{vmatrix} 1 & 1 \\ 1 & 0 \end{vmatrix} = 1 \cdot 0 - 1 \cdot 1 = -1 \quad |J| = 1$$

$$P_{\xi'}(x', z) = \frac{P_{\xi}(x, y)}{|J|} \Big|_{\substack{x=x' \\ y=z-x'}} = P_{\xi}(x', z-x')$$

$$P_{\xi}(z) = \int_{-\infty}^{\infty} P_{\xi'}(x', z) dx' = \int_{-\infty}^{\infty} P_{\xi}(x', z-x') dx' = \int_{-\infty}^{\infty} P_{\xi}(x, z-x) dx$$

ξ_1, ξ_2 ARE STATISTICALLY INDEPENDENT

$$P_{\xi}(x, z-x) = P_{\xi_1}(x) \cdot P_{\xi_2}(z-x)$$

$$P_f(z) = \int_{-\infty}^{\infty} P_f(x) \cdot P_y(z-x) dx = P_f(z) * P_y(z-x) = P_{f_y}(z)$$

• n - SLUČAJNI PROMENLIVI:

$$\xi_i, \quad i=1, 2, \dots, n$$

$$\xi = \sum_{i=1}^n \xi_i$$

$$P_f(x) = P_{\xi_1(x)} * P_{\xi_2(x)} * \dots * P_{\xi_n(x)}$$

$$W_f(j\Omega) = \int_{-\infty}^{\infty} P_f(x) e^{+j\Omega x} dx \Rightarrow \text{KARAKTERISTIČNA FUNKCIJA = KONJUGIRANA FURJEVA TRANSFORM.}$$

$$W_f(j\Omega) = W_{\xi_1}(j\Omega) \cdot W_{\xi_2}(j\Omega) \cdot \dots \cdot W_{\xi_n}(j\Omega)$$

$$P_f(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} W_f(j\Omega) e^{-j\Omega x} d\Omega = \frac{1}{2\pi} \int_{-\infty}^{\infty} \prod W_{\xi_i}(j\Omega) e^{-j\Omega x} d\Omega \quad (**)$$

$n \rightarrow \infty$ $P_f(x) \rightarrow$ GAUŠOVA RASPREDELINA

• n - normalno rasporedeni promenlivi

$$\xi_i, \quad i=1, 2, \dots, n; \quad P_{\xi_i}(x_i) = \frac{1}{\sqrt{2\pi\sigma_i^2}} e^{-\frac{(x_i-\mu_i)^2}{2\sigma_i^2}}$$

$$W_{\xi_i}(j\Omega) = \int_{-\infty}^{\infty} P_{\xi_i}(x_i) e^{j\Omega x_i} dx_i = \frac{1}{\sqrt{2\pi\sigma_i^2}} \int_{-\infty}^{\infty} e^{-\frac{(x_i-\mu_i)^2}{2\sigma_i^2}} e^{j\Omega x_i} dx_i$$

$$= \frac{1}{\sqrt{2\pi\sigma_i^2}} \int_{-\infty}^{\infty} e^{-\frac{(x_i-\mu_i)^2}{2\sigma_i^2}} e^{j\Omega(x_i-\mu_i)} e^{j\Omega\mu_i} dx_i = \frac{e^{j\Omega\mu_i}}{\sqrt{2\pi\sigma_i^2}} \int_{-\infty}^{\infty} e^{-\frac{(x_i-\mu_i)^2 + j\Omega 2\sigma_i^2(x_i-\mu_i)}{2\sigma_i^2}} dx_i \quad (*)$$

$$|x_i - \mu_i = m \quad dx_i = dm| = \frac{e^{j\Omega\mu_i}}{\sqrt{2\pi\sigma_i^2}} \int_{-\infty}^{\infty} e^{-\frac{m^2 + j\Omega 2\sigma_i^2 m}{2\sigma_i^2}} dm$$

$$I = \int_{-\infty}^{\infty} e^{-\frac{m^2}{2\sigma_i^2}} e^{j\Omega m} dm = \frac{1}{j\Omega} \int_{-\infty}^{\infty} e^{-\frac{m^2}{2\sigma_i^2}} d e^{j\Omega m}$$

$$\mu = e^{-\frac{m^2}{2\sigma_i^2}} \quad \sigma = \int e^{j\Omega m} dm = \frac{1}{j\Omega} \int e^{j\Omega m} d(j\Omega m) = \frac{e^{j\Omega m}}{j\Omega}$$

$$I = e^{-\frac{M^2}{2\sigma^2}} \frac{e^{j\Omega M}}{j\Omega} = \int \frac{e^{j\Omega M}}{j\Omega} \cdot \delta\left(e^{-\frac{M^2}{2\sigma^2}}\right)$$

$$I_1 = \frac{1}{j\Omega} \int e^{j\Omega M} e^{-\frac{M^2}{2\sigma^2}} \frac{2M}{2\sigma^2} dM$$

$$I = \int_{-\infty}^{\infty} e^{-\frac{M^2}{2\sigma^2} + j\Omega M} dM = \frac{1}{2} \int_{-\infty}^{\infty} \underbrace{\cos(\Omega M)}_{\text{SALFA}} \underbrace{e^{-\frac{M^2}{2\sigma^2}}}_{\text{SALFA}} dM + \frac{1}{2} \int_{-\infty}^{\infty} \underbrace{\sin(\Omega M)}_{\text{NEMK}} \underbrace{e^{-\frac{M^2}{2\sigma^2}}}_{\text{PAR}} dM$$

$\int_{-\infty}^{\infty} \sin(\Omega M) e^{-\frac{M^2}{2\sigma^2}} dM = 0$

$$I = \frac{1}{2} \int_{-\infty}^{\infty} \cos(\Omega M) e^{-\frac{M^2}{2\sigma^2}} dM$$

$$u = e^{-\frac{M^2}{2\sigma^2}} \quad du = -e^{-\frac{M^2}{2\sigma^2}} \frac{2M}{2\sigma^2} dM \quad v = \int \cos(\Omega M) dM = \frac{1}{\Omega} \sin(\Omega M)$$

$$I = \frac{1}{2} \left(e^{-\frac{M^2}{2\sigma^2}} \cdot \frac{1}{\Omega} \sin(\Omega M) \right) + \int \frac{2M}{2\sigma^2} e^{-\frac{M^2}{2\sigma^2}} \cdot \frac{1}{\Omega} \sin(\Omega M) dM$$

$$\int_{-\infty}^{\infty} e^{-\frac{M^2}{2\sigma^2} + j\Omega M} dM = \sqrt{2\pi\sigma^2} e^{-\frac{\sigma^2 \Omega^2}{2}}$$

$$W_g(j\Omega) = \frac{e^{-\frac{\sigma^2 \Omega^2}{2}}}{\sqrt{2\pi\sigma^2}}$$

$$W_g(j\Omega) = e^{-\frac{\sigma^2 \Omega^2}{2}} e^{j\Omega \sum_{i=1}^N x_i}$$

$$W_g(j\Omega) = \prod_{i=1}^N W_{g_i}(j\Omega) = e^{-\frac{\sigma^2 \Omega^2}{2} + j\Omega \sum_{i=1}^N x_i}$$

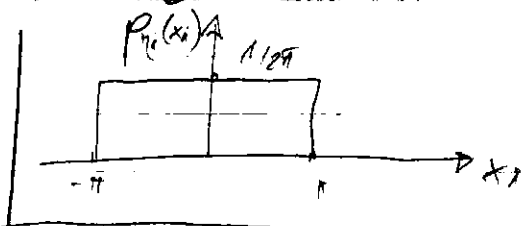
$$\sigma^2 = \sum_{i=1}^N \sigma_i^2$$

$$m = \sum_{i=1}^N m_i$$

• SUMA OD SINUSO I D. SO. SLOŽENJA
FAZA

$$x_i = A_i \sin \omega_i t$$

$$x = \sum_{i=1}^N A_i \sin \omega_i t$$

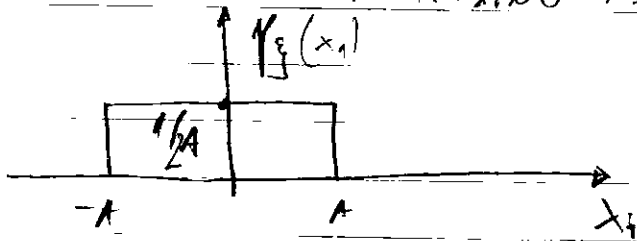


$$P_{i0}(x_i) = \begin{cases} \frac{1}{2A_i} & \text{if } |x_i| \leq A_i \\ 0 & \text{other} \end{cases}$$

$$x = \sum_{i=1}^N x_i \quad W_g(j\Omega) = e^{-\frac{\sigma^2 \Omega^2}{2}} \quad P_j(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{x^2}{2\sigma^2}}$$

$$P_i = \frac{A_i^2}{2} = \left(\frac{A_i}{\sqrt{2}}\right)^2 = \frac{A_i^2}{2} \quad P = N^2 = \sum_{i=1}^N \sigma_i^2 = \sum_{i=1}^N \frac{A_i^2}{2}$$

SUMA OD UNIFORMNO RAZMEREZI RAVNOMI PROMERENI



$$f_{xi}(x_i) = \begin{cases} \frac{1}{2A} & -A \leq x_i \leq A \\ 0 & \text{alters} \end{cases}$$

$$W_{f_{xi}}(j\omega) = \int_{-\infty}^{\infty} f_{f_{xi}}(x_i) e^{+j\omega x_i} dx_i = \int_{-A}^A \frac{1}{2A} e^{j\omega x_i} dx_i$$

$$W_{f_{xi}}(j\omega) = \frac{1}{2A} \frac{1}{j\omega} \int_{-A}^A e^{j\omega x_i} d(j\omega x_i) = \frac{1}{2jA\omega} (e^{+j\omega A} - e^{-j\omega A})$$

$$W_{f_{xi}}(j\omega) = \frac{1}{A\omega} \sin(\omega A) = \frac{\sin \omega A}{\omega A}$$

RAYLEIGH - RAZMEREZENJE

$$E_z(t) = E(t) \cos[\omega t - \varphi(t)]$$

$$E(t) = \sqrt{I_c^2(t) + I_s^2(t)} \quad \varphi(t) = \arctg \frac{I_s(t)}{I_c(t)}$$

$$f_{I_c}(x) = f_{I_s}(x) = \frac{1}{2\sigma^2} e^{-\frac{x^2}{2\sigma^2}}$$

$$\sigma = \sigma_c = \frac{\epsilon_0^2}{2}$$

$$f_r(r) = \frac{r}{\sigma^2} e^{-\frac{r^2}{2\sigma^2}} \quad r > 0$$

$$f_{xy}(x, y) = f_x(x) \cdot f_y(y)$$

$f_x(x), f_y(y) \Rightarrow$ GAUSSIAN DISTRIBUTION

$$f_{xy}(x, y) = \frac{1}{2\pi\sigma^2} e^{-\frac{x^2+y^2}{2\sigma^2}} = \frac{1}{2\pi\sigma^2} e^{-\frac{r^2}{2\sigma^2}}$$

$$\begin{aligned} x &= r \cos \varphi \\ y &= r \sin \varphi \end{aligned} \quad |J| = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \varphi} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \varphi} \end{vmatrix} = \begin{vmatrix} \cos \varphi & -r \sin \varphi \\ \sin \varphi & r \cos \varphi \end{vmatrix} = r$$

$$r(t) = \sqrt{I_c^2(t) + I_s^2(t)}$$

$$dxdy = |J| dr d\varphi \quad f_{xy}(r, \varphi) = |J| f_{xy}(x, y)$$

$$f_{xy}(r, \varphi) = \frac{r}{2\pi\sigma^2} e^{-\frac{r^2}{2\sigma^2}}$$

$$f(r) = \int_0^{2\pi} \frac{1}{2\pi\sigma^2} e^{-\frac{r^2}{2\sigma^2}} \cdot r d\varphi = \frac{r}{\sigma^2} e^{-\frac{r^2}{2\sigma^2}} \cdot 2\pi = \frac{r}{\sigma^2} e^{-\frac{r^2}{2\sigma^2}}$$

$$f(r) = \frac{r}{\sigma^2} e^{-\frac{r^2}{2\sigma^2}} \Rightarrow \text{RAYLEIGH DISTRIBUTION}$$

$$P(\varphi) = \int_0^{\infty} p(r, \varphi) dr = \int_0^{\infty} \frac{r}{2\pi G^2} e^{-\frac{r^2}{2G^2}} dr = \frac{1}{2G^2} \int_0^{\infty} r e^{-\frac{r^2}{2G^2}} dr$$

$$I = \left(\begin{array}{l} u = e^{-\frac{r^2}{2G^2}} \\ du = -e^{-\frac{r^2}{2G^2}} \cdot \frac{r}{G^2} dr \end{array} \right) \quad \left(\begin{array}{l} v = \int r dr \\ v = \frac{r^2}{2} \end{array} \right) = \frac{r^2}{2} e^{-\frac{r^2}{2G^2}} \Big|_0^{\infty} + \int \frac{r^3}{2} e^{-\frac{r^2}{2G^2}} dr$$

$$I = \frac{-2G^2}{2} \int_0^{\infty} e^{-\frac{r^2}{2G^2}} d\left(\frac{r^2}{2G^2}\right) = -G^2 e^{-\frac{r^2}{2G^2}} \Big|_0^{\infty} = -G^2 \left(\frac{1}{\infty} - 1\right) = G^2$$

$$P_r(\varphi) = \frac{1}{2\pi G^2} \cdot G^2 = \frac{1}{2\pi}$$

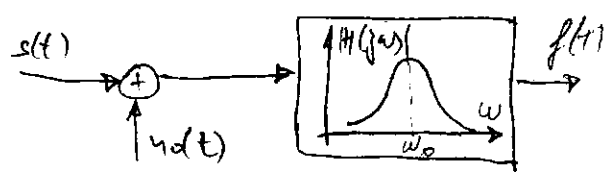
$$P_{xy}(r, \varphi) = P_r(r) \cdot P_\varphi(\varphi)$$

RAYLEIGH - UNIFORM

$$P_{xy}(r, \varphi) = \frac{r}{2\pi G^2} e^{-\frac{r^2}{2G^2}} = \frac{r}{G^2} e^{-\frac{r^2}{2G^2}} \cdot \frac{1}{2\pi}$$

$\frac{r}{G^2} e^{-\frac{r^2}{2G^2}}$ $\frac{1}{2\pi}$

$f(r)$ $P(\varphi)$



$$f(t) = s(t) + u(t)$$

$u(t)$ - noise - MODE OF NOISE
 $s(t) = A \cos(\omega_0 t)$

$$f(t) = A \cos \omega_0 t + x(t) \cos(\omega_0 t) + y(t) \sin(\omega_0 t) = [A + x(t)] \cos(\omega_0 t) - y(t) \sin(\omega_0 t)$$

$$z(t) = A \quad z = A + x(t)$$

$$f(t) = r(t) \cdot \cos[\omega_0 t + \varphi(t)]$$

$$z(t) = r(t) \cdot \cos(\varphi(t))$$

$$y(t) = r(t) \cdot \sin(\varphi(t))$$

$$r(t) = \sqrt{z^2(t) + y^2(t)}$$

$$\varphi(t) = \arctan \frac{y(t)}{z(t)} \pm k\pi$$

$$P_{r,\varphi}(r, \varphi) = r \cdot P_{xy}(z, y) = \frac{r}{2\pi G^2} \cdot e^{-\frac{z^2 + y^2}{2G^2}} = \frac{r}{2\pi G^2} \cdot e^{-\frac{z^2 + y^2}{2G^2}}$$

$$= \frac{r}{2\pi G^2} e^{-\frac{(r \cos \varphi - A)^2 + r^2 \sin^2 \varphi}{2G^2}} = \frac{r}{2\pi G^2} e^{-\frac{r^2 + A^2 - 2rA \cos \varphi}{2G^2}}$$

$$P(r) = \int_0^{2\pi} p(r, \varphi) d\varphi = \frac{r}{2\pi G^2} e^{-\frac{r^2 + A^2}{2G^2}} \int_0^{2\pi} e^{\frac{2rA \cos \varphi}{2G^2}} d\varphi$$

$$P(r) = \frac{r}{G^2} e^{-\frac{r^2 + A^2}{2G^2}} \cdot \frac{1}{2\pi} \int_0^{2\pi} e^{\frac{rA \cos \varphi}{G^2}} d\varphi$$

$$P(r) = \frac{r}{G^2} \cdot e^{-\frac{r^2 + A^2}{2G^2}} \cdot I_0\left(\frac{r \cdot A}{G^2}\right)$$

GAUSSIAN DISTRIBUTION

ПАРАМЕТРИ НА ЗАКЛЕИЛИН КАСКЕРОСАА:

$$\bar{r} = \int_0^{\infty} r f(r) dr \quad f(r) = \frac{r}{b^2} e^{-\frac{r^2}{2b^2}} = \frac{r}{b} e^{-\frac{r^2}{2b^2}}$$

$$\bar{r} = \int_0^{\infty} \frac{r^2}{b^2} e^{-\frac{r^2}{2b^2}} dr = \int_0^{\infty} \frac{r^2}{b} e^{-\frac{r^2}{2b^2}} dr$$

$$M = r; \quad \sigma = \int_0^{\infty} r e^{-\frac{r^2}{2b^2}} dr = \int_0^{\infty} e^{-\frac{r^2}{2b^2}} \frac{r^2}{2b^2} dr$$

$$v = -\frac{1}{2} e^{-\frac{r^2}{2b^2}}; \quad dm = dr$$

$$\bar{r} = -\frac{r}{2} e^{-\frac{r^2}{2b^2}} \Big|_0^{\infty} + \int_0^{\infty} e^{-\frac{r^2}{2b^2}} dr = -\frac{r}{2} e^{-\frac{r^2}{2b^2}} \Big|_0^{\infty} + I$$

$$\lim_{r \rightarrow \infty} \frac{(r)^1}{(e^{-\frac{r^2}{2b^2}})^1} = \lim_{r \rightarrow \infty} \frac{1}{\frac{2r}{2b^2} \cdot e^{-\frac{r^2}{2b^2}}} = 0 \quad \lim_{r \rightarrow 0} \frac{r}{e^{-\frac{r^2}{2b^2}}} = 0$$

$$\bar{r} = \int_0^{\infty} e^{-\frac{r^2}{2b^2}} dr = \int_0^{\infty} \frac{e^{-\frac{m^2}{2b^2}}}{\sqrt{2\pi}} dm = \frac{1}{\sqrt{2\pi}} \int_0^{\infty} e^{-\frac{m^2}{2b^2}} dm$$

$$\bar{r} = \frac{1}{4} \int_0^{\infty} \frac{e^{-\frac{m^2}{2b^2}}}{\sqrt{\pi}} dm$$

$$\int e^{-x^2} dx = \int e^{-x^2} dx \quad \Delta \frac{1}{2}$$

$$\bar{r} = \frac{1}{2} \left(\frac{1}{\sqrt{2\pi} \cdot b} \int_0^{\infty} e^{-\frac{r^2}{2b^2}} dr \right) \cdot \sqrt{2\pi} \cdot b = \frac{1}{4} \sqrt{2\pi} b$$

$$\bar{r} = \int_0^{\infty} e^{-\frac{r^2}{2b^2}} dr = \left(\frac{1}{\sqrt{2\pi} b} \int_0^{\infty} e^{-\frac{r^2}{2b^2}} dr \right) \sqrt{2\pi} b = \frac{\sqrt{2\pi} b}{2}$$

$$\bar{r} = \frac{\sqrt{b}}{\sqrt{2}} = \frac{\sqrt{2} b}{\sqrt{2}} = \frac{\sqrt{2\pi} b}{\sqrt{2\pi}} \quad \text{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-u^2} du =$$

$$= \frac{\sqrt{2}}{\sqrt{2\pi}} \int_0^{\infty} e^{-u^2} du = \frac{1}{\sqrt{\pi}} \int_0^{\infty} e^{-u^2} du =$$

$$f(x) = \frac{1}{\sqrt{\pi}} \int_{-\infty}^x e^{-u^2} du \quad \left(u = \frac{x-y}{\sqrt{2b}} \right)$$

$$\operatorname{erfc}(x) = \frac{1}{\sqrt{\pi}} \int_x^{\infty} e^{-u^2} du = 1 - \frac{1}{\sqrt{\pi}} \int_{-\infty}^x e^{-u^2} du = 1 - \operatorname{erf}(x)$$

$$P(a \leq \xi \leq b) = \frac{1}{\sqrt{\pi b^2}} \int_a^b e^{-\frac{(x-y)^2}{2b^2}} dx = \frac{1}{\sqrt{\pi}} \int_a^b e^{-\frac{(x-y)^2}{2b^2}} d\left(\frac{x-y}{\sqrt{2b}}\right)$$

$$= \left| \begin{array}{l} u = \frac{x-y}{\sqrt{2b}} \\ du = \frac{1}{\sqrt{2b}} dx \end{array} \right|_{x=a}^{x=b} = \frac{1}{\sqrt{\pi}} \int_{\frac{a-y}{\sqrt{2b}}}^{\frac{b-y}{\sqrt{2b}}} e^{-u^2} du$$

$$= \frac{1}{\sqrt{\pi}} \int_0^{\frac{b-y}{\sqrt{2b}}} e^{-u^2} du - \frac{1}{\sqrt{\pi}} \int_0^{\frac{a-y}{\sqrt{2b}}} e^{-u^2} du = \frac{1}{2} \left[\operatorname{erf}\left(\frac{b-y}{\sqrt{2b}}\right) - \operatorname{erf}\left(\frac{a-y}{\sqrt{2b}}\right) \right]$$

$$\Phi(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-u^2} du$$

→ ГАУССОН ИНТЕГРАЛ НА ГРЕКА

$$\bar{R}^2 = \int_0^{\infty} r^2 \cdot \frac{r}{b} e^{-\frac{r^2}{2b}} dr = 2b \int_0^{\infty} \frac{r^2}{2b} e^{-\frac{r^2}{2b}} d\left(\frac{r^2}{2b}\right) = 2b \int_0^{\infty} u e^{-u} du$$

$$\left| \begin{array}{l} u = u \\ du = du \\ \int u e^{-u} du = -e^{-u} \end{array} \right| = 2b \left(-u e^{-u} + \int e^{-u} du \right) \Big|_0^{\infty}$$

$$\bar{R}^2 = 2b \lim_{u \rightarrow \infty} \left(-u e^{-u} - 1 e^{-u} \right) - \lim_{u \rightarrow 0} \left(-u e^{-u} - 1 e^{-u} \right) = 2b$$

$$\sigma_1^2 = \bar{R}^2 - \bar{R}^2 = 2b - \left(\frac{b\sqrt{\pi}}{\sqrt{2}} \right)^2 = 2b^2 - \frac{\pi b^2}{2} = \frac{(2-\pi)b^2}{2}$$

$$\bar{R} = b \sqrt{\frac{\pi}{2}} = 1.2533 \sqrt{b} ; \quad \bar{R}^2 = 2b ; \quad \sigma = \sqrt{\frac{(2-\pi)b^2}{2}} = 0.4292b$$

MEDIANA: $\frac{1}{2} = \int_0^x r e^{-\frac{r^2}{2}} dr \Rightarrow \boxed{r_m = 1.1774b} = 1.1774\sqrt{b}$

$$RMS = \sqrt{\bar{R}^2} = \sqrt{2b} = \sqrt{2} \sqrt{b} = 1.415$$

СПЕКТРАЛНА ГУСТИНА НА СИГНАЛ МОЩНОСТ

$$v(t) = z(t) \cos[\omega_c t - \varphi(t)] = z_c(t) \cos \omega_c t - z_s(t) \sin \omega_c t$$

TEORIJA NA INFORMACIJI - VOLEZACIONI FUNKCII I SREŠTOK

• $f(t) = f(t + nT)$ $n = 0, 1, 2, \dots, \infty$ $T = \frac{2\pi}{\omega}$
 DIFERENCIOV USLOV

$$\int_{-T/2}^{T/2} |f(t)| dt < \infty \quad f(t) = \sum_{n=-\infty}^{\infty} F(jn\omega) e^{-jn\omega t}$$

$$F(jn\omega) = \frac{1}{T} \int_{-T/2}^{T/2} f(t) e^{-jn\omega t} dt$$

AVTOKORRELACIONA FUNKCIJA ZA PERIODIČNI SIGNALI

$$P_{11}(\tau) = \frac{1}{T} \int_{-T/2}^{T/2} f_1(t) f_1(t+\tau) dt = \overline{f_1(t) f_1(t+\tau)}$$

VOLZACIJA NA PERIODIČNI SIGNALI: OSNOVNI TEORIJA

$$f_1(t) = \sum_{n=-\infty}^{\infty} (F_n)_1 e^{jn\omega t} \quad f_2(t) = \sum_{n=-\infty}^{\infty} (F_n)_2 e^{jn\omega t}$$

$$P_{12}(\tau) = \frac{1}{T} \int_{-T/2}^{T/2} f_1(t) f_2(t+\tau) dt = \sum_{n=-\infty}^{\infty} (F_n)_1^* (F_n)_2 e^{jn\omega \tau}$$

$$(F_n)_1^* (F_n)_2 = \frac{1}{T} \int_{-T/2}^{T/2} P_{12}(\tau) e^{-jn\omega \tau} d\tau$$

FURIJEV TRANSFORMACIONEN PAR

AVTOKORRELACIONA: $f_1(t) = f_2(t) = f(t)$

$$P_{11}(\tau) = \frac{1}{T} \int_{-T/2}^{T/2} f(t) f(t+\tau) dt = \sum_{n=-\infty}^{\infty} |F_n|^2 e^{jn\omega \tau}$$

$$|F_n|^2 = \frac{1}{T} \int_{-T/2}^{T/2} P_{11}(\tau) e^{-jn\omega \tau} d\tau$$

AVTOKORRELACIONA FUNKCIJA I SREŠTOK NA ČMAŠA ČINAT FURIJEV TRANSFORMACIONEN PAR.

$$L_{11}(\omega) = \frac{1}{T} \int_{-T/2}^{T/2} |f(t)|^2 dt = \sum_{n=-\infty}^{\infty} |F_n|^2 //$$

Verwandt mit dem periodischen DS-KI:

$$S_{12}(\tau) = \int_{-T/2}^{T/2} f_1(t) f_2(\tau-t) dt = \sum_{n=-\infty}^{\infty} (\bar{F}_n)_1 (\bar{F}_n)_2 e^{jn\omega\tau}$$

$$(\bar{F}_n)_1 (\bar{F}_n)_2 = \frac{1}{T} \int_{-T/2}^{T/2} S_{12}(\tau) e^{-jn\omega\tau} d\tau \quad \text{FUL. TRANS. PAIR}$$

Verwandtschaft mit dem periodischen Dirac-KI:

$$f_2(t) = \delta_T(t) = \frac{1}{T} \sum_{n=-\infty}^{\infty} e^{jn\omega t} \quad (\bar{F}_n)_2 = \frac{1}{T}$$

$$f_1(t) = \frac{e^{\alpha t}}{T} \sum_{n=-\infty}^{\infty} \frac{\sin \frac{n\omega t}{2}}{\frac{n\omega t}{2}} e^{-jn\omega t} = \frac{1}{T} \sum_{n=-\infty}^{\infty} e^{-jn\omega t}$$

$$S_{12}(\tau) = \int_{-T/2}^{T/2} f_1(t) \delta_T(\tau-t) dt = \frac{1}{T} \sum_{n=-\infty}^{\infty} (\bar{F}_n)_1 e^{jn\omega\tau}$$

$$P_{12}(\tau) = \frac{1}{T} \int_{-T/2}^{T/2} f_1(t) f_2(t+\tau) dt = \frac{1}{T} \int_{-T/2}^{T/2} f_1(t) \sum_{n=-\infty}^{\infty} (\bar{F}_n)_2 e^{jn\omega(t+\tau)} dt$$

$$= \sum_{n=-\infty}^{\infty} (\bar{F}_n)_2 e^{jn\omega\tau} \int_{-T/2}^{T/2} f_1(t) e^{jn\omega t} dt = \sum_{n=-\infty}^{\infty} (\bar{F}_n)_1 (\bar{F}_n)_2 e^{jn\omega\tau}$$

$$S_{12} = \frac{1}{T} \int_{-T/2}^{T/2} f_1(t) f_2(\tau-t) dt = \int_{-T/2}^{T/2} f_1(t) \left(\sum_{n=-\infty}^{\infty} (\bar{F}_n)_2 e^{jn\omega(\tau-t)} \right) dt$$

$$= \sum_{n=-\infty}^{\infty} (\bar{F}_n)_2 e^{jn\omega\tau} \int_{-T/2}^{T/2} f_1(t) e^{-jn\omega t} dt = \sum_{n=-\infty}^{\infty} (\bar{F}_n)_1 (\bar{F}_n)_2 e^{jn\omega\tau}$$

$$\bar{F}_n = \frac{1}{2} (a_n - j b_n) \quad \bar{F}_n = \frac{1}{T} \int_{-T/2}^{T/2} f(t) e^{-jn\omega t} dt = \frac{1}{T} \int_{-T/2}^{T/2} f(t) (\cos n\omega t - j \sin n\omega t) dt$$

$$\bar{F}_n = \frac{1}{T} \int_{-T/2}^{T/2} f(t) \cos n\omega t dt - \frac{j}{T} \int_{-T/2}^{T/2} f(t) \sin n\omega t dt$$

$$= \frac{1}{2} \left[\frac{2}{T} \int_{-T/2}^{T/2} f(t) \cos n\omega t dt - \frac{2j}{T} \int_{-T/2}^{T/2} f(t) \sin n\omega t dt \right]$$

$$\begin{aligned} \bar{F}_n &= \frac{1}{2} [a_n - j b_n] & \bar{F}_n^* &= \frac{1}{2} [a_n + j b_n] = \\ &= \frac{1}{2} \left[\frac{2}{T} \int_{-T/2}^{+T/2} f(t) \cos(n\omega t) dt + \frac{2j}{T} \int_{-T/2}^{+T/2} f(t) \sin(n\omega t) dt \right] \\ &= \frac{1}{T} \int_{-T/2}^{+T/2} f(t) [\cos(n\omega t) + j \sin(n\omega t)] dt = \frac{1}{T} \int_{-T/2}^{+T/2} f(t) e^{jn\omega t} dt \end{aligned}$$

$$f(t) = \frac{a_0}{2} + \sum_{n=1}^{\infty} a_n \cos(n\omega t) + b_n \sin(n\omega t)$$

$$f(t) = \sum_{n=-\infty}^{\infty} \bar{F}_n e^{jn\omega t} = \sum_{n=-\infty}^{\infty} \frac{1}{2} (a_n - j b_n) (\cos n\omega t + j \sin n\omega t)$$

$$= \sum_{n=-\infty}^{\infty} \frac{1}{2} (a_n \cos(n\omega t) + j a_n \sin(n\omega t) - j b_n \cos(n\omega t) + b_n \sin(n\omega t))$$

$$= \sum_{n=-\infty}^{\infty} \frac{1}{2} (a_n \cos(n\omega t) + j a_n \sin(n\omega t) - j b_n \cos(n\omega t) + b_n \sin(n\omega t))$$

$$+ \frac{1}{2} a_0 - j \frac{1}{2} b_0 + \sum_{n=1}^{\infty} \frac{1}{2} (a_n \cos(n\omega t) + j a_n \sin(n\omega t) - j b_n \cos(n\omega t) + b_n \sin(n\omega t))$$

$$= \sum_{n=0}^{\infty} \frac{1}{2} (a_n \cos(n\omega t) + j a_n \sin(n\omega t) - j b_n \cos(n\omega t) + b_n \sin(n\omega t))$$

$$+ \frac{1}{2} \sum_{n=1}^{\infty} (a_n \cos(n\omega t) + j a_n \sin(n\omega t) - j b_n \cos(n\omega t) + b_n \sin(n\omega t))$$

~~$$\frac{1}{2} \sum_{n=1}^{\infty} (a_n \cos(n\omega t) + j a_n \sin(n\omega t) - j b_n \cos(n\omega t) + b_n \sin(n\omega t))$$~~

$$\boxed{a_n = \frac{2}{T} \int_{-T/2}^{+T/2} f(t) \cos(n\omega t) dt} \quad \boxed{b_n = \frac{2}{T} \int_{-T/2}^{+T/2} f(t) \sin(n\omega t) dt}$$

$$\boxed{a_{-n} = a_n} \quad \boxed{b_{-n} = -b_n}$$

$$= \sum_{n=1}^{\infty} \frac{1}{2} [a_n \cos(n\omega t) - j a_n \sin(n\omega t) + j b_n \cos(n\omega t) + b_n \sin(n\omega t)]$$

$$+ \frac{a_0}{2} + \sum_{n=1}^{\infty} \frac{1}{2} [a_n \cos(n\omega t) + j a_n \sin(n\omega t) - j b_n \cos(n\omega t) + b_n \sin(n\omega t)]$$

$$= \frac{a_0}{2} + \sum_{n=1}^{\infty} a_n \cos(n\omega t) + b_n \sin(n\omega t)$$

• SREĆNA FUNKCIJA NA $T/2$ PERIODIČNI SIGNALI

$$R_{nn}(\tau) = \frac{1}{T} \int f_1(t) f_1(t+\tau) dt = \sum_{n=-\infty}^{\infty} (\bar{F}_n)_1 (\bar{F}_n)_1^* e^{jn\omega_0 \tau}$$

$$R_{nn}(\tau) = \sum_{n=-\infty}^{\infty} |\bar{F}_n|^2 e^{jn\omega_0 \tau} \quad |\bar{F}_n|^2 = \frac{1}{T} \int_{-T/2}^{T/2} R_{nn}(\tau) e^{-jn\omega_0 \tau} d\tau$$

$$R_{nn}(\tau) = \sum_{n=-\infty}^{\infty} |F_1(jn\omega_0)|^2 \cdot e^{jn\omega_0 \tau}$$

$$|F_1(jn\omega_0)|^2 = \frac{1}{T} \int_{-T/2}^{T/2} R_{nn}(\tau) e^{-jn\omega_0 \tau} d\tau \quad \left. \begin{array}{l} \\ \\ \end{array} \right\} R_{nn}(\omega) = \frac{1}{T} \int_{-T/2}^{T/2} f^2(t) dt$$

$$R_{nn}(\omega) = \sum_{n=-\infty}^{\infty} |F_1(jn\omega_0)|^2 \quad \Rightarrow \text{SREĆNA STRANA NA PERIODIČNI SIGNALI}$$

• MEKNOVOLIZACIJA FUNKCIJA NA DVA PERIODIČNI SIGNALI SO ISTA ~~SREĆNA~~ PERIODA:

$$R_{12}(\tau) = \frac{1}{T} \int_{-T/2}^{T/2} f_1(t) f_2(t+\tau) dt = \sum_{n=-\infty}^{\infty} F_1(jn\omega_0) \cdot F_2^*(jn\omega_0) e^{jn\omega_0 \tau}$$

• SREĆNA FUNKCIJA NA APROXIMACIJI SIGNALI

$$\int_{-\infty}^{\infty} |f(t)| dt < \infty \quad f(t) = \frac{1}{2\pi} \int F(j\omega) e^{j\omega t} d\omega$$

$$F(j\omega) = \int_{-\infty}^{\infty} f(t) e^{-j\omega t} dt \quad R_{11}(\tau) = \int_{-\infty}^{\infty} f_1(t) f_1(t+\tau) dt$$

$$f_1(t+\tau) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F_1(j\omega) e^{j\omega(t+\tau)} d\omega$$

$$R_{11}(\tau) = \frac{1}{2\pi} \int_{-\infty}^{\infty} f_1(t) \left[\int_{-\infty}^{\infty} F_1(j\omega) e^{j\omega t} e^{j\omega \tau} d\omega \right] dt =$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} F_1(j\omega) e^{j\omega \tau} \left[\int_{-\infty}^{\infty} f_1(t) e^{j\omega t} dt \right] d\omega = \frac{1}{2\pi} \int_{-\infty}^{\infty} |F_1(j\omega)|^2 e^{j\omega \tau} d\omega$$

$$R_{11}(\tau) = \frac{1}{2\pi} \int_{-\infty}^{\infty} |F_1(j\omega)|^2 e^{j\omega \tau} d\omega$$

↑ FURIJEVA TRANSFORMACIJA

$$R_{12}(\tau) = \int_{-\infty}^{\infty} f_1(t) f_2(t+\tau) dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} F_1(j\omega) F_2^*(j\omega) e^{j\omega \tau} d\omega$$

• USPREDAVANJE PO VELENE I UREDNOSTI PO ANZAMPL. NA SUVAZI PROMERZIVI

$$\lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T f^{(k)}(t) dt = \bar{m}$$

VREMENSKA SREDNA VR.
 $k = 1, 2, 3, \dots$

$$\bar{f}(t) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T f(t) dt$$

$$f^{(1)}(x_k^{(1)}), f^{(2)}(x_k^{(2)}), \dots, f^{(k)}(x_k^{(k)})$$

$$\bar{x}_k = \bar{x} = \int_{-\infty}^{\infty} x p_g(x) dx$$

$$\bar{f}(t) = \bar{f}$$

SREDNA VR. PO VELENE I UREDNOSTI NA SUVAZI PROMERZIVI

$$\lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T f(t) dt = \int_{-\infty}^{\infty} f(x) p_g(x) dx$$

$$\bar{f}(t) = \bar{f}(x)$$

$$\lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T F\{f(t)\} dt = \int_{-\infty}^{\infty} F(x) p_g(x) dx$$

• AVTOKORRELACIONA FUNKCIJA NA SUVAZI PROMERZIVI:

$$[f^{(k)}(-\nu t), f^{(k)}(-\nu t + \tau)], \quad \nu = 0, 1, 2, \dots$$

$$\bar{f}^{(k)}(t) \bar{f}^{(k)}(t + \tau) = \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T f^{(k)}(t) \cdot f^{(k)}(t + \tau) dt$$

$$R_f(\tau) = \bar{f}(t) \bar{f}(t + \tau) = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T}^T f(t) f(t + \tau) dt = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T f(t) f(t + \tau) dt$$

$R_f(\tau)$ - VREMENSKA KORRELACIONA FTA NA SUVAZI PROMERZIVI $f(t)$

$$t = t_1, \quad t = t_1 + \Delta t = t_1 + \tau = t_2$$

$$[f^{(k)}(-\nu t), f^{(k)}(-\nu t + \tau)] \quad [x_1^{(k)}, x_2^{(k)}] \quad \xi_1, \xi_2$$

$$\xi_1 \xi_2 = \int \int x_1 x_2 p_{\xi_1, \xi_2}(x_1, x_2, \tau) dx_1 dx_2 = R_{\xi_1 \xi_2}(\tau) = R_f(\tau)$$

• ZA EUKLIDOVEN PRAZ $\xi_1 \xi_2 = \bar{f}(t) \bar{f}(t + \tau) \quad R_{\xi_1 \xi_2}(\tau) = R_f(\tau)$

• OSODINI NA AVTOKORRELACIONITE FUNKCIJI:

$$R_{ff}(\tau) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T f(t) \cdot f(t + \tau) dt = \int_{-\infty}^{\infty} f(x) \cdot f(x + \tau) p(x) dx = R_{ff}(\tau)$$

$$R_{ff}(0) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T f^2(t) dt = \overline{f^2(t)} = \overline{f^2}$$

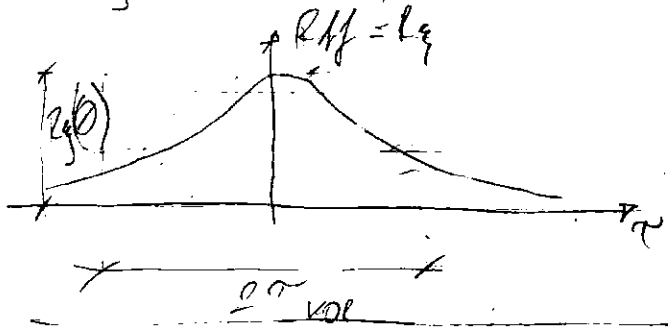
$$\tau \uparrow \rightarrow R_{ff}(\tau) \rightarrow \lim_{T \rightarrow \infty} R_{ff}(\tau) = \begin{cases} \lim_{\tau \rightarrow 0} R_{ff}(\tau) & \text{two point} \\ \text{SR. VL} \\ \text{two point} & \text{SR. VL} \\ \text{SR. VL} & \end{cases}$$

$$\lim_{T \rightarrow \infty} R_{gg}(\tau) = \lim_{T \rightarrow \infty} \iint_{-T}^T x_1 x_2 \gamma_{gg}(x_1, x_2, \tau) dx_1 dx_2 = \text{⊙}$$

$T \rightarrow \infty$ AMPLITUDE NA SIGMAOT SE STATISTIČKI NEKON.

$$\text{⊙} = \int_{-\infty}^{\infty} x_1 \gamma_{gg}(x_1, 0, \tau) dx_1 \int_{-\infty}^{\infty} x_2 \gamma_{gg}(x_2, 0, \tau) dx_2 = \begin{cases} \sum & \text{LAD SR. VL} \\ \emptyset & \text{OSTA SE VL} \end{cases}$$

$$R_{gg}(\tau \geq T_{kor}) = \emptyset \quad T_{kor} - \text{TRAJENJE NA TVTOY OKREDAVANJA}$$



$$2 T_{kor} \cdot R_{gg}(0) = \int_{-T_{kor}}^{T_{kor}} |R_{ff}(\tau)| d\tau$$

$$T_{kor} = \frac{1}{2 R_{gg}(0)} \int_{-T_{kor}}^{T_{kor}} |R_{ff}(\tau)| d\tau$$

MEBUCORRELACIJA F-M NA SR. KOSU:

$$R_{fg}(\tau) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T f(t)g(t+\tau) dt$$

$$R_{gg}(\tau) = \iint_{-T}^T x_1 x_2 \gamma_{gg}(x_1, x_2, \tau) dx_1 dx_2$$

$$R_{gg}(\tau) = \sum_{x_1=-\infty}^{\infty} \sum_{x_2=-\infty}^{\infty} x_1 x_2 \gamma_{gg}(x_1, x_2, \tau)$$

$$R_{gg}(\tau) = \sum_{x_1=-\infty}^{\infty} \sum_{x_2=-\infty}^{\infty} x_1 x_2 \gamma_{gg}(x_1, x_2, \tau)$$

$$|R_{fg}(\tau)| < \frac{1}{2} [R_{ff}(0) + R_{gg}(0)]$$

$$\lim_{T \rightarrow \infty} \int_{-T}^T [f(t) - g(t+\tau)]^2 dt > 0 \quad \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T f^2(t) dt +$$

$$\lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T g^2(t+\tau) dt + \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T f(t)g(t+\tau) dt > 0$$

$$R_{ff}(0) + R_{gg}(0) \pm R_{fg}(\tau) > 0$$

$$|R_{fg}| < R_{ff}(0) + R_{gg}(0)$$

$$\lim_{T \rightarrow \infty} P_{ff}(T) = 0 \quad \int_{-\infty}^{\infty} V_f = 0$$

$P_{gg}(T) = 0$ $\int_{-\infty}^{\infty} y$ se neodređeno i.e. divergov

• STATISTIČKA SUSTINA NA SVAZANJA S. MOĆASI

$$P_{ff}(T) = \int_{-\infty}^{\infty} f(t) f(t+T) dt = \frac{1}{2T} \int_{-\infty}^{\infty} |F(j\omega)|^2 e^{j\omega T} d\omega \quad / 2T$$

$$\frac{1}{2T} \int_{-\infty}^{\infty} f(t) f(t+T) dt = \frac{1}{2T} \int_{-\infty}^{\infty} \frac{|F(j\omega)|^2}{2T} e^{j\omega T} d\omega$$

$$P_T(T) = \frac{1}{2T} \int_{-\infty}^{\infty} \frac{|F(j\omega)|^2}{2T} e^{j\omega T} d\omega = \hat{P}_f(T)$$

$$\hat{P}_f(T) = \overline{P_T(T)} = \frac{1}{2T} \int_{-\infty}^{\infty} \frac{|F(j\omega)|^2}{2T} e^{j\omega T} d\omega$$

$$P_f(T) = P_g(T) = \frac{1}{2T} \int_{-\infty}^{\infty} \frac{|F(j\omega)|^2}{2T} e^{j\omega T} d\omega$$

$$P_g(T) = \lim_{T \rightarrow \infty} \hat{P}_f(T) = \frac{1}{2T} \int_{-\infty}^{\infty} \left(\lim_{T \rightarrow \infty} \frac{|F(j\omega)|^2}{2T} \right) e^{j\omega T} d\omega$$

SGS: $\Phi_f(\omega) = \lim_{T \rightarrow \infty} \frac{|F(j\omega)|^2}{2T}$ VINČER - HILBERTOVA TEOREMA

$$P_g(T) = \frac{1}{2T} \int_{-\infty}^{\infty} \Phi_f(\omega) e^{j\omega T} d\omega \quad \Phi_f(\omega) = \int_{-\infty}^{\infty} P_g(T) e^{-j\omega T} dT$$

INTEGRACIONA TEOREMA ZA SLUČAJI SIG-OCI

$$P_g(0) = \frac{1}{2T} \int_{-\infty}^{\infty} \Phi_f(\omega) d\omega = \bar{F} \quad \text{VUKA SLEPA S OSA}$$

$$\Phi_f(\omega) (=) \frac{W}{Hz} \Rightarrow P_g(=) W$$

$$P_g(T) = \frac{1}{2T} \int_{-\infty}^{\infty} \Phi_f(\omega) \cos(\omega T) d\omega \quad \} \quad \Phi_f(\omega) \text{ PARNA}$$

$$P_g(T) = \frac{1}{T} \int_0^{\infty} \Phi_f(\omega) \cos(\omega T) d\omega \quad \Phi_f(\omega) = 2 \int_0^{\infty} P_g(T) \cos(\omega T) dT$$

MATEMATIČKA SIG: $\overline{P(\omega_1, \omega_2)} = 2 \int_{-\infty}^{\infty} \phi(\omega) d\omega$

REALNA SIG: $P(\phi_1, \phi_2) = \int_{-\infty}^{\infty} \phi(\phi) d\phi$ $\phi(\phi) = 2\phi_{\omega}$
 $\omega > 0$

MEĐUVODZAKAZNA REALNA SIG. STACIONARNI I ERGODIČNI
 $\xi(t); \eta(t)$

$$\Phi_{\xi\eta}(\omega) = \int_{-\infty}^{\infty} R_{\xi\eta}(\tau) e^{-j\omega\tau} d\tau, \quad R_{\xi\eta}(\tau) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \Phi_{\xi\eta}(\omega) e^{j\omega\tau} d\omega$$

$$R_{\xi\eta}(-\tau) = R_{\eta\xi}(\tau) \quad \Phi_{\xi\eta}(\omega) = \Phi_{\eta\xi}^*(\omega) \quad \Phi_{\xi\xi}(-\omega) = \Phi_{\xi\xi}(\omega)$$

SIG NA SUMA I PROJEKCIJA OD SIG. PROCESA
 $\xi(t); \eta(t)$ STACIONARNI SIG. PROCESI

• $\xi(t) = \xi_1(t) + \xi_2(t) \quad \eta(t) = \eta_1(t) + \eta_2(t)$

$$R_{\xi\xi}(\tau) = \overline{\xi(t)\xi(t+\tau)} = \overline{(\xi_1(t) + \xi_2(t))(\xi_1(t+\tau) + \xi_2(t+\tau))} =$$

$$= \overline{\xi_1(t)\xi_1(t+\tau)} + \overline{\xi_1(t)\xi_2(t+\tau)} + \overline{\xi_2(t)\xi_1(t+\tau)} + \overline{\xi_2(t)\xi_2(t+\tau)}$$

$$R_{\xi\xi}(\tau) = R_{\xi_1\xi_1}(\tau) + R_{\xi_1\xi_2}(\tau) + R_{\xi_2\xi_1}(\tau) + R_{\xi_2\xi_2}(\tau)$$

AKO STACIONARNI PROCESI SU NEKORELIRANI I E ORTOGONALNI

$$R_{\xi_1\xi_2}(\tau) = R_{\xi_2\xi_1}(\tau) = 0$$

$$R_{\xi\xi}(\tau) = R_{\xi_1\xi_1}(\tau) + R_{\xi_2\xi_2}(\tau)$$

$$\xi_i = \xi_{i1}, \dots, \xi_{in} \quad \xi = \sum_{i=1}^n \xi_i \quad R_{\xi\xi}(\tau) = \sum_{i=1}^n R_{\xi_i\xi_i}(\tau)$$

$$\Phi_{\xi\xi}(\omega) = \Phi_{\xi_1\xi_1}(\omega) + \Phi_{\xi_2\xi_2}(\omega) \quad \Phi_{\xi\xi}(\omega) = \sum_{i=1}^n \Phi_{\xi_i\xi_i}(\omega)$$

• $\eta(t) = \xi(t) \cdot \gamma(t) \quad R_{\eta\eta}(\tau) = \overline{\xi(t) \cdot \gamma(t) \xi(t+\tau) \gamma(t+\tau)} = R_{\xi\xi}(\tau) R_{\gamma\gamma}(\tau)$

$$\mathcal{F}\{R_{\eta\eta}(\tau)\} = \mathcal{F}\{R_{\xi\xi}(\tau)\} * \mathcal{F}\{R_{\gamma\gamma}(\tau)\}$$

$$\Phi_{\eta\eta}(\omega) = \int_{-\infty}^{\infty} R_{\eta\eta}(\tau) e^{-j\omega\tau} d\tau = \int_{-\infty}^{\infty} R_{\xi\xi}(\tau) R_{\gamma\gamma}(\tau) e^{-j\omega\tau} d\tau$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} \Phi_{\xi}(\omega_1) \Phi_{\gamma}(\omega - \omega_1) d\omega_1$$

$$R_{\xi\xi}(\tau) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \Phi_{\xi}(\omega) e^{j\omega\tau} d\omega$$

$$\Phi_{\eta\eta}(\omega) = \Phi_{\xi}(\omega) * \Phi_{\gamma}(\omega)$$

$$\xi = \sum_{i=1}^n \xi_i \quad R_{\xi\xi}(\tau) = \sum_{i=1}^n R_{\xi_i\xi_i}(\tau)$$

$$v(t) = z(t) \cos(\omega_0 t + \varphi(t)) = T_c(t) \cos(\omega_0 t) - T_s \sin(\omega_0 t)$$

$$v(t) \cdot v(t+\tau) = (T_c(t) \cos(\omega_0 t) - T_s \sin(\omega_0 t)) (T_c(t+\tau) \cos(\omega_0(t+\tau)) - T_s(t+\tau) \sin(\omega_0(t+\tau)))$$

$$= \left| \begin{array}{l} T_c(t) T_s(t) = 0 \\ T_s(t) T_c(t) = 0 \end{array} \right| = T_c(t) T_c(t+\tau) \cos(\omega_0 \tau) - T_s(t) T_s(t+\tau) \sin(\omega_0 \tau)$$

$$\left[\begin{array}{l} \phi_{T_c T_c} = \phi_{T_s T_s} \\ \phi_{T_c T_s} = -\phi_{T_s T_c} \end{array} \right] \rightarrow \text{AUTOCORRELACIONI T.E. METODU OFFERCIORI FURKONI NA SI FROM } T_c \text{ I } T_s$$

$\varphi_n \neq \varphi_m \quad n \neq m$

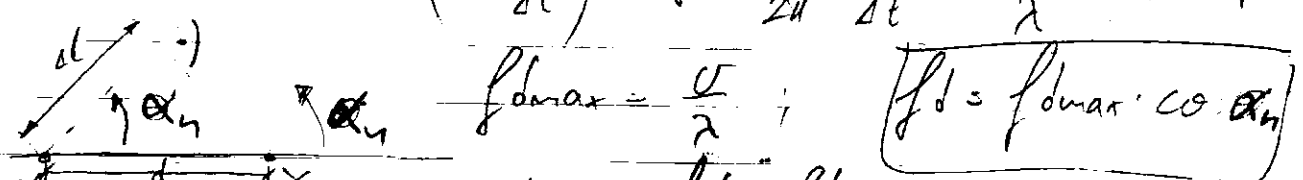
$$\phi_{T_c T_c}(\tau) = \overline{T_c(t) T_c(t+\tau)} \stackrel{\text{USE DRUVAJE FO AGOL } d_n \rightarrow d}{=} \frac{\epsilon_0^2}{2} E_{dn} \left\{ \sin[\omega_{dn} \tau \cos \alpha_n] \right\}$$

$$T_c = \epsilon_0 \sum_{n=1}^N C_n \cos(\omega_{dn} t + \varphi_n) \quad T_s = \epsilon_0 \sum_{n=1}^N C_n \sin(\omega_{dn} t + \varphi_n)$$

$T_c(t), T_s(t)$ GAUZOVI PARAMETRI $T_c^2 = \frac{\epsilon_0^2}{2} \sum Q(t)$
 The Mobile PROPAGATION CHANNEL $T_c \equiv I(t) \quad T_s \equiv Q(t)$

$$\Delta \phi = \frac{2\pi d \ell}{\lambda} = \frac{2\pi d \cdot \cos \theta}{\lambda} = \frac{2\pi \cdot v \cdot \Delta t \cos \theta}{\lambda}$$

$$\left(v = \frac{d}{dt} \right) \quad f_d = \frac{1}{2\pi} \frac{\Delta \phi}{\Delta t} = \frac{v}{\lambda} \cdot \cos \alpha_n$$



$$f_{dmax} = \frac{v}{\lambda} \quad ; \quad \boxed{f_d = f_{dmax} \cdot \cos \alpha_n}$$

$$\alpha_n = 0 \quad f_d = f_{dmax}$$

$$\alpha_n = \pi \quad f_d = -f_{dmax}$$

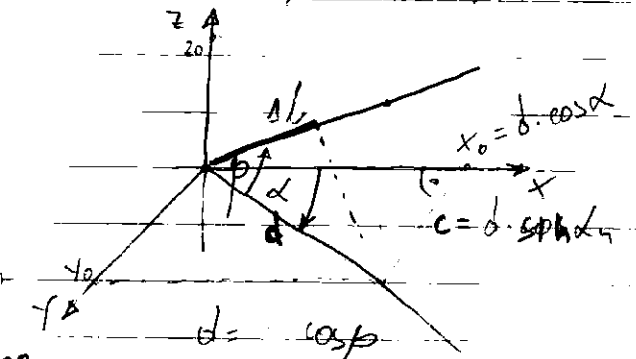
$$\boxed{f \in [f_c - f_{dmax}, f_c + f_{dmax}]}$$

$$\boxed{\omega_{dn} = \frac{2\pi v}{\lambda} \cdot \cos \alpha_n}$$

$$E_z = \sum_{n=1}^N C_n = \epsilon_0 \sum_{n=1}^N C_n \cos(\omega_{dn} t + \theta_n)$$

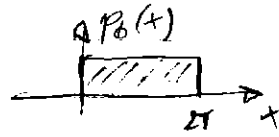
SHORT TERM FADING (RAYSON)

n -th incoming wave has amplitude C_n , PHASE θ_n AND SPACIAL ANGLES OF ARRIVAL: α_n, β_n



$$E \{ C_n^2 \} = \frac{\epsilon_0}{N}$$

ϵ_0 - POSITIVE CONSTANT
 Clarke's Model
 $f_{m} = 0$

$$E(t) = \sum_{n=1}^N E_n(t) \quad b_n \in [0, 2\pi] \quad \rho P_0(x)$$


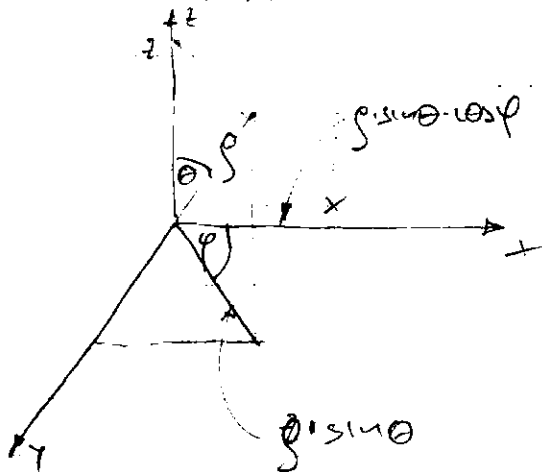
$$\{x_0, y_0, z_0\}$$

$$E_n(t) = C_n \cos(\omega_n t - \frac{\pi \Delta l}{\lambda} + \varphi_n)$$

$$\Delta l = x_0 \cos \alpha_n \cos \beta_n + y_0 \sin \alpha_n \cos \beta_n + z_0 \sin \beta_n$$

$$\cos \alpha_n = \frac{x_0}{d} ; \quad x_0 = d \cdot \cos \alpha \quad \Delta l = d \cdot \cos \rho$$

SPHERICAL COORDINATES



$$x = \rho \sin \theta \cdot \cos \varphi$$

$$y = \rho \sin \theta \cdot \sin \varphi$$

$$z = \rho \cdot \cos \theta$$

$$E(t) = I(t) \cdot \cos(\omega t) - Q(t) \cdot \sin(\omega t)$$

$$I(t) = \sum_{n=1}^N C_n \cos(\omega_n t + \theta_n)$$

$$Q(t) = \sum_{n=1}^N C_n \sin(\omega_n t + \theta_n)$$

$$P_x(x) = \frac{1}{\sqrt{2\pi} \sigma} e^{-\frac{x^2}{2\sigma^2}}$$

$$I(t), \text{ r.e. } x = Q(t)$$

$$E\{I(t)\} = E\{Q(t)\} = 0$$

$$E\{C_n^2\} = \frac{\epsilon_0}{N}$$

$$r(t) = I(t) \cos[\omega_c t - \varphi(t)] = I_c(t) \cos(\omega_c t) - I_s(t) \sin(\omega_c t)$$

$$r(t) \cdot r(t+\tau) = I_c(t) I_c(t+\tau) \cos(\omega_c t) - I_s(t) I_s(t+\tau) \sin(\omega_c t)$$

$$I_c(t) \cos(\omega_c t) \cdot I_c(t+\tau) \cos(\omega_c(t+\tau)) = \left(\sum_{n=1}^N C_n \cos(\omega_n t + \theta_n) \right) \cdot \left(\sum_{m=1}^N C_m \cos(\omega_m(t+\tau) + \theta_m) \right)$$

$$\cos(\omega_c t) \cdot \cos(\omega_c(t+\tau)) dt$$

$$\cos(\omega_c t + \tau) = \cos(\omega_c t) \cdot \cos(\omega_c \tau) - \sin(\omega_c t) \cdot \sin(\omega_c \tau)$$

$$= \int_{-\infty}^{\infty} I_c(t) \cdot \cos(\omega_c t) \cdot I_c(t+\tau) \cdot \cos(\omega_c t) \cos(\omega_c \tau) dt$$

$$V(t)V(t+\tau) = T_c(t)T_c(t+\tau) \cos(\omega_c \tau) - T_s(t)T_s(t+\tau) \sin(\omega_c \tau) \\ = \phi_{T_c T_c} \cos(\omega_c \tau) - \phi_{T_s T_s} \sin(\omega_c \tau)$$

$$\phi_{T_c T_c}(\tau) = \overline{T_c(t)T_c(t+\tau)} = \frac{E_s^2}{2} E_{\alpha_n} \left\{ \cos[\omega_{c-\alpha_n} \tau \cdot \cos(\alpha_n)] \right\}$$

PARSON: $E \{ E(t)E(t+\tau) \} = E \{ I(t)I(t+\tau) \} \cos \omega_c \tau - E \{ Q(t)Q(t+\tau) \} \sin \omega_c \tau$

$$E(t)E(t+\tau) = a(\tau) \cos(\omega_c \tau) - c(\tau) \sin(\omega_c \tau)$$

$$a(\tau) = \frac{\epsilon_0}{2} E \{ \cos \omega_c \tau \} \quad c(\tau) = \frac{\epsilon_0}{2} E \{ \sin \omega_c \tau \}$$

$P_\alpha(\alpha) = \frac{1}{2\pi}$ UNIFORM PDF for incoming waves

$$a(\tau) = \frac{\epsilon_0}{2} \int_0^\pi J_0(2\pi f_{in} \tau \cos \beta) P_\beta(\beta) d\beta \quad c(\tau) = 0$$

$$P_\beta(\beta) = \delta(\beta) \quad \beta = 0$$

$$a_0(\tau) = \frac{\epsilon_0}{2} J_0(2\pi f_{in} \tau)$$

$$J(x) = \frac{1}{2\pi} \int_0^{2\pi} e^{+ix \cos \mu} d\mu$$

$$a_0(\tau) = \frac{\epsilon_0}{4\pi} \int_0^{2\pi} e^{2\pi f_{in} \tau \cos \mu} d\mu \quad f_{in} = \frac{v}{\lambda}$$

EXAMPLE: $\lambda = \frac{300}{[MHz]} = \frac{300}{900} = 0.33 \text{ m}; \quad f_{in} = \frac{10^5 \text{ cm} / 3600 \text{ sec}}{0.33}$

$$f_{in} = \frac{27.7}{0.33} = 83.33 \text{ Hz}$$

$$\tau = \frac{1}{j} \cdot 10^{-9} \text{ sec}$$

$$a_0(\tau) = 1.0000000085 \cdot \frac{\epsilon_0}{2} \approx 0.5 \epsilon_0$$

$$A_0(f) = \mathcal{F}[a_0(\tau)] = \int_{-\infty}^{\infty} a_0(\tau) e^{-j\omega \tau} d\tau$$

$$\mathcal{F}\{J_0(t)\} = \sqrt{\frac{2}{\pi}} \frac{\text{rect}(\frac{\omega}{2})}{\sqrt{1-\omega^2}}$$

$$A_0(f) = \frac{\epsilon_0}{2} \frac{\text{rect}(f)}{\sqrt{1-4\pi^2 f^2}}$$

$$A_0(f) = \mathcal{F}\{a_0(\tau)\} = \begin{cases} \frac{\epsilon_0}{4\pi f_{in}} \frac{1}{\sqrt{1-(f/f_{in})^2}} \\ 0 \end{cases}$$

$|f| \leq f_{in}$
elsewhere

wiki: $\Delta_0' \approx \epsilon_0 \frac{1}{\sqrt{1 - 4\pi^2 f^2}}$ $\epsilon_0 \frac{20 f_m}{20 f_m} \frac{1}{\sqrt{1 - 4\pi^2 f^2}}$ 7

$\Delta_0' = \frac{\epsilon_0}{2}$ $\frac{1}{20 f_m}$ $\frac{\epsilon_0}{20 f_m}$

$a_0(\tau) = \frac{\epsilon_0}{2} J_0(2\pi f_m \tau)$ $\mathcal{F}[J_0(\tau)] = \frac{2}{\sqrt{1 - 4\pi^2 f^2}}$

$\int_{-\infty}^{\infty} J_0(20 f_m \tau) e^{-j\omega \tau} d\tau = \int_{-\infty}^{\infty} J_0(m) e^{-j\omega \frac{m}{20 f_m}} dm = \frac{1}{20 f_m} J_0'(\omega) e^{-j \frac{20 f_m}{20 f_m} m} dm$

$m = 20 f_m \tau$
 $dm = 20 f_m d\tau$
 $d\tau = \frac{dm}{20 f_m}$

$J(\xi) = \frac{1}{20 f_m} \int_{-\infty}^{\infty} J_0(\xi) e^{-j\xi m} dm = \frac{1}{20 f_m} \frac{2}{\sqrt{1 - \xi^2}}$

$J_0'(\xi) = \frac{\epsilon_0}{2} \frac{1}{20 f_m} \frac{2}{\sqrt{1 - \frac{\xi^2}{f_m^2}}}$

$\bar{F}_n = F(\omega = 0) = \frac{1}{T} \int_{-T/2}^{T/2} f(t) \cdot e^{-j\omega t} dt$ $\frac{1}{T} \int_{-T/2}^{T/2} f(t) e^{-j\omega t} dt$

$R_{AM}(\tau) = \frac{1}{T} \int_{-T/2}^{T/2} f(t) f(t+\tau) dt = \frac{1}{T} \int_{-T/2}^{T/2} f(t) \left(\frac{1}{T} \int_{-T/2}^{T/2} \bar{F}_n e^{j\omega(t+\tau)} dt \right) e^{j\omega t} dt$

$= e^{j\omega \tau} \sum_{n=-\infty}^{\infty} \bar{F}_n \frac{1}{T} \int_{-T/2}^{T/2} f(t) e^{j\omega t} dt = \sum_{n=-\infty}^{\infty} |\bar{F}_n|^2 e^{j\omega \tau}$

$R_{AM}(\tau) = \sum_{n=-\infty}^{\infty} |\bar{F}_n|^2 e^{j\omega \tau}$ FOR I.L. PAR

THE RECEIVED SIGNAL ENVELOPE:

СИГНАЛА ПРАКТИЧНО:

$P_f(k, m) \quad f = k; \quad k = 0, 1, 2, 3, \dots, n$

$P(A) = p$ ВЕЛОЧАСТІ ТА СЕ СЛУЧІ УХВАТИТИ А

$P(\bar{A}) = 1 - p = q$ ВЕЛОЧАСТІ ТА СЕ СЛУЧІ \bar{A}

$p^k q^{n-k}$ } $\left\{ \begin{array}{l} \text{velo\u0161tost od } n^{\text{ta}} \text{ \u010dadi} \\ k \text{ - yati} \end{array} \right.$ A se realiziralo (n-k) pati

$$P_g(k, n) = C_n^k p^k q^{n-k} = \frac{n!}{k!(n-k)!} p^k q^{n-k}$$

$n=3 \quad k=1 \quad P_g(k, n) = \frac{3!}{1!2!} \cdot p^1 q^{2} = 3 \cdot p^1 q^2 =$

$= (p=q=0.5) = 3 \cdot 0.5 \cdot 0.25 = 1.5 \cdot 0.25 = \underline{0.375}$

$(p+q)^n = \sum_{k=0}^n C_n^k p^k q^{n-k}$ \leftarrow σ - pomo\u0161na funkcija

$\sigma=1: (p+q)^n = \sum_{k=0}^n C_n^k p^k q^{n-k} = 1 = \sum_{k=0}^n P_g(k, n)$

$\boxed{\bar{g}=?}$ $(p+q)^n = \sum_{k=0}^n C_n^k p^k q^{n-k} \quad \left| \frac{d}{d\sigma} \right.$

$n \cdot p (p+q)^{n-1} = \sum_{k=0}^n k C_n^k p^k q^{n-k} \quad (**)$

$\boxed{\sigma=1}$ $\left[n p (p+q)^{n-1} = \sum_{k=0}^n k C_n^k p^k q^{n-k} \right]$ $P_g(k, n)$

$n \cdot p = \sum_{k=0}^n k \cdot P_g(k, n) = \bar{g} = \bar{k}$ $\boxed{\bar{g} = n \cdot p}$

$(*) \cdot \sigma \quad n \cdot p \cdot \sigma (p+q)^{n-1} = \sum_{k=0}^n k \cdot C_n^k p^k q^{n-k} \quad \left| \frac{d}{d\sigma} \right.$

$n \cdot p \cdot (p+q)^{n-1} + n(n-1) p^2 \cdot \sigma \cdot (p+q)^{n-2} = \sum_{k=0}^n k^2 C_n^k p^k q^{n-k}$

$\sigma=1: n \cdot p (p+q)^{n-1} + n(n-1) p^2 (p+q)^{n-2} = \sum_{k=0}^n k^2 C_n^k p^k q^{n-k}$ $P_g(k, n)$

$\textcircled{1} = \left| \frac{d}{d\sigma} \right| = n \cdot p + n(n-1) p^2 = \sum_{k=0}^n k^2 P_g(k, n) = \bar{g}^2$

$\bar{g}^2 = n p (1 + (n-1) p) = n p + n^2 p^2 - n p^2$

$\sigma^2 = \bar{g}^2 - \bar{g}^2 = n p + n^2 p^2 - n p^2 - n^2 p^2 = n p - n p^2$

$\boxed{\sigma^2 = n p (1-p) = n p q}$

$\boxed{\sigma_g = \sqrt{n p q}}$

$$\frac{\sigma_q}{\sigma_{\text{red}}} = \sigma_{\text{red}} = \frac{\sqrt{npq}}{np} = \sqrt{\frac{q}{np}} = \sigma_{\text{red}}$$

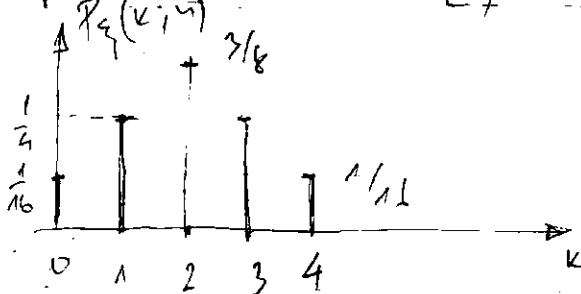
$\sigma_{\text{red}} \downarrow \quad n \uparrow$

Primer: $n=4$ $k=0,1,2,3,4$ $p=q=0.5$ $P_q(k;4) = C_n^k p^k q^{n-k}$

$$\bar{x} = n \cdot p = 4 \cdot 0.5 = 2$$

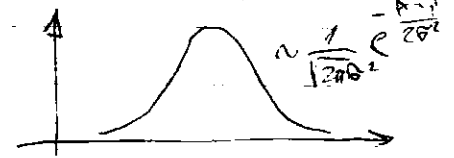
$$P_q(1;4) = C_4^1 \frac{1}{2} \cdot \left(\frac{1}{2}\right)^3 = \frac{4!}{3! \cdot 1!} \frac{1}{2} \cdot \frac{1}{8} = 4 \cdot \frac{1}{2} \cdot \frac{1}{8} = \frac{1}{4}$$

$$P_q(0;4) = 1 \cdot 1 \cdot \left(\frac{1}{2}\right)^4 = \frac{1}{16}$$



$$P(3;4) = C_4^3 \cdot \frac{1}{8} \cdot \frac{1}{2} = \frac{4!}{1! \cdot 3!} \frac{1}{16} = 4 \cdot \frac{1}{16} = \frac{1}{4}$$

$$P(2;4) = C_4^2 \cdot \frac{1}{4} \cdot \frac{1}{4} = \frac{4!}{2! \cdot 2!} \frac{1}{16} = \frac{6}{16} = \frac{3}{8}$$



① $n \rightarrow \infty$ $p = \text{const}$

② $n \rightarrow \infty$ $p \rightarrow 0$

$$\bar{x} = n \cdot p = \text{const}$$

$$\bar{x} = n \cdot p \rightarrow \infty$$

$$\bar{x} = n \cdot p = \lambda \quad \left| p = \frac{\lambda}{n} \right|$$

$\lambda = \text{const}$

$$\lim_{n \rightarrow \infty} P_q(k;n) = \lim_{n \rightarrow \infty} C_n^k p^k (1-p)^{n-k} = \lim_{n \rightarrow \infty} \frac{n!}{k!(n-k)!} \left(\frac{\lambda}{n}\right)^k \left(1 - \frac{\lambda}{n}\right)^{n-k}$$

$$= \frac{\lambda^k}{k!} \lim_{n \rightarrow \infty} \frac{n(n-1)\dots(n-k+1)}{k!} \left(1 - \frac{\lambda}{n}\right)^{n-k} = \frac{\lambda^k}{k!} \lim_{n \rightarrow \infty} \left(1 - \frac{\lambda}{n}\right)^n = \frac{\lambda^k}{k!} e^{-\lambda}$$

$$\left(1 - \frac{\lambda}{n}\right)^n = C_n^0 \left(\frac{-\lambda}{n}\right)^0 + C_n^1 \left(\frac{-\lambda}{n}\right)^1 + \dots$$

$$f(x) = 1 + \frac{x}{1!} f'(0) + \frac{x^2}{2!} f''(0) + \dots + \frac{x^k}{k!} f^{(k)}(0) + \dots$$

$$f(x) = e^x = 1 + \frac{x}{1!} \cdot 1 + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots + \frac{x^n}{n!} + \dots$$

$$e^{-x} = 1 - x + \frac{x^2}{2!} - \frac{x^3}{3!} + \dots + \frac{x^n}{n!} + \dots$$

$$(p+q)^n = \sum_{k=0}^n C_k^n p^k q^{n-k}$$

$$\begin{aligned} \left(1 - \frac{\lambda}{n}\right)^n &= (-1)^n \left(\frac{\lambda}{n} - 1\right)^n = \left[1 + \left(\frac{-\lambda}{n}\right)\right]^n = \left[1 + \left(\frac{-\lambda}{n}\right)\right]^n \\ &= \sum_{k=0}^n C_k^n \left(\frac{-\lambda}{n}\right)^k (1)^{n-k} = \sum_{k=0}^n C_k^n (-1)^k \left(\frac{\lambda}{n}\right)^k = C_0^n \cdot 1 + C_1^n \left(\frac{-\lambda}{n}\right) \\ &+ C_2^n \left(\frac{-\lambda}{n}\right)^2 + C_3^n \left(\frac{-\lambda}{n}\right)^3 + \dots + C_k^n \left(\frac{-\lambda}{n}\right)^k + \dots \end{aligned}$$

$$\textcircled{1} = 1 + \frac{n!}{(n-1)! \cdot 1!} \frac{(-\lambda)}{n} + \frac{n!}{(n-2)! \cdot 2!} \left(\frac{-\lambda}{n}\right)^2 + \dots + \frac{n!}{(n-k)! \cdot k!} \left(\frac{-\lambda}{n}\right)^k + \dots$$

$$\textcircled{*} = \frac{(n-k+1)!}{k!} \frac{\lambda^k (-1)^k}{n^k} = \frac{(-\lambda)^k}{k!} \underbrace{1 \left(1 - \frac{1}{n}\right) \left(1 - \frac{2}{n}\right) \dots \left(1 - \frac{k-1}{n}\right)}_{\textcircled{2}}$$

$$\lim_{n \rightarrow \infty} \textcircled{*} = \frac{(-1)^k \lambda^k}{k!}$$

$$\lim_{n \rightarrow \infty} \textcircled{1} = \lim_{n \rightarrow \infty} \left(1 - \frac{\lambda}{n}\right)^n$$

$$\lim_{n \rightarrow \infty} \left(1 - \frac{\lambda}{n}\right)^n = 1 - \lambda + \frac{\lambda^2}{2!} - \frac{\lambda^3}{3!} + \dots = \underline{\underline{e^{-\lambda}}}$$

$$\lim_{n \rightarrow \infty} P_f(k; n) = \lim_{n \rightarrow \infty} C_k^n p^k (1-p)^{n-k} = \frac{\lambda^k}{k!} e^{-\lambda}$$

$$\boxed{\bar{f} = \lambda} \quad \boxed{P_f(k, \lambda) = \frac{\lambda^k}{k!} e^{-\lambda}}$$

$$\begin{aligned} \bar{f} &= \sum_{k=0}^{\infty} k P_f(k, \lambda) = \sum_{k=0}^{\infty} k \frac{\lambda^k}{k!} e^{-\lambda} = \sum_{k=1}^{\infty} k \frac{\lambda^k}{k!} e^{-\lambda} \\ &= e^{-\lambda} \lambda \sum_{k=1}^{\infty} \frac{\lambda^{k-1}}{(k-1)!} = e^{-\lambda} \lambda \sum_{k=0}^{\infty} \frac{\lambda^k}{k!} = e^{-\lambda} \lambda \underbrace{\sum_{k=0}^{\infty} \frac{\lambda^k}{k!}}_{e^{\lambda}} \\ &= \boxed{\bar{f} = e^{-\lambda} \cdot \lambda \cdot e^{\lambda} = \lambda} \end{aligned}$$

$$\sigma_f^2 = ? \quad \sigma_f^2 = \left(\bar{f} - \bar{f}\right)^2 = \int_{-\infty}^{\infty} (x - \bar{f})^2 p_f(x) dx =$$

$$= \int_{-\infty}^{\infty} x^2 p_f(x) dx - 2\bar{f} \int_{-\infty}^{\infty} x p_f(x) dx + \bar{f}^2 \int_{-\infty}^{\infty} p_f(x) dx = \underbrace{\int_{-\infty}^{\infty} x^2 p_f(x) dx}_{\sigma_f^2} - 2\bar{f} \underbrace{\int_{-\infty}^{\infty} x p_f(x) dx}_{\bar{f}} + \bar{f}^2 \underbrace{\int_{-\infty}^{\infty} p_f(x) dx}_{1} = \sigma_f^2 - 2\bar{f}^2 + \bar{f}^2$$

$$\begin{aligned} \sigma_{\xi}^2 &= \overline{\xi^2} - \bar{\xi}^2; \quad \overline{\xi^2} = \sum_{k=0}^{\infty} k^2 \frac{\lambda^k e^{-\lambda}}{k!} = \sum_{k=1}^{\infty} k \frac{\lambda^{k-1}}{(k-1)!} \lambda e^{-\lambda} = \\ &= \lambda e^{-\lambda} \sum_{k=1}^{\infty} k \frac{\lambda^{k-1}}{(k-1)!} = \lambda e^{-\lambda} \left[\sum_{k=1}^{\infty} (k-1) \frac{\lambda^{k-1}}{(k-1)!} + \sum_{k=1}^{\infty} \frac{\lambda^{k-1}}{(k-1)!} \right] \end{aligned}$$

$$\overline{\xi^2} = \left[\sum_{\mu=0}^{\infty} \mu \frac{\lambda^{\mu}}{\mu!} + \sum_{\mu=0}^{\infty} \frac{\lambda^{\mu}}{\mu!} \right] \lambda e^{-\lambda} = (\lambda + e^{\lambda}) \lambda e^{-\lambda} = \lambda^2 + \lambda$$

$$\overline{\xi^2} = \lambda^2 + \lambda; \quad \sigma_{\xi}^2 = \overline{\xi^2} - \bar{\xi}^2 = \lambda^2 + \lambda - \lambda^2 = \lambda$$

$$\boxed{\sigma_{\xi}^2 = \lambda} \quad P_{\xi}(k, \lambda) = \frac{\lambda^k}{k!} e^{-\lambda} \quad \left[\begin{array}{l} \mu = \lambda \\ r = \frac{\lambda}{\mu} \end{array} \right]$$

$$P_{\xi}(x) = \sum_{k=0}^{\infty} \frac{\lambda^k}{k!} e^{-\lambda} \delta(x-k) = \sum_{k=0}^{\infty} P_{\xi}(k, \lambda) \delta(x-k)$$

$$F_{\xi}(x) = P(\xi \leq x) = \sum_{k=0}^{\lfloor x \rfloor} P_{\xi}(k, \lambda)$$

$$\lambda = c \cdot \tau \quad P_{\xi}(k; \tau) = \frac{(c\tau)^k}{k!} e^{-c\tau}$$

ΤΕΛΕΓΡΑΦΙΚΗ ΣΗΜΑΤΑ: Η ΕΥΧΑΙΡΙΣΤΙΑ ΔΑ ΥΠΟΛΟΓΙΖΕΤΑΙ ΩΣ ΜΙΑ ΚΑΙ ΚΑΝΟΝΙΚΗ ΝΑ ΝΙΒΟΥ ΣΗΜΑΤΟΣ Ε ΒΑΣΙΣΤΕΛΕΜΑ ΤΟ ΠΑΡΑΚΑΤΩΤΟ ΖΗΤΗΜΑ !!!

$\xi_i \in \{-A, A\}$ ΜΟΜΕΝΤΙΑ ΚΑΙ ΚΑΙΝΟΤΑ ΣΗΜΑΤΟΣ

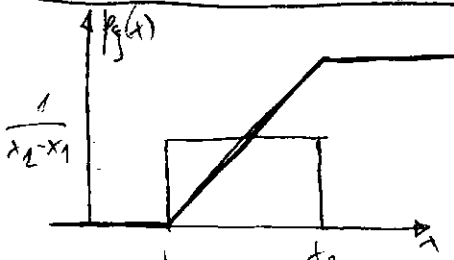
$\gamma_i \in \{0, 1\}$ ΜΑΡΤΑΝ ΔΑ ΥΠΟ ΔΙΔΕΝ ΜΟΜΕΝΤ ΜΑ ΠΡΟΜΕΤΑ ΝΑ ΝΙΒΟΥ

$$P_{\gamma}(k; \tau) = \frac{(c\tau)^k}{k!} e^{-c\tau}$$

$$P(\gamma=1) = c \cdot d\tau \quad P(\gamma=0) = 1 - c \cdot d\tau$$

c - ΠΡΟΒΑΡΗ ΔΙΟΥ ΜΑΡΤΑΝ ΥΠΟ ΜΙΑ ΚΑΙΝΟΤΑ

ΜΑΡΤΑΝ ΠΑΡΑΚΑΤΩΤΟ ΔΑ



$$f_{\xi}(x) = \begin{cases} \frac{1}{x_2 - x_1} & x_1 \leq x \leq x_2 \\ 0 & \text{ΟΤΑΙ ΕΞΩ} \end{cases}$$

$$\bar{\xi} = \int_{-\infty}^{\infty} x \frac{1}{x_2 - x_1} dx = \frac{1}{x_2 - x_1} \int_{x_1}^{x_2} x dx =$$

$$= \frac{1}{x_2 - x_1} \frac{x^2}{2} \Big|_{x_1}^{x_2} = \frac{1}{x_2 - x_1} \frac{1}{2} (x_2^2 - x_1^2) = \frac{x_2 + x_1}{2}$$

$$\sigma_{\xi}^2 = \overline{\xi^2} - \bar{\xi}^2 = \frac{1}{x_2 - x_1} \int_{x_1}^{x_2} x^2 dx - \bar{\xi}^2 = \frac{1}{x_2 - x_1} \frac{x^3}{3} \Big|_{x_1}^{x_2} - \left(\frac{x_2 + x_1}{2} \right)^2 = \frac{1}{x_2 - x_1} \frac{x_2^3 - x_1^3}{3} - \frac{(x_2 + x_1)^2}{4}$$

$$b^2 = \frac{1}{x_2 - x_1} \frac{x_2^2 - x_1^2}{3} - \frac{(x_1 + x_2)^2}{4}$$

$$a^3 - b^3 = (a-b)(a^2 + ab + b^2) = a^3 + a^2b - ba^2 - ab^2 - b^3 = a^3 - b^3$$

$$b^2 = \frac{1}{3(x_2 - x_1)} \frac{(x_2^2 + 2x_1x_2 + x_1^2)}{1} - \frac{x_1^2 + 2x_1x_2 + x_2^2}{4}$$

$$= \frac{4x_2^2 + 4x_1x_2 + 4x_1^2 - 3x_1^2 - 6x_1x_2 - 3x_2^2}{12} = \frac{x_1^2 - 2x_1x_2 + x_2^2}{12}$$

$$b^2 = \frac{(x_1 - x_2)^2}{12}$$

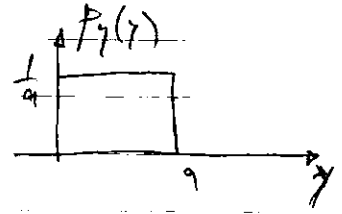
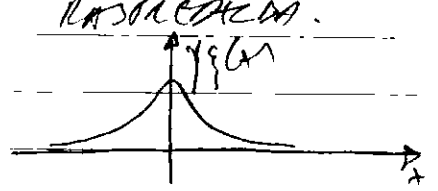
$$F_g(x) = \int_{x_1}^x \frac{1}{x_2 - x_1} dx = \frac{1}{x_2 - x_1} x \Big|_{x_1}^x = \frac{x - x_1}{x_2 - x_1}$$

$f_g(x) =$	$\frac{x - x_1}{x_2 - x_1}$	$x_1 \leq x \leq x_2$
	0	$x < x_1$
	1	$x > x_2$

$$P(x \leq \xi \leq x + dx) = P(y \leq \eta \leq y + dy)$$

$$p_g(x) dx = p_h(y) dy \quad \left[p_h(y) = \frac{p_g(x)}{\left| \frac{dy}{dx} \right|} \right]_{x=g(y)}$$

• BILLO KOTRA RASPREDEBA NA GUSTINA NA VERJATNOST MORE SE SE PREGVORI SO SOODVETNA TRANSFORMACIJA VO VISOKY. RASPREDEBA.



$$\eta = f(\xi)$$

$$\xi = f^{-1}(\eta)$$

$$p_h(\eta) = \frac{p_g(\xi)}{\left| \frac{d\xi}{d\eta} \right|} \Big|_{\xi=f^{-1}(\eta)}$$

$$\eta = a \cdot F_g(\xi)$$

$$\frac{d\eta}{d\xi} = a \cdot \frac{d}{d\xi} (F_g(\xi)) = a \cdot p_g(\xi)$$

$$F_g(x) \in [0, 1]$$

$$\eta \in [0, a]$$

$$p_h(\eta) = \frac{p_g(\xi)}{a p_g(\xi)} = \frac{1}{a} \quad \eta \in (0, a)$$

LAPLACEOVA

$$p_g(x) = \frac{a}{2} e^{-a|x|}$$

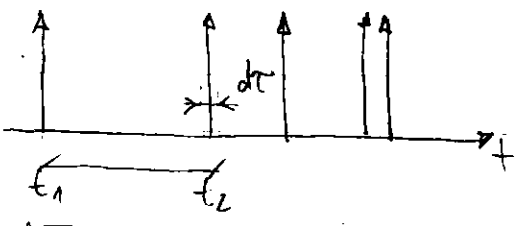
REZLIEVA:

$$p_g(x) = \frac{xL}{2a} e^{-\frac{xL}{2a}} \cdot h(x)$$

• KOSIĆEVA: $f_y(k) = \frac{c}{\pi} \frac{a}{a^2 + k^2}$

PRAZNOVI NIZI OD DILATOVI IMPULSI

1. UNIPOLARNA NIZA



$P_y(k; \tau) = \frac{(c e^{k\tau})}{k} e^{-c\tau}$

c - HODIEN DIO NA IMPULSI VO EPIMCI VLEME
 VELOKOST VO INTERVALU T
 IMA "K" IMPULSI
 VO VA IMPULSI

$\lim_{A \rightarrow \infty} A dt = 1$

$P(y=1) = c dt = P(A)$ $P(y=0) = 1 - c dt = P(0)$

$R_g(\tau) = \sum_{i=1}^2 \sum_{j=1}^2 x_{ii} x_{jj} P_{g_1 g_2}(x_{ij}; x_{ii}, j; \tau) =$
 $= \sum_{i=1}^2 \sum_{j=1}^2 x_{ii} x_{jj} P_{g_1}(x_{ii}) P_{g_2}(x_{jj}/x_{ii}; \tau)$

x_{ii}	x_{jj}
0	0
0	A
A	0
A	A

$R_g(\tau) = A \cdot A \cdot P(A) P(A/A; \tau)$

$R_{gg} = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T f(t) f(t+\tau) dt = \overline{f(t) f(t+\tau)}$

$R_{gg} = \int_{-T}^T \int_{-T}^T x_1 x_2 f_{g_1 g_2}(x_1, x_2; \tau) dx_1 dx_2$

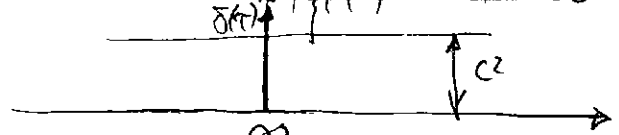
$P(A/A; \tau) = P(A) = c \cdot dt$

$R_g(\tau) = A^2 \cdot P(A) P(A)$

$\tau \neq 0$ $R_g(\tau) = A^2 \cdot c dt \cdot c dt = A^2 \cdot c^2 \cdot dt^2 = c^2$
 $\lim_{A \rightarrow \infty} A \cdot dt = 1$

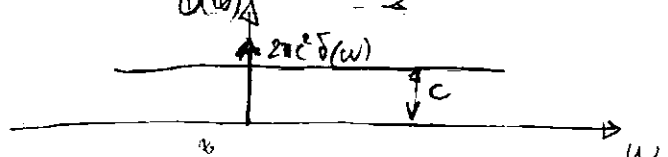
$\tau = 0$ $P(A/A, 0) = 1$ $R_g(\tau) = A^2 \cdot c dt = \frac{c \cdot \delta(\tau)}{A \rightarrow \infty}$

$R_g(\tau) = c^2 + c \delta(\tau)$



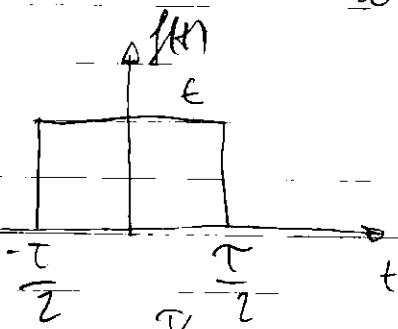
$D(\omega) = \int_{-\infty}^{\infty} R_g(\tau) \cdot e^{-j\omega\tau} d\tau = \int_{-\infty}^{\infty} (c^2 + c\delta(\tau)) e^{-j\omega\tau} d\tau$

$= 2\pi c^2 \delta(\omega) + c$



$\int_0^{\infty} c^2 e^{-j\omega\tau} d\tau = c \int_{-\infty}^{\infty} (c\omega\tau e^{-j\omega\tau}) d\tau = c^2 \int_{-\infty}^{\infty} \cos(\omega\tau) d\tau$

$$\int_{-\infty}^{\infty} \cos(\omega t) dt = \frac{e^2}{\omega} \int_{-\infty}^{\infty} \cos \omega t dt = \frac{2e^2}{\omega} \sin \omega t \Big|_0^{\infty}$$



$$F(j\omega) = \int_{-\infty}^{\infty} f(t) \cdot e^{-j\omega t} dt$$

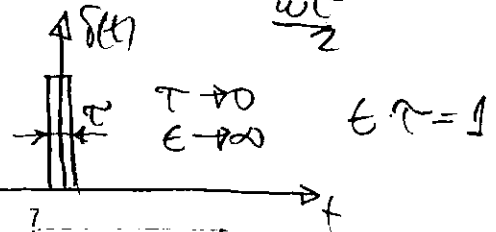
$$F(j\omega) = \int_{-\tau/2}^{\tau/2} E \cdot e^{-j\omega t} dt = E \int_{-\tau/2}^{\tau/2} e^{-j\omega t} dt$$

$$\begin{aligned} u &= -j\omega t \\ du &= -j\omega dt \\ t = -\tau/2 & \Rightarrow u = +j\omega\tau/2 \\ t = \tau/2 & \Rightarrow u = -j\omega\tau/2 \end{aligned}$$

$$F(j\omega) = E \frac{-1}{j\omega} \int_{j\omega\tau/2}^{-j\omega\tau/2} e^u du = \frac{-E}{j\omega} \left(e^{-j\omega\tau/2} - e^{j\omega\tau/2} \right)$$

$$= \frac{2E}{2j\omega} \left(e^{j\omega\tau/2} - e^{-j\omega\tau/2} \right) = \frac{2E}{\omega} \sin \omega\tau/2 = \frac{E\tau}{\omega\tau/2} \cdot \sin \omega\tau/2$$

$$F(j\omega) = E \cdot \tau \frac{\sin \omega\tau/2}{\omega\tau/2}$$



$$\Delta(j\omega) = \mathcal{F}\{\delta(t)\} = \lim_{\tau \rightarrow 0} F(j\omega) = 1$$

$$\mathcal{F}\{\delta(t-t_0)\} = 1 \cdot e^{-j\omega t_0}$$

$$\int_{-\infty}^{\infty} \delta(t-t_0) f(t) dt = f(t_0)$$

$$\Delta(j\omega) = \int_{-\infty}^{\infty} \delta(t) e^{-j\omega t} dt$$

$$\Delta(j\omega) = 1$$

$$\delta(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \Delta(j\omega) e^{j\omega t} d\omega$$

$$\delta(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{j\omega t} d\omega$$

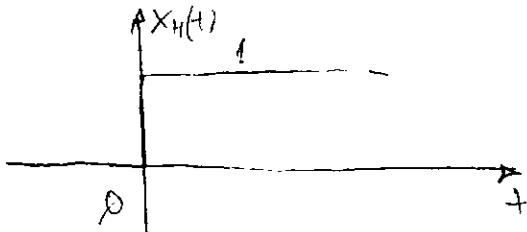
$$\mathcal{F}\{k\} = \int_{-\infty}^{\infty} k e^{-j\omega t} dt = k \int_{-\infty}^{\infty} e^{-j\omega t} dt$$

$$\begin{aligned} t &= -\omega \\ \omega &= -t \\ \delta(-\omega) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-j\omega t} dt \end{aligned}$$

$$\int_{-\infty}^{\infty} e^{-j\omega t} dt = 2\pi \delta(-\omega) = 2\pi \delta(\omega)$$

$$\mathcal{F}\{k\} = k \cdot 2\pi \delta(\omega)$$

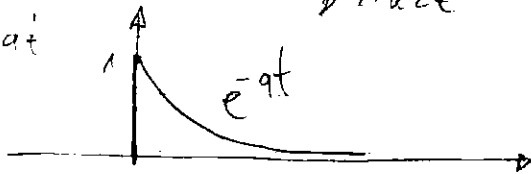
• SAEVITASA GOS, VRA TA AMPLIUMA I FASENA NA NEVSEPOV S. S. CA



$$x_H(t) = \begin{cases} 1 & t \geq 0 \\ 0 & t < 0 \end{cases}$$

⊗ $\int_{-\infty}^{\infty} x_H(t) e^{-at} dt \rightarrow \infty$

NE GO ISKORUVVA USLOV NA PIVUCE ZA FURIERA TRANSFORMACIJA



$$F(j\omega) = \int_{-\infty}^{\infty} e^{-at} \cdot e^{-j\omega t} dt = \int_0^{\infty} e^{-(a+j\omega)t} dt = \int_0^{\infty} e^{-(a+j\omega)t} dt = -\frac{1}{a+j\omega} e^{-(a+j\omega)t} \Big|_0^{\infty}$$

$$\frac{1}{a+j\omega} \left[\frac{1}{e^{-\infty}} - 1 \right] = \frac{1}{a+j\omega} = \frac{a-j\omega}{a^2+\omega^2}$$

$$F(j\omega) = \frac{1}{a^2+\omega^2} (a-j\omega) = \frac{1}{a^2+\omega^2} \left[a - j\omega \right] = \frac{e^{-j\omega \arctan \frac{\omega}{a}}}{\sqrt{a^2+\omega^2}}$$

$$F \left[e^{-at} x_H(t) \right] = \frac{1}{a+j\omega}$$

$$a \rightarrow 0 \quad F \left[x_H(t) \right] = \frac{1}{j\omega} + K = \frac{1}{j\omega} + F \{ x_H(0) \}$$

$$x_H(t) \Big|_{t=0} = \frac{1}{2} \left[x_H(0^-) + x_H(0^+) \right] = \frac{1}{2}$$

$$F \{ K \} = 2\pi K \delta(\omega) \Rightarrow F \left\{ \frac{1}{2} \right\} = \pi \delta(\omega)$$

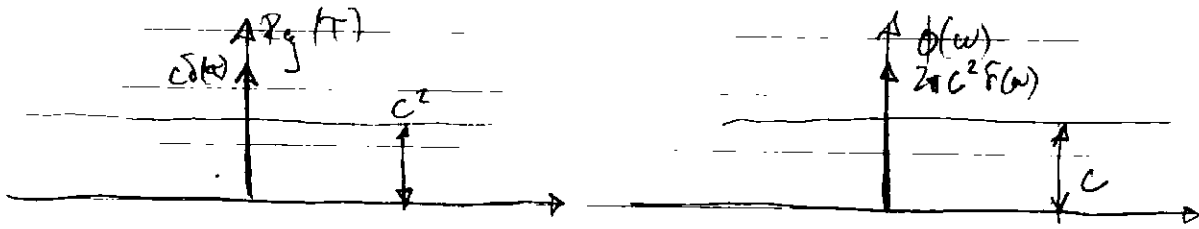
$$F \{ x_H(t) \} = \frac{1}{j\omega} + \pi \delta(\omega)$$

$$Z_g(\tau) = A^2 \cdot P(A)P(A) \quad \tau \neq 0 \quad Z_g(\tau) = A^2 \cdot c \delta \tau \cdot c \delta \tau = c^2$$

$$\tau = 0 \quad Z_g(\tau) = A^2 \cdot P(A/\tau=0)P(A) = A^2 \cdot c \delta \tau = c \cdot \tau(\tau)$$

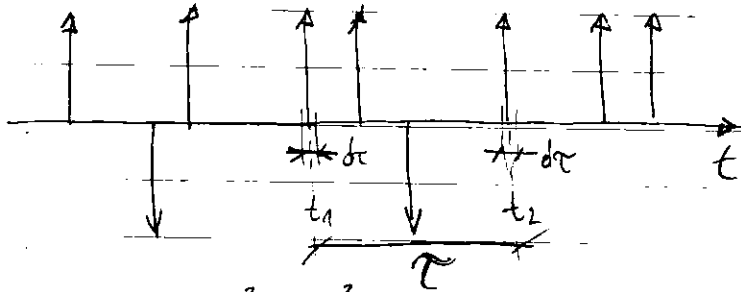
$$Z_g(\tau) = c^2 + c \delta(\tau) \quad \Phi(\omega) = \int_{-\infty}^{\infty} [c^2 + c \delta(\tau)] e^{j\omega \tau} d\tau$$

$$\Phi(\omega) = 2\pi c^2 \delta(\omega) + c$$



$$\left[\overline{\xi}^2 = 2\pi c^2 \right] \rightarrow \text{EDROKASOČNA VRASTA}$$

5. TRANSIJBARNA NIŽA



$$P(y=1) = c \cdot dt$$

$$P(A) = P(-A) = \frac{c dt}{2}$$

$P(0) = 1 - c dt \rightarrow$ VEROJAJNOST DA NE POTOVI NIŠKES

$$Z_g(\tau) = \sum_{i=1}^3 \sum_{j=1}^3 x_{i1} x_{2j} P_{g_1, g_2}(x_{i1}, x_{2j}, \tau)$$

$\begin{pmatrix} A & A \\ A & 0 \end{pmatrix}$	$\begin{pmatrix} -A & A \\ -A & 0 \end{pmatrix}$	$\begin{pmatrix} 0 & A \\ 0 & 0 \end{pmatrix}$	} MOŽEMO VREDNOSTI NA x_{i1}, x_{2j} VO MOMENTE t_1, t_2
$\begin{pmatrix} A & -A \\ -A & -A \end{pmatrix}$	$\begin{pmatrix} -A & -A \\ -A & -A \end{pmatrix}$	$\begin{pmatrix} 0 & -A \\ 0 & -A \end{pmatrix}$	

$$P_g(\tau) = \sum_{i=1}^3 \sum_{j=1}^3 x_{i1} x_{2j} P_{g_1}(x_{i1}) P_{g_2}(x_{2j} | x_{i1}, \tau)$$

$$= A^2 P(A) \cdot P(A/A; \tau) + A^2 P(-A) P(-A/-A; \tau) - A^2 P(A) P(-A/A; \tau) - A^2 P(-A) P(A/-A; \tau) = 2A^2 P(A) P(A/A; \tau) - 2A^2 P(A) P(-A/A; \tau)$$

$$P(A/A; \tau) = P(-A/-A; \tau) = P(A) = \frac{c dt}{2}$$

$$P(-A/A; \tau) = P(A/-A; \tau) = P(-A) = \frac{c dt}{2}$$

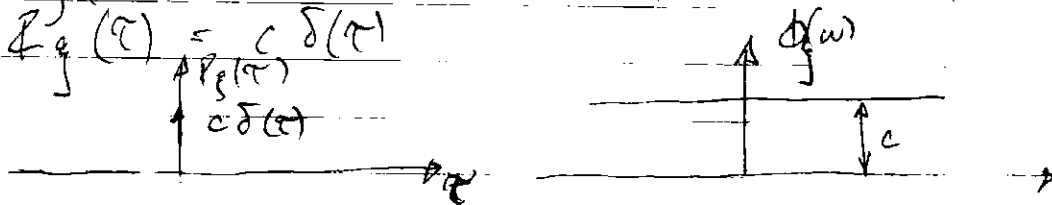
$$Z_g(\tau) = 2A^2 \cdot \frac{c^2 dt d\tau}{4} - 2A^2 \cdot \frac{c^2 dt d\tau}{4} = 0 \quad \underline{\tau \neq 0}$$

$Z_g(\tau) = 0$ ZA $\tau \neq 0$ TRANSIJBARNA NIŽA JE NEKORELIRANA ZA $\tau \neq 0$.

za: $\tau = 0$ $P(A/A; 0) = 1$ $P(-A/A; 0) = 0$

$$Z_g(\tau) = A^2 P(A) \cdot 1 + A^2 P(-A) \cdot 1 = 2A^2 P(A) = A^2 \cdot c dt = c \delta(\tau)$$

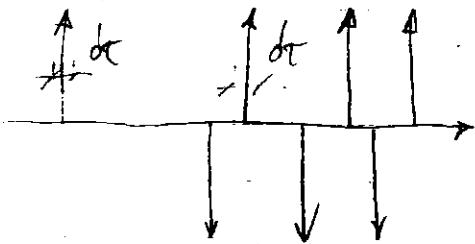
$$Z_g(\tau) = c \delta(\tau)$$



6. ALTERNATIVO MATEMATICA NISA

$$P_{y|X}(y/x) = \frac{P_{xy}(x,y)}{P_x(x)} \quad ; \quad P_x(x) > 0$$

$$P_{y|X}(x/y) = \frac{P_{xy}(x,y)}{P_y(y)} \quad ; \quad P_y(y) > 0$$



$$P_y(\tau) = \sum_{i=1}^2 \sum_{j=1}^2 x_{ij} x_{ij} P_{x_{ij}}(x_{ij}) P_{y_{ij}}(y_{ij}|x_{ij}, \tau)$$

$$P_y(\tau) = 2A^2 P(A) P(A/A; \tau) - 2A^2 P(A) P(A/A; \tau)$$

$$P(A) = P(-A) = \frac{c \cdot dt}{2}$$

$$P(A/A; \tau) = c \cdot dt \sum_{k=1,3,5,\dots} P_y(k, \tau) \quad \tau \neq 0$$

⊕ - VETORADIN VO t_2 DA IMA KODS

(⊕) - VETORADIN VO t_2 DA IMA A. KODS $A \equiv$ VO τ IMA NEKOLIKI KODS

$$P(-A/A; \tau) = c \cdot dt \sum_{k=2,4,6,\dots} P_y(k, \tau)$$

$$P_y(\tau) = 2A^2 \cdot c \cdot dt \left[\sum_{k=1,3,5,\dots} P_y(k, \tau) - \sum_{k=2,4,6,\dots} P_y(k, \tau) \right]$$

$$= A^2 (c \cdot dt)^2 \left[\sum_{k=1,3,5,\dots} \frac{(c \cdot dt)^k}{k!} e^{-c \cdot dt} - \sum_{k=2,4,6,\dots} \frac{(c \cdot dt)^k}{k!} e^{-c \cdot dt} \right] =$$

$$= A^2 (c \cdot dt)^2 \left[\sum_{k=0}^{\infty} \frac{(c \cdot dt)^k}{k!} e^{-c \cdot dt} - \sum_{k=0}^{\infty} \frac{(c \cdot dt)^k}{k!} e^{-c \cdot dt} - \sum_{k=0}^{\infty} \frac{(c \cdot dt)^k}{k!} e^{-c \cdot dt} + \sum_{k=0}^{\infty} \frac{(c \cdot dt)^k}{k!} e^{-c \cdot dt} \right]$$

$$= \frac{A^2 (c \cdot dt)^2}{2} \left[-2 \sum_{k=0}^{\infty} \frac{(c \cdot dt)^k}{k!} e^{-c \cdot dt} \right] = -A^2 (c \cdot dt)^2 e^{-c \cdot dt} \sum_{k=0}^{\infty} \frac{(c \cdot dt)^k}{k!}$$

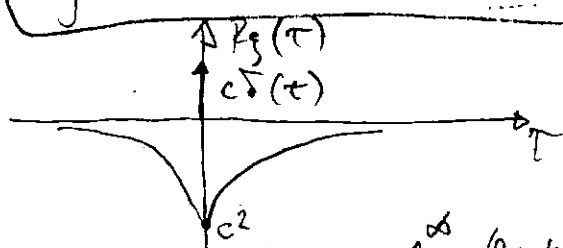
$$P_y(\tau) = -A^2 c^2 dt^2 e^{-c \cdot dt} = -c^2 e^{-2c \cdot dt} = -c^2 e^{-2c \cdot dt}$$

$$t > 0 \quad P_y(\tau) = -c^2 e^{-2c \cdot dt}$$

$$t = 0 \quad P(A/A; 0) = 1 \quad P(-A/A; 0) = 0$$

$$Z_y(0) = 2A \cdot \frac{c \cdot dt}{2} \cdot 1 = A^2 c \cdot dt = A \cdot c \Big|_{A \rightarrow \infty} = c \delta(\tau)$$

$$P_y = c \delta(\tau) - c^2 e^{-2c \cdot dt} \quad t \geq 0$$



$$\Phi(\omega) = \int P_y(\tau) e^{-j\omega \tau} d\tau =$$

$$= c - c^2 \int_0^{\infty} e^{-2c \tau} e^{-j\omega \tau} d\tau =$$

$$= c + 2c^2 \int_0^{\infty} e^{-(2c+j\omega)\tau} d\tau \Big|_{(2c+j\omega)\tau} = c + 2c^2 \frac{1}{2c+j\omega} e^{-(2c+j\omega)\tau} \Big|_0^{\infty} = c - \frac{2c^2}{2c+j\omega}$$

$$\Phi_g(\omega) = c - \frac{2c^2}{2c + j\omega} = c - \frac{2c^2(2c - j\omega)}{4c^2 + \omega^2} = c - \frac{4c^3}{4c^2 + \omega^2} + \frac{2c^2 \omega}{4c^2 + \omega^2}$$

$$\Phi_g(\omega) = c - \frac{4c^3}{4c^2 + \omega^2}$$

$$\Phi_g(\omega) = c - c^2 \int_{-\infty}^{\infty} e^{-2ct} e^{-j\omega t} dt = c - c^2 \int_{-\infty}^{\infty} e^{-2ct} (\cos \omega t - j \sin \omega t) dt$$

$$\Phi_g(\omega) = c - c^2 \int_{-\infty}^{\infty} e^{-2ct} \cos(\omega t) dt = c - c^2 \cdot 2 \int_0^{\infty} e^{-2ct} \cos \omega t dt$$

$$I = \int_{-\infty}^{\infty} e^{-ax} e^{j\omega x} dx = \frac{2a}{a^2 + \omega^2}$$

$$I = \int_{-\infty}^0 e^{+ax} e^{j\omega x} dx + \int_0^{\infty} e^{-ax} e^{j\omega x} dx =$$

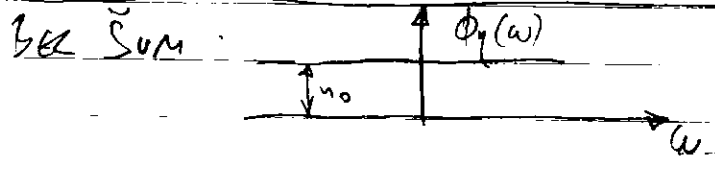
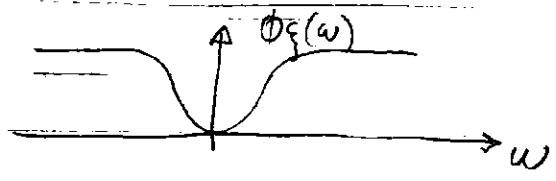
$$= \int_{-\infty}^0 e^{(a+j\omega)x} dx + \int_0^{\infty} e^{-(a-j\omega)x} dx = \frac{1}{a+j\omega} e^{(a+j\omega)x} \Big|_{-\infty}^0 - \frac{1}{a-j\omega} e^{-(a-j\omega)x} \Big|_0^{\infty}$$

$$= \frac{1}{a+j\omega} + \frac{1}{a-j\omega} = \frac{2}{a+j\omega} \cdot \frac{a-j\omega}{a-j\omega} = \frac{2a - j\omega}{a^2 + \omega^2}$$

$$\text{Re}\{I\} = \frac{2a}{a^2 + \omega^2}$$

$$\text{Im}\{I\} = \frac{-\omega}{a^2 + \omega^2}$$

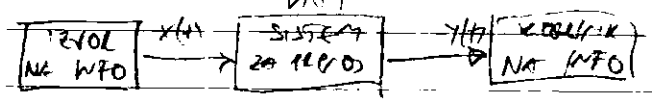
$$\Phi_g(\omega) = c - \frac{4c^3}{4c^2 + \omega^2}$$



$$R_p(\tau) = \frac{1}{2\pi} \int_{-\infty}^{\infty} n_0 e^{j\omega \tau} d\omega$$

$$R_p(\tau) = n_0 \delta(\tau)$$

Princip NA SVU (NM) procesi NIZ LINEARNI SP.



$$y(t) = \int_{-\infty}^{\infty} h(\tau) x(t-\tau) d\tau$$

$$y(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau =$$

$$= \int_{-\infty}^{\infty} h(\tau) x(t-\tau) d\tau = x(t) \int_{-\infty}^{\infty} h(\tau) d\tau$$

$$H(\omega) = \int_{-\infty}^{\infty} h(t) e^{-j\omega t} dt \quad F^{-1}(\omega) = \int_{-\infty}^{\infty} f(t) dt$$

SP. VEED

$$\boxed{Y(\omega) = H(\omega) X(\omega)}$$

SP. GUSI. NA VIKRA $\Phi_{YY}(\omega)$

$$R_{YY}(\tau) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T y(t) y(t+\tau) dt$$

$$= \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T \left\{ \int_{-\infty}^{\infty} h(\mu) x(t-\mu) d\mu \int_{-\infty}^{\infty} h(\sigma) x(t+\tau-\sigma) d\sigma \right\} dt =$$

$$= \int_{-\infty}^{\infty} h(\mu) d\mu \int_{-\infty}^{\infty} h(\sigma) d\sigma \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T x(t-\mu) x(t+\tau-\sigma) dt$$

$$R_{XX}(x+\tau-\sigma, t+\mu) = R_{XX}(\tau+\mu-\sigma)$$

$$R_{YY}(\tau) = \int_{-\infty}^{\infty} h(\mu) d\mu \int_{-\infty}^{\infty} h(\sigma) R_{XX}(\tau+\mu-\sigma) d\sigma$$

$$\Phi_{YY}(\omega) = \int_{-\infty}^{\infty} e^{-j\omega\tau} d\tau \int_{-\infty}^{\infty} h(\mu) d\mu \int_{-\infty}^{\infty} h(\sigma) R_{XX}(\tau+\mu-\sigma) d\sigma$$

$$v = \mu + \tau - \sigma \quad \tau = v - \mu + \sigma \quad d\tau = dv$$

$$\Phi_{YY}(\omega) = \int_{-\infty}^{\infty} e^{-j\omega(v-\mu+\sigma)} dv \int_{-\infty}^{\infty} h(\mu) e^{+j\omega\mu} d\mu \int_{-\infty}^{\infty} h(\sigma) R_{XX}(v) d\sigma =$$

$$= \int_{-\infty}^{\infty} h(\mu) e^{+j\omega\mu} d\mu \int_{-\infty}^{\infty} h(\sigma) e^{-j\omega\sigma} d\sigma \int_{-\infty}^{\infty} R_{XX}(v) e^{-j\omega v} dv$$

$$= H^*(j\omega) \cdot H(j\omega) \cdot \Phi_{XX}(\omega) = |H(j\omega)|^2 \Phi_{XX}(\omega)$$

$$R_{XX}(\tau) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T x(t) x(t+\tau) dt = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T x(t) dt \int_{-\infty}^{\infty} h(\mu) x(t+\tau-\mu) d\mu$$

$$= \int_{-\infty}^{\infty} h(\mu) d\mu \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T x(t) x(t+\tau-\mu) dt$$

$$R_{yy}(\tau) = \int_{-\infty}^{\infty} h(\mu) R_{yy}(\tau - \mu) d\mu$$

KORVOLICITA OD KAPLICEVOST
ODNIV I AVTOKORRELACIJSKI NA
VNEŠNOSTI SLOKAZ

$$\boxed{\Phi_{yy}(\omega) = |H(j\omega)|^2 \Phi_{yy}(\omega)}$$

VLEČIO - IZVEŠTA
ODNIV I AVTOKORRELACIJSKI
VNEŠNOSTI SLOKAZ

2157

• AVTOKORRELACIJA NA KAPLICEVOSTI ODRUČEN

$$R_{yy}(\tau) = \int_{-\infty}^{\infty} h(\mu) d\mu \int_{-\infty}^{\infty} h(\sigma) R_{yy}(\tau + \mu - \sigma) d\sigma \quad t = \sigma - \mu$$

$$\sigma = t - \mu \quad d\sigma = dt = \int_{-\infty}^{\infty} h(\mu) d\mu \int_{-\infty}^{\infty} h(t - \mu) R_{yy}(\tau - t) dt$$

$$= \int_{-\infty}^{\infty} \underbrace{h(t - \mu) h(t - \mu)}_{R_{hh}(t)} d\mu \int_{-\infty}^{\infty} R_{yy}(\tau - t) dt = \int_{-\infty}^{\infty} R_{hh}(t) R_{yy}(\tau - t) dt$$

$$\Phi_y(\omega) = |H(j\omega)|^2 \Phi_x(\omega)$$

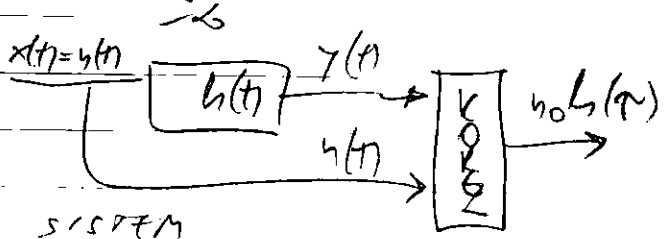
$$R_{hh}(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} |H(j\omega)|^2 e^{j\omega t} d\omega$$

• ODRUČENOST NA K-KI NA LINEARNI SISTEM SO NEODR-
REKCIJA

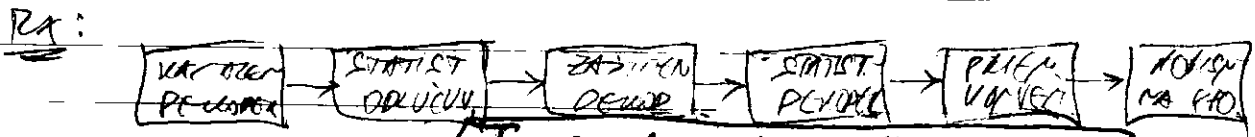
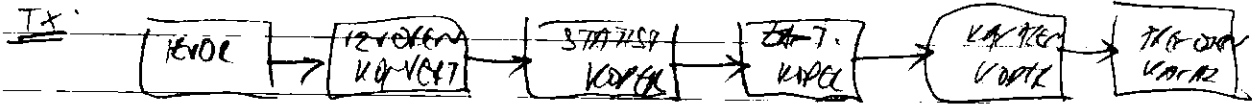
$$x(t) = u(t) \quad R_{xx} = u_0 \delta(\tau)$$

$$R_{yy}(\tau) = \int_{-\infty}^{\infty} h(\mu) R_{xx}(\tau - \mu) d\mu = \int_{-\infty}^{\infty} h(\mu) u_0 \delta(\tau - \mu) d\mu$$

$$\boxed{R_{yy}(\tau) = u_0 h(\tau)}$$



• Model NA KOMUNIKACIONI SISTEM



TEORIJA NA INFORMACIJA

$$S = \{s_1, s_2, \dots, s_n\} \quad 2 \text{ DISKRETNI SIMBOLI}$$

$$\{P(s_i)\}; \quad i=1, 2, \dots, n \quad 9 \text{ VELOČASTIČNOST NA IZVODNOSTI NA SIMBOLU}$$

$$\sum_{i=1}^n P(s_i) = 1$$

$$I(s_i) \sim \frac{1}{P(s_i)}$$

$$I_i, I_j; \quad I(S_i, S_j) = \frac{1}{I(S_i)I(S_j)} = \frac{1}{P(S_i)P(S_j)}$$

$$I(S) = \log_a \frac{1}{P(S)} \quad I(S_i, S_j) = \log_a \frac{1}{P(S_i)P(S_j)} = \log_a \frac{1}{P(S_i)} + \log_a \frac{1}{P(S_j)}$$

$$I(S_i, S_j) = I(S_i) + I(S_j)$$

$$(1) \quad I(S_i) = \log_{10} \frac{1}{P(S_i)} \quad [\text{Hercex}], \quad I(S_i) = \log_2 \frac{1}{P(S_i)} \quad [\text{Lut}]$$

$$(2) \quad I(S_i) = \log_2 \frac{1}{P(S_i)} = \log_2 \frac{1}{P(S_i)} = -\log_2 P(S_i) \quad [\text{SL}]$$

2.110

Pravilni izračun na informaciji iz množice

ENTROPJA - PROSEČNO KOLIČESTVO NA KJ ODMARČA TO SKLAD

$$H(S) = \sum_{i=1}^n I(S_i) P(S_i) = \sum_{i=1}^n P(S_i) \log_2 \frac{1}{P(S_i)} = H(S)$$

PROSEČNA KOLIČESTVO ZA ODMARČA NA ODMARČENI SIMBOLI

$$S = \{S_1, S_2, \dots, S_n\}$$

0113 22.07.07

Primer (2.110. 2.110)

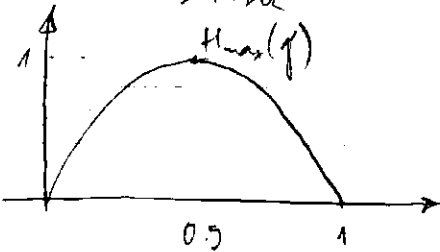
$$S = \{S_1, S_2\} = \{0, 1\}$$

S_i	$P(S_i)$
S_1	p
S_2	$1-p$

$$H(S) = \sum_{i=1}^2 P(S_i) \log_2 \frac{1}{P(S_i)} = p \log_2 \frac{1}{p} + (1-p) \log_2 \frac{1}{1-p}$$

$$H(S) (=) \frac{S_1}{\text{SIMBOL}}$$

$$H(p) (=) \frac{S_2}{\text{BIT}}$$



$$H'(S) = \left(-p \frac{\ln(p)}{\ln(2)} - (1-p) \frac{\ln(1-p)}{\ln(2)} \right)'$$

$$= -\frac{\ln(p)}{\ln(2)} - p \frac{1}{p \ln(2)} + \frac{\ln(1-p)}{\ln(2)} + \frac{(1-p)}{\ln(2)} \frac{1}{1-p}$$

$$\log_x = \frac{\ln(x)}{\ln(2)}$$

$$-\ln(p) + 1 + \ln(1-p) + 1 = 0$$

$$\ln(p) = \ln(1-p)$$

$$\ln\left(\frac{1-p}{p}\right) = 0 \Rightarrow$$

$$\frac{1-p}{p} = 1$$

$$1-p = p$$

$$2p = 1$$

$$p = \frac{1}{2}$$

$$H(S) = H_{\max} = 1$$

$$H = \frac{1}{2} \log_2 2 + \frac{1}{2} \log_2 2 = \frac{1}{2} + \frac{1}{2} = 1$$

$$H(S) \geq 0$$

$$H'(S)_{\max} = \log_2 2$$

$$2 = \frac{1}{P(S_i)}$$

$$P(S_i) = \frac{1}{2}$$

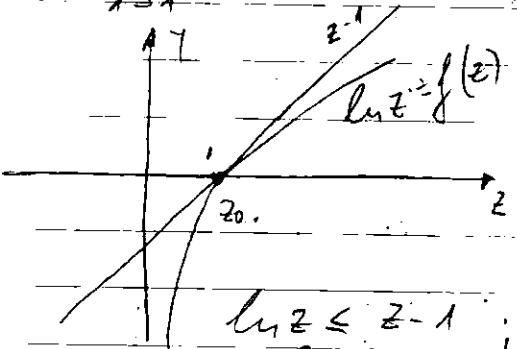
$$H(S)_{\max} = \sum_{i=1}^2 \frac{1}{2} \log_2 2 = 2 \cdot \frac{1}{2} \cdot \log_2 2 = \log_2 2$$

POKAZ:

$$\log_2 H(s) = \log_2 \left(\prod_{i=1}^n P(s_i) \right) \log_2 \frac{1}{P(s_i)} =$$

$$= \sum_{i=1}^n \frac{1}{2} \log_2 \frac{1}{P(s_i)} = \sum_{i=1}^n P(s_i) \log_2 \frac{1}{P(s_i)} = \sum_{i=1}^n P(s_i) \left[-\log_2 \frac{1}{P(s_i)} \right]$$

$$= - \sum_{i=1}^n P(s_i) \log_2 \frac{1}{P(s_i)} = \frac{1}{\ln 2} \sum_{i=1}^n P(s_i) \ln \frac{1}{P(s_i)}$$



$$y = f'(z_0)(z - z_0)$$

$$y = \frac{1}{z_0}(z - 1) = 1(z - 1) = z - 1$$

TANGENTA NA $f(z)$ VO z_0

$$\ln z \leq z - 1 \quad ; \quad -\ln z \geq 1 - z$$

$$\Rightarrow \frac{1}{\ln 2} \sum_{i=1}^n P(s_i) \left[1 - \frac{1}{P(s_i)} \right] = \frac{1}{\ln 2} - \frac{1}{\ln 2} = 0$$

$$\log_2 H(s) \geq 0 \quad ; \quad H(s) \leq \log_2 \Rightarrow \boxed{H_{max}(s) = \log_2}$$

INFORMACIONEN DEKUS $\Phi(s) = H(s) \cdot \sigma(s)$

$\sigma(s)$ - VEŠTINA NA SEČENJE NA ŠKALOVIŠE VO IZVODU

$$\Phi(s) = \frac{sh}{sm} \cdot \frac{sm}{sec} = \frac{sh}{sec} \quad \Phi(s) = \left[\frac{sh}{sec} \right]$$

PROJEKCIJA NA DISKRETEN IZVOD BČE METOD

PROJEKCIJA OD 2 RED (SEČENJE SO POLJE 2)

$$s = \{s_1, s_2\} = \left\{ \frac{0, 1}{2} \right\}$$

s_i	$P(s_i)$
s_1	$P(s_1)$
s_2	$P(s_2)$

$$w = \{w_1, w_2, w_3, w_4\} = \{00, 01, 10, 11\}$$

43:17

PROJEKCIJA OD 2 RED BČE:

$$s = \{s_1, s_2, \dots, s_n\}$$

$$w_i = \{s_{i1}, s_{i2}, \dots, s_{in}\}$$

$$P(w_i) = P(s_{i1}, s_{i2}, \dots, s_{in}) = \prod_{k=1}^n P(s_{ik})$$

w_i	$P(w_i)$
w_1	$P(s_{11}) \cdot P(s_{12}) \cdot \dots \cdot P(s_{1n})$
w_2	
\vdots	
w_m	

$$H(w) = \sum_{i=1}^{2^n} P(w_i) \log_2 \frac{1}{P(w_i)}$$

$$H(w) = n \cdot H(s)$$

34:18

$$\begin{aligned}
 H(W) &= \sum_{i=1}^{2^n} P(w_i) \log \frac{1}{P(w_i)} = \sum_{i=1}^{2^n} P(w_i) \log \frac{1}{P(s_{i_1})P(s_{i_2}) \dots P(s_{i_n})} = \\
 &= \sum_{i=1}^{2^n} P(w_i) \log \frac{1}{P(s_{i_n})} = \sum_{i=1}^{2^n} P(w_i) \log \frac{1}{P(s_{i_2})} + \dots + \sum_{i=1}^{2^n} P(w_i) \log \frac{1}{P(s_{i_1})} = (*) \\
 &= \sum_{i=1}^{2^n} P(w_i) \log \frac{1}{P(s_{i_n})} = \sum_{i=1}^{2^n} [P(s_{i_1})P(s_{i_2}) \dots P(s_{i_n})] \log \frac{1}{P(s_{i_n})} = \\
 &= \sum_{i_1=1}^2 P(s_{i_1}) \log \frac{1}{P(s_{i_1})} \underbrace{\sum_{i_2=1}^2 P(s_{i_2}) \dots \sum_{i_n=1}^2 P(s_{i_n})}_1 = H(S)
 \end{aligned}$$

$$(*) = n \cdot H(S)$$

$$H(W) = n \cdot H(S)$$

DISKRETI IZVODI SO MEMORIJOM

$$\begin{aligned}
 K_S &= \{s_1, s_2, \dots, s_2\} \\
 P(s_i / s_{j_1, j_2, \dots, j_{p-1}, j_{p+1}, \dots, j_k}) & \quad \begin{matrix} i = 1, 2, \dots, 2 \\ j = 1, 2, \dots, 2 \end{matrix}
 \end{aligned}$$

VEROVATNOSTA NA ENA SOBOTATA

$$P(s_{j_1, j_2, \dots, j_{p-1}, j_{p+1}, \dots, j_k}), \quad j_r = 1, 2, \dots, 2$$

SUKUPINO

$$P(S_p) \quad p = 1, 2, \dots, 2^k$$

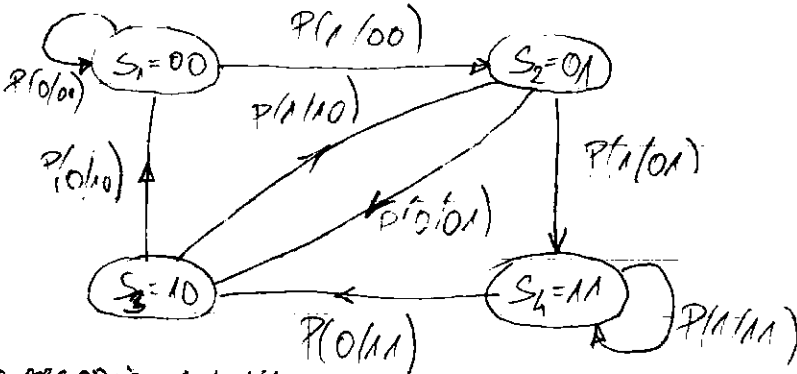
S - SOBOTATA
j - SIMBOL

$$P(s_i / S_p) \quad \begin{matrix} i = 1, 2, \dots, 2 \\ p = 1, 2, \dots, 2^k \end{matrix}$$

• MARKOV IZVOD OD VTOR RED:

$$P(s_i / S_p) \quad s_i \in (0, 1) \quad S_p \in (\infty, 0, 1, 10, 11)$$

$$2^k = 2^2 = 4 \text{ SOBOTATA} \quad 2 \text{ SIMBOL}$$



$$\sum_{i=1}^2 P(s_i / S_p) = 1 \quad p = 1, 2, 3, 4$$

$$P(s_i / S_p) \neq 0 \quad \begin{matrix} i = 1, 2 \\ p = 1, 2, 3, 4 \end{matrix}$$

ERGODICEN MARKOV IZVOD

• ERGODICEN IZVOD NA MARKOV IZVOD OD K-TI RED

$$P(s_i / S_p) \neq 0 \quad \begin{matrix} i = 1, 2, \dots, 2 \\ p = 1, 2, \dots, 2^k \end{matrix}$$

INFORMACIJA NA MARKOV IZVOR

$$I(x/s_r) = \sum_{i=1}^q \frac{1}{P(s_i/s_r)} \log \frac{1}{P(s_i/s_r)}$$

$$s_r = (s_{j1}, s_{j2}, \dots, s_{jr}, \dots, s_{jk})$$

$$j = 1, 2, \dots, q$$

$$H(x/s_r) = \sum_{i=1}^q P(s_i/s_r) \log \frac{1}{P(s_i/s_r)} = I(x/s_r)$$

INFORMACIJA ENTROPIJA = PROSEČNO VOJICEVNO INFORMACIJA PO SIMBOLU
 POSEBA IZLOČIT SE NAČINA VO BOLA IMAJA SPECIF. SOSTAVA

$$H(x) = H(x/s_r) = \sum_{r=1}^q \sum_{i=1}^q P(s_i) \log \frac{1}{P(s_i/s_r)}$$

INFORMACIJA IZVOR NA INFORMACIJA

$$P(s_1) = P(s_{11})P(0/s_1) + P(s_{12})P(0/s_1)$$

$$P(s_2) = P(s_{21})P(1/s_2) + P(s_{22})P(1/s_2)$$

$$P(s_3) = P(s_{31})P(0/s_3) + P(s_{32})P(0/s_3)$$

$$P(s_4) = P(s_{41})P(1/s_4) + P(s_{42})P(1/s_4)$$

$$s \in (-\infty, \infty) \text{ or } f(s)$$

$$H(s) = \int_{-\infty}^{\infty} f(s) \log \frac{1}{f(s)} ds = \int_{-\infty}^{\infty} f(s) \log \frac{1}{f(s)} ds \quad (=) \frac{sh}{\text{sample}}$$

$$D(s) = f(s) \cdot v(s) (=) \frac{sh}{\text{sec}} \cdot \frac{1}{\text{sec}} (=) \frac{sh}{\text{sec}}$$

$$T_s \leq \frac{1}{2f_g} \quad \frac{1}{f_s} \leq \frac{1}{2f_g} \quad (f_s \geq 2f_g)$$

$$v(s) = 2f_g \quad (D(s) = 2f_g H(s))$$

2. TIP NA KONTINUACIJA IZVOR

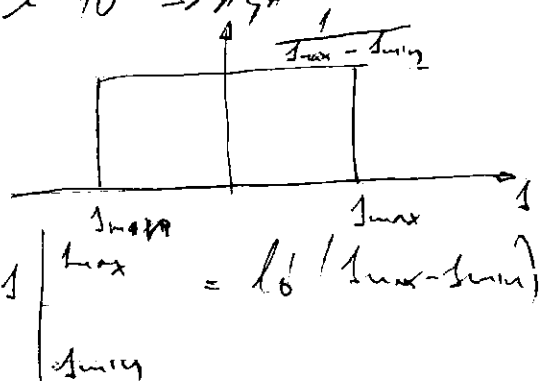
(a) $s \in [s_{min}, s_{max}]$

OSKARICEN PO ~~S~~ AMPLITUDE

(b) $s \in (-\infty, \infty)$

OSKARICEN PO ~~S~~ FREKVENCIA

(a) $H(s) = \int_{s_{min}}^{s_{max}} p(s) \log \frac{1}{p(s)} ds$



$$H_{max}(s) = \frac{1}{s_{max} - s_{min}} \log(s_{max} - s_{min}) \quad \left| \begin{matrix} s_{max} \\ s_{min} \end{matrix} \right. = \log(s_{max} - s_{min})$$

$$s_{max} = 1g \quad s_{min} = -1g \quad (H_{max}(s) = \log(21g))$$

$$\textcircled{8} \quad \int_{-\infty}^{\infty} \delta^2 \gamma(s) ds < \infty \quad \gamma(s) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{s^2}{2\sigma^2}}$$

$$H(s) = \int_{-\infty}^{\infty} \gamma(s) \ln \left| \frac{1}{\gamma(s)} \right| ds = \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{s^2}{2\sigma^2}} \left(\ln \left(\sqrt{2\pi\sigma^2} e^{\frac{s^2}{2\sigma^2}} \right) \right) ds$$

$$\ln \frac{1}{\gamma(s)} = \ln \sqrt{2\pi\sigma^2} + \ln e^{\frac{s^2}{2\sigma^2}}$$

$$\ln \sqrt{2\pi\sigma^2} = 2.26 \quad \ln e^{\frac{s^2}{2\sigma^2}} = \frac{s^2}{2\sigma^2}$$

$$\textcircled{9} = \frac{1}{\ln 2} \left[\ln \sqrt{2\pi\sigma^2} + \ln e^{\frac{s^2}{2\sigma^2}} \right]$$

$$H(s) = \frac{1}{\ln 2 \sqrt{2\pi\sigma^2}} \int_{-\infty}^{\infty} e^{-\frac{s^2}{2\sigma^2}} \left[\ln \sqrt{2\pi\sigma^2} + \frac{s^2}{2\sigma^2} \right] ds =$$

$$= \frac{1}{\ln 2 \sqrt{2\pi\sigma^2}} \left[\underbrace{\ln \sqrt{2\pi\sigma^2} \int_{-\infty}^{\infty} e^{-\frac{s^2}{2\sigma^2}} ds}_{I_1} + \underbrace{\int_{-\infty}^{\infty} \frac{s^2 e^{-\frac{s^2}{2\sigma^2}}}{2\sigma^2} ds}_{I_2} \right]$$

$$I_1 = \int_{-\infty}^{\infty} e^{-u^2} du = \sqrt{\pi} \quad \left(u = \frac{s}{\sqrt{2\sigma^2}}, \quad du = \frac{ds}{\sqrt{2\sigma^2}} \right) = \sqrt{2\sigma^2} \int_{-\infty}^{\infty} e^{-u^2} du = \sqrt{2\pi\sigma^2}$$

$$I_2 = \int_{-\infty}^{\infty} \frac{s^2 e^{-\frac{s^2}{2\sigma^2}}}{2\sigma^2} ds = \frac{1}{\sqrt{2\pi\sigma^2}} \cdot \frac{\sqrt{\pi}}{\sqrt{2\sigma^2}} \int_{-\infty}^{\infty} s^2 e^{-\frac{s^2}{2\sigma^2}} ds$$

$$I_2 = \frac{\sqrt{\pi}}{\sqrt{2\sigma^2}} \cdot \sigma^2 = \frac{\sqrt{\pi}\sigma}{\sqrt{2}} = \frac{\sqrt{\pi}}{2} \sigma$$

$$H(s) = \frac{1}{\ln 2 \sqrt{2\pi\sigma^2}} \left(\ln \sqrt{2\pi\sigma^2} \cdot \sqrt{2\pi\sigma^2} + \frac{\sqrt{\pi}}{2} \sigma \right)$$

$$H(s) = \ln \sqrt{2\pi\sigma^2} + \frac{1}{\ln 2 \sqrt{2\pi\sigma^2}} \frac{\sqrt{\pi}}{2} \sigma = \ln \sqrt{2\pi\sigma^2} + \frac{1}{2 \ln 2} \frac{\sqrt{\pi}}{\sqrt{\sigma^2}}$$

$$H(s) = \ln \sqrt{2\pi\sigma^2} + \frac{\ln e}{2 \ln 2} = \ln \sqrt{2\pi\sigma^2} + \frac{\ln e}{2 \ln 2} = \ln \sqrt{2\pi e \sigma^2}$$

$$\boxed{H_{\max}(s) = \ln \sqrt{2\pi e \sigma^2}}$$

$$H(s) \leq H_{\max}(s)$$

STATISTIČNO KODIRANJE

21:36

$s_i \rightarrow X_i = \{x_{i1}, x_{i2}, \dots, x_{ik}, \dots, x_{in}\}$ $i = 1, 2, \dots, 2$
ŠIFRA NA KODIRANJU
 $x_{jk} \in \{x_1, x_2, \dots, x_m\}$ KODIRANJE

$m^n = 2$

$n = \log_m 2$

$$Z(x) = \sum_{i=1}^2 l_i p(s_i) = \sum_{i=1}^2 k_i p(s_i)$$

DOLŽINA ČA ZAPISKA:

$\left\lceil \frac{k}{2} \right\rceil l_{min} < l < \left\lfloor \frac{k+1}{2} \right\rfloor l_{max}$

k - ŠIFRA ČA KODIRANJA

s_i	s_0	s_1
s_1	0	1
s_2	11	
s_3	100	
s_4	101	

• $k=1$ $\left\lceil \frac{1}{2} \right\rceil \cdot 1 < l < \left\lfloor \frac{1+1}{2} \right\rfloor \cdot 3$

$1 < l < [1] \cdot 3$ $1 < l < 3$

• s_0, s_1, s_2 ($k=3$)
 $\left\lceil \frac{3}{2} \right\rceil \cdot 2 < l < \left\lfloor \frac{4}{2} \right\rfloor \cdot 3$

$4 < l < 6$

• KRAFTOVO NEURAVENSTVO:

$$\sum_{i=1}^2 m^{-l_i} \leq 1$$

$l_i = \{l_1, l_2, \dots, l_2\}$

$N(l_i) \Rightarrow$ ŠIFRA NA KODIRANJU ZAPOVI SO DOLŽINA l_i

$$\sum_{i=1}^{l_{max}} N(l_i) \leq 2$$

• OSNOVNA TEOREMA NA STATISTIČNO KODIRANJE

$$Z(x) \geq \frac{H(S)}{l_{min}}$$

$$Z(x)_{min} = \frac{H(S)}{l_{min}}$$

$S = \{s_1, s_2, \dots, s_2\}; \{p(s_1), p(s_2), \dots, p(s_2)\}$

KODIRANJE: $X = \{x_1, x_2, \dots, x_m\}$

$L = \{l_1, l_2, \dots, l_2\}$

$x_i \geq 0 \quad \sum_{i=1}^2 x_i = 1$

$y_i \geq 0 \quad \sum_{i=1}^2 y_i = 1$

$$\sum_{i=1}^2 x_i l_i^{\frac{y_i}{x_i}} = \frac{1}{l_{min}} \sum_{i=1}^2 x_i l_{min}^{\frac{y_i}{x_i}}$$

$$l_{min} Z \leq 2 - 1$$

$$f(x) = 1 + x f'(0) + \frac{x^2}{2} f''(0) + \frac{x^3}{3!} f'''(0)$$

$$(\ln x)' = \frac{1}{x} \quad (\ln x)'' = \left(\frac{1}{x}\right)' = -\frac{1}{x^2}$$

$$\frac{1}{\ln 2} \sum_{i=1}^2 x_i \ln \frac{y_i}{x_i} \leq \frac{1}{\ln 2} \sum_{i=1}^2 x_i \left(\frac{y_i}{x_i} - 1\right) = \frac{1}{\ln 2} \left[\sum_{i=1}^2 y_i - \sum_{i=1}^2 x_i \right]$$

$$\sum_{i=1}^2 x_i \left(\ln \frac{1}{x_i} + \ln y_i \right) = \sum_{i=1}^2 x_i \ln \frac{1}{x_i} - \sum_{i=1}^2 x_i \ln \frac{1}{y_i} = 0$$

$$\left[\sum_{i=1}^2 x_i \ln \frac{1}{x_i} \leq \sum_{i=1}^2 x_i \ln \frac{1}{y_i} \right] \quad x_i = P(s_i)$$

$$\sum_{i=1}^2 x_i \ln \frac{1}{x_i} = \sum_{i=1}^2 P(s_i) \ln \frac{1}{P(s_i)} = H(S)$$

$$y_i = \frac{1}{\sum_{j=1}^2 w^{-l_j}}, \quad i=1, 2, \dots, 2$$

$$H(S) = \sum_{i=1}^2 P(s_i) \ln \frac{1}{P(s_i)} \leq \sum_{i=1}^2 P(s_i) \ln \frac{\sum_{j=1}^2 w^{-l_j}}{w^{-l_i}} =$$

$$= \sum_{i=1}^2 P(s_i) \ln \sum_{j=1}^2 w^{-l_j} - \sum_{i=1}^2 P(s_i) \ln (w^{-l_i})$$

$$= \ln \sum_{i=1}^2 w^{-l_i} + \sum_{i=1}^2 P(s_i) l_i \ln w$$

$$H(S) \leq \ln \sum_{i=1}^2 w^{-l_i} + \sum_{i=1}^2 P(s_i) l_i \ln w$$

$$H(S) \leq \ln \sum_{i=1}^2 w^{-l_i} + \ln(w) \cdot \sum_{i=1}^2 P(s_i) l_i$$

$$H(S) \leq \ln(w) \cdot L_n(x)$$

$$\ln(x) \geq \frac{H(S)}{\ln(w)} = H_n(S)$$

$$H_n(S) = \frac{1}{\ln(w)} \sum_{i=1}^2 P(s_i) \ln \frac{1}{P(s_i)} = \frac{1}{\ln(w)} \sum_{i=1}^2 P(s_i) \frac{\ln \frac{1}{P(s_i)}}{\ln 2}$$

$$= \sum_{i=1}^2 P(s_i) \log_w \frac{1}{P(s_i)} \quad \log_w x = \frac{\ln x}{\ln(w)}$$

$$i \rightarrow P(s_i) = \frac{w_i}{\sum_{j=1}^n w_j} \quad i=1,2,\dots,n$$

$$P(s_i) = w_i^{-l_i} \quad i=1,2,\dots,n \quad L_m(x)_{min} = \frac{H(s)}{\log(m)}$$

OSNOVNA TEOREMA NA STAT. KODIRANJE

$$L_m(x) = \sum_{i=1}^n l_i P(s_i)$$

$$L_m(x) \geq \frac{H(s)}{\log(m)} \quad ; \quad L_m(x) = \frac{H(s)}{\log(m)} \quad \text{ZA } P(s_i) = w_i^{-l_i}$$

PRIMER: $L_2(x) = L_m(x) \geq \frac{H(s)}{\log(2)} = H(s) \quad [L_2(x) \geq H(s)]$

$$P(s_i) = w_i^{-l_i} / \log \quad \log P(s_i) = -l_i \log m$$

$$l_i = \frac{\log P(s_i)}{\log m}$$

$$l_i = \left\lceil \log_m \frac{1}{P(s_i)} \right\rceil = \left\lceil \frac{\log \frac{1}{P(s_i)}}{\log m} \right\rceil \quad i=1,2,\dots,n$$

$$\frac{H(s)}{\log m} \leq L_m(x) \leq \frac{H(s)}{\log m} + 1$$

PRVA SHANNONOVA TEOREMA

$$\frac{H(s)}{\log m} \leq L_m(x^n) \leq \frac{H(s^n)}{\log(m)} + 1$$

$$\frac{n \cdot H(s)}{\log m} \leq L_m(x^n) \leq \frac{n \cdot H(s)}{\log(m)} + 1$$

$$\frac{H(s)}{\log m} \leq \frac{L_m(x^n)}{n} \leq \frac{H(s)}{\log(m)} + \frac{1}{n}$$

$$\lim_{n \rightarrow \infty} \frac{L_m(x^n)}{n} = \frac{H(s)}{\log m}$$

110-111
 112 NA
 113 ZA HCA
 PO SIMAD
 OD DRIS LISTA

METODI ZA OPTIMIZIRANO KODIRANJE

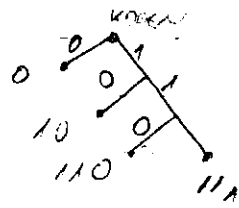
• FANOVA POTAŠKA:

$$L_i = \frac{\log P(s_i)}{\log m}$$

$$P(s_i) = \frac{1}{m^{L_i}}$$

$$P(s_i) = \left(\frac{1}{m}\right)^{L_i}$$

s_i	$P(s_i)$			x_i
s_1	$\frac{1}{2}$	I		0
s_2	$\frac{1}{4}$	II	I	10
s_3	$\frac{1}{8}$		II	I
s_4	$\frac{1}{8}$	II	II	111



$m=2$

$$L_2(x) = \sum_{i=1}^4 L_i P(s_i) = 1 \cdot \frac{1}{2} + 2 \cdot \frac{1}{4} + 3 \cdot \frac{1}{8} + 3 \cdot \frac{1}{8} = \frac{4 + 4 + 3 + 3}{8} = \frac{14}{8}$$

$$L_2(11) = \frac{7}{4}$$

$$H(s) = \sum_{i=1}^4 P(s_i) \log \frac{1}{P(s_i)} = \frac{1}{2} \cdot \log 2 + \frac{1}{4} \cdot \log 4 + \frac{1}{8} \cdot \log 8 + \frac{1}{8} \cdot \log 8$$

$$H(s) = \frac{1}{2} + \frac{1}{2} + \frac{3}{8} + \frac{3}{8} = \frac{4 + 4 + 3 + 3}{8} = \frac{14}{8} = \frac{7}{4} = 1.75$$

$L(s) \approx H(s)$ NUMERIČNA KODIRANJE

$L(s) = 1.75$ SIMBOL $H(s) = 1.75$ SIMBOL

EFIKASNOST I REDUNDANCA NA STATISTIČKIM KODIRANJIMA

$$\eta = \frac{H_m(s)}{L_m(x)} = \frac{H(s)}{\log(m) L_2(x)}$$

$$\eta \rightarrow 1$$

$$L_m(x) \approx H_m(s)$$

PROBIRANJE IZVORA:

$$\eta = \frac{H_m(s)}{H_m(s) + \frac{1}{m}} = \frac{H(s)}{H(s) + \frac{\log m}{m}}$$

$$\eta = m^y \quad y = \log_m \eta$$

$$S_{\text{red}} = \frac{y}{L_m(x) \log m} = \frac{\lceil \log_m 2 \rceil}{\sum_{i=1}^4 P(s_i) \lceil \log_m \frac{1}{P(s_i)} \rceil} = \left| \begin{array}{l} m=2 \\ \text{BROJNO} \\ \text{KODIRANJE} \end{array} \right|$$

$$S_{\text{red}} = S_r = \frac{\lceil \log_2 2 \rceil}{L_2(x)} = \frac{\lceil \log_2 2 \rceil}{\sum_{i=1}^4 L_i P(s_i)}$$

$$S_v < S_r$$

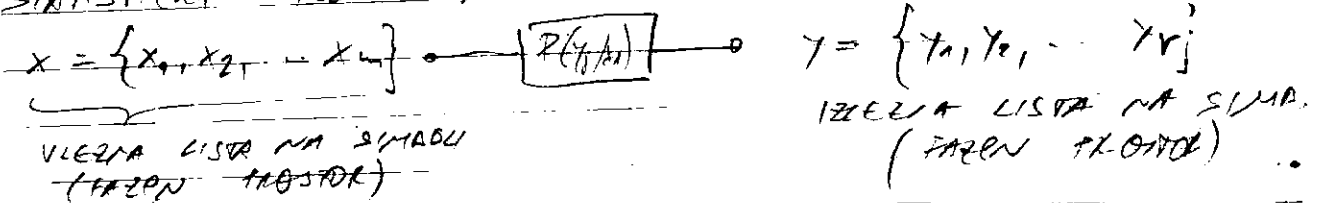
• Redundance: $Red = 1 - \eta = 1 - \frac{H_m(s)}{L_m(x)} = \frac{L_m(s) - H_m(s)}{L_m(x)}$
 PROBIRANO KODIRANJE NA NEKODIRANOJ INFORMACIJI
 O SJ SADRŽAT VOJITE ZBOROVI (MAOZI)

$$l) = \frac{\sum_{i=1}^m b(x_{ji}) P(x_i)}{L_m(x)} \quad j = 1, 2, \dots, m$$

$b(x_{ji})$ - BLOK NA KOJIM ZNACI x_{ji} VO ZADOT x_i
 $x_i = \{x_{i1}, x_{i2}, \dots, x_{im}\}$ - KOJA LISTA

8) PEROXEN VARAZ

• STATISTIČKI MODEL NA KVAZI DEK MEMODIJA.



	y_1	y_2	...	y_r
x_1	$P(y_1/x_1)$	$P(y_2/x_1)$...	$P(y_r/x_1)$
x_2	$P(y_1/x_2)$	$P(y_2/x_2)$...	$P(y_r/x_2)$
...				
x_m	$P(y_1/x_m)$	$P(y_2/x_m)$...	$P(y_r/x_m)$

$\sum_{j=1}^r P(y_j/x_i) = 1 \quad i = 1, 2, \dots, m$

$$P(j) = \sum_{i=1}^m P(x_i) \cdot P(y_j/x_i)$$

$j = 1, 2, \dots, r$

$$P_{ij} = P(y_j/x_i)$$

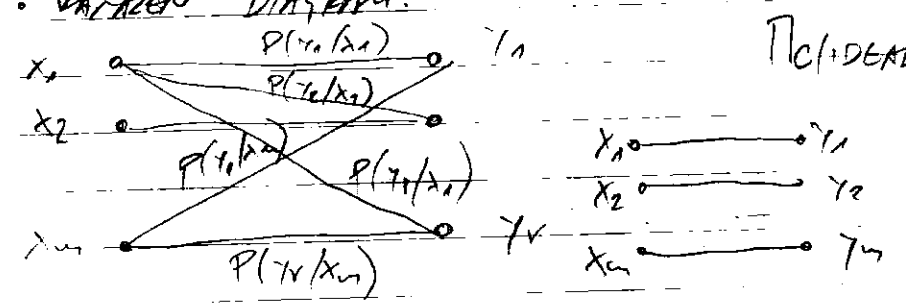
$$\Pi_C = \begin{bmatrix} P_{11} & P_{12} & \dots & P_{1r} \\ P_{21} & P_{22} & \dots & P_{2r} \\ \vdots & \vdots & \ddots & \vdots \\ P_{m1} & P_{m2} & \dots & P_{mr} \end{bmatrix}$$

$$\Pi_x = \begin{bmatrix} P(x_1) \\ P(x_2) \\ \vdots \\ P(x_m) \end{bmatrix}$$

$$\Pi_y = \begin{bmatrix} P(y_1) \\ P(y_2) \\ \vdots \\ P(y_r) \end{bmatrix}$$

$$\Pi_y = \Pi_C^T \cdot \Pi_x = \Pi_x \cdot \Pi_C$$

• VARIJEN DIJAGRAM:



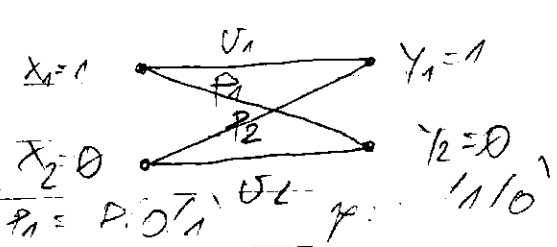
$$\Pi_C(\text{IDEAL}) = \begin{bmatrix} 1 & 0 & \dots & 0 & 0 \\ 0 & 1 & \dots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & 1 & 0 \\ 0 & 0 & \dots & 0 & 1 \end{bmatrix}$$

IDEALNI RESENI VARAZ

$$\Pi_y = \Pi_C \cdot \Pi_x = \Pi_x$$

• BICIMEN KVAZ:

$$\Pi_{BC} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} \sigma_1 & p_1 \\ \sigma_2 & \sigma_2 \end{bmatrix}$$



U_i - TRANSFORMACIJA NA VEŠEN PRAVOS

P_i - " " NA POSLEDN " "

simetrični vrtenje krogov: $\frac{1}{L} P_{\text{BSC}} = \begin{bmatrix} 0 & P \\ P & 0 \end{bmatrix}$

8.2 TRANSFORMACIJA

$X = \{x_1, x_2, \dots, x_m\}$ $Y = \{y_1, y_2, \dots, y_r\}$

- APRIORNA ENTROPIJA: $H(X) = \sum_{i=1}^m P(x_i) \log \frac{1}{P(x_i)}$
- POSTERIORNA " " : $H(X|Y) = \sum_{i=1}^m \sum_{j=1}^r P(x_i|y_j) \log \frac{1}{P(x_i|y_j)}$

EVNIVODNOSTA

$H(X|Y) = H(X, Y) - H(Y) = \sum_{i=1}^m \sum_{j=1}^r H(x_i, y_j) P(x_i, y_j) = \sum_{i=1}^m \sum_{j=1}^r P(x_i, y_j) \log \frac{1}{P(x_i, y_j)}$

$P(x_i, y_j) = P(y_j) P(x_i|y_j) = P(x_i) \cdot P(y_j|x_i)$

$H(X|Y) = \sum_{i=1}^m \sum_{j=1}^r P(x_i, y_j) \log \frac{1}{P(x_i, y_j)}$

$I(X; Y) = H(X) - H(X|Y) = \left[\frac{sh}{simb} \right] P(x_i, y_j)$

TRANSFORMACIJA

$I(X; Y) = \sum_{i=1}^m P(x_i) \log \frac{1}{P(x_i)} - \sum_{j=1}^r P(y_j|x_i) H(Y) = \sum_{i=1}^m \sum_{j=1}^r P(x_i) P(y_j|x_i) \log \frac{1}{P(x_i)}$

$I(X; Y) = \sum_{i=1}^m \sum_{j=1}^r P(x_i, y_j) \log \frac{1}{P(x_i)} = \sum_{i=1}^m \sum_{j=1}^r P(x_i, y_j) \log \frac{1}{P(x_i, y_j)}$

$I(X; Y) = \sum_{i=1}^m \sum_{j=1}^r P(x_i, y_j) \log \frac{P(x_i, y_j)}{P(x_i)} = \sum_{i=1}^m \sum_{j=1}^r P(x_i, y_j) \log \frac{P(x_i, y_j)}{P(x_i) P(y_j)}$

TRANSFORMACIJA JE OD PREDKODIRANJA NA VERTIČNE SINJLE
1 OD $P(x)$ (KVAZIJATA MATRICA)

• OSOBNI NA $I(X; Y)$

\rightarrow KVAZIJATA \in VO PREDN

① $I(X; Y) \geq 0$ $I(X; Y) = 0$ $P(x_i, y_j) = P(x_i) P(y_j)$

② $I(Y; X) = -I(X; Y)$ $I(Y; X) = P(y_j|x_i) = P(y_j/x_i)$

$I(Y; X) = \sum_{j=1}^r \sum_{i=1}^m P(x_i, y_j) \log \frac{P(x_i, y_j)}{P(x_i) P(y_j)} = \sum_{j=1}^r \sum_{i=1}^m P(x_i, y_j) \log \frac{P(x_i, y_j)}{P(y_j)}$

$= \sum_{j=1}^r \sum_{i=1}^m P(y_j) P(x_i|y_j) \log \frac{1}{P(y_j)} = \sum_{j=1}^r \sum_{i=1}^m P(x_i, y_j) \log \frac{1}{P(y_j|x_i)}$

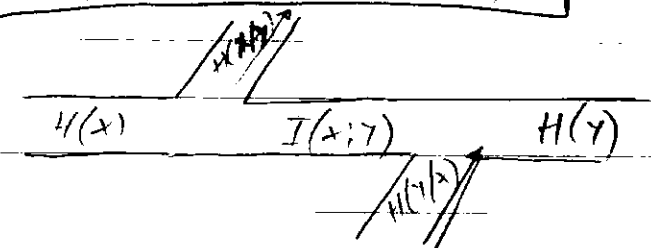
$= \sum_{j=1}^r P(y_j) \log \frac{1}{P(y_j)} - H(Y/X) = H(Y) - H(Y/X)$

$$I(y|x) = H(y) - H(y/x) \quad \text{II}$$

$$I(x|y) = H(x) - H(x/y) \quad \text{I}$$

$H(y|x)$ RECEVANGIJA
ENTROPIJA NA SUHOT NA VARIJABLA

$I(x|y)$ TRANSFORMACIJA



$$H(y) = I(x, y) + H(y|x)$$

$$I(x, y) = H(x) - H(x|y)$$

• FORMULA ENTROPIJA:

$$H(x, y) = \sum_{i=1}^n \sum_{j=1}^m P(x_i, y_j) \log \frac{1}{P(x_i, y_j)}$$

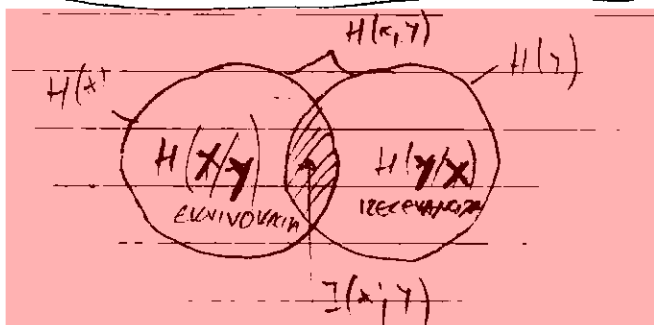
$$H(x, y) = \sum_{i=1}^n \sum_{j=1}^m P(x_i, y_j) \log \frac{P(x_i)P(y_j)}{P(x_i, y_j)P(x_i)P(y_j)} \quad \text{II}$$

$$= \sum_{i=1}^n \sum_{j=1}^m P(x_i, y_j) \log \frac{P(x_i)P(y_j)}{P(x_i, y_j)} + \sum_{i=1}^n \sum_{j=1}^m P(x_i, y_j) \log \frac{1}{P(x_i)}$$

$$+ \sum_{j=1}^m \sum_{i=1}^n P(x_i, y_j) \log \frac{1}{P(y_j)} = -I(x, y) + H(x) + H(y)$$

$$H(x, y) = H(x) + H(y) - I(x, y) \quad I(x, y) = \sum \sum P(x_i, y_j) \log \frac{P(x_i)P(y_j)}{P(x_i, y_j)}$$

$$H(x, y) = H(x) - H(y|x) \quad ; \quad H(x, y) = H(y) - H(x|y)$$



$$H(x, y) = H(x) + H(y) - I(x, y)$$

$$I(x, y) = H(y) - H(y|x)$$

$$I(x, y) = H(x) - H(x|y)$$

VARIJABLA NA DISKRETEN IZBOR

$$I(x, y) = \sum \sum P(x_i, y_j) \log \frac{P(x_i)P(y_j)}{P(x_i, y_j)} = \sum \sum P(x_i, y_j) \log \frac{P(x_i)P(y_j)}{P(x_i, y_j)}$$

$$P(y_j) = \sum_{i=1}^n P(x_i, y_j) = \sum_{i=1}^n P(x_i)P(y_j/x_i)$$

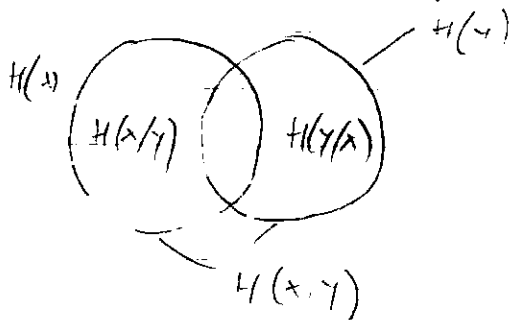
$$P(x) = \int P(x, y) dx$$

$$I(x, y) = \sum_{i=1}^n \sum_{j=1}^m P(x_i) P(y_j/x_i) \cdot \log \frac{P(y_j/x_i)}{\sum_{i=1}^n P(x_i) P(y_j/x_i)}$$

Max. vrednost na $I(x, y)$ zavisi samo od $P(x_i)$ zavisio $P(y_j/x_i)$ se determinira od varijaciona matrica Σ . SOMOT NA KANALCOT.

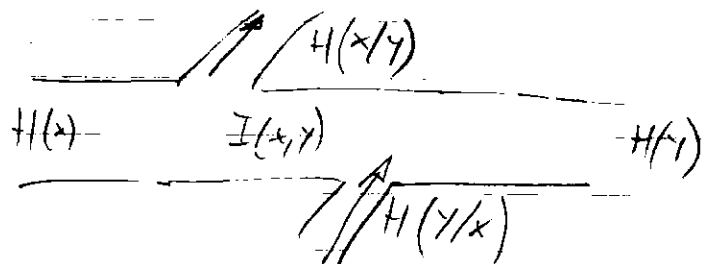
(Opaziti 0.05, determinacionu, amplitudu) REPLEK
AMPLITUDE

Solun 3 + 2 cagki



$$H(x, y) = H(y) + H(x/y)$$

$$H(x, y) = H(x) + H(y/x)$$



$$H(x) = I(x, y) + H(x/y)$$

$$H(y) = I(x, y) + H(y/x)$$

$$I(x, y) = H(x) - H(x/y)$$

$$I(x, y) = H(y) - H(y/x)$$

(I)
(II)

$$I(x, y) = \sum_{i=1}^n \sum_{j=1}^m P(x_i, y_j) \cdot \log \frac{P(x_i, y_j)}{P(x_i) P(y_j)}$$

$$P(x_i, y_j) = P(x_i) \cdot P(y_j/x_i)$$

$$\sum_{i=1}^n P(x_i) P(y_j/x_i) = P(y_j)$$

$$I(x, y) = \sum_{i=1}^n \sum_{j=1}^m P(x_i) P(y_j/x_i) \cdot \log \frac{P(y_j/x_i)}{\sum_{i=1}^n P(x_i) P(y_j/x_i)}$$

$$C = U(x, y) \max_{P(x_i)} [I(x, y)]$$

• ISPNF $\sigma = \frac{1}{2} \sigma_g$

$\sigma_{\text{max}} = 2 \sigma_g = U(x, y) = \sigma_0$

$$\Phi(x, y) = \sigma(x, y) \cdot I(x, y) \left[\frac{\text{sl}}{\text{s}} \right]$$

$$\eta_c = \frac{\Phi(x, y)}{C}$$

KOEFICIENT NA ISPOKLESTENOST !!
NA KANALCOT

$$\eta_{\text{class}} = \frac{I(x, y)}{\max_{P(x)} [I(x, y)]} \quad \eta_{\text{class}} = \frac{U(x, y) I(x, y)}{U_0 \max_{P(x_i)} [I(x, y)]}$$

$C \neq U(x) \cdot H(x) = \Phi(x)$ INFORMACIONEN FAX NA 121000

• IDEJEN DEJUVEN KARAZ

$$I(x, y) = H(x) - H(x/y) = H(x) - H(y/x)$$

$$H(x/y) = H(y/x) = 0 \quad H(x, y) = H(x) = H(y)$$

• BESKOPJEN KARAZ ($C=0$)

$$I(x, y) = 0 \quad H(x) = H(y) \quad H(y) = H(x)$$

$$I(x, y) = \sum_{i=1}^m \sum_{j=1}^v P(x_i, y_j) \log \frac{P(y_j/x_i)}{P(y_j)}$$

$$P(y_j) = P(y_j/x_i) \quad \forall i, j$$

$$\Pi_y = \Pi_c^T \cdot \Pi_x \quad P_{ij} = P(y_j/x_i)$$

$$\begin{bmatrix} P_{11} & P_{12} & \dots & P_{1n} \\ P_{21} & P_{22} & \dots & P_{2n} \\ \dots & \dots & \dots & \dots \\ P_{m1} & P_{m2} & \dots & P_{mn} \end{bmatrix}$$

$$\begin{bmatrix} 0,2 & 0,3 & 0,5 \\ 0,2 & 0,3 & 0,5 \\ 0,2 & 0,3 & 0,5 \end{bmatrix}$$

(PERMUTACIJA (10 REDICI 190 KOLONI))

• SIMETRIJEN KARAZ

$$H(y/x_i) = \sum_{j=1}^v P(y_j/x_i) \log \frac{1}{P(y_j/x_i)} = \text{const} \quad i=1, 2, \dots, m \quad \forall i$$

$$H(y/x_i) = \text{const} \quad \forall i \quad H(y/x_i) = \sum_{j=1}^v P_{ij} \log \frac{1}{P_{ij}}$$

$$\bullet \text{ [OUT]} \quad P(x_i) = \frac{1}{m} \quad i=1, 2, \dots, m$$

$$P(y_j) = \sum_{i=1}^m P(x_i) P(y_j/x_i) = \frac{1}{m} \sum_{i=1}^m P(y_j/x_i) = \frac{1}{m} \cdot \text{const} \quad \text{const za } \forall j$$

$$\begin{bmatrix} 1/2 & 1/3 & 1/6 \\ 1/6 & 1/2 & 1/3 \\ 1/3 & 1/6 & 1/2 \end{bmatrix}$$

$$\begin{bmatrix} 1/3 & 1/3 & 1/6 & 1/6 \\ 1/6 & 1/6 & 1/3 & 1/3 \end{bmatrix}$$

• VARNOST OD SPOVEDNI VARNOSTI

$$\Pi_{C_1} \rightarrow \Pi_{C_2} = \Pi_{C_3} \dots \Pi_{C_n}$$

$$\Pi_C = \Pi_{C_1} \Pi_{C_2} \dots \Pi_{C_n}$$

• PRESRETKA NA C KANAL SIMETRICNI VARNOSTI:

$$C = \sigma(x, y) \max_{P(x_i)} [I(x, y)] \quad I(x, y) = H(y) - H(y/x)$$

$$\max_{P(x_i)} [I(x, y)] = \log 2 - \sum_{j=1}^2 P(y_j/x_i) \log \frac{1}{P(y_j/x_i)}$$

$$\max [H(y)] = \sum_{j=1}^2 P(y_j) \log \frac{1}{P(y_j)} = \sum_{j=1}^2 \frac{1}{2} \log 2 = 1 \cdot \log 2 = \log 2$$

$$H(y/x) = \sum_{j=1}^2 \sum_{i=1}^2 P(x_i, y_j) \log \frac{1}{P(y_j/x_i)} = x \cdot 1$$

$$= \sum_{i=1}^2 \sum_{j=1}^2 P(x_i) P(y_j/x_i) \log \frac{1}{P(y_j/x_i)} = \sum_{i=1}^2 P(x_i) \sum_{j=1}^2 P(y_j/x_i) \log \frac{1}{P(y_j/x_i)}$$

$$H(y/x) = H(y/x_i) = \sum_{j=1}^2 P(y_j/x_i) \log \frac{1}{P(y_j/x_i)} \quad \text{const}$$

$$H(y/x_i) = H(y/x) = H(y/x_i)$$

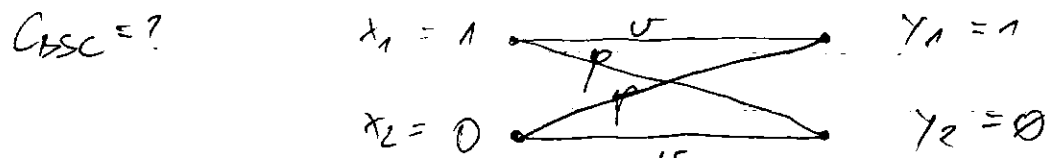
$$\max_{P(x_i)} [I(x, y)] = \log 2 - \sum_{j=1}^2 P(y_j/x_i) \log \frac{1}{P(y_j/x_i)}$$

• VARNOSTI NA SIM VARNOST

$$C = \sigma(x, y) \left[\log 2 - \sum_{j=1}^2 P(y_j/x_i) \log \frac{1}{P(y_j/x_i)} \right]$$

SUMA NA VOSE NA VARNOSTI MATRICA PO BILU KOZA BERICA

• BINARNI SIMETRICNI VARNOST



$$C_{BSC} = \sigma(x, y) \left[\log 2 - \sum_{j=1}^2 P(y_j/x_i) \log \frac{1}{P(y_j/x_i)} \right] = \sigma(x, y) [1 - H(p)]$$

$$1 \begin{bmatrix} 0 & p \\ p & 0 \end{bmatrix} \quad 2 \begin{bmatrix} 1-p & p \\ p & 1-p \end{bmatrix} \quad \textcircled{*} = P_{11} \log \frac{1}{P_{11}} + P_{12} \log \frac{1}{P_{12}} = \sigma \log \frac{1}{\sigma} + p \log \frac{1}{p}$$

$$\textcircled{*} = (1-p) \log \frac{1}{1-p} + p \log \frac{1}{p} = \log \frac{1}{1-p} + p \left(\log \frac{1}{1-p} + \log \frac{1}{p} \right)$$

$$\textcircled{*} = \log \frac{1}{1-p} + p \log \frac{1-p}{p} = H(p) \rightarrow \text{ENTROPYNA FUNKCIJA NA BINAARNI BERICI}$$

$$H(S) = \sum_{i=1}^2 P(S_i) \ln \frac{1}{P(S_i)} \quad S = \{s_1, s_2, \dots, s_2\}$$

$$q = 2 \Rightarrow S = \{0, 1\} \quad H(S) = P(s_1) \ln \frac{1}{P(s_1)} + P(s_2) \ln \frac{1}{P(s_2)}$$

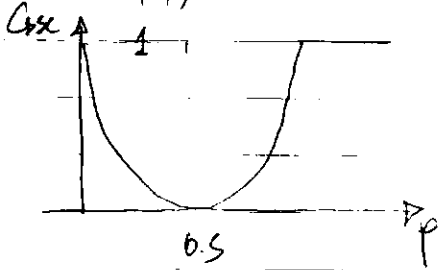
$$P(0) = p \quad P(1) = q = 1-p \quad H(S) = p \ln \frac{1}{p} + (1-p) \ln \frac{1}{1-p}$$

$$C_{BSC} = U(x, \gamma) [1 - H(\gamma)]$$

IF: $U(x, \gamma) = 1$

$$\phi(x) = U(x) \cdot H(x)$$

$$\Rightarrow \frac{SMB}{SEC} \cdot \frac{SH}{SMB} = \frac{SH}{SEC}$$



$$\Pi_{BSC} = \begin{bmatrix} p & q \\ q & p \end{bmatrix}$$

$$p = 0.5 \Rightarrow q = 1-p = 0.5 \quad C_{BSC} = 0$$

VARIANZ & VD KODIRIN

$$\Pi_{BSC} = \begin{bmatrix} p & q \\ q & p \end{bmatrix} \quad \Pi_{BSC}^{(2)} = \begin{bmatrix} p & q \\ q & p \end{bmatrix} \begin{bmatrix} p & q \\ q & p \end{bmatrix} = \begin{bmatrix} p^2+q^2 & 2pq \\ 2pq & p^2+q^2 \end{bmatrix}$$

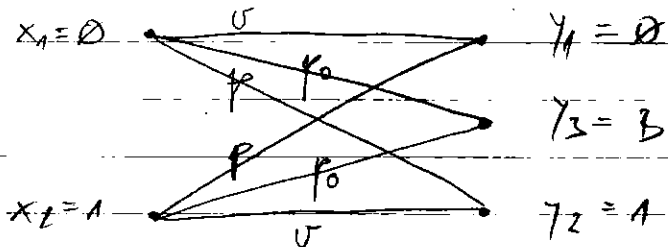
$$\Pi_{BSC}^{(3)} = \begin{bmatrix} p^2+q^2 & 2pq \\ 2pq & p^2+q^2 \end{bmatrix} \begin{bmatrix} p & q \\ q & p \end{bmatrix} = \begin{bmatrix} p^3+q^2p+2p^2q & p^2q+p^3+2pq^2 \\ 2p^2q+p^2q+q^3 & p^3+3pq^2 \end{bmatrix}$$

$$= \begin{bmatrix} p^3+3pq^2 & p^2q+3p^2q \\ p^2q+3pq^2 & p^3+3pq^2 \end{bmatrix}$$

$$C_{BSC}^{(2)} = U(x, \gamma) [1 - H(\gamma_{BSC})] = U(x, \gamma) [1 - H(2pq)]$$

$$C_{BSC}^{(3)} = U(x, \gamma) [1 - H(p^3+3pq^2)]$$

• BEWAHREN KARAKTER SO BEI EINER



$$\Pi_C = \begin{bmatrix} p & q & p_0 \\ q & p & p_0 \end{bmatrix} \quad P(x_1) \quad P(x_2)$$

$$\gamma_0 = pP(x_1) + qP(x_2)$$

$$\gamma_2 = pP(x_1) + qP(x_2)$$

$$\gamma_3 = p_0P(x_1) + p_0P(x_2)$$

$$C = U(x, \gamma) \left[\max_{P(x)} [H(\gamma)] - \sum_{j=1}^r P(\gamma_j | x_i) \ln \frac{1}{P(\gamma_j | x_i)} \right]$$

$$H(\gamma) = H(\gamma)_{max} \quad \text{IF } P(x_1) = P(x_2) = 0.5$$

$$P(\gamma_1) = P(\gamma_0 | x_1) P(x_1) + P(\gamma_0 | x_2) P(x_2) = \frac{1}{2}(p+q)$$

$$P(\gamma_2) = P(\gamma_2 | x_1) P(x_1) + P(\gamma_2 | x_2) P(x_2) = \frac{1}{2}(p+q)$$

$$P(\gamma_1) + P(\gamma_2) + P(\gamma_3) = 1 \quad P(\gamma_3) = 1 - P(\gamma_1) - P(\gamma_2) = 1 - (p+q) p_0$$

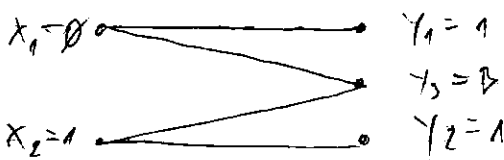
$$\max_{P(x_i)=0.5} [H(\gamma)] = \sum_{j=1}^3 P(\gamma_j) \log \frac{1}{P(\gamma_j)} = 2 \cdot \frac{1}{2} (\sigma + \gamma) \log \frac{2}{(\sigma + \gamma)} + (1 - \sigma - \gamma) \log \frac{1}{1 - (\sigma + \gamma)}$$

$$\sum_{j=1}^3 P(\gamma_j/x_i) \log \frac{1}{P(\gamma_j/x_i)} = \sigma \log \frac{1}{\sigma} + \gamma \log \frac{1}{\gamma} + p_0 \log \frac{1}{p_0}$$

$$C = \sigma(x, \gamma) \left[(\sigma + \gamma) \log \frac{2}{(\sigma + \gamma)} + p_0 \log \frac{1}{p_0} - \sigma \log \frac{1}{\sigma} - \gamma \log \frac{1}{\gamma} - p_0 \log \frac{1}{p_0} \right]$$

$$C = \sigma(x, \gamma) \left[(\sigma + \gamma) \left[1 - \log(\sigma + \gamma) \right] + \sigma \log \sigma + \gamma \log \gamma \right]$$

• IDEJEN KARAL SO PISENJE ($\gamma = 0$)



$$C = \sigma(x, \gamma) \left[\sigma(1 - \log \sigma) + \sigma \log \sigma \right]$$

$$C = \sigma(x, \gamma) \left[(\sigma + \gamma) \left[1 - \log(\sigma + \gamma) \right] + \sigma \log \sigma - \gamma \log \frac{1}{\gamma} \right]$$

$$\textcircled{*} = \lim_{\gamma \rightarrow 0} \gamma \log \frac{1}{\gamma}$$

$$\ln x = \gamma \quad x = e^\gamma \quad x = e^{\ln x}$$

$$\textcircled{*} = - \lim_{\gamma \rightarrow 0} \gamma \log \gamma = - \lim_{\gamma \rightarrow 0} \gamma \frac{\ln \gamma}{\ln 2} = + \frac{1}{\ln 2} \underbrace{\lim_{\gamma \rightarrow 0} (\gamma) \cdot \ln \gamma}_{\textcircled{1}}$$

$$\textcircled{1} = \lim_{\gamma \rightarrow 0} \frac{\ln \gamma}{-\frac{1}{\gamma}} = \lim_{\gamma \rightarrow 0} \frac{\ln \frac{1}{2}}{-2} = \left| \frac{+\infty}{-\infty} = \frac{\infty}{\infty} \right| = \lim_{\gamma \rightarrow 0} \frac{\frac{1}{2} \cdot \left(-\frac{1}{2^2}\right)}{-1}$$

$$\textcircled{1} = \lim_{\gamma \rightarrow 0} \gamma \cdot \frac{1}{2^\gamma} = \lim_{\gamma \rightarrow 0} \frac{1}{2} = \frac{1}{2}$$

$$\textcircled{*} = \frac{1}{\ln(2)} \cdot \textcircled{1} = \frac{1}{2 \ln(2)}$$

$$C = \sigma(x, \gamma) \left[\sigma(1 - \log(\sigma)) + \sigma \log \sigma \right] = \sigma(x, \gamma) \left[\sigma \right]$$

$\sigma + \gamma_0 = 1 \quad \sigma = 1 - \gamma_0$

$$C = \sigma(x, \gamma) (1 - \gamma_0)$$

• DOVERLIVOST NA IZKAZENIJE FORMI

$$d(\gamma_j) = x_i \quad j = 1, 2, \dots, r$$

$$x_i \in \{x_1, x_2, \dots, x_n\}$$

$$\textcircled{*} \quad P(x_i/\gamma_j) + P(\epsilon/\gamma_j) = 1$$

⊕ - VEROVANOST NA TOČNO ODGOVOR
⊕⊕ - VER. NA GLASU ODR.

VERJANA VER. NA GLASU $P(\epsilon) = P(\epsilon/\gamma_j) = \sum_{j=1}^r P(\epsilon/\gamma_j) P(\gamma_j)$

$$P(\varepsilon/\gamma_i) = 1 - P(d(\gamma_i)/\gamma_i) \quad d(\gamma_i) = x_0 \quad \text{t.j.} \quad P(x_0/\gamma_i) \geq P(x_i/\gamma_i) \quad \forall i$$

$$P(x_0/\gamma_i) \geq P(x_i/\gamma_i) \quad \forall i$$

$$P(x_0) \cdot P(\gamma_i/x_0) \neq P(x_i) \cdot P(\gamma_i/x_i) \quad \forall i$$

$$P(x_i) = \sum_{\gamma} P(\gamma_i/x_i) \Rightarrow P(\gamma_i/x_0) \geq P(\gamma_i/x_i) \quad \forall i$$

$$P(\varepsilon) = \sum_{i=1}^K P(\varepsilon/\gamma_i) P(\gamma_i) = \sum_{i=1}^K [1 - P(x_0/\gamma_i)] P(\gamma_i) =$$

$$P(\varepsilon) = 1 - \sum_{i=1}^K P(x_0, \gamma_i)$$

$$\sum_x \sum_{\gamma} P(x_i, \gamma_i) = 1 \quad \sum_{x=x_0} \sum_{\gamma} P(x_i, \gamma_i) + \sum_{i=1}^K P(x_0, \gamma_i) = 1$$

$$P(\varepsilon) = \sum_{x=x_0} \sum_{\gamma} P(x_i, \gamma_i) = \sum_{x=x_0} \sum_{\gamma} P(x_i) P(\gamma_i/x_i)$$

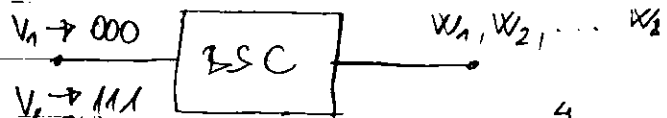
$$P(\varepsilon) = \sum_{k=1}^K \sum_{j=1}^I \underbrace{P(x_i) P(\gamma_i/x_i)}_{\text{SITE MINIMIZI PROMENI TO KONCI}} \quad x_i \neq x_{0j}$$

$$P(\omega) = 1 - P(\varepsilon) = 1 - \sum_{x=x_0} \sum_{\gamma} P(x_i, \gamma_i) = \sum_{\gamma} P(x_0, \gamma_i)$$

$$P(\sigma) = \sum_{i=1}^K P(x_0) P(\gamma_i/x_0) \quad \text{MAXIMIZI PROMENI TO KONCI}$$

ZASTITNO KODIRANJE

$$P_e(n, e) = C_n^e p^e \sigma^{n-e}$$



- w_1 000
- w_2 001
- w_3 010
- w_4 100
- w_5 011
- w_6 101
- w_7 110
- w_8 111

$$P(\varepsilon) = P(V_1) \sum_{i=1}^8 P(w_i/v_1) + P(V_2) \cdot \sum_{i=1}^4 P(w_i/v_2)$$

	w_1	w_2	...	w_8
V_1	$P(w_1/v_1)$	$P(w_2/v_1)$...	$P(w_8/v_1)$
V_2	$P(w_1/v_2)$	$P(w_2/v_2)$...	$P(w_8/v_2)$

$$P(\varepsilon) = P(3,2) + P(3,3)$$

$$P(\varepsilon) = C_3^2 p^2 \sigma^1 + C_3^3 p^3 \sigma^0 = \frac{3!}{1! \cdot 2!} p^2 \sigma + \frac{3!}{0! \cdot 3!} p^3 = 3 p^2 \sigma + p^3$$

$$P(\varepsilon) = 3 \cdot (0.1)^2 \cdot 0.9 + (0.1)^3 = 2.7 \cdot 0.01 + 0.001 = 0.027 + 0.001 = 0.028$$

$$n=5 \quad P(\varepsilon) = C_n^e p^e \sigma^{n-e} = P(5,5) + P(5,4) + P(5,3) = C_5^3 p^3 \sigma^2 + C_5^4 p^4 \sigma^1 + C_5^5 p^5 \sigma^0$$

$$162 + C_5^3 p^3 \sigma^0 = \frac{5!}{2! \cdot 3!} p^3 \sigma^2 + \frac{5!}{1! \cdot 4!} p^4 \sigma + p^5 = 10 p^3 \sigma^2 + 5 p^4 \sigma + p^5$$

$$P(\epsilon) = \sum_{c=\lfloor \frac{n}{2} \rfloor}^n P_E(n, \epsilon) = \sum_{c=\lfloor \frac{n}{2} \rfloor}^n \binom{n}{c} p^c (1-p)^{n-c}$$

• BITNA NA MENCUVANJE NA FORKITE

$$R = U(x, \gamma) = \frac{\log M}{n} \left[\frac{s_1}{s} \right] \quad \text{--- GROT NA DITI PO KODIRANU POLAKA}$$

$$\Phi = U(x, \gamma) \cdot H(x) (=) \frac{\text{foraka}}{\text{sec}} \cdot \frac{s_1}{\text{foraka}} (=) \frac{s_1}{\text{sec}}$$

$$H(x) = \sum_{i=1}^m P(x_i) \left[\log \frac{1}{P(x_i)} \right] \rightarrow I(x)$$

$$R(=) \frac{\text{binarni broj na foraki}}{\text{sec}}$$

II SHENONOVA TEOREMA:

$$R \leq C$$

• HEMINGOVO RAZTOZANIE:

$$V_i, V_j \quad D(V_i, V_j) = D(i, j) \quad \text{--- HEMINGOVO RAZTOZANIE}$$

• SVOTSTVA:

$$(1^\circ) D(i, j) \geq 0 \quad (2^\circ) D(i, j) = D(j, i)$$

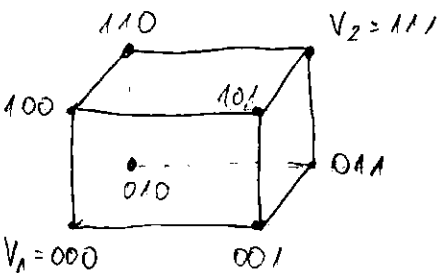
$$(3^\circ) D(i, k) + D(j, k) \geq D(i, j) \quad \text{PRAVLO NA TRIKOTNIK}$$

$$D(V_i, W_j)$$

V_i - VSELEN BINARNI KODEN ZAK
 W_j - VSELEN " " " "

$$\min [D(V_i, W_j)]$$

→ PRAVLO NA OBLUCIVANJE



$$W_j = 100$$

$$D(V_{11}, V_j) = 1 \leq D(V_2, W_j) = 2$$

V_1

• OŠT SE VIND: $d(w_j) = V_0$ AKO $D(w_j, V_0) \leq D(w_j, V_i) \quad \forall V_i$

$$D(V_i, V_j) \geq e_b + 1$$

(e_b) → BLOK NA POŠTENO DITI ŠTO MOZE DA SI DETECTIRA ZA OT NA VSELEN KODIRANI FORAKI

MINIMIZIRO HEMINGOVO RAZTOZANIE

$$D(V_i, V_j) \geq 2e_c + 1$$

(e_c) → BLOK NA POŠTENO MERESECI DITI KOI NEMERIKOT MOZE DA SI KODIRANA

$$D(V_i, V_j) \geq 1 + 2e_c + (e_b - e_c) = 1 + e_b + e_c \quad e_b \geq e_c$$

• ZAŠTITA KODIRANJE SO KONTROLA UH MANAST

l - informacioni biti

$$l+k=4$$

k - zaštitni biti

- kod za detekciju na jedno greška

$e_d = 1$ $D(v_i, v_j) = 2$ } Hammingovo matiranje kodu
 (najmanje razlike)

$$l+1 = n$$

$$\begin{array}{cccc|c} 0 & 0 & 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 & 1 & 0 \end{array}$$

l k

• kod za korekciju na jedno greška

$$k \geq \lceil \log_2(k+l+1) \rceil$$

$$v_i = (x_1 x_2 \dots x_l x_{l+1} \dots x_{l+k}) \quad i = 1, 2, \dots, M$$

$$x_i \in \{0, 1\}$$

$$\sum_{i=1}^l a_i 2^{i-1} = a_{l+1} 2^l + \dots + a_{l+k} 2^{l+k-1} + a_{l+k+1} 2^{l+k}$$

$$l = \log_2(M)$$

HAMINGOV KOD SO K KONTROLNI BITI

$$v_{11} = 1011$$

$$\log_2 M = \log_2 12 = 4 = l$$

broj na inform. biti

$$k = \lceil \log_2(k+l+1) \rceil$$

$$k = 3 \quad \log_2(8) = 3$$

$x_1 \ x_2 \ x_4$

$$v_{11} = \begin{array}{cccc|ccc} x_1 & x_2 & 1 & x_4 & 0 & 1 & 1 \\ \hline & & 1 & 2 & 3 & 4 & 5 & 6 & 7 \end{array}$$

"xx1"	1 3 5 7
"x1x4"	2 3 6 7
"1xx4"	4 5 6 7

$$S_1 = x_1 \oplus 1 \oplus 0 \oplus 1 = 0 \quad x_1 = 0$$

$$S_2 = x_2 \oplus 1 \oplus 1 \oplus 1 = 0 \quad x_2 = 1$$

$$S_3 = x_4 \oplus 0 \oplus 1 \oplus 1 = 0 \quad x_4 = 0$$

$$v_{11} = 0110011$$

ex.: error na bit 5

$$\Rightarrow v_{11} = \begin{array}{cccccccc} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ 0 & 1 & 1 & 0 & 1 & 1 & 1 & 1 \end{array}$$

$$S_1 = 0 \oplus 1 \oplus 1 \oplus 1 = 1$$

$$S_2 = 1 \oplus 1 \oplus 1 \oplus 1 = 0$$

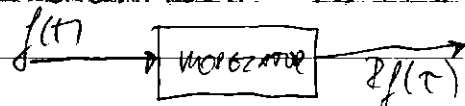
$$S_3 = 0 \oplus 1 \oplus 1 \oplus 1 = 1$$

$$N_k = S_1 S_2 S_3 = 101$$

5 - 01 bit e greška

DETEKCIJA (IZPRIZNANJE) NA PERIODIČNI SIGNALI

• AUTOKORELACIONA FUNKCIJA



$$R_f(\tau) = \int_{-T}^T f(t) f(t+\tau) dt$$

$$f(t) = s(t) + n(t)$$

$$R_f(\tau) = \int f(t) f(t+\tau) dt = \int (s(t) + n(t)) (s(t+\tau) + n(t+\tau)) dt$$

$$P_{11}(\tau) = \frac{1}{T} \int_{-T/2}^{T/2} f_1(t) f_1(t-\tau) dt \quad f_1(t) = \sum_{-\infty}^{\infty} F_1(jn\omega_0) e^{jn\omega_0 t}$$

$$P_{11}(\tau) = \frac{1}{T} \int_{-T/2}^{T/2} f_1(t) \left[\sum_{-\infty}^{\infty} F_1(jn\omega_0) e^{jn\omega_0 t} \right] e^{j\omega_0 t} dt =$$

$$= \sum_{-\infty}^{\infty} F_1(jn\omega_0) e^{jn\omega_0 \tau} \left[\frac{1}{T} \int_{-T/2}^{T/2} f_1(t) e^{jn\omega_0 t} dt \right] = \sum_{-\infty}^{\infty} |F_1(jn\omega_0)|^2 e^{jn\omega_0 \tau}$$

$$P_{11}(\tau) = \sum_{-\infty}^{\infty} |F_1(jn\omega_0)|^2 e^{jn\omega_0 \tau} \quad F_1^*(j\omega_0)$$

↑ FUR. TRANS. PAAR

$$P_f(\tau) = \frac{1}{T} \int_{-T/2}^{T/2} (s(t) + y(t)) (s(t+\tau) + y(t+\tau)) dt = \frac{1}{T} \int_{-T/2}^{T/2} s(t) s(t+\tau) dt + \frac{1}{T} \int_{-T/2}^{T/2} y(t) y(t+\tau) dt + \frac{1}{T} \int_{-T/2}^{T/2} s(t) y(t+\tau) dt + \frac{1}{T} \int_{-T/2}^{T/2} y(t) s(t+\tau) dt$$

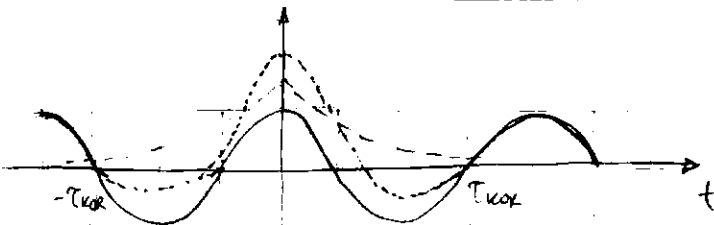
$$= P_s(\tau) + P_y(\tau) + P_{sy}(\tau) + P_{ys}(\tau)$$

$$P_{sy}(\tau) = P_{ys}(\tau) = 0$$

СИММЕТРИЧ. МЕНШИ $y(t) = 0$

$$P_f(\tau) = P_s(\tau) + P_y(\tau)$$

$$P_y(\tau > \tau_{cor}) = 0$$



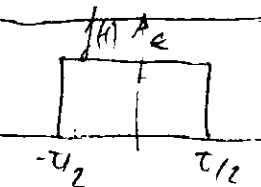
$$s(t) = A \cos(\omega t)$$

$$S(j\omega_0) = \frac{1}{T} \int_{-T/2}^{T/2} A \cos(\omega t) e^{-j\omega_0 t} dt$$

$$S(j\omega_0) = \frac{A}{2} \delta(\omega - \omega_0) + \frac{A}{2} \delta(\omega + \omega_0)$$

$$S'(j\omega_0) = \frac{1}{T} \int_{-T/2}^{T/2} \frac{A}{2} (e^{j\omega t} + e^{-j\omega t}) e^{-j\omega_0 t} dt = \frac{A}{2} \left[\frac{1}{T} \int_{-T/2}^{T/2} e^{j(\omega - \omega_0)t} dt + \frac{1}{T} \int_{-T/2}^{T/2} e^{-j(\omega + \omega_0)t} dt \right]$$

$$= \frac{A}{2} \delta(\omega - \omega_0) + \frac{A}{2} \delta(\omega + \omega_0)$$



$$\mathcal{F}\{f(t)\} = \int_{-tau/2}^{tau/2} A e^{j\omega t} dt = A \tau \frac{e^{j\omega \tau/2} - e^{-j\omega \tau/2}}{j\omega}$$

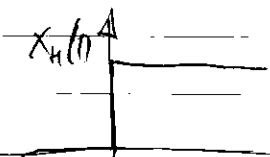
$$\tau \rightarrow 0$$

$$A = \frac{1}{\tau}$$

$$\lim_{\tau \rightarrow 0} \frac{1}{\tau} \int_{-tau/2}^{tau/2} 1 e^{-j\omega t} dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} 1 e^{-j\omega t} d\omega$$

$$= 1 = \Delta(j\omega)$$

$$\Delta(j\omega) = \mathcal{F}\{\delta(t)\}$$



$$x_H(t) = \begin{cases} 1 & t > 0 \\ 0 & t < 0 \end{cases}$$

$$\int_{-\infty}^{\infty} |x_H| dt \rightarrow \infty$$

$$x_H(0) = \frac{1}{2} \{ x_H(0^-) + x_H(0^+) \} = \frac{1}{2}$$

$$X_H(j\omega) = \frac{1}{j\omega} + \mathcal{F}\left\{ \frac{1}{2} \right\}$$

НЕ С УПОРЕТ УСЛОВИЯ
PIKULE
($e^{-\infty} - e^{-\infty}$)

$$\int_0^{\infty} e^{j\omega t} dt = \frac{1}{j\omega} \int_0^{\infty} e^{-j\omega t} d(j\omega t) = \frac{1}{j\omega} \left(e^{-j\omega t} \Big|_0^{\infty} \right) = \frac{1}{j\omega}$$

$$\mathcal{F}\{x\} = \int_{-\infty}^{\infty} k e^{-j\omega t} dt = k \int_{-\infty}^{\infty} e^{-j\omega t} dt = 2\pi k \delta(\omega)$$

$$\delta(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-j\omega t} d\omega = \left. \begin{matrix} \omega = t \\ t = \omega \end{matrix} \right| = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-j\omega t} dt$$

$$X_H(j\omega) = \frac{1}{j\omega} + \mathcal{F}\left\{ \frac{1}{2} \right\} = \frac{1}{j\omega} + 2\pi \frac{1}{2} \delta(\omega) = \frac{1}{j\omega} + \pi \delta(\omega)$$

$$\boxed{\mathcal{F}\{1\} = 2\pi \delta(\omega)}$$

• FUR. TRANSF. $\cos(\omega_0 t)$, $\sin(\omega_0 t)$

$$\mathcal{F}\{e^{j\omega_0 t}\} = \mathcal{F}\{1 \cdot e^{j\omega_0 t}\} = \left| \mathcal{F}\{1\} = 2\pi \delta(\omega) \right|$$

$$= 2\pi \delta(\omega - \omega_0)$$

$$\boxed{\mathcal{F}\{\cos(\omega_0 t)\} = \pi \delta(\omega - \omega_0) + \pi \delta(\omega + \omega_0)}$$

$$\mathcal{F}\{\sin(\omega_0 t)\} = \mathcal{F}\left\{ \frac{1}{2j} (e^{j\omega_0 t} - e^{-j\omega_0 t}) \right\}$$

$$= -j\pi \delta(\omega - \omega_0) + j\pi \delta(\omega + \omega_0)$$

$$s(t) = A \cos(\omega_0 t) \quad R_s(\tau) = \int_{-\infty}^{\infty} s(t) \cdot s(t+\tau) dt$$

$$R_s(\tau) = \frac{1}{2\pi} \int_{-\infty}^{\infty} |S(j\omega)|^2 e^{j\omega \tau} d\omega = \frac{1}{2\pi} \int_{-\infty}^{\infty} A^2 \pi^2 (\delta(\omega - \omega_0) + \delta(\omega + \omega_0))^2 e^{j\omega \tau} d\omega$$

$$= \frac{A^2 \pi^2}{2\pi} \left[\int_{-\infty}^{\infty} \delta(\omega - \omega_0) e^{j\omega \tau} d\omega + \int_{-\infty}^{\infty} 2\delta(\omega - \omega_0) \delta(\omega + \omega_0) e^{j\omega \tau} d\omega + \int_{-\infty}^{\infty} \delta(\omega + \omega_0) e^{j\omega \tau} d\omega \right]$$

$$R_s(\tau) = \frac{A^2 T^2}{2T} [e^{j\omega_0 \tau} + e^{-j\omega_0 \tau}] = A^2 T \cos(\omega_0 \tau)$$

$$f(t) = A \cos(\omega_0 t + \varphi) \quad R_f(\tau) = ?$$

$$R_f(\tau) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T f(t) \cdot f(t+\tau) dt \quad \left[\omega_0 = \frac{2\pi}{T_0} \quad T_0 \neq T \right]$$

$$\lim_{T \rightarrow \infty} \frac{A^2}{2T} \int_{-T}^T \cos(\omega_0 t + \varphi) \cdot \cos(\omega_0 t + \omega_0 \tau + \varphi) dt = \textcircled{*}$$

$$\left. \begin{array}{l} \cos(\alpha + \beta) = \cos \alpha \cos \beta - \sin \alpha \sin \beta \\ \cos(\alpha - \beta) = \cos \alpha \cos \beta + \sin \alpha \sin \beta \end{array} \right\} \begin{array}{l} \cos(2 + \rho) + \cos(2 - \rho) = \\ = 2 \cos 2 \cos \rho \end{array}$$

$$\textcircled{*} = \lim_{T \rightarrow \infty} \frac{A^2}{2T} \left[\int_{-T}^T \frac{1}{2} \cos(\omega_0 \tau) dt + \int_{-T}^T \frac{1}{2} \cos(2\omega_0 t + 2\omega_0 \tau + \varphi) dt \right]$$

$$= \lim_{T \rightarrow \infty} \frac{A^2}{2T} \cdot \frac{1}{2} (\cos \omega_0 \tau) \cdot 2T + \lim_{T \rightarrow \infty} \frac{A^2}{2T} \int_{-T}^T \frac{1}{2} \cos(2\omega_0 t) \cos(2\omega_0 \tau + \varphi) dt$$

$$- \lim_{T \rightarrow \infty} \frac{A^2}{2T} \int_{-T}^T \frac{1}{2} \sin(2\omega_0 t) \sin(2\omega_0 \tau + \varphi) dt$$

$$\textcircled{*} = \lim_{T \rightarrow \infty} \frac{A^2}{2T} \cdot \frac{1}{2} \cos(2\omega_0 \tau + \varphi) \int_{-T}^T \cos(2\omega_0 t) dt =$$

$$= \frac{A^2}{4T} \cdot \cos(2\omega_0 \tau + \varphi) \lim_{T \rightarrow \infty} \left[\frac{\sin(2\omega_0 t)}{2\omega_0} \Big|_{-T}^T \right] =$$

$$= \frac{A^2}{4T} \cos(2\omega_0 \tau + \varphi) \lim_{T \rightarrow \infty} \frac{2 \sin(2\omega_0 T)}{2\omega_0}$$

$$= \frac{A^2}{2} \cos(2\omega_0 \tau + \varphi) \lim_{T \rightarrow \infty} \frac{\sin(2\omega_0 T)}{2\omega_0 T}$$

$$\left(\lim_{x \rightarrow \infty} \frac{\sin x}{x} = 0 \right)$$

$$\textcircled{*} = k \cdot \int_{-T}^T \sin(2\omega_0 t) dt = 0$$

НЕПРАВДА
ФУНКЦИЯ

$$R_f(\tau) = \frac{A^2}{2} \cos(\omega_0 \tau)$$

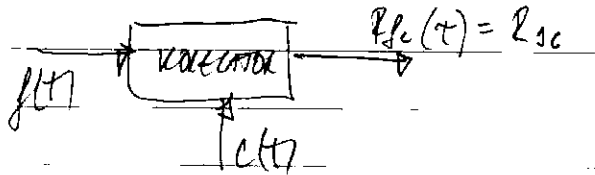
$$\Phi_f(\omega) = \int_{-\infty}^{\infty} R_f(\tau) e^{-j\omega \tau} d\tau = \int_{-\infty}^{\infty} \frac{A^2}{2} \frac{1}{2} (e^{j\omega_0 \tau} + e^{-j\omega_0 \tau}) e^{-j\omega \tau} d\tau$$

$$= \frac{A^2}{4} [2\pi \delta(\omega - \omega_0) + 2\pi \delta(\omega + \omega_0)] = \frac{A^2 T}{2} [\delta(\omega - \omega_0) + \delta(\omega + \omega_0)]$$

$$s(t) = A \cos(\omega_0 t) \rightarrow P_s(\tau) = \frac{A^2}{2} \cos(\omega_0 \tau)$$

NA IZLEGE OD KOLEKCIJOT 11
 NEMA SUM T.E TOT E BEIMINIRAN

• МЕДУКОЛЕКАЦИОНА ПОСТАВКА



$$f(t) = s(t) + c(t)$$

$$P_{fc}(\tau) = [s(t) + c(t)] c(t + \tau) = P_{sc}(\tau) + P_{cc}(\tau)$$

$$c(t) = A_c \cos(\omega_0 t + \varphi_c)$$

$$s(t) = A \cos(\omega_0 t + \varphi_s)$$

$$P_{sc} = \frac{A \cdot A_c}{2} \cos(\cos \omega_0 \tau + \varphi)$$

$$\varphi = \varphi_c - \varphi_s$$

• МЕДУКОЛЕКАЦИОНА ПОСТАВКА КАДРЕ ПОМОЉНОСТ СИГ Е Д(t)



$$P_{\delta f}(\tau) = \delta(t) \cdot (c(t + \tau) + s(t + \tau)) =$$

$$= P_{\delta c}(\tau) + P_{\delta s}(\tau) = \frac{1}{T} s(\tau)$$

$$P_{\delta c}(\tau) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T \delta(t) A \cos(\omega_0 t + \omega_0 \tau) dt$$

$$s(t) = \sum_{n=-\infty}^{\infty} S(j\omega) e^{jn\omega t} = \sum_{n=-\infty}^{\infty} e^{jn\omega t} \frac{\pi}{T} \int_{-T/2}^{T/2} s(\tau) e^{-jn\omega \tau} d\tau =$$

$$= \int_{-T/2}^{T/2} s(\tau) \left[\sum_{n=-\infty}^{\infty} \frac{1}{T} e^{jn\omega(t-\tau)} \right] d\tau = \int_{-T/2}^{T/2} s(\tau) \cdot \delta(t-\tau) d\tau$$

$$\frac{\pi}{T} s(t) = \frac{1}{T} \int_{-T/2}^{T/2} s(\tau) \delta(t-\tau) d\tau = P_{\delta s}(\tau) = P_{\delta s}(\tau)$$

STATISTIČNA TEORIJA NA ODLOČEVANJE

• **BAJESOV KRITERIJUM ZA ODLOČEVANJE**

$H_0, H_1 \rightarrow$ DVE HIPOTEZE

- 1.) $P(H_0), P(H_1)$
- 2.) $f_0(\sigma), f_1(\sigma)$
- 3.) **MATRIČA NA CILJENJE**

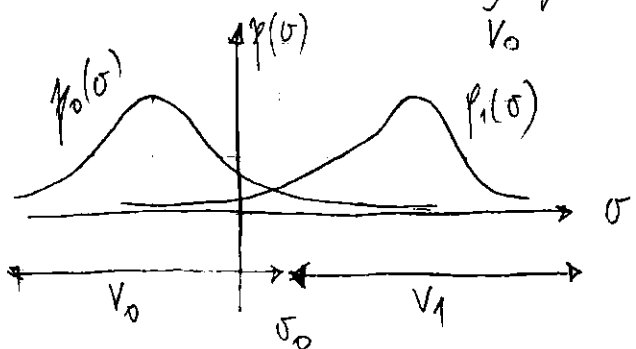
$$K = \begin{bmatrix} K_{0,0} & K_{0,1} \\ K_{1,0} & K_{1,1} \end{bmatrix} \quad \begin{array}{l} K_{0,0} \text{ } K_{1,1} \text{ NAJLEPŠA ZA TOČNA ODLUKA} \\ K_{0,1} \text{ } K_{1,0} \text{ KAZENA} \end{array}$$

• **VEROJATNOST NA POGLAVNA ODLUKA T.E. KUMULATIVNA VER. NA GRANIČNI**

$$P(H_1/H_0) = Q_{1,0} = \int_{V_1}^{\infty} f_0(\sigma) d\sigma = \int_{\sigma_0}^{\infty} f_0(\sigma) d\sigma$$

DEFEKTVAN & H₁
NEDEFKTVAN & H₀

$$P(H_0/H_1) = Q_{0,1} = \int_{-\infty}^{V_0} f_1(\sigma) d\sigma = \int_{-\infty}^{\sigma_0} f_1(\sigma) d\sigma$$



$$Q_{0,0} = \int_{-\infty}^{\infty} f_0(\sigma) d\sigma = \int_{V_0}^{\infty} f_0(\sigma) d\sigma$$

$$Q_{1,1} = \int_{V_0}^{\infty} f_1(\sigma) d\sigma = \int_{V_1}^{\infty} f_1(\sigma) d\sigma$$

$$P(\epsilon) = P(H_0) P(H_1/H_0) + P(H_1) P(H_0/H_1)$$

• **VARNEN SLEDEN RIZIK:**

$$\bar{K}_0 = P(H_0) (K_{1,0} Q_{1,0} + K_{0,0} Q_{0,0})$$

$$\bar{K}_1 = P(H_1) (K_{0,1} Q_{0,1} + K_{1,1} Q_{1,1})$$

SLEDEN RIZIK
ZA REALIZACIJA NA H₀
SLEDEN RIZIK
ZA REALIZACIJA NA H₁

$$\bar{K} = \bar{K}_0 + \bar{K}_1 = \bar{K}(\sigma) = P(H_0) \left(K_{1,0} \int_{\sigma_0}^{\infty} f_0(\sigma) d\sigma + K_{0,0} \int_{-\infty}^{\sigma_0} f_0(\sigma) d\sigma \right) +$$

$$P(H_1) \left(K_{0,1} \int_{-\infty}^{\sigma_0} f_1(\sigma) d\sigma + K_{1,1} \int_{\sigma_0}^{\infty} f_1(\sigma) d\sigma \right)$$

$$\frac{\partial \bar{K}}{\partial \sigma_0} = 0 \rightarrow \sigma_0$$

$$\frac{\partial \bar{K}}{\partial \sigma_0} = P(H_0) \left(-K_{1,0} f_0(\sigma_0) + K_{0,0} f_0(\sigma_0) \right) + P(H_1) \left(K_{0,1} f_1(\sigma_0) - K_{1,1} f_1(\sigma_0) \right)$$

$$\int_{\sigma_0}^{\infty} f_0(\sigma) d\sigma + \int_{\sigma_0}^{\infty} f_1(\sigma) d\sigma = 1$$

$$\int_{-\infty}^{\sigma_0} f_0(\sigma) d\sigma = 1 - \int_{\sigma_0}^{\infty} f_0(\sigma) d\sigma$$

$$\frac{\partial}{\partial \sigma_0} \left[1 - \int_{-\infty}^{\sigma_0} f_0(\sigma) d\sigma \right] = -f_0(\sigma)$$

$$P(H_0) [-k_{1,0} \gamma_0(\sigma_0) + k_{0,0} \gamma_0(\sigma_0)] + P(H_1) [k_{0,1} \gamma_1(\sigma_0) - k_{1,1} \gamma_1(\sigma_0)] = 0$$

$$P(H_0) [k_{0,0} - k_{1,0}] \gamma_0(\sigma_0) = P(H_1) [k_{1,1} - k_{0,1}] \gamma_1(\sigma_0)$$

$$\boxed{\frac{\gamma_1(\sigma_0)}{\gamma_0(\sigma_0)} = \frac{P(H_0)}{P(H_1)} \frac{k_{0,0} - k_{1,0}}{k_{1,1} - k_{0,1}} = \lambda_0}$$

$\sigma_0 = \sigma_{opt}$ $\lambda_0 = \text{KOEFFICIENT NA VELOZATNOST}$

$$k(\sigma_0) = k(\sigma)_{min}$$

$$\frac{\gamma_1(\sigma)}{\gamma_0(\sigma)} \gtrless \lambda_0 \begin{cases} \frac{\gamma_1(\sigma)}{\gamma_0(\sigma)} > \lambda_0 \Rightarrow \text{ODLUČI } H_1 \\ \sigma \in V_1 \\ \frac{\gamma_1(\sigma)}{\gamma_0(\sigma)} < \lambda_0 \Rightarrow \text{ODLUČI } H_0 \\ \sigma \in V_0 \end{cases}$$

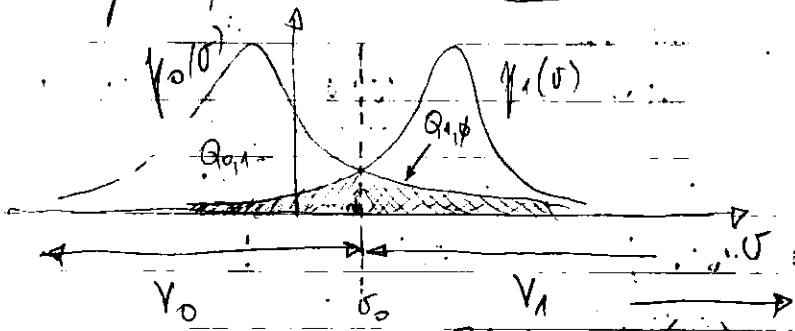
• Ako $k_{0,0} = k_{1,1}$ $k_{0,1} = k_{1,0}$

$$\frac{\gamma_1(\sigma)}{\gamma_0(\sigma)} \gtrless \frac{P(H_0)}{P(H_1)} = \lambda_0$$

• Ako HIPOTEZE SE ODRAZUJU VELOZATNOM:

T.E. $P(H_0) = P(H_1)$
 $> H_1$
 $< H_0$

$$\frac{\gamma_1(\sigma)}{\gamma_0(\sigma)} \gtrless 1 \quad \left[\gamma_1(\sigma) \gtrless \gamma_0(\sigma) \right]$$



$P(H_0) > P(H_1)$ PRAVO: ODI KON. ROMAZOVNER HIPOTEZA

• MINIMALNI KRITERIJUM ZA ODLUCIVANJE (KOJA NE SE POKAZUJE) $P(H_0)$ I $P(H_1)$
 $P(H_0) = \xi$ $P(H_1) = 1 - \xi$ $0 \leq \xi \leq 1$

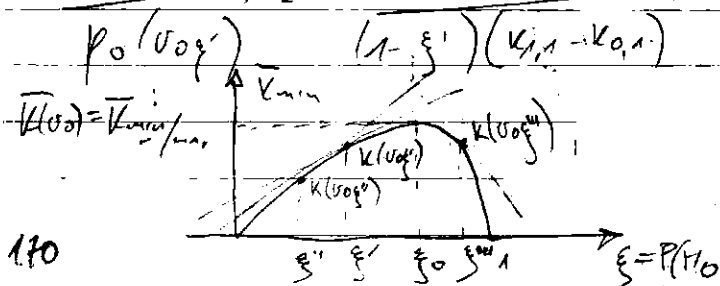
$$\bar{K} = \xi (k_{0,0} Q_{0,0} + k_{1,0} Q_{1,0}) + (1 - \xi) (k_{1,1} Q_{1,1} + k_{0,1} Q_{0,1}) =$$

$$= \xi [(k_{0,0} Q_{0,0} + k_{1,0} Q_{1,0}) - (k_{1,1} Q_{1,1} + k_{0,1} Q_{0,1})] + (k_{1,1} Q_{1,1} + k_{0,1} Q_{0,1})$$

$$\boxed{\bar{K} = m \cdot \xi + C}$$

VKUPEN STROK ZIK

$$\frac{\gamma_1(\sigma_{0\xi})}{\gamma_0(\sigma_{0\xi})} = \frac{\xi (k_{0,0} - k_{1,0})}{(1 - \xi) (k_{1,1} - k_{0,1})} = \lambda_0 \Rightarrow \sigma_{0\xi} = \dots$$



MINIMIZIRANJE ZA DODU-KRITERIJUM ZA LAZICNI "xi"

$$K_{min}/m = C \quad (m = 0)$$

$$m=0 \Rightarrow \int_{-\infty}^{\infty} p_0(\sigma) d\sigma + \int_{-\infty}^{\infty} p_0(\sigma) d\sigma = \int_{\sigma_0}^{\infty} p_1(\sigma) d\sigma + \int_{-\infty}^{\sigma_0} p_1(\sigma) d\sigma$$

$$\frac{p_1(\sigma)}{p_0(\sigma)} \approx \frac{P(\pi_0)_m (K_{0,0} - K_{1,0})}{[1 - P(\pi_0)_m] [K_{1,1} - K_{0,1}]}$$

P(π₀)_m ⇒ APPROXIMATE VELOCITY TO GO MAXIMIZE THROUGHPUT EFFICIENCY

COOPERATIVE COMMUNICATIONS

$$X_1(t) = [a_{11} b_1^{(1)} c_1(t), a_{12} b_1^{(2)} c_1(t), a_{13} b_1^{(2)} c_1(t) + a_{14} b_2^{(2)} c_2(t)]$$

$$X_2(t) = [a_{21} b_2^{(1)} c_2(t), a_{22} b_2^{(2)} c_2(t), a_{23} b_1^{(2)} c_1(t) + a_{24} b_2^{(1)} c_2(t)]$$

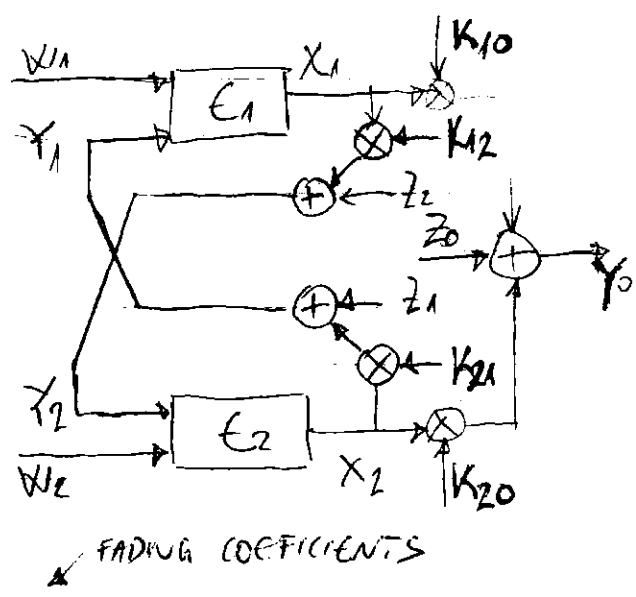
DVD 1/4 + comb, jsac, uctm
 DVD 2/4 + com

PIOMK PINSKI 13
 3124340 } CRYAN
 3125106 }

CONVOLUTIONAL CODING (MATLAB)

2.032, 2.035, ~~2.081~~, 2.082, 2.088, 2.132, 2.134, 2.143

USER COOPERATION DIVERSITY PART 1



- W_i $i=1,2$ - user's information
- $Y_0(t) = K_{10}X_1(t) + K_{20}X_2(t) + Z_0(t)$
- $Y_1(t) = K_{21}X_2(t) + Z_1(t)$
- $Y_2(t) = K_{12}X_1(t) + Z_2(t)$
- X_i HAVE AVERAGE POWER CONSTRAINT P_i $i=1,2$
- $Z_i(t)$ ZERO-MEAN COMPLEX GAUSSIAN RANDOM PROCES WITH SPECTRAL HEIGHT $N/2$ $i=0,1,2$

- K_{ij} ZERO-MEAN COMPLEX GAUSSIAN RANDOM VAR. WITH VARIANCE σ_{ij}^2 (CORRESPONDS TO RAYLEIGH FADING)

$Y_0 = K_{10}X_1 + K_{20}X_2 + Z_0$
 $Y_1 = K_{21}X_2 + Z_1$
 $Y_2 = K_{12}X_1 + Z_2$

$Z_0 \sim N(0, \sigma_0); Z_1 \sim N(0, \sigma_1); Z_2 \sim N(0, \sigma_2)$
 $\sigma_1 = \sigma_2$

TRANSMIT B BLOCKS OF LENGTH L

• the signal of user 1 at time j : $j=1, \dots, L$
 $X_1(W_{11}, Y_1(j-1), Y_1(j-2), \dots, Y_1(1))$

• for user 2:
 $X_2(W_{21}, Y_2(j-1), Y_2(j-2), \dots, Y_2(1))$

$X_1 = X_{10} + X_{12} + U_1$ $P_1 = P_{10} + P_{12} + P_{U1}$

Theorem 1: Achievable rate region of the system is the closure of the convex hull of all rate pairs (R_1, R_2)

$$R_1 = R_{10} + R_{12} \quad R_2 = R_{20} + R_{21}$$

$$R_{12} < \epsilon \left\{ C \left(\frac{K_{12}^2 R_{12}}{K_{12}^2 P_{10} + \Theta_1} \right) \right\} \quad R_{21} < \epsilon \left\{ C \left(\frac{K_{21}^2 R_{21}}{K_{21}^2 P_{20} + \Theta_2} \right) \right\}$$

$$R_{10} < \epsilon \left\{ C \left(\frac{K_{10}^2 P_{10}}{\Theta_0} \right) \right\} \quad R_{20} < \epsilon \left\{ C \left(\frac{K_{20}^2 P_{20}}{\Theta_0} \right) \right\}$$

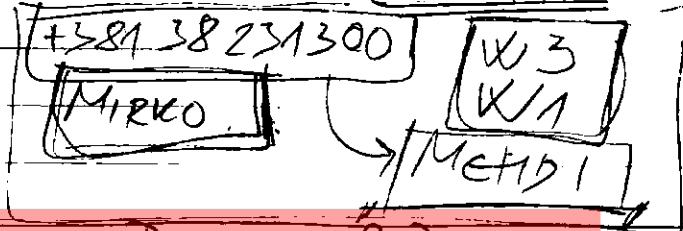
$$R_{10} + R_{20} < \epsilon \left\{ C \left(\frac{K_{10}^2 P_{10} + K_{20}^2 P_{20}}{\Theta_0} \right) \right\}$$

$$R_{10} + R_{20} + R_{12} + R_{21} < \epsilon \left\{ C \left(\frac{K_{10}^2 P_{10} + K_{20}^2 P_{20} + 2K_{10}K_{20} \sqrt{P_{10}P_{20}}}{\Theta_0} \right) \right\}$$

$$R_1 = P_{10} + P_{12} + P_{21} \quad R_2 = P_{20} + P_{21} + P_{12}$$

$$C(x) = \frac{1}{2} \log(1+x)$$

CAPACITY OF AWGN channel



WIRELESS COMMUNICATIONS PRINCIPLES & PRACTICE

- S DUPLEX CHANNELS

- k - NUMBER OF CHANNELS PER CELL ↑ i.e. CLUSTER SIZE
 N - NUMBER OF CELLS IN A CLUSTER

$$S = k \cdot N$$

$$C = M \cdot k \cdot N$$

CLUSTER CAPACITY

$$N = 4, 7, 12$$

$$N = 1^2 + 1j^2 + j^2$$

$$j = 2$$

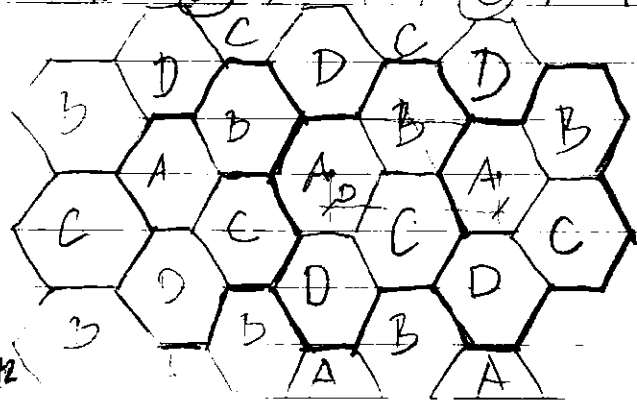
$$N = 9 + 6 + 4 = 19$$

Freq. Reuse = $1/N = 1/19$

Example 2.1 33MHz TOTAL BANDWIDTH FDD, 25kHz channel to provide voice & CC

- NUMBER OF CHANNELS AVAILABLE PER CELL = ?

FOR: (a) N=4 ; (b) N=7 ; (c) N=12



(a) N=4 k=?

$$S = \frac{33 \cdot 10^6}{25 \cdot 10^3} = \frac{33}{25} \cdot 10^3 = 1320 \text{ ch.} = 1320$$

$$1320 = k \cdot N$$

$$k = \frac{1320}{4} = 330 \text{ ch/cell}$$

(b) $k = \frac{1320}{7} = 188$ (c) $k = \frac{1320}{12} = 110$

• CO-CHANNEL INTERFERENCE

R - RADIUS OF THE CELL

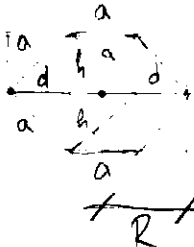
D - DISTANCE BETWEEN NEAREST CO-CHANNEL CELLS

$\frac{D}{R} \uparrow \rightarrow$ BETTER SPATIAL SEPARATION

$$Q = \frac{D}{R} = \sqrt{3N}$$

CO-CHANNEL REUSE RATIO

$$d^2 = R^2 + d^2 \quad h = d$$



$$2d = \sqrt{a^2 + a^2}$$

$$2d = a\sqrt{2}$$

$$d = \frac{a}{2}\sqrt{2}$$

$$R = \frac{a}{2} + \frac{a}{2}\sqrt{2}$$

$$2 = \frac{a}{2} (1 + \sqrt{2})$$

$$N = 4 \Rightarrow D = 2R + a = \frac{a}{2}(1 + \sqrt{2}) + a$$

$$D = \frac{a}{2}(1 + 1 + \sqrt{2}) = \frac{a}{2}(2 + \sqrt{2})$$

$$Q = \frac{D}{R} = 2 \frac{2 + \sqrt{2}}{1 + \sqrt{2}} \cdot \frac{1 + \sqrt{2}}{1 + \sqrt{2}} = 2 \frac{2 - 2\sqrt{2} + \sqrt{2} - 2}{1 - 2} = 2(1 - \sqrt{2}) = 2\sqrt{2}$$

$$Q = 2\sqrt{2} \Rightarrow Q = \sqrt{3 \cdot 4} = 2\sqrt{3}$$

• SIGNAL TO INTERFERENCE

$$\frac{S}{I} = \frac{S}{\sum_{i=1}^N I_i}$$

I_0 - NUMBER OF INTERFERING CELLS

• AVERAGE POWER AT DISTANCE "d"

$$P_r = P_0 \left(\frac{d}{d_0}\right)^{-n} \quad P_r \Big|_{d=d_0} = P_0 \Big|_{d=d_0} - 10n \log\left(\frac{d}{d_0}\right)$$

P_0 - POWER AT A CLOSE-IN REFERENCE POINT

d_0 - DISTANCE BETWEEN REFERENCE POINT AND ANTENNA

n - PATH LOSS EXPONENT (2-4 FOR URBAN CELLULAR SYSTEMS)

$$\frac{S}{I} = \frac{P^{-n}}{\sum_{i=1}^N D_i^{-n}}$$

$$D_1 \approx D_2 \approx \dots \approx D_{N_0}$$

$$\frac{S}{I} = \frac{P^{-n}}{N_0 D^{-n}} = \frac{(D/R)^n}{N_0} = \frac{D^n}{N_0 R^n}$$

$$\frac{S}{I} = \frac{(\sqrt{3N})^n}{N_0}$$

$$63 = \frac{(\sqrt{3N})^n}{6}$$

$$378 = (\sqrt{3N})^n$$

$$N^2 = \frac{108}{9} \Rightarrow N = \frac{1}{3} \sqrt{378} \quad N = 6.48$$

$$18 = 10 \log\left(\frac{S}{I}\right) \quad \left(\frac{S}{I}\right)^{10} = 10^{18} \quad \frac{S}{I} = 10^{\frac{18}{10}} = 10^{1.8} = 63$$

\rightarrow MINIMUM REQUIRED INTERFERENCE

$$\frac{S}{I} = \frac{P}{\sum_{i=1}^n D^{-n}} = \frac{P^{-4}}{2D^{-4} + 2(D+R)^{-4} + 2(D-R)^{-4}} = \frac{1}{2Q^{-4} + 2(Q+1)^{-4} + 2(Q-1)^{-4}}$$

$$Q = \sqrt{307} = \sqrt{21} \approx 4.6 \Rightarrow \text{Worst case } \frac{S}{I} = 17.8 \text{ dBm}$$

EXAMPLE 2.2

$\frac{S}{I} = 15 \text{ dB}$ $Q = ?$ $\textcircled{a} n = 4$
 $\textcircled{b} n = 3$
 $I_{10} = 6$

$$\frac{S}{I} = \frac{(\sqrt{3N})^n}{I_{10}} \quad 15 \text{ dB} = 10 \log \left(\frac{S}{I} \right)$$

$$\left(\frac{S}{I} \right)^{10} = 10^{15} \quad \left(\frac{S}{I} = 10^{1.5} \right) \quad \frac{S}{I} = 31.62$$

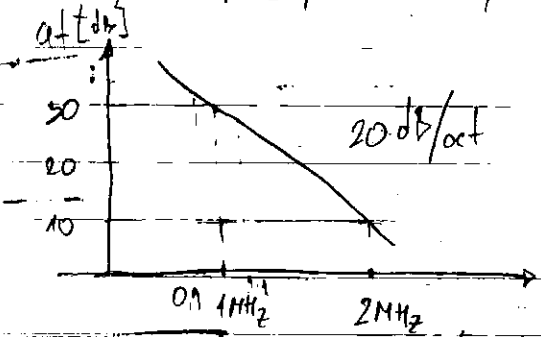
$$31.62 \cdot 6 = (\sqrt{3N})^n \quad Q^n = 31.62 \cdot 6 = 189.72$$

$\textcircled{a} Q = \sqrt[4]{189.72} = 3.71$

$Q = \sqrt{3N} \quad N = \frac{Q^2}{3} = \underline{\underline{459}}$

$\textcircled{b} Q = \sqrt[3]{189.72} = 5.74$

$N = \frac{Q^3}{3} = 11.01$



$$\frac{S}{I} = (20)^{-4}$$

$$(-4) \cdot 10 \log 20 = -40(\log 2 + 1)$$

$$= -40(0.3 + 1) = \underline{\underline{-52 \text{ dB}}}$$

Example 2.3

666 duplex channels

• 1989 FCC LOCATED ADDITIONAL 10 MHz i.e. 166 new ch.
 TOTAL = 666 + 166 = 832 ch.

FC 870,030 MHz } ch. 1-666
 PC 825,030 MHz }

FC 889,98 MHz } ch. 667-832
 PC 844,98 MHz }

EXTENDED BAND 667-799
 990-1023

TRUNKING

$A_u = \lambda \cdot H$ [Er]

H - AVERAGE DURATION OF A CALL
 λ - AVERAGE NUMBER OF CALL REQUESTS PER UNIT TIME
 A_u - TRAFFIC INTENSITY

• FOR SYSTEM CONTAINING U USERS TOTAL OFFERED TRAFFIC IS:

$A = U \cdot A_u$ [Er]

$A_c = \frac{A}{C} = \frac{U \cdot A_u}{C}$ traffic intensity per channel

$$P_r[\text{blocking}] = \frac{\frac{A^C}{C!}}{\sum_{k=0}^C \frac{A^k}{k!}}$$

ERLANG B
FOR INFINITE
NUMBER OF USERS
BLOCK CALLS CLEARED

C - NUMBER OF TRUNKED CHANNELS
A - TOTAL OFFERED TRAFFIC
C → ∞

$$P_r = \frac{A^C}{C!} e^{-A}$$

• ERLANG C FORMULA

$$P_r[\text{delay} > 0] = \frac{A^C}{A^C + C! \left(1 - \frac{A}{C}\right) \sum_{k=0}^{C-1} \frac{A^k}{k!}}$$

ERLANG C
BLOCK CALLS REJECTED

$$P(A, B) = P(A) P(B/A)$$

$$\begin{aligned} \text{GOS} = P_r[\text{delay} > t] &= P_r[\text{delay} > 0] \cdot P_r[\text{delay} > t / \text{delay} > 0] \\ &= P_r[\text{delay} > 0] \cdot \exp(-(C-A) \cdot t/H) \end{aligned}$$

AVERAGE DELAY OF A CALL:

$$D = P_r[\text{delay} > 0] \cdot \frac{H}{C-A}$$

EXAMPLE 2.4 HOW MANY USERS CAN BE SUPPORTED FOR
 $P_r = 0.5\%$ (0,005) BLOCK CALLS CLEARED

(a) C=1 (b) C=5 (c) C=10 (d) C=20 (e) C=100

$$A_u = 0.1 [\text{ER}] \quad A = U \cdot A_u$$

$$P_r = \frac{\frac{A^C}{C!}}{\sum_{k=1}^C \frac{A^k}{k!}} \Rightarrow \text{(a) } A = \left. \begin{matrix} P_r = 0.005 \\ C = 1 \end{matrix} \right| = 0.005025$$

$$U = \frac{A}{A_u} = \frac{0.005025}{0.1} = 0.05$$

(b) U=113 (c) U=396 (d) U=1109 (e) U=8091

EXAMPLE 2.5 - 2M RESIDENTS i. A, B, C COMPETING MOBILE PROVIDERS

- A - 394 CELLS WITH 19 CH
- B - 98 CELLS WITH 57 CH
- C - 49 CELLS WITH 100 CH

$P_r = 2\%$ EACH USER MAKES 2 CALLS/HOUR DURATION 3 MIN

$$A_u = 2 \cdot 3 \text{ min} / 60 \text{ min} = 6/60 = 0,1 [\text{ER}]$$

$$A = U \cdot A_u = 2 \cdot 10^6 \cdot 0,1 = 200.000,00 [\text{ER}]$$

- ALL THREE OPERATE AT MAXIMUM CAPACITY. MARKET PENETRATION OF EACH PROVIDER = ?

(a) $C_A = 394 \cdot 19 = 7486$

$$0,02 = \frac{\frac{A_A^{C_A}}{C_A!}}{\sum_{k=0}^{C_A} \frac{A_A^k}{k!}}$$

$$\begin{aligned} C_A &= 19 \\ A_A &= 12.333 [\text{ER}] \\ U_A &= 394 \cdot U = 48591 \text{ users} \end{aligned}$$

$$\begin{aligned} A_A &= U \cdot A_u \\ U &= \frac{12.333}{0,1} = 123.33 \\ &= 123.33 \end{aligned}$$

② $C = 57$ $A = 468 \text{ [Er]} = U \cdot A_0$ $U = \frac{A}{A_0} = 468$

$U_3 = 98 \cdot U = 45879,71$

③ $C = 100$ $A = 87,77$ $U = 879,7$

$U_c = 49 \cdot 87,77 = 43106,27$

$P_A = 2,42\%$ $P_B = 2,27\%$ $P_C = 2,16\%$ $P = (U_A + U_B + U_C) / 2 \cdot 10^6 = 6.9\%$

EXAMPLE 2.6

CITY AREA = 1500 mi^2

$N = 7$

CELL RADIUS $R = 4 \text{ mi}$

$B = 40 \text{ MHz}$

CHANNEL BANDWIDTH $B_c = 60 \text{ kHz}$ (FULL DUPLEX)

$GOS = 0,02 = 2\%$ $A_0 = 0,03 \text{ Er}$

① number of cells in area

② number of ch/cell

③ traffic intensity/cell

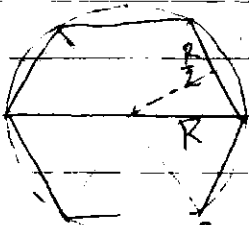
④ maximum carried traffic

⑤ total number of user that can be served

⑥ mobiles/channel = ?

⑦ theoretical max number of users served in one time

⑧ Cell Number = $\frac{1500}{R^2 \pi} = \frac{1500}{16 \pi} = 29,86$



$P = 6 \cdot R \cdot \frac{h}{2}$ $h = \sqrt{R^2 - \frac{R^2}{4}} = \frac{R}{2} \sqrt{3}$

$P = 3 \cdot R \cdot \frac{R}{2} \sqrt{3} = \frac{3R^2}{2} \sqrt{3} = \frac{16}{2} \cdot 3\sqrt{3}$

$P = \frac{3R^2}{2} \sqrt{3}$ Cell Number = $\frac{1500}{8 \cdot 3\sqrt{3}} = \frac{31,273}{8} \approx 31$

⑨ $S = k \cdot N = \frac{40 \cdot 10^6}{60 \cdot 10^3} = 0,666 \cdot 10^3 = 666 \text{ ch}$

$k = C = \frac{666}{N} = \frac{666}{7} = 95,23$ $C = 95$

⑩ $0,02 = \frac{A/C}{\sum_{k=1}^C \frac{A^k}{k!}} \rightarrow A = 83,13 \text{ [Er]}$

⑪ Max. carried traffic = $A \cdot 31 = 2582 \text{ [Er]}$

⑫ $A = A_0 \cdot U \rightarrow U = \frac{A}{A_0} = \frac{83,13}{0,03} = 2771 \text{ users}$

Total number of user = $277 \cdot 31 = 85901$

⑬ mobile/ch = $\frac{85901}{666} = 129$ mobiles/channel

⑭ Max User = $31 \cdot 95 = 2945$ users $\frac{2945}{85901} = 3,4\%$

EXAMPLE 2.7

- 4 CELL SYSTEM $R = 1,387 \text{ km}$
- TOTAL CHANNELS = 60
- LOAD PER USER $A_U = 0,029 \text{ [Er]}$ $\lambda = 1 \text{ call/hour}$
- ERLANG C SYSTEM $P_r[\text{delayed}] = 0,05$

$$P_r[\text{delay} > 0] = \frac{A^C}{A^C + (1 - \frac{1}{C}) \sum_{k=0}^{C-1} \frac{A^k}{k!}}$$

FIND: (a) $U = ?$ (users per square km) (b) $P_r[\text{delay} > 10s] = ?$
 (c) $P_r[\text{delay} > 10 | \text{delay}] = ?$

(a) $P = \frac{387^2}{2} \sqrt{3} = 5 \cdot 10^6 \text{ m}^2$
 CHANNELS PER CELL = $\frac{60}{4} = 15 \text{ ch/cell}$

$A = U \cdot A_U$ $U = ?$ $P_r = 0,05 \Rightarrow A = 10,745$
 $U = \frac{A}{A_U} = \frac{10,745}{0,029} = 370 \text{ users}$ $U_{\text{cell}} = \frac{370}{5} = 74 \frac{\text{users}}{\text{km}^2}$

(b) $P_r[\text{delay} > t] = P_r[\text{delay} > 0] \cdot e^{-\frac{(C-A)t}{H}}$
 $H = \text{holding time}$ $A_U = H \cdot \lambda$ $0,029 = H \cdot 1/60$
 $H = 0,029 \cdot 60 = 1,74 \text{ min/call} = 0,029 \text{ hours/call} = 104 \text{ sec/call}$

$P_r[\text{delay} > 10s] = 0,05 \cdot e^{-\frac{(15 - 10,745) \cdot 10}{104,4}} = 0,033 = 3,3\%$

(c) $P_r[\text{delay} > 10 | \text{delay}] = e^{-\frac{(C-A)t}{H}} = e^{-\frac{(15 - 10,745)}{10,44}} = 0,665 = 66,5\%$

VEROZATROST DENA ORLOVAN. 10VNIK RE IEMA PINECE OD 10SEC DISCUSSION

$P_r(10, A) = 0,01$	$A = 4,46 \text{ Er}$	} 1 CELL WITH 10 CHANNELS
$P_r(5, A) = 0,01$	$A = 1,36 \text{ Er}$	
		} 2 CELLS WITH 5 CHANNELS
		SUPPORT TRAFFIC OF $2 \times 1,36 = 2,72 \text{ Er}$

• CELL SPLITTING
 $P_r[\text{old cell band}] \sim P_{t1} R^{-4}$
 $P_r[\text{new cell band}] \sim P_{t2} (\frac{R}{2})^{-4}$
 • IF $u=4$ $P_{t1} R^{-4} = P_{t2} (\frac{R}{2})^{-4}$ $\frac{P_{t2}}{P_{t1}} = \frac{16}{24}$ $P_{t2} = \frac{P_{t1}}{16}$
 $10 \log P_{t2} = 10 \log P_{t1} - 10 \log(16) = 10 \log P_{t1} - 16 \text{ dB}$

EXAMPLE 28

BASE STATION USES 60CH

$R_{HELLO} = 1 \text{ km}$ $R_M = 0,5 \text{ km}$

NUMBER OF CHANNELS IN $3 \times 3 \text{ km}$ SQUARE

- (a) WITHOUT USE OF μ -cell
 - (b) μ -cell used & M-cell used
 - (c) μ -cell used
- (a) $5 \cdot 60 = 300 \text{ ch}$ (b) $11 \cdot 60 = 660 \text{ ch}$ (c) $17 \cdot 60 = 1020 \text{ ch}$

SECTORING

$$\frac{S}{I} = \frac{P}{\sum_{k=1}^N D^{-n}} = \frac{P}{10 D^{-n}} = \frac{(D/R)^n}{10} = \frac{(\sqrt{3N})^n}{2}$$

$N=7 \Rightarrow \frac{(\sqrt{3 \cdot 7})^4}{2} = \frac{(21)^2}{2} = 220,5$ $10 \log 220,5 = 23,4 \text{ dB}$

UNSECTORED $\frac{N-A}{N} 10 \log \frac{S}{I} = 10 \log \frac{21^2}{6} = 18,66 \text{ dB}$

$\frac{N=12}{N} 10 \log \frac{S}{I} = 10 \log \frac{(12 \cdot 3)^2}{11} = 20,71 \text{ dB}$

EXAMPLE 2.9

AVERAGE CALL LASTS 2 min $P_R = 0,01$
 $H = 2 \text{ min}$ $\lambda = 1 \text{ CALL/HOUR}$

$C = 395$ $N = 7$ $C_{cell} = 56,42 \approx 57$, ERLANG B

$P_R = \frac{\frac{AC}{C!}}{\sum_{k=0}^C \frac{A^k}{k!}}$ $P_R = 0,01 \Rightarrow A = 44,22 \text{ Er}$

$A_U = \lambda \cdot H = \frac{1}{60} \cdot 2 = \frac{1}{30} = 0,033$

$A = U \cdot A_U \Rightarrow U = \frac{A}{A_U} = \frac{44}{0,033} = 1340 \text{ users (CELL)}$
 i.e. calls/hour

120° SECTORING $\Rightarrow \frac{57}{3} = 19$

$P_R(19, A) = 0,01$
 $\Rightarrow A = 11,25 \text{ Er}$

$U = \frac{A}{A_U} = \frac{11,25}{0,033} = 336,93 \text{ CALLS/HOUR (SECT)}$ $3 \cdot 336 = 1008 \text{ CALLS/HOUR (CELL)}$

$\frac{1340}{1008} = 1,33$ $1340(1-x) = 1008$ $x = \frac{1340 - 1008}{1340}$

$x = 24,8\%$ ~~DECREASE OF TRUNKING EFFICIENCY~~
 $1008 \cdot x + 1008 = 1340$ $x = \frac{1340 - 1008}{1008} = 33\% \text{ INCREASE}$

60° SECTORING $N=7$ $10 \log \left(\frac{S}{I} \right) = 10 \log \left(\frac{(\sqrt{3 \cdot 7})^4}{1} \right) = 10 \log 21^2 = 26,6 \text{ dB}$

$\frac{57}{6} = 9,5 \approx 9 \text{ CH}$ $P_R(9, A) = 0,01 \Rightarrow A = 3,78$

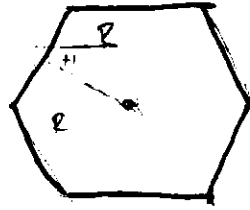
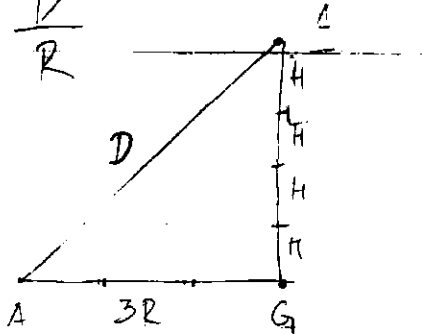
$U = \frac{A}{A_U} = \frac{3,78}{0,033} = 114,62 \text{ users i.e. CALLS/HOUR}$
 $114,62 \cdot 6 = 687$ $x = \frac{1340 - 687}{1340} = 48\% \text{ DECREASE}$

$$G = \frac{D}{2} = \sqrt{3N} \Rightarrow N = \frac{1}{3} \left(\frac{D}{2} \right)^2 = \left| \frac{D}{2} - 3 \right| = \frac{9 - 3}{3} = 2$$

• PROBLEMS

PR.2.1

$$G = \frac{D}{2}$$



$$H = \sqrt{R^2 - \frac{R^2}{4}}$$

$$H = \frac{\sqrt{3}}{2} R$$

$$D^2 = 9R^2 + \left(\frac{4R\sqrt{3}}{2} \right)^2$$

$$D^2 = 9R^2 + 4R^2 \cdot 3 = 9R^2 + 12R^2$$

$$D^2 = 21R^2 \quad \frac{D}{R} = \sqrt{21} = \sqrt{3N}$$

MOBILE RADIO PROPAGATION

$$P_r = P_o \left(\frac{d}{d_0} \right)^{-n}$$

$$10 \log P_r = 10 \log P_o + 10 \log \left(\frac{d}{d_0} \right)^{-n}$$

$$10 \log P_r = 10 \log P_o - 10n \log \frac{d}{d_0}$$

$$10 \log \frac{P_r}{P_o} = -10n \log \frac{d}{d_0} \quad \text{IF } P_o = 1 \text{ mW} \quad P_r [\text{dBm}] = -10n \log \frac{d}{d_0}$$

FREE SPACE PROPAGATION MODEL

• FRIS FREE SPACE EQUATION:

$$P_r(d) = \frac{P_t G_t G_r \lambda^2}{(4\pi)^2 d^2 L}$$

P_t - TRANSMITTED POWER
 P_r - RECEIVED POWER

G_t - TRANSMITTER ANTENNA GAIN

G_r - RECEIVER ANTENNA GAIN

d - T-R SEPARATION DISTANCE (m)

L - SYSTEM LOSS FACTOR

$L \geq 1$ λ - WAVELENGTH (m)

$$G = \frac{4\pi A_e}{\lambda^2}$$

A_e - RELATIVE APERTURE

$$\lambda = \frac{c}{f} = \frac{299792458}{f}$$

$$d_2 = 10d_1$$

$$\frac{P_{r2}}{P_{r1}} = \frac{G_t G_r \lambda^2}{(4\pi)^2 d_2^2 L}$$

$$\frac{P_{r2}}{P_{r1}} = \frac{G_t G_r \lambda^2}{(4\pi)^2 10d_1^2 L}$$

$$\frac{P_{r2}/P_{r1}}{P_{r1}/P_{r2}} = \frac{1/d_2^2}{1/d_1^2} = 100$$

$$10 \log \frac{P_{r2}}{P_{r1}} - 10 \log \frac{P_{r1}}{P_{r2}} = 20 \text{ dB}$$

$$\alpha_1 - \alpha_2 = 20 \text{ dB}$$

isotropic radiator is ideal antenna which radiates power with unit gain uniformly in all directions.

$$EIRP = P_t G_t$$

effective isotropic radiated power

• half wave dipole antenna $G = 1.64$ i.e. 2.15 dB above isotropic antenna

$$EIRP = EIRP + 2.15 \text{ dB}$$

EIRP - effective radiated power

$$10 \log 1.64 = 2.15 \text{ dB}$$

dB_i - GAIN OF THE ANTENNA COMPARED TO ISOTROPIC ANT

dB_d - ANTENNA GAIN WITH RESPECT TO HALF-WAVE DIPOLE

• PATH LOSS

$$PL = 10 \log \frac{P_T}{P_R} = 10 \log \frac{P_T}{\frac{P_T G_T G_R \lambda^2}{(4\pi)^2 d^2}} = -10 \log \frac{G_T G_R \lambda^2}{(4\pi)^2 d^2}$$

• $G_T, G_R = 1$ $PL = -10 \log \frac{\lambda^2}{(4\pi)^2 d^2}$

• d_f - FAR FIELD DISTANCE $\left[d_f = \frac{2D^2}{\lambda} \right]$ $d_f \gg D$
 $d_f \gg \lambda$

D - LARGEST PHYSICAL LINEAR DIMENSION OF THE ANTENNA

• d_0 - REFERENCE DISTANCE LIES IN THE FAR FIELD REGION

i.e. $\left[d_0 \gg d_f \right]$

$$P_r(d) = \frac{P_T \cdot G_T G_R \cdot \lambda^2}{(4\pi)^2 d^2 L} \quad P_r(d_0) = \frac{P_T G_T G_R \lambda^2}{(4\pi)^2 d_0^2 L}$$

$$\frac{P_r(d)}{P_r(d_0)} = \frac{1/d^2}{1/d_0^2} = \left(\frac{d_0}{d} \right)^2 \quad P_r(d) = P_r(d_0) \frac{d_0^2}{d^2} = P_r(d_0) \left(\frac{d_0}{d} \right)^2$$

$$\left[P_r(d) [dB_m] = 10 \log \frac{P_r(d)}{1 \text{ mW}} + 20 \log \left(\frac{d_0}{d} \right) \right] \quad d \geq d_0 \gg d_f$$

Ex 3.1 far field distance? $D = 1 \text{ m}$ $f = 900 \text{ MHz}$

$$d_f = \frac{2D^2}{\lambda} \quad \lambda = \frac{300}{f [\text{MHz}]} = \frac{300}{900} = \frac{1}{3} = 0,333 \text{ m}$$

$$\left[d_f = \frac{2 \cdot 1^2}{\frac{1}{3}} = 6 \text{ m} \right]$$

Ex 3.2 $P_T = 50 \text{ W}$ $G_T = 1$ $f = 900 \text{ MHz}$ $P_r [dB_m] = ?$

$d = 100 \text{ m}$ $P_r = ?$

$d = 10 \text{ km}$ $P_r = ?$

$$P_T [dB_m] = 10 \log \frac{50}{10^3} = 46 \text{ dB}_m \quad P_T [dBW] = 17 \text{ dBW}$$

$$P_r = \frac{P_T \cdot G_T \cdot G_R \cdot \lambda^2}{(4\pi)^2 d^2} = \frac{50 \text{ W} \cdot 1 \cdot \left(\frac{1}{3}\right)^2}{(4\pi)^2 d^2} = \frac{50}{169 \pi^2 \cdot 10^4}$$

$$P_r = \frac{5}{144 \pi^2 \cdot 10^3} = 3,518 \cdot 10^{-6} \quad P_r [dB_m] = -24,5 \text{ dB}_m$$

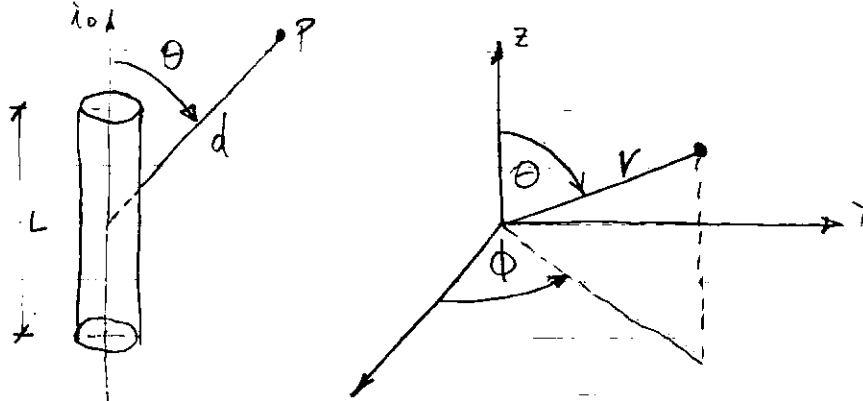
$$P_r [10 \text{ km}] = P_r [100 \text{ m}] + 20 \log \left(\frac{d_0}{d} \right) = -24,5 + 20(-2) = -64,5 \text{ dB}_m$$

180 $P_r [10 \text{ km}] [W] = ?$ $40 \text{ dB}_m = 10 \log P$

$$-64,5 = 10 \log \frac{P_r [100\text{W}]}{0,001} \Rightarrow \left[\frac{P_r (100\text{W})}{0,001} \right]^{10} = 10^{64,5}$$

$$P_r (100\text{W}) = 0,001 \cdot 10^{-6,45} = 35 \cdot 10^{-9} \text{ W} = \underline{\underline{35 \text{ pW}}}$$

• RELATING POWER TO ELECTRIC FIELD



$$E_v = \frac{\lambda_0 L \cos \theta}{2\pi \epsilon_0 c} \left\{ \frac{1}{d^2} + \frac{c}{j\omega c d^3} \right\} e^{j\omega c(t-dc)}$$

ELECTROSTATIC FIELD (1/d²)

$$E_\theta = \frac{\lambda_0 L \sin \theta}{4\pi \epsilon_0 c^2} \left\{ j\omega c \frac{c}{d} - \frac{c}{d^2} + \frac{c^2}{j\omega c d^3} \right\} e^{-j\omega c(t-dc)}$$

RADIATION FIELD (1/d)

$$H_\phi = \frac{\lambda_0 L \sin \theta}{4\pi c} \left\{ \frac{j\omega c}{d} + \frac{c}{d^2} \right\} e^{j\omega c(t-dc)}$$

INDUCTIVE FIELD (1/d²)

$$E_\phi = H_r = H_\theta = 0$$

TERM: $\frac{1}{d^2}$ - REPRESENT INDUCTION FIELD COMPONENT

TERM: $\frac{1}{d}$ - REPRESENT ELECTROSTATIC FIELD COMPONENT

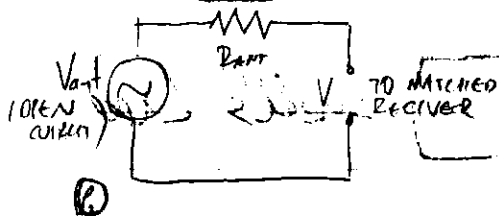
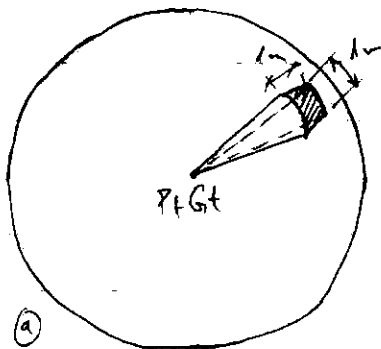
TERM: $1/d$ - REPRESENT RADIATION FIELD COMPONENT

• POWER FLUX DENSITY

$$P_d = \frac{E^2 R_p}{4\pi d^2} = \frac{P_t G_t}{4\pi d^2} = \frac{c^2}{4\pi d^2} = \frac{c^2}{4\pi} \left[\frac{\text{W}}{\text{m}^2} \right]$$

Z_{fs} - INTRINSIC IMPEDANCE OF FREE SPACE $\eta = 120\pi \Omega (377\Omega)$

$$P_d = \frac{E^2}{377\Omega} = \frac{\text{W}}{\text{m}^2}$$



$$P_d = \frac{P_t G_t}{4\pi d^2} = \frac{E^2 R_p}{4\pi d^2}$$

$$P_r(d) = P_d A_e = \frac{E^2 R_p}{4\pi d^2} A_e = \frac{P_t G_t G_r \lambda^2}{(4\pi)^2 d^2} \text{ [Watts]}$$

$$P_r(d) = \frac{V^2}{Z_{ant}} = \frac{(V_{ant}/2)^2}{Z_{ant}} = \frac{V_{ant}^2}{4 Z_{ant}}$$

$$A_e = \frac{G_r \lambda^2}{4\pi}$$

Ex 3.3

RECEIVER LOCATED AT $d = 10 \text{ km}$ $F = 50 \text{ W}$ $f_c = 300 \text{ MHz}$

$G_t = 1$ $G_r = 2$

- (a) $P_r = ?$ (b) $|E| = ?$ (c) rms voltage? $R_{ant} = 50 \Omega$

(a) $P_r = \frac{P_t \cdot G_t \cdot G_r \cdot \lambda^2}{(4\pi d)^2 \cdot L} = \frac{50 \cdot 1 \cdot 2 \cdot (\frac{1}{3})^2}{(4\pi)^2 \cdot 10^8} = \frac{10^2}{16\pi^2 \cdot 10^8 \cdot 9} = \frac{1}{144\pi^2 \cdot 10^6}$

$P_r = 0.7 \cdot 10^{-9} = 0.7 \text{ nW} = 700 \text{ pW} = -61 \text{ dBm}$

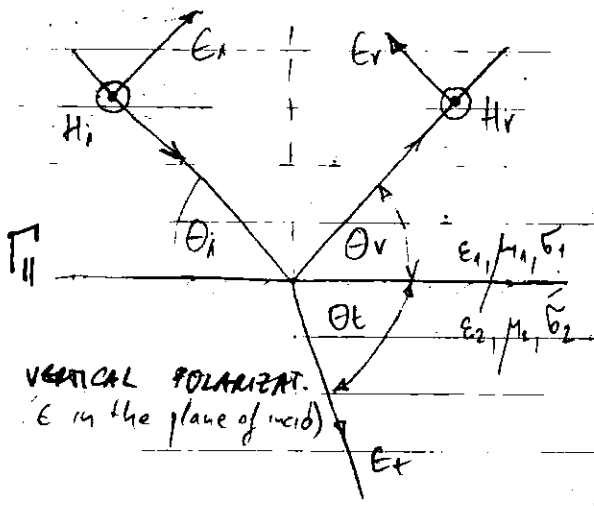
(b) $P_r(d) = P_d A_e = \frac{|E|^2}{120\pi} A_e$ $|E|^2 = \frac{120\pi P_r(d)}{A_e}$

$|E| = \sqrt{\frac{120\pi P_r(d)}{A_e}} = \frac{0.51 \cdot 10^{-3}}{\sqrt{A_e}} = \sqrt{A_e = \frac{G_r \lambda^2}{4\pi}} = \frac{0.51 \cdot 10^{-3}}{0.153} = 3.3 \cdot 10^{-3} \text{ V/m}$

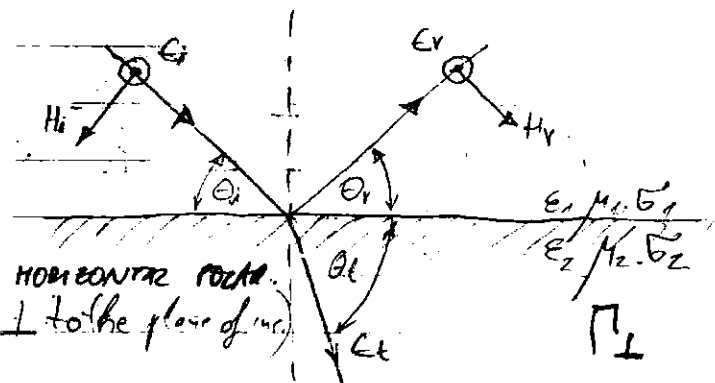
(c) $P_r = \frac{V^2}{R_{ant}}$ $V = \sqrt{P_r \cdot R_{ant}} = 0.18 \text{ mV} = 0.18 \cdot 10^{-3}$

$V_{ant} = 2V = 0.36 \text{ mV}$

REFLECTION FROM DIELECTRICS



ϵ - permittivity (dielectric constant)
 μ - permeability
 σ - conductance



PERFECTS DIELECTRIC

$\epsilon = \epsilon_0 \cdot \epsilon_r$ $\epsilon_0 = 8.85 \cdot 10^{-12} \text{ F/m}$

LOSSY DIELECTRIC

$\epsilon = \epsilon' - j\sigma/\omega$

$\epsilon' = \frac{\sigma}{\omega \tan \delta}$

σ - conductivity
 σ [SIEMENS/meter]

$n_i = \sqrt{\frac{\mu_i}{\epsilon_i}}$

INTRINSIC IMPEDANCE

$v = \frac{1}{\sqrt{\mu \epsilon}}$

WAVELENGTH IN EM WAVE

$\Gamma_{\parallel} = \frac{\epsilon_2 \sin 2\theta_t - \epsilon_1 \sin 2\theta_i}{\epsilon_2 \sin 2\theta_t + \epsilon_1 \sin 2\theta_i}$
 $\Gamma_{\perp} = \frac{\epsilon_2 \sin \theta_t - \epsilon_1 \sin \theta_i}{\epsilon_2 \sin \theta_t + \epsilon_1 \sin \theta_i}$

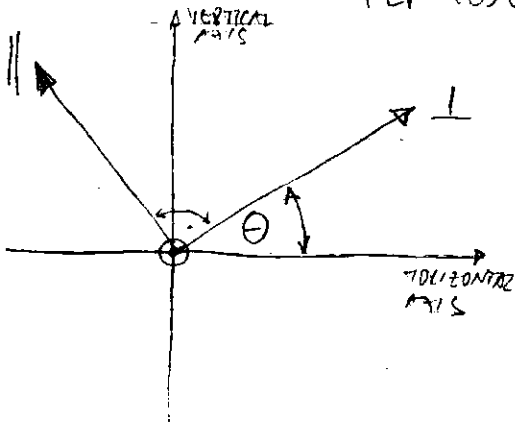
BOUNDARY CONDITIONS AT THE SURFACE OF INCIDENCE

$\sqrt{\mu_1 \epsilon_1} \sin(90 - \theta_i) = \sqrt{\mu_2 \epsilon_2} \sin(90 - \theta_t)$ Snell's Law

- FROM THE BOUNDARY CONDITIONS OF MAXWELL EQUATION \Rightarrow $\boxed{E_{\parallel} = \Theta_V \quad \text{and} \quad \epsilon_1 E_{\perp} = \epsilon_2 E_{\perp}}$ Γ (Γ_{\parallel} OR Γ_{\perp})
- FREE SPACE (FIRST MEDIUM) & $\mu_1 = \mu_2 = \mu \quad \epsilon = \epsilon_0 \epsilon_r$

$$\Gamma_{\parallel} = \frac{n_2 \sin \theta_t - n_1 \sin \theta_i}{n_2 \sin \theta_t + n_1 \sin \theta_i} = \frac{-\epsilon_2 \sin \theta_t + \sqrt{\epsilon_2 - \cos^2 \theta_i}}{\epsilon_2 \sin \theta_t + \sqrt{\epsilon_2 - \cos^2 \theta_i}}$$

$$\Gamma_{\perp} = \frac{\sin \theta_i - \sqrt{\epsilon_r - \cos^2 \theta_i}}{\sin \theta_i + \sqrt{\epsilon_r - \cos^2 \theta_i}}$$



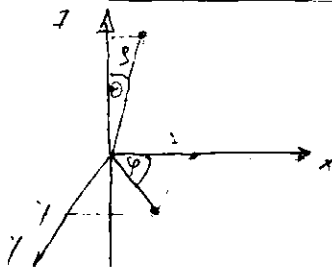
$$\begin{bmatrix} E_{\parallel}^d \\ E_{\perp}^d \end{bmatrix} = R^T D_C R \begin{bmatrix} E_{\parallel}^i \\ E_{\perp}^i \end{bmatrix}$$

$$R = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$$

$$D_C = \begin{bmatrix} D_{\parallel} & 0 \\ 0 & D_{\perp} \end{bmatrix} \rightarrow \text{DIAGONALIZATION MATRIX}$$

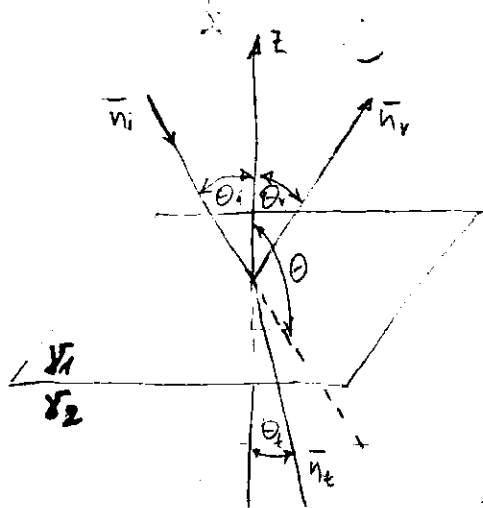
$$D_{xx} = \Gamma_x \quad (\text{REFLECTION})$$

$$D_{xt} = T_x = 1 + \Gamma_x \quad (\text{REFLECTED + TRANSMISSION})$$



$$\begin{aligned} z &= \rho \cos \theta \\ x &= \rho \sin \theta \cos \phi \\ y &= \rho \sin \theta \sin \phi \end{aligned}$$

• ОДНАКЪНЕ И РЕФРАКЦИЈА НА Е.М.В



$$\theta = \pi - \theta_i \quad \delta^2 = -\omega^2 \epsilon \mu \quad \boxed{\delta = \sqrt{\mu \epsilon \omega^2}}$$

$$U = U_0 e^{-\delta(x \sin \theta \cos \phi + y \sin \theta \sin \phi + z \cos \theta)}$$

$$\delta_1(x \sin \theta_i \cos \phi_i + y \sin \theta_i \sin \phi_i + z \cos \theta_i) =$$

$$\delta_1(x \sin \theta_r \cos \phi_r + y \sin \theta_r \sin \phi_r + z \cos \theta_r) =$$

$$\delta_2(x \sin \theta_t \cos \phi_t + y \sin \theta_t \sin \phi_t + z \cos \theta_t)$$

$$\delta_1 \sin \theta_i \cos \phi_i = \delta_1 \sin \theta_r \cos \phi_r \quad \text{I}$$

$$\delta_1 \sin \theta_i \sin \phi_i = \delta_2 \sin \theta_t \sin \phi_t \quad \text{II}$$

$$\delta_1 \sin \theta_i \cos \phi_i = \delta_2 \sin \theta_t \cos \phi_t \quad \text{III}$$

$$\delta_1 \sin \theta_i \sin \phi_i = \delta_2 \sin \theta_t \sin \phi_t \quad \text{IV}$$

$$\frac{\text{III}}{\text{I}} \quad \text{tg } \phi_i = \text{tg } \phi_r \Rightarrow \boxed{\phi_i = \phi_r} \quad (*)$$

$$(*) \text{ I} \Rightarrow \sin \theta_i = \sin \theta_r \Rightarrow \boxed{\theta_i = \theta_r} \quad \text{I} \text{ SNELL'S LAW}$$

$$\frac{\text{IV}}{\text{II}} \quad \text{tg } \phi_i = \text{tg } \phi_t \Rightarrow \boxed{\phi_i = \phi_t} \quad (1)$$

$$\text{I, II} \quad \delta_1 \sin \theta_i = \delta_2 \sin \theta_t \Rightarrow \boxed{\frac{\sin \theta_i}{\sin \theta_t} = \frac{\delta_2}{\delta_1} = \frac{\sqrt{\epsilon_2 \mu_2}}{\sqrt{\epsilon_1 \mu_1}} = \frac{n_2}{n_1}} \quad \text{II SNELL'S LAW}$$

• INDEX NA PREKUSVANJE:

$$n_1 = \frac{c}{v_1}$$

$$v_1 = \frac{1}{\sqrt{\epsilon_1 \mu_1}} \quad ; \quad v_2 = \frac{c}{n_2}$$

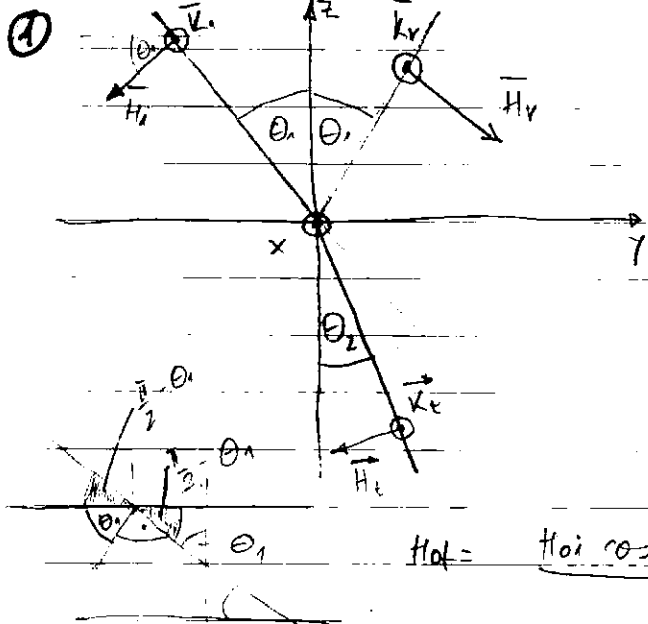
$$v_2 = \frac{1}{\sqrt{\epsilon_2 \mu_2}} \Rightarrow n_1 = c \sqrt{\epsilon_1 \mu_1} \quad ; \quad n_2 = c \sqrt{\epsilon_2 \mu_2}$$

II SNEKOV ZAKON

$$c \sqrt{\epsilon_1 \mu_1} \sin \theta_1 = c \sqrt{\epsilon_2 \mu_2} \sin \theta_2 \quad ; \quad \sqrt{\epsilon_1 \mu_1} \sin \theta_1 = \sqrt{\epsilon_2 \mu_2} \sin \theta_2$$

• FLENEZONI KOEFICIENTI

$$z = \frac{K}{H}$$



$$\begin{aligned} K_{oi} + K_{or} &= K_{ot} \\ H_{oi} \cos \theta_1 - H_{or} \cos \theta_1 &= H_{ot} \cos \theta_2 \\ H_{oi} &= \frac{K_{oi}}{z_1} \quad ; \quad H_{or} = \frac{K_{or}}{z_1} \\ z_1 &= \sqrt{\frac{\mu_1}{\epsilon_1}} \quad ; \quad H_{ot} = \frac{K_{ot}}{z_2} \\ z_2 &= \sqrt{\frac{\mu_2}{\epsilon_2}} \end{aligned}$$

$$K_{or} = K_{ot} - K_{oi} = z_2 H_{ot} - K_{oi}$$

$$H_{ot} = \frac{H_{oi} \cos \theta_1 - H_{or} \cos \theta_1}{\cos \theta_2}$$

$$K_{or} = z_2 \left(\frac{K_{oi}}{z_1} \cos \theta_1 - \frac{K_{or}}{z_1} \cos \theta_1 \right) - K_{oi}$$

$$K_{or} \cos \theta_2 = \frac{z_2}{z_1} K_{oi} \cos \theta_1 - \frac{z_2}{z_1} K_{or} \cos \theta_1 - K_{oi} \cos \theta_2$$

$$K_{or} \left(\cos \theta_2 + \frac{z_2}{z_1} \cos \theta_1 \right) = K_{oi} \left(\frac{z_2}{z_1} \cos \theta_1 - \cos \theta_2 \right)$$

$$K_{or} = \frac{z_2 \cos \theta_1 - z_1 \cos \theta_2}{z_1 \cos \theta_2 + z_2 \cos \theta_1} K_{oi}$$

\vec{k} e normalno NA INCIDENTNATI SLOMILINI

$$K_{ot} = K_{or} + K_{oi} = H_{or} z_1 + K_{oi}$$

$$H_{or} = \frac{H_{oi} \cos \theta_1 - H_{ot} \cos \theta_2}{\cos \theta_1}$$

$$K_{ot} = z_1 \left(\frac{K_{oi}}{z_1} \cos \theta_1 - \frac{K_{ot}}{z_2} \cos \theta_2 \right) + K_{oi}$$

$$K_{ot} \cos \theta_1 = K_{oi} \cos \theta_1 - \frac{z_1}{z_2} K_{ot} \cos \theta_2 + K_{oi} \cos \theta_1$$

$$K_{ot} \left(\cos \theta_1 + \frac{z_1}{z_2} \cos \theta_2 \right) = 2 K_{oi} \cos \theta_1$$

$$K_{ot} = \frac{2 z_2 \cos \theta_1 K_{oi}}{z_1 \cos \theta_2 + z_2 \cos \theta_1}$$

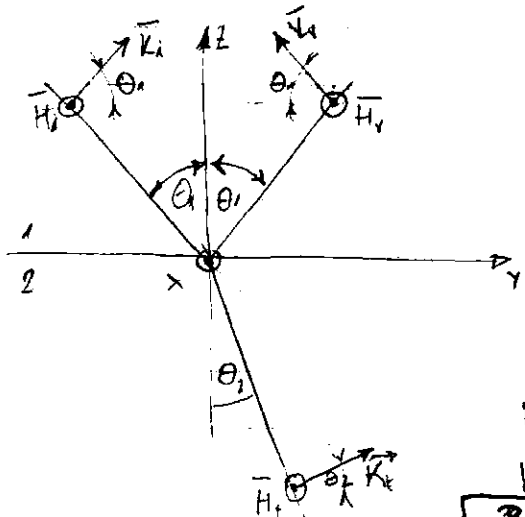
$$K_{or} = R_n \cdot K_{oi} \quad ; \quad R_n = \frac{z_2 \cos \theta_1 - z_1 \cos \theta_2}{z_1 \cos \theta_2 + z_2 \cos \theta_1}$$

$$z_1 \sin \theta_1 = z_2 \sin \theta_2$$

$$\cos \theta_2 = \sqrt{1 - \frac{z_1^2}{z_2^2} \sin^2 \theta_1}$$

$$\cos \theta_2 = \sqrt{1 - \frac{z_1^2}{z_2^2} \sin^2 \theta_1}$$

②



$$K_{oi} \cos \theta = K_{or} \cos \theta_1 - K_{ot} \cos \theta_2$$

$$H_{oi} + H_{or} = H_{ot}$$

$$H_{oi} = \frac{K_{oi}}{z_1}; H_{or} = \frac{K_{or}}{z_1}; H_{ot} = \frac{K_{ot}}{z_2}$$

$$K_{or} \cos \theta_1 = K_{oi} \cos \theta_1 - K_{ot} \cos \theta_2$$

$$-K_{or} \cos \theta_1 = K_{oi} \cos \theta_1 - \frac{K_{ot}}{z_2} z_2 \cos \theta_2$$

$$K_{or} \cos \theta_1 = K_{oi} \cos \theta_1 - \left(\frac{K_{oi}}{z_1} + \frac{K_{or}}{z_1} \right) z_2 \cos \theta_2$$

$$K_{or} / \cos \theta_1 + \frac{z_2 \cos \theta_2}{z_1} = K_{oi} \left(\cos \theta_1 + \frac{z_2 \cos \theta_2}{z_1} \right)$$

$$K_{or} = \frac{z_1 \cos \theta_1 - z_2 \cos \theta_2}{z_1 \cos \theta_1 + z_2 \cos \theta_2} K_{oi}$$

$$K_{ot} = \frac{2 z_2 \cos \theta_1}{z_1 \cos \theta_1 + z_2 \cos \theta_2} K_{oi}$$

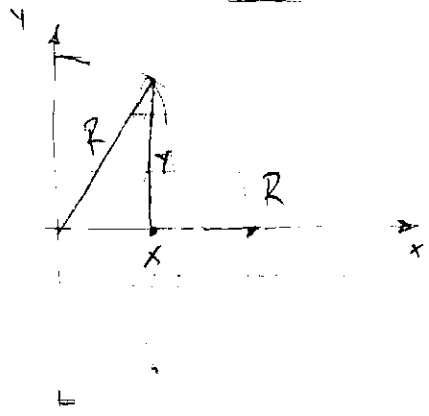
$$K_{or} = P_r \cdot K_{oi}$$

$$K_{ot} = T_r \cdot K_{oi}$$

$$K_{ot} \cos \theta_2 = K_{oi} \cos \theta - z_1 (H_{ot} - H_{or}) \cos \theta_1 = K_{oi} \cos \theta - z_1 \left(\frac{K_{ot}}{z_2} - \frac{K_{or}}{z_1} \right) \cos \theta_1$$

$$K_{ot} \cos \theta_2 + \frac{z_1}{z_2} K_{ot} \cos \theta_1 = 2 \cdot K_{oi} \cos \theta_1$$

$$K_{ot} = \frac{2 z_2 \cos \theta_1}{z_1 \cos \theta_1 + z_2 \cos \theta_2} \cdot K_{oi}$$



$$V = \int_0^R \left(\sqrt{R^2 - x^2} \right)^2 \pi dx$$

$$= 2 \int_0^R (R^2 - x^2) \pi dx = 2 \pi R^2 x \Big|_0^R - 2 \pi \frac{x^3}{3} \Big|_0^R$$

$$V = 2 \pi R^2 R - 2 \pi \frac{R^3}{3} = 2 \pi \left(R^3 - \frac{R^3}{3} \right) = 2 \pi \frac{2R^3}{3} = \frac{4}{3} \pi R^3$$

Ex. 34 ? DEMONSTRATE THAT $|\Gamma_{||}|, |\Gamma_{\perp}| \rightarrow 1$ IF $\theta_i \rightarrow 0$

$$\Gamma_{||} = \frac{n_2 \cos \theta_i - n_1 \cos \theta_t}{n_2 \cos \theta_i + n_1 \cos \theta_t} \quad \Gamma_{\perp} = 1 + \Gamma_{||} = \frac{2 n_2 \cos \theta_i}{n_1 \cos \theta_i + n_2 \cos \theta_t}$$

$$\lim_{\theta_i \rightarrow 0} \frac{n_2 \cos \theta_i - n_1 \cos \theta_t}{n_2 \cos \theta_i + n_1 \cos \theta_t} = \frac{n_2 - n_1 \cos \theta_t}{n_2 + n_1 \cos \theta_t} = \frac{\sqrt{\frac{\mu_2}{\epsilon_2}} - \sqrt{\frac{\mu_1}{\epsilon_1}} \cos \theta_t}{\sqrt{\frac{\mu_2}{\epsilon_2}} + \sqrt{\frac{\mu_1}{\epsilon_1}} \cos \theta_t}$$

$$|\epsilon_r = \epsilon_r \cdot \epsilon_0 = \epsilon_0| = \frac{\sqrt{\frac{\mu}{\epsilon_r \epsilon_0}} - \sqrt{\frac{\mu}{\epsilon_0}} \cos \theta_t}{\sqrt{\frac{\mu}{\epsilon_r \epsilon_0}} + \sqrt{\frac{\mu}{\epsilon_0}} \cos \theta_t} = \frac{1}{\sqrt{\epsilon_r}} - \cos \theta_t}{\frac{1}{\sqrt{\epsilon_r}} + \cos \theta_t}$$

$$\mu_1 = \mu_2 = \mu \quad \epsilon = \epsilon_0 \epsilon_r$$

$$\Gamma_{\perp} = \frac{n_2 \sin \theta_i - n_1 \sin \theta_t}{n_2 \sin \theta_i + n_1 \sin \theta_t} = \frac{\sqrt{\frac{\mu}{\epsilon_0 \epsilon_r}} \sin \theta_i - \sqrt{\frac{\mu}{\epsilon_0}} \sin \theta_t}{\sqrt{\frac{\mu}{\epsilon_0 \epsilon_r}} \sin \theta_i + \sqrt{\frac{\mu}{\epsilon_0}} \sin \theta_t}$$

$$n_2 = \sqrt{\frac{\mu}{\epsilon_0 \epsilon_r}} \quad n_1 = \sqrt{\frac{\mu}{\epsilon_0}}$$

$$\Gamma_{\perp} = \frac{\frac{1}{\sqrt{\epsilon_r}} \sin \theta_i - \sin \theta_t}{\frac{1}{\sqrt{\epsilon_r}} \sin \theta_i + \sin \theta_t}$$

$$\sqrt{\mu \cdot \epsilon_0} \sin(90 - \theta_i) = \sqrt{\mu \cdot \epsilon_0 \epsilon_r} \sin(90 - \theta_t)$$

$$\cos \theta_i = \sqrt{\epsilon_r} \cos \theta_t$$

$$\cos \theta_i = \sqrt{\epsilon_r} \sqrt{1 - \sin^2 \theta_t} \quad \epsilon_r - \epsilon_r \sin^2 \theta_t = \cos^2 \theta_i$$

$$\epsilon_r \sin^2 \theta_t = \epsilon_r - \cos^2 \theta_i \quad \sqrt{\epsilon_r} \sin \theta_t = \sqrt{\epsilon_r - \cos^2 \theta_i}$$

$$\Gamma_{\perp} = \frac{\sin \theta_i - \sqrt{\epsilon_r} \sin \theta_t}{\sin \theta_i + \sqrt{\epsilon_r} \sin \theta_t} = \frac{\sin \theta_i - \sqrt{\epsilon_r - \cos^2 \theta_i}}{\sin \theta_i + \sqrt{\epsilon_r - \cos^2 \theta_i}}$$

$$\Gamma_{\perp} = \frac{n_2 \sin \theta_t - n_1 \sin \theta_i}{n_2 \sin \theta_t + n_1 \sin \theta_i} = \frac{\sqrt{\frac{\mu}{\epsilon_0 \epsilon_r}} \sin \theta_t - \sqrt{\frac{\mu}{\epsilon_0}} \sin \theta_i}{\sqrt{\frac{\mu}{\epsilon_0 \epsilon_r}} \sin \theta_t + \sqrt{\frac{\mu}{\epsilon_0}} \sin \theta_i}$$

$$\Gamma_{\perp} = \frac{\sin \theta_t - \sqrt{\epsilon_r} \sin \theta_i}{\sin \theta_t + \sqrt{\epsilon_r} \sin \theta_i} \quad \sin \theta_t = \frac{1}{\sqrt{\epsilon_r}} \sqrt{\epsilon_r - \cos^2 \theta_i}$$

$$\Gamma_{\perp} = \frac{\sqrt{\epsilon_r - \cos^2 \theta_i} - \epsilon_r \sin \theta_i}{\sqrt{\epsilon_r - \cos^2 \theta_i} + \epsilon_r \sin \theta_i}$$

$$\Gamma_{\parallel} = \frac{-\epsilon_r \sin \theta_i + \sqrt{\epsilon_r - \cos^2 \theta_i}}{\epsilon_r \sin \theta_i + \sqrt{\epsilon_r - \cos^2 \theta_i}}$$

Ex 3.4 $|\Gamma_{\perp}|/|\Gamma_{\parallel}| \rightarrow 1$ if $\theta_i \rightarrow 90$

$$\lim_{\theta_i \rightarrow 90} \left| \frac{\sin \theta_i - \sqrt{\epsilon_r - \cos^2 \theta_i}}{\sin \theta_i + \sqrt{\epsilon_r - \cos^2 \theta_i}} \right| = \left| \frac{0 - \sqrt{\epsilon_r - 1}}{0 + \sqrt{\epsilon_r - 1}} \right| = \left| \frac{-1}{1} \right| = 1$$

$$\lim_{\theta_i \rightarrow 90} |\Gamma_{\parallel}| = \left| \frac{-0 + \sqrt{\epsilon_r - 1}}{0 + \sqrt{\epsilon_r - 1}} \right| = 1$$

Brewster ANGLE

$$\Gamma_{\parallel} = \frac{\epsilon_r}{\epsilon_i} = \frac{n_2 \sin \theta_t - n_1 \sin \theta_i}{n_2 \sin \theta_t + n_1 \sin \theta_i} = 0$$

$$n_2 \sin \theta_t - n_1 \sin \theta_i = 0$$

$$n_2 \sin \theta_t = n_1 \sin \theta_i$$

$$\sqrt{\frac{\mu_2}{\epsilon_2}} \sin \theta_t = \sqrt{\frac{\mu_1}{\epsilon_1}} \sin \theta_i$$

$$\sqrt{\epsilon_1 \mu_1} \sin(90 - \theta_i) = \sqrt{\epsilon_2 \mu_2} \sin\left(\frac{\pi}{2} - \theta_t\right)$$

$$\sqrt{\epsilon_1 \mu_1} \cdot \cos(\theta_{i1}) = \sqrt{\epsilon_2 \mu_2} \cos \theta_t = \sqrt{\epsilon_2 \mu_2} \sqrt{1 - \sin^2 \theta_t}$$

$$\frac{\epsilon_1 \mu_1}{\epsilon_2 \mu_2} \cos^2(\theta_{i1}) = 1 - \sin^2 \theta_t \quad \sin \theta_t = \sqrt{1 - \frac{\epsilon_1 \mu_1}{\epsilon_2 \mu_2} \cos^2(\theta_{i1})}$$

$$\sqrt{\frac{\mu_1}{\epsilon_2}} \sqrt{1 - \frac{\epsilon_1 \mu_1}{\epsilon_2 \mu_2} \cos^2 \theta_{i1}} = \sqrt{\frac{\mu_1}{\epsilon_1}} \sqrt{1 - \cos^2 \theta_{i1}}$$

$$\frac{\mu_2}{\epsilon_2} \left(1 - \frac{\epsilon_1 \mu_1}{\epsilon_2 \mu_2} \cos^2 \theta_{i1}\right) = \frac{\mu_1}{\epsilon_1} (1 - \cos^2 \theta_{i1})$$

$$\frac{\mu_2}{\epsilon_2} \frac{\epsilon_2 \mu_2 - \epsilon_1 \mu_1 \cos^2 \theta_{i1}}{\epsilon_2 \mu_2} = \frac{\mu_1}{\epsilon_1} (1 - \cos^2 \theta_{i1})$$

$$\epsilon_1 \epsilon_2 \mu_2 - \epsilon_1^2 \mu_1 \cos^2 \theta_{i1} = \epsilon_2^2 \mu_2 - \epsilon_2^2 \mu_1 \cos^2 \theta_{i1}$$

$$\epsilon_1 \epsilon_2 \mu_2 - \epsilon_2^2 \mu_1 = (\epsilon_1^2 \mu_1 - \epsilon_2^2 \mu_1) \cos^2 \theta_{i1}$$

$$\cos^2 \theta_{i1} = \frac{\epsilon_1 \epsilon_2 \mu_2 - \epsilon_2^2 \mu_1}{\epsilon_1^2 \mu_1 - \epsilon_2^2 \mu_1}$$

$$1 - \sin^2 \theta_{i1} = \frac{\epsilon_1 \epsilon_2 \mu_2 - \epsilon_2^2 \mu_1}{\epsilon_1^2 \mu_1 - \epsilon_2^2 \mu_1}$$

$$\frac{\epsilon_1^2 \mu_1 - \epsilon_2^2 \mu_1 - \epsilon_1 \epsilon_2 \mu_2 + \epsilon_2^2 \mu_1}{\epsilon_1^2 \mu_1 - \epsilon_2^2 \mu_1} = \sin^2 \theta_{i1}$$

$$\sin^2 \theta_{i1} = \frac{\epsilon_1 (\epsilon_1 \mu_1 - \epsilon_2 \mu_2)}{\mu_1 (\epsilon_1^2 - \epsilon_2^2)} = \left| \frac{\mu_1 - \mu_2}{\mu_1} \right| = \frac{\epsilon_1 \mu_1 (\epsilon_1 - \epsilon_2)}{\mu_1 (\epsilon_1^2 - \epsilon_2^2)}$$

$$\sin^2 \theta_{i1} = \frac{\epsilon_1}{\epsilon_1 + \epsilon_2}$$

$$\sin \theta_B = \sqrt{\frac{\epsilon_1}{\epsilon_1 + \epsilon_2}}$$

• FREE SPACE VS. DIELECTRIC

$$\sin \theta_B = \sqrt{\frac{\epsilon_0}{\epsilon_0 + \epsilon_0 \epsilon_r}} = \sqrt{\frac{1}{1 + \epsilon_r}} = \sqrt{\frac{1 - \epsilon_r}{1 - \epsilon_r^2}}$$

$$\sin \theta_B = \sqrt{\frac{\epsilon_r - 1}{\epsilon_r^2 - 1}} \quad \text{ONLY FOR VERTICAL POLARIZATION}$$

EX. 3.5 $\epsilon_r = 4$ $\sin \theta_B = \frac{1}{\sqrt{1 + \epsilon_r}}$ $\theta_B = \arcsin \frac{1}{\sqrt{5}}$

$$\theta_B = 0,46 \text{ rad}$$

$$1 \text{ rad} = \frac{180^\circ}{\pi}$$

$$\theta_B = 0,46 \cdot \frac{180}{\pi} = 26,6^\circ$$

• NA ROVNIŠTA NA IDEALNI PLOVODNIK

$$k_{\text{tang}} = 0 \quad H_n = 0$$

HORIZ POLARIZACIJA:

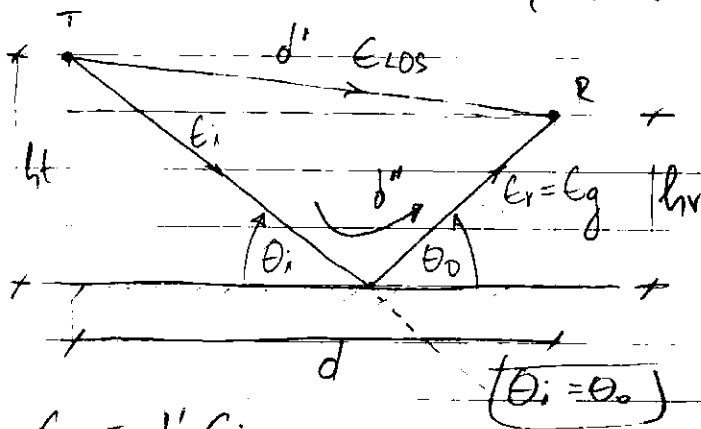
$$E_i = -E_r, \theta_i = \theta_r$$

VERTICALNA - " - :

$$E_i = E_r, \theta_i = \theta_r$$

$$\Gamma_{\perp} = \frac{n_2 \sin \theta_i - n_1 \sin \theta_t}{n_2 \sin \theta_i + n_1 \sin \theta_t} = 1 \quad \Gamma_{\parallel} = \frac{n_2 \sin \theta_t - n_1 \sin \theta_i}{n_2 \sin \theta_t + n_1 \sin \theta_i} = -1$$

• Ground reflection (2 RAY MODE)



$$E_{TOT} = E_{LOS} + E_g$$

$$E(d, t) = \frac{\epsilon_0 d_0}{d} \cos\left(\omega_c \left(t - \frac{d}{c}\right)\right)$$

$$d > d_0$$

$$E_{LOS}(d', t) = \frac{\epsilon_0 d_0}{d'} \cos\left(\omega_c \left(t - \frac{d'}{c}\right)\right)$$

$$E_g(d'', t) = \Gamma \frac{\epsilon_0 d_0}{d''} \cos\left(\omega_c \left(t - \frac{d''}{c}\right)\right)$$

$$E_g = \Gamma E_i$$

$$E_t = (1 + \Gamma) E_i$$

$$\Gamma = -1$$

$$|E_{TOT}| = |E_{LOS} + E_g|$$

$$E_{TOT}(d, t) = \frac{\epsilon_0 d_0}{d'} \cos\left(\omega_c \left(t - \frac{d'}{c}\right)\right) + (-1) \frac{\epsilon_0 d_0}{d''} \cos\left(\omega_c \left(t - \frac{d''}{c}\right)\right)$$

$$\Delta = d'' - d' = \sqrt{(h_t + h_r)^2 + d^2} - \sqrt{(h_t - h_r)^2 + d^2}$$

$$f(x) = f(x_0) + f'(x_0)(x-x_0) + \frac{f''(x_0)}{2!}(x-x_0)^2 + \frac{f^{(3)}(x_0)}{3!}(x-x_0)^3 + \dots$$

$$\left(\sqrt{(h_t + h_r)^2 + d^2}\right)' = \frac{1}{2} \frac{2d}{\sqrt{(h_t + h_r)^2 + d^2}}$$

$$\left(\sqrt{(h_t - h_r)^2 + d^2}\right)' = \frac{1}{2} \frac{2d}{\sqrt{(h_t - h_r)^2 + d^2}}$$

$$\frac{1}{\sqrt{(h_t + h_r)^2 + d^2}} - \frac{1}{\sqrt{(h_t - h_r)^2 + d^2}}$$

$$\frac{1}{\sqrt{(h_t + h_r)^2 + d^2}} - \frac{1}{\sqrt{(h_t - h_r)^2 + d^2}}$$

$$\Delta = (h_t + h_r) \left(\frac{1}{\sqrt{(h_t - h_r)^2 + d^2}} - \frac{1}{\sqrt{(h_t + h_r)^2 + d^2}} \right)$$

$$\Delta \approx \frac{2h_t h_r}{d}$$

$$f(x) = \sqrt{x} \quad f'(x) = \frac{1}{2\sqrt{x}} \quad f''(x) = -\frac{1}{4x^{3/2}}$$

$$x_0 = 0 \Rightarrow f(x) \approx \frac{1}{2}\sqrt{x}$$

$$f(x) = e^x$$

$$f'(x) = \frac{1}{x}$$

$$f(x) \approx f(x_0) + f'(x_0)(x-x_0) = e^0 + e^{x_0}(x-0) = 1+x$$

$$f'(x) \approx \frac{1}{x_0} - \frac{1}{x_0^2}(x-x_0) = 1 - \frac{1}{x_0^2}(x-1) = 1 - (x-1)$$

$$f(x) = \sqrt{1+x}$$

$$f(x) \approx 1 + \frac{1}{2}x$$

$$f'(x) = \frac{1}{2} \frac{1}{\sqrt{1+x_0}} = \frac{1}{2}$$

$$f'(x_0)(x-x_0) = \frac{1}{2}x$$

$$\textcircled{*} = \sqrt{(l_t + l_r)^2 + d^2} = (l_t + l_r) \sqrt{1 + \left(\frac{d}{l_t + l_r}\right)^2} = (l_t + l_r) \left(1 + \frac{d^2}{2(l_t + l_r)^2}\right)$$

$$\textcircled{+} = (l_t + l_r) + \frac{d^2}{2(l_t + l_r)} = \frac{(l_t + l_r)^2 + d^2}{2(l_t + l_r)}$$

$$\textcircled{**} = \frac{(l_t - l_r)^2 + d^2}{2(l_t - l_r)}$$

$$\Delta = d'' - d' = \textcircled{+} - \textcircled{**} = \frac{[(l_t + l_r)^2 + d^2](l_t - l_r) - [(l_t - l_r)^2 + d^2](l_t + l_r)}{2(l_t + l_r)(l_t - l_r)}$$

$$= \frac{l_t^2 - l_r^2}{2(l_t + l_r)(l_t - l_r)}$$

MMV

$$d \gg l_t + l_r \quad \frac{l_t l_r}{d} \rightarrow 0$$

$$\textcircled{*} = \sqrt{(l_t + l_r)^2 + d^2} = d \sqrt{1 + \frac{(l_t + l_r)^2}{d^2}} \approx d \left(1 + \frac{(l_t + l_r)^2}{2d^2}\right)$$

$$\textcircled{**} = d \left(1 - \frac{(l_t - l_r)^2}{2d^2}\right)$$

$$\textcircled{*} - \textcircled{**} = d + \frac{(l_t + l_r)^2}{2d} - d + \frac{(l_t - l_r)^2}{2d} =$$

$$= \frac{l_t^2 + 2l_t l_r + l_r^2 + l_t^2 - 2l_t l_r + l_r^2}{2d} = \frac{2l_r^2}{2d} = \frac{l_r^2}{d}$$

MMV

$$\Theta_L = \frac{2\pi r}{\lambda} = \frac{\Delta \cdot d}{c}$$

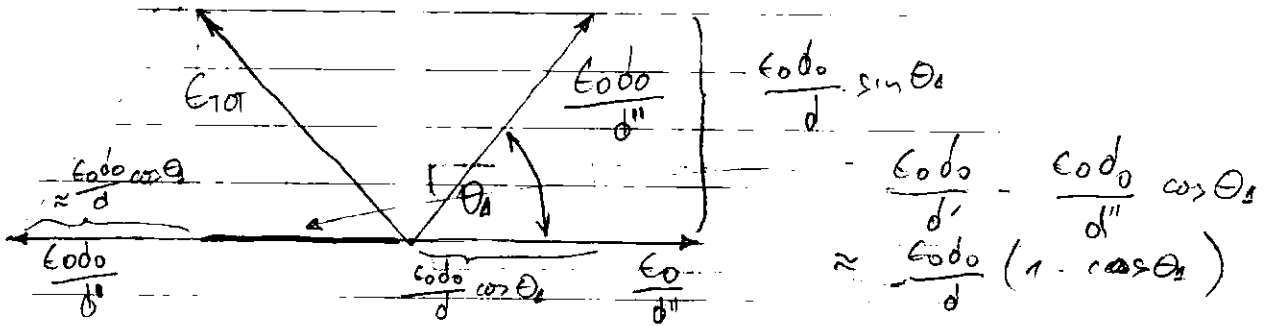
$$x = \frac{c}{f} = \frac{c}{\frac{2\pi c}{\lambda}} = \frac{\lambda}{2\pi}$$

$$\left| \frac{\epsilon_0 d_0}{d} \right| \approx \left| \frac{\epsilon_0 d_0}{d'} \right| \approx \left| \frac{\epsilon_0 d_0}{d''} \right|$$

$$\tau_{d'} = \frac{1}{c} - \tau = \frac{\Delta \cdot d}{c} = \frac{\Theta_L}{2\pi f}$$

$$\left[\frac{\epsilon_0 d_0}{d'} \cos\left(\omega c \left(\frac{d'' \cdot d'}{c}\right)\right) \right] - \frac{\epsilon_0 d_0}{d''} \cos(0)$$

$$\frac{\epsilon_0 d_0}{d'} \cos\left(\frac{\Delta \cdot \omega c \cdot d'}{c}\right) - \frac{\epsilon_0 d_0}{d''} \approx \frac{\epsilon_0 d_0}{d} (\cos \Theta_L - 1)$$



$$|E_{TOT}(d)| = \left| \left(\frac{E_0 d_0}{d} \right)^2 (\cos \theta_2 - 1)^2 + \left(\frac{E_0 d_0}{d} \right)^2 \sin^2 \theta_2 \right| =$$

$$= \left| \left(\frac{E_0 d_0}{d} \right)^2 (\cos^2 \theta_2 - 2 \cos \theta_2 + 1 + \sin^2 \theta_2) \right| =$$

$$= \left| \left(\frac{E_0 d_0}{d} \right)^2 2(1 - \cos \theta_2) \right| = \frac{\sqrt{2} E_0 d_0}{d} \sqrt{1 - \cos \theta_2}$$

$$= \frac{\sqrt{2} E_0 d_0}{d} \sqrt{\cos^2 \frac{\theta_2}{2} + \sin^2 \frac{\theta_2}{2} - \cos \theta_2} = \frac{\sqrt{2} E_0 d_0}{d} \sqrt{2 \sin^2 \frac{\theta_2}{2}}$$

$$|E_{TOT}(d)| = \frac{2 E_0 d_0}{d} \sin \frac{\theta_2}{2}$$

$$\frac{\theta_2}{2} = \frac{L \cdot \omega c}{2 c d} = \frac{2 \pi h_f h_r d c}{2 c d} = \frac{2 \pi h_f h_r}{\lambda d}$$

$$\frac{\theta_2}{2} < 0.3 \Rightarrow \frac{2 \pi h_f h_r}{\lambda d} < \frac{3}{10}$$

$$d > \frac{20 \pi h_f h_r}{3 \lambda} \approx \frac{20 h_f h_r}{\lambda}$$

$$E_{TOT} \approx \frac{2 E_0 d_0}{d} \frac{2 \pi h_f h_r}{\lambda d} \approx \frac{k}{d^2}$$

$$E_{TOT} = \frac{4 \pi E_0 d_0 h_f h_r}{\lambda d^2}$$

$$P_R = \frac{G_T G_R \cdot \lambda^2 P_T}{(4 \pi)^2 d^2 L}, \quad L=1, \quad P_R = \frac{G_T G_R \cdot \lambda^2 P_T}{(4 \pi)^2 d^2}$$

$$G = \frac{4 \pi A_L}{\lambda^2}, \quad P_R = P_T G_T$$

$$\lambda^2 = \frac{4 \pi E_0 d_0 h_f h_r}{E_{TOT} d^2}, \quad P_R = \frac{G_T G_R P_T}{(4 \pi)^2 d^2} \cdot \frac{(4 \pi)^2 E_0 d_0 h_f h_r}{E_{TOT} d^2}$$

$$P_R = P_T G_T G_R \frac{h_f^2 h_r^2}{d^4} \cdot \frac{E_0 d_0}{E_{TOT}}$$

$$P_R = P_T G_T G_R \frac{h_f^2 h_r^2}{d^4}$$

$$P_L = 10 \log \frac{P_T}{P_R} = 10 \log d^4 - 10 \log G_T G_R h_f^2 h_r^2$$

$$= 40 \log d - (10 \log G_T + 10 \log G_R + 20 \log h_f + 20 \log h_r)$$

$$\theta_A = \frac{2\pi \Delta}{\lambda} = \frac{2\pi \cdot 2 \text{htlr}}{\lambda \cdot d} = \frac{4\pi \text{htlr}}{\lambda d}$$

IF: $\theta_A = \pi$ $\pi = \frac{4\pi \text{htlr}}{\lambda d}$

$\lambda = \frac{4 \text{htlr}}{d}$

100% GOOD IS
 10% FIRST
 = REVER
 ZONE

Ex-36 $d = 5 \text{ km}$ ANTENNA MONOPOLE $\frac{\lambda}{4}$ $G_R = 2,55 \text{ dB}$

$2 \text{ dB} = 10 \log(1.2)$ $10^{0,255}$ $\Rightarrow G_R = 1,799$
 $E_0 = 10^{-3} \text{ V/m}$ AT $d_0 = 1 \text{ km}$; $f_c = 300 \text{ MHz}$

(a) $G_R = ?$ $l_R = ?$

(b) 2-RAY MODEL $P_e = ?$ $h_T = 50 \text{ m}$ $h_R = 1,5 \text{ m}$

(a) $P_r(d_0) = P_d \cdot A_e = \frac{1 \text{ W}}{120\pi} A_e$; $A_e = \frac{G_R \lambda^2}{4\pi}$

$\lambda = \frac{c}{f[\text{MHz}]} = \frac{300}{300} = 1$

$P_r(d) = 10 \log \frac{P_r(d_0)}{1 \text{ mW}} - 20 \log \frac{d}{d_0}$

$\frac{P_r}{P_t} = \frac{G_T G_R \lambda^2}{(4\pi)^2 d^2}$

$\frac{P_r(d)}{P_r(d_0)} = \frac{\frac{1}{d^2}}{\frac{1}{d_0^2}} = \frac{d_0^2}{d^2}$

$P_r(d) = \frac{d_0}{d} P_r(d_0) = \frac{d_0}{d} \cdot \frac{1 \text{ W}}{120\pi} \cdot \frac{G_R \lambda^2}{4\pi}$

$l_R = \frac{\lambda}{4} = \frac{1}{4} = 0,25 \text{ m} = 25 \text{ cm}$ $G_R = 1,8$

(b) $E_{\text{TOT}} = \frac{4\pi \epsilon_0 d_0 h_T h_R}{\lambda \cdot d^2} = \frac{4\pi \cdot 10^{-3} \cdot 10^3 \cdot 50 \cdot 1,5}{1 \cdot 25 \cdot 10^6}$

$E_{\text{TOT}} = 12\pi \cdot 3 \cdot 10^{-6} = 36\pi \cdot 10^{-6} \text{ V/m} = 113,1 \cdot 10^{-6} \text{ V/m}$

$P_r(d) = \frac{1 \text{ W}}{120\pi} \cdot A_e = \frac{1 \text{ W}}{120\pi} \cdot \frac{G_R \lambda^2}{4\pi} = \frac{(18\pi \cdot 10^{-6})^2}{120\pi} \cdot \frac{1,8 \cdot 1}{4\pi}$

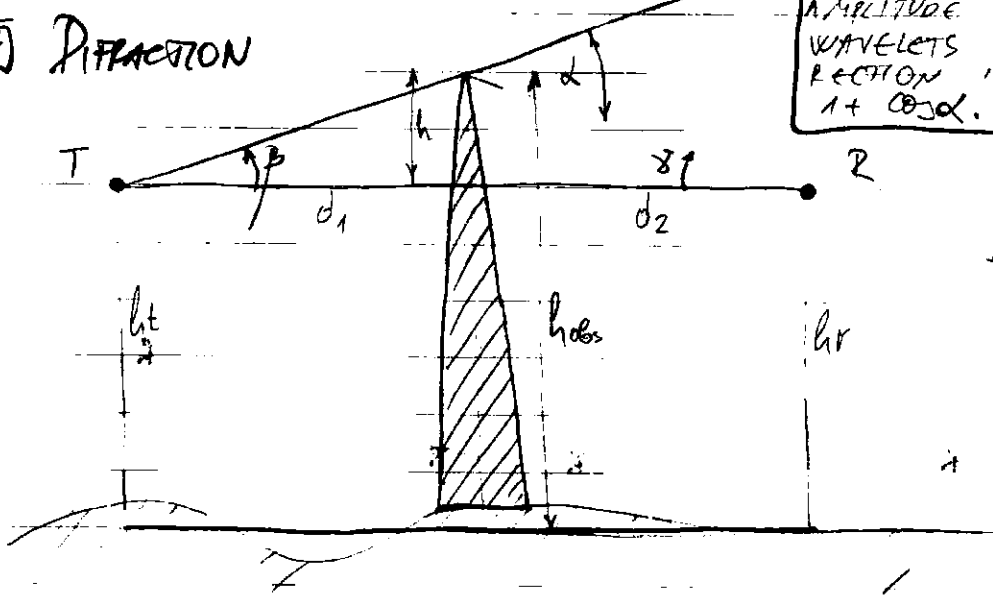
$P_r(d) = \frac{36^2 \cdot \pi^2 \cdot 10^{-12} \cdot 1,8}{120 \cdot 36 \cdot \pi^2} = 0,54 \cdot 10^{-12} = 0,54 \text{ pW}$

$10 \log \frac{0,54 \cdot 10^{-12}}{10^{-3}} = -10 \log 54,0 \cdot 10^{-10} = -92,7 \text{ dBm}$

$P_r[\text{dBW}] = 10 \log 0,54 \cdot 10^{-12} = -122,6 \text{ dBW}$

3.3 DIFFRACTION

AMPLITUDE OF THE SECONDARY WAVELETS IN A GIVEN DIRECTION IS PROPORTIONAL TO $1 + \cos \alpha$.



$$\Delta = \frac{l^2(d_1 + d_2)}{2d_1d_2}$$

$$\Delta = d'' - d' = \sqrt{d_1^2 + l^2} + \sqrt{d_2^2 + l^2} - d_1 - d_2$$

$$d_1, d_2 \gg l \Rightarrow \sqrt{1+x^2} \approx 1 + \frac{x^2}{2} \quad x \rightarrow 0$$

$$d_1 \sqrt{1 + \left(\frac{l}{d_1}\right)^2} \approx d_1 \left(1 + \frac{l^2}{2d_1^2}\right) \quad d_2 \sqrt{1 + \left(\frac{l}{d_2}\right)^2} \approx d_2 \left(1 + \frac{l^2}{2d_2^2}\right)$$

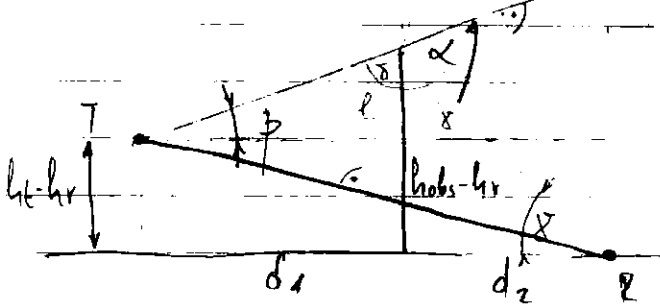
$$\Delta = d_1 + \frac{l^2}{2d_1} + d_2 + \frac{l^2}{2d_2} - d_1 - d_2 = \frac{l^2 d_2 + l^2 d_1}{2d_1 d_2} = \frac{l^2(d_1 + d_2)}{2d_1 d_2}$$

$$\phi = \frac{2\pi \Delta}{\lambda} = \frac{2\pi}{\lambda} \frac{l^2}{2} \frac{d_1 + d_2}{d_1 d_2}$$

$$\Delta = \frac{l^2(d_1 + d_2)}{2d_1 d_2}$$

when $f(x) \approx x$, then $\alpha = \beta + \gamma$

$$\alpha \approx l \frac{d_1 + d_2}{d_1 d_2} \quad (*)$$



$$\delta = 180 - \beta - \gamma$$

$$\alpha = 180 - \delta = 180 - 180 + \beta + \gamma$$

$$\alpha = \beta + \gamma$$

$$\sigma = l \sqrt{\frac{2(d_1 + d_2)}{\lambda d_1 d_2}} \left(\frac{d_1 d_2}{(d_1 + d_2)} \cdot \frac{d_1 + d_2}{d_1 d_2} \right) = l \frac{d_1 + d_2}{d_1 d_2} \sqrt{\frac{2d_1 d_2}{\lambda(d_1 + d_2)}}$$

$$\sigma = \alpha \sqrt{\frac{2d_1 d_2}{\lambda(d_1 + d_2)}}$$

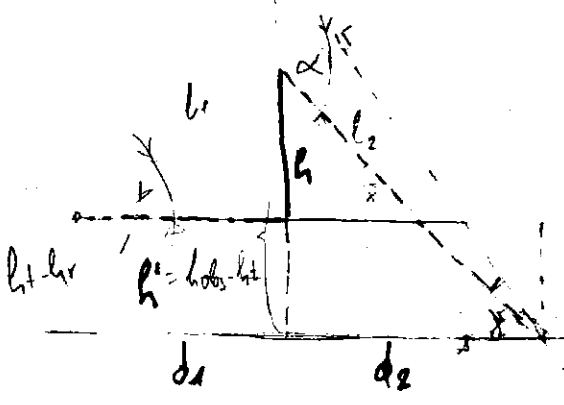
Fresnel-Kirchhoff diffraction parameter

$$\sigma^2 = l^2 \frac{2(d_1 + d_2)}{d_1 d_2} = 2 \cdot \left(\frac{l^2}{2}\right) \left(2 \cdot \frac{2\pi}{\lambda} \cdot \frac{d_1 + d_2}{d_1 d_2}\right) \cdot \frac{\lambda}{2\pi}$$

$$\phi = \frac{\pi \sigma^2}{2}$$

$$f_g p = \frac{l}{d_1}$$

$$\sigma = l \sqrt{\frac{2(d_1 + d_2)}{\lambda d_1 d_2}}$$



$$l_2 = \sqrt{h^2 + d_1^2} = h \sqrt{1 + \left(\frac{d_1}{h}\right)^2}$$

$$l_2 = h \left(1 + \frac{d_1^2}{2h^2}\right) = h + \frac{d_1^2}{2l_2}$$

$$l_1 = h + \frac{d_1^2}{2l_1}$$

PROOF FOR

$$\tan(\beta) = \frac{h}{d_1 + d_2} = \alpha + \beta$$

$$\tan \beta = \frac{\sin(\alpha + \beta)}{\cos(\alpha + \beta)} = \frac{\sin \alpha \cos \beta + \cos \alpha \sin \beta}{\cos \alpha \cos \beta - \sin \alpha \sin \beta} = \frac{\tan \alpha + \tan \beta}{1 - \tan \alpha \tan \beta}$$

$$\tan \beta = \frac{\tan \alpha - \frac{h'}{d_2}}{1 + \tan \alpha \frac{h'}{d_2}} \quad \frac{d_2 \tan \alpha - h'}{d_2 + h' \tan \alpha} = \frac{h}{d_1}$$

$h' = h$

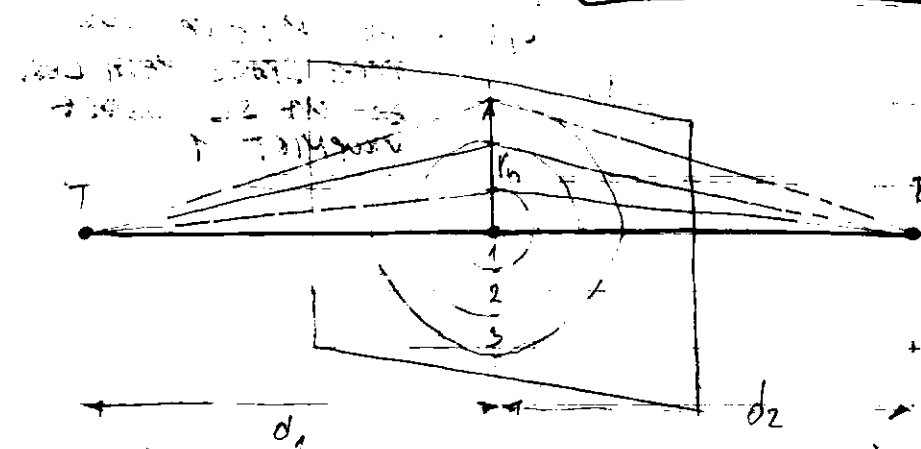
$$(d_2 \tan \alpha - h) d_1 = h (d_2 + h \tan \alpha)$$

$$d_1 d_2 \tan \alpha - h d_1 = h d_2 + h^2 \tan \alpha \quad (d_1 d_2 - h^2) \tan \alpha = h (d_1 + d_2)$$

$$\tan \alpha = \frac{h (d_1 + d_2)}{d_1 d_2 - h^2} \quad d_1 d_2 \gg h^2 \Rightarrow \tan \alpha \approx \frac{h (d_1 + d_2)}{d_1 d_2}$$

$\alpha \rightarrow 0 \quad \tan \alpha \approx \alpha$

$$\alpha \approx \frac{h (d_1 + d_2)}{d_1 d_2}$$



$$d'' = \sqrt{d_1^2 + R^2} + \sqrt{d_2^2 + R^2} \approx d_1 \left(1 + \frac{R^2}{2d_1^2}\right) + d_2 \left(1 + \frac{R^2}{2d_2^2}\right)$$

$$n \cdot \frac{\lambda}{2} = \left(d_1 + \frac{R^2}{2d_1} + d_2 + \frac{R^2}{2d_2}\right) - (d_1 + d_2)$$

$$2 d_1 d_2 \cdot \frac{n \lambda}{2} = 2 d_1 d_2 + R^2 d_2 + 2 d_1 d_2^2 + R^2 d_1 - 2 d_1 d_2 (d_1 + d_2)$$

$$R^2 (d_1 + d_2) = d_1 d_2 \left(\frac{n \lambda}{2} - 2(d_1 + d_2) + 2 \left(\frac{d_1}{d_2} + \frac{d_2}{d_1}\right) \right)$$

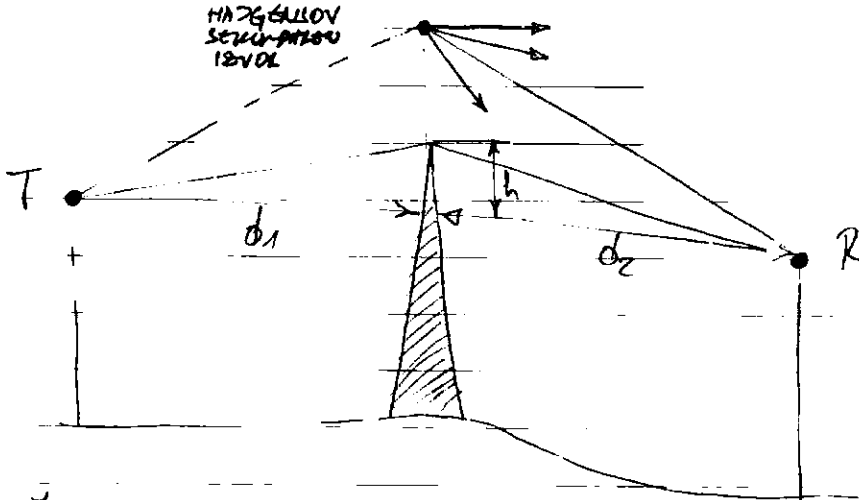
$$R = \frac{n \lambda d_1 d_2}{d_1 + d_2} \quad \text{RADIUS NA FRENZELVITZ ZON}$$

Ex 3: $d_1 = 3 \text{ km}$ $d_2 = 3 \text{ km}$ $\lambda = \frac{1}{3} \text{ m}$ ($f = 900 \text{ MHz}$)

$$V_1 = \sqrt{\frac{\lambda \cdot d_1 \cdot d_2}{d_1 + d_2}} = \sqrt{\frac{1}{3} \frac{3 \cdot 10^3 \cdot 3 \cdot 10^3}{6 \cdot 10^3}} = \sqrt{\frac{3 \cdot 10^3}{6}} = \sqrt{5 \cdot 10^2}$$

$V_1 = 223 \text{ m}$

• KNIFE EDGE DIFFRACTION MODEL



- JACNATA NA ELEKTROSTROJICE ZA "KNIFE-EDGE DIFFRACTED WAVE" e:

$$\frac{E_d}{E_0} = F(u) = \frac{1+j}{2} \int_0^{\infty} e^{-t^2 - j \frac{\pi}{2} t^2} dt$$

$F(u)$ - FRESNEL FUNKCIJA

$u \propto \sqrt{\frac{2 \cdot d_1 \cdot d_2}{\lambda (d_1 + d_2)}}$ FRESNEL-KIRCHHOFF PARAMETER.

DIFFRACTION GAIN:

$$G_d(dB) = 20 \log |F(u)|$$

$|G_d|$ - SE DODAVA NA FREE SPACE PATH LOSS ZA DA SE DOKLE VKUPNIOT PL.

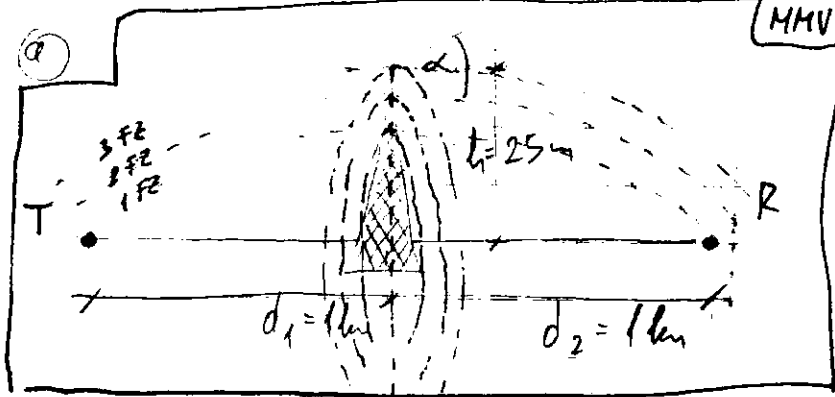
• APPROXIMATE SOLUTION:

$$G_d = \begin{cases} 0 & u \leq -1 \\ 20 \log(0.5 - 0.62u) & -1 \leq u \leq 0 \\ 20 \log(0.5 \exp(-0.955u)) & 0 \leq u \leq 1 \\ 20 \log(0.4 - \sqrt{0.1184 - (0.38 - 0.1u)^2}) & 1 \leq u \leq 2.4 \\ 20 \log\left(\frac{0.225}{u}\right) & u > 2.4 \end{cases}$$

Ex 3.7 diff. loss = ? for THE THREE CASES FROM Fig. 3.12

$\lambda = \frac{1}{3} \text{ m}$ $d_1 = 1 \text{ km}$ $d_2 = 1 \text{ km}$
 (a) $h = 25 \text{ m}$ (b) $h = 0$ (c) $h = -25 \text{ m}$

• COMPARE VALUES OBTAINED BY EXACT AND APPROX. SOLUTION



$$\sigma = \alpha \sqrt{\frac{2d_1 d_2}{\lambda(d_1 + d_2)}} = \dots$$

$$= L \frac{d_1 + d_2}{d_1 d_2} \sqrt{\frac{2d_1 d_2}{d_1 + d_2}} = \dots$$

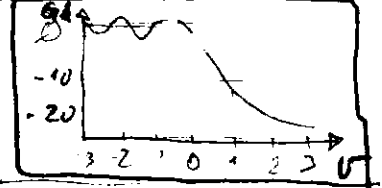
$$= \frac{1}{2} \sqrt{30} = 2,74$$

$$G_d(\sigma) = -21,7 \text{ dB}$$

(b) $L_1 = 0 \Rightarrow \sigma = 0$

$G_d = -6 \text{ dB}$

(c) $G_d(\sigma) = -0,74 \text{ dB}$



$$\sigma = L \frac{d_1 + d_2}{d_1 d_2} \sqrt{\frac{2d_1 d_2}{\lambda(d_1 + d_2)}} = L \sqrt{\frac{2}{\lambda(d_1 + d_2)}}$$

(a) $\Delta = \frac{L^2 (d_1 + d_2)}{2d_1 d_2} = \frac{5}{8} = 0,625 \text{ cm}$

COMPLETELY BLOCKS FIRST 3 FZ
NEXT CORES

$\frac{\lambda}{2} = \frac{1}{6} \Rightarrow \frac{1}{6} \cdot n = \frac{5}{8} \Rightarrow n = \frac{30}{8} = 3,75$

(b) $\Delta = 0$ TIP LIES IN THE MIDDLE OF FIRST FZ

(c) $\Delta = 0,625 \quad n = 3,75$ (COMPLETELY BLOCKS FIRST 3 FZ BELOW LOS \Rightarrow NEGATIVE LOS)

$$\sigma = L \sqrt{\frac{2(d_1 + d_2)}{\lambda d_1 d_2}} \quad L_1 = \sigma n = \sqrt{\frac{L \lambda d_1 d_2}{d_1 + d_2}}$$

$$\sigma = \sqrt{\frac{L \lambda d_1 d_2}{d_1 + d_2}} \sqrt{\frac{2(d_1 + d_2)}{\lambda d_1 d_2}} = \sqrt{2n} \quad \sigma = \sqrt{2L}$$

If $L_1 = 10 \text{ m} \Rightarrow \Delta = \frac{L^2 (d_1 + d_2)}{2d_1 d_2} = \frac{100(2000)}{2 \cdot 10^6}$

$\Delta = \frac{2 \cdot 10^5}{2 \cdot 10^6} = \frac{1}{10} = 0,1 \text{ m}$

$$\Delta = n \frac{\lambda}{2}$$

$n = \frac{2\Delta}{\lambda} = \frac{2 \cdot 1/10}{1/3} = \frac{2 \cdot 3}{10} = \frac{6}{10} = 0,6$

$G_d(\sigma) = -11$

$L_1 = ?$ T.S 0,55 (55%) OF 1-FZ E C'ORRIGIDA

$$L_1^2 \frac{(d_1 + d_2)}{2d_1 d_2} = 0,55 \cdot \frac{\lambda}{2}$$

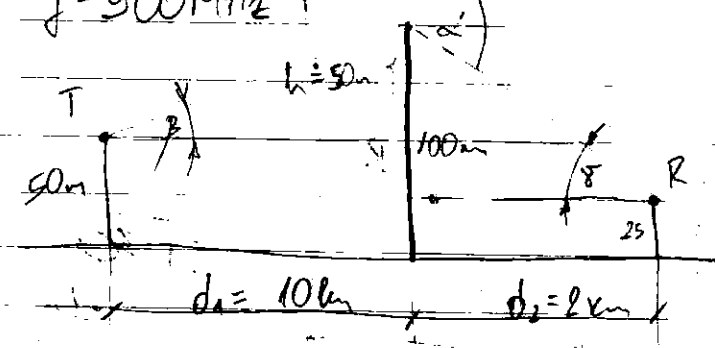
$$L_{1 \text{ max}} = \sqrt{0,55 \frac{\lambda d_1 d_2}{d_1 + d_2}}$$

$L_{1 \text{ max}} = \sqrt{0,55 \frac{0,55 \cdot 10^3}{2 \cdot 10^3}} = \sqrt{\frac{0,55 \cdot 0,55 \cdot 10^3}{2}} = 9,57$

Ex 3.8

$f = 900 \text{ MHz}$

263 940



- (a) $G_d = ?$ (b) $h = ?$ for $G_d = -6 \text{ dB}$

(a)
$$v = h \sqrt{\frac{2(d_1 + d_2)}{\lambda d_1 d_2}} = 50 \sqrt{\frac{2 \cdot 12 \cdot 10^3}{\frac{1}{3} \cdot 20 \cdot 10^3}} = 100 \sqrt{\frac{18 \cdot 10^3}{5 \cdot 10^3}} = 3$$

$G_d(\alpha) = G_d(\beta) = -22,52 \text{ dB}$ $PL = +22,52 \text{ dB}$

(b) $G_d = -6 \text{ dB} \Rightarrow v = 0 \Rightarrow h = 0$

POČEN PRISTUP

ALT:

$\beta + \delta + \frac{\pi}{2} - \alpha = \pi \quad \alpha = \beta + \delta$

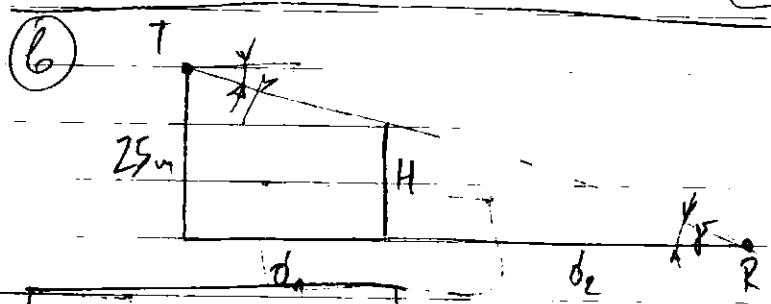
$\tan \beta = \frac{50}{d_1} = \frac{50}{10 \cdot 10^3} = 5 \cdot 10^{-3} \quad \beta = \arctan 5 \cdot 10^{-3} = 0,05 \text{ rad} = 2,86^\circ$

$\tan \delta = \frac{75}{d_2} = \frac{75}{2 \cdot 10^3} = 37,5 \cdot 10^{-3} \quad \delta = \arctan 37,5 \cdot 10^{-3} = 0,037 \text{ rad} = 2,15^\circ$

$\alpha = \beta + \delta = 2,434^\circ = 0,0425 \text{ rad}$

$$v = \alpha \sqrt{\frac{2d_1 d_2}{\lambda(d_1 + d_2)}} = 0,0425 \sqrt{\frac{2 \cdot 10^4 \cdot 2 \cdot 10^3}{\frac{1}{3} (12 \cdot 10^3)}} = 0,0425 \sqrt{\frac{4 \cdot 10^7}{4 \cdot 10^3}}$$

$v \approx 0,0425 \sqrt{10^4} = 4,25 \quad G_d(\alpha) = -25,5 \text{ dB}$



$\beta = \delta$
 $h = 0$

$\frac{50}{d_1 + d_2} = \frac{H}{d_2}$

$H = \frac{25 d_2}{d_1 + d_2} = \frac{25 \cdot 2 \cdot 10^3}{6 \cdot 10^3}$

$H = \frac{25}{6} = 4,17 \text{ m}$

SCATTERING

$h_c = \frac{\lambda}{8 \sin \alpha}$

RAYleigh CRITERION

$h < h_c \rightarrow$ SMOOTH

$h > h_c \rightarrow$ ROUGH

- If surface height is gaussian random variable

$$G_s = \exp \left[-2 \left(\frac{\pi G_y \sin \theta_i}{\lambda} \right)^2 \right]$$

for rough surfaces reflection coefficients to be multiplied by G_s

$$\sigma_h^2 = (h - \bar{h})^2$$

$$P_s = \exp\left[-8 \left(\frac{\gamma G_h \sin \theta_i}{\lambda}\right)^2\right] I_0\left[8 \left(\frac{\gamma G_h \sin \theta_i}{\lambda}\right)^2\right]$$

$$P_{\text{rough}} = P_s P$$

• RAYLEIGH CROSS SECTION MODEL

$$P_r / P_t = P_f(\text{dB}_m) + G_{\text{TT}}(\text{dB}_i) + 20 \log(\lambda) + 20 \log(d) - 30 \log(4\pi) - 20 \log(d_r) - 20 \log(d_r)$$

• PRACTICAL LINK BUDGET DESIGN USING PATH LOSS MODELS

$$P_L(d) \sim \left(\frac{d}{d_0}\right)^n \quad P_L(d) = P_L(d_0) + 10n \log\left(\frac{d}{d_0}\right)$$

(n=2) FOR FREE SPACE

PATH LOSS EXPONENT

• LOG-NORMAL SHADOWING

$$P_L(d) = P_L(d_0) + 20 \log\left(\frac{d}{d_0}\right) + X_G \quad \text{MMV}$$

$$P_r(d) = P_t(d) - P_L(d) \quad [\text{dB}]$$

$$\frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} e^{-u^2} du = \frac{1}{\sqrt{\pi}} \left(\int_{-\infty}^0 e^{-u^2} du + \int_0^{\infty} e^{-u^2} du \right) = \frac{1}{2} + \frac{1}{\sqrt{\pi}} \int_0^{\infty} e^{-u^2} du$$

$$(1.2) \quad \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{-\frac{x^2}{2}} dx = \frac{1}{2} \left[1 - \text{erf}\left(\frac{z}{\sqrt{2}}\right) \right]$$

$$\text{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-u^2} du$$

$$Q(z) = \frac{1}{\sqrt{2\pi}} \int_z^{\infty} e^{-\frac{u^2}{2}} du \quad x = z - u = \frac{z}{\sqrt{2}} \quad \frac{1}{\sqrt{2\pi}} \int_{\frac{z}{\sqrt{2}}}^{\infty} e^{-\frac{u^2}{2}} du$$

$$= \frac{1}{\sqrt{\pi}} \int_{\frac{z}{\sqrt{2}}}^{\infty} e^{-u^2} du = \frac{1}{\sqrt{\pi}} \int_{\frac{z}{\sqrt{2}}}^{\infty} e^{-u^2} du = \frac{1}{\sqrt{\pi}} \int_{\frac{z}{\sqrt{2}}}^{\infty} e^{-u^2} du = \frac{1}{\sqrt{\pi}} \int_{\frac{z}{\sqrt{2}}}^{\infty} e^{-u^2} du$$

$$Q(z) = 1 - \text{erf}\left(\frac{z}{\sqrt{2}}\right)$$

$$\text{erf}\left(\frac{z}{\sqrt{2}}\right) = \frac{2}{\sqrt{\pi}} \int_0^{\frac{z}{\sqrt{2}}} e^{-u^2} du \quad \text{erf}\left(\frac{z}{\sqrt{2}}\right) = 1 - \frac{1}{\sqrt{\pi}} \int_{\frac{z}{\sqrt{2}}}^{\infty} e^{-u^2} du = \frac{1}{\sqrt{\pi}} \int_0^{\frac{z}{\sqrt{2}}} e^{-u^2} du$$

$$= 1 - \frac{1}{\sqrt{\pi}} \int_0^{\frac{z}{\sqrt{2}}} e^{-u^2} du = \frac{1}{\sqrt{\pi}} \int_0^{\frac{z}{\sqrt{2}}} e^{-u^2} du$$

$$Q(z) = \frac{1}{2} \left[1 - \operatorname{erf} \left(\frac{z}{\sqrt{2}} \right) \right]$$

$$Q(z) = \frac{1}{\sqrt{2\pi}} \int_z^{\infty} e^{-\frac{x^2}{2}} dx \quad \begin{matrix} x = z \\ \mu = \frac{z}{\sqrt{2}} \end{matrix} \quad \begin{matrix} \sigma = \frac{1}{\sqrt{2}} \\ \mu = \frac{z}{\sqrt{2}} \end{matrix}$$

$$Q(z) = \frac{1}{\sqrt{2\pi}} \int_{\frac{z}{\sqrt{2}}}^{\infty} e^{-\mu^2} d\mu = \frac{1}{2} \frac{2}{\sqrt{\pi}} \int_{\frac{z}{\sqrt{2}}}^{\infty} e^{-\mu^2} d\mu = \frac{1}{2} \operatorname{erfc} \left(\frac{z}{\sqrt{2}} \right)$$

$$Q(z) = \frac{1}{2} \operatorname{erfc} \left(\frac{z}{\sqrt{2}} \right) = \frac{1}{2} \left[1 - \operatorname{erf} \left(\frac{z}{\sqrt{2}} \right) \right]$$

$$\operatorname{erf}(z) = \frac{2}{\sqrt{\pi}} \int_0^z e^{-\mu^2} d\mu \quad \operatorname{erfc} = \frac{2}{\sqrt{\pi}} \int_z^{\infty} e^{-\mu^2} d\mu$$

$$\begin{aligned} \operatorname{erfc}(z) &= \frac{2}{\sqrt{\pi}} \int_{-\infty}^z e^{-\mu^2} d\mu - \frac{2}{\sqrt{\pi}} \int_{-\infty}^z e^{-\mu^2} d\mu \\ &= \frac{2}{\sqrt{\pi}} \int_{-\infty}^z e^{-\mu^2} d\mu - \frac{2}{\sqrt{\pi}} \int_{-\infty}^0 e^{-\mu^2} d\mu - \frac{2}{\sqrt{\pi}} \int_0^z e^{-\mu^2} d\mu \\ &= 2 - 1 - \operatorname{erf}(z) = 1 - \operatorname{erf}(z) \end{aligned}$$

• PROBABILITY THAT THE RECEIVED SIGNAL LEVEL WILL EXCEED A CERTAIN VALUE γ

$$Pr [P_r(d) > \gamma] = Q \left(\frac{\gamma - P_r(d)}{\sigma} \right) \rightarrow \text{TAKE } \gamma$$

$$Pr [P_r(d) < \gamma] = \frac{1}{2} \left[1 + \operatorname{erf} \left(\frac{P_r(d) - \gamma}{\sigma} \right) \right] \rightarrow \text{TAKE } \gamma$$

• DETERMINATION OF PERCENTAGE OF COVERAGE AREA

$U(\gamma)$ - PERCENTAGE OF USEFUL SERVICE AREA

$$U(\gamma) = \frac{1}{\pi R^2} \int Pr [P_r(r) > \gamma] dA = \frac{1}{\pi R^2} \int_0^R \int_0^{2\pi} Pr [P_r(r) > \gamma] r dr d\theta$$

$$Pr [P_r(d) > \gamma] = \frac{1}{2} \left[1 - \operatorname{erf} \left[\frac{\gamma - (P_t - (P_L(d_0) + 10 \log \frac{r}{d_0}))}{\sigma} \right] \right]$$

$$P_L(r) = P_L(d_0) + 10 \log \frac{r}{d_0} + 10 \log \left(\frac{r}{R} \right)$$

$$P_r[P_r(r) > \gamma] = \frac{1}{2} - \frac{1}{2} \operatorname{erf} \left[\frac{\gamma - (P_t - P_n(d_0) + 10 \log \frac{R}{d_0} + 10 \log \frac{r}{R})}{\sigma \sqrt{2}} \right]$$

$$a = \gamma - P_t + P_n(d_0) + 10 \log \frac{R}{d_0}$$

$$b = \frac{10 \log e}{\sigma \sqrt{2}}$$

$$P_r[P_r(r) > \gamma] = \frac{1}{2} - \frac{1}{2} \operatorname{erf} \left[\frac{a + 10 \log \left(\frac{r}{R} \right)}{\sigma \sqrt{2}} \right] = \frac{1}{2} - \frac{1}{2} \operatorname{erf} \left(a + b \ln \frac{r}{R} \right)$$

$$\log(x) = \frac{\ln x}{\ln 10}$$

$$\log \frac{r}{R} = \frac{\ln \frac{r}{R}}{\log 10}$$

$$\ln(x) = \frac{\ln x}{\ln e}$$

$$\log(x) = \log_e \ln x$$

$$x = e^{\ln x}$$

$$\log(x) = \log_e e^{\ln x} = \ln x \log_e e$$

$$U(\gamma) = \frac{1}{\pi R^2} \int_0^{2\pi} \int_0^R \left[\frac{1}{2} - \frac{1}{2} \operatorname{erf} \left(a + b \ln \frac{r}{R} \right) \right] r dr d\theta =$$

$$= \frac{2}{R^2} \int_0^R \frac{1}{2} r dr - \frac{2}{R^2} \frac{1}{2} \int_0^R r \operatorname{erf} \left(a + b \ln \frac{r}{R} \right) dr =$$

$$\text{①} = \frac{2}{2R^2} \frac{R^2}{2} = \frac{1}{2}$$

$$U(\gamma) = \frac{1}{2} - \frac{1}{R^2} \int_0^R r \operatorname{erf} \left(a + b \ln \frac{r}{R} \right) dr$$

$$t = \operatorname{erf} \left(a + b \ln \frac{r}{R} \right)$$

$$\operatorname{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-u^2} du$$

$$g(x) = \int f(x) dx$$

$$\frac{dg(x)}{dx} = f(x)$$

$$dt = \frac{2}{\sqrt{\pi}} e^{-(a + b \ln \frac{r}{R})^2} dr$$

$$U(\gamma) = \frac{1}{2} - \frac{1}{R^2} \int_0^R \frac{2r}{\sqrt{\pi}} e^{-(a + b \ln \frac{r}{R})^2} dr = \frac{1}{2} - \frac{2}{\sqrt{\pi} R^2} \int_0^R r e^{-(a + b \ln \frac{r}{R})^2} dr$$

$$\text{②} = \left| \begin{aligned} m &= a + b \ln \frac{r}{R} & \ln \frac{r}{R} &= \frac{m-a}{b} & \left[r = R e^{\frac{m-a}{b}} \right] \\ dm &= b \frac{1}{\left(\frac{r}{R} \right)} \cdot \frac{1}{R} dr & & & \\ &= \frac{b}{r} dr & & & \end{aligned} \right.$$

$$\begin{aligned} r=0 & \quad m = -\infty \\ r=R & \quad m = a + b \ln \frac{R}{R} = a \end{aligned}$$

$$\int r e^{-m^2} \frac{r dm}{b} = \frac{1}{b} \int r^2 e^{-m^2} dm = \frac{1}{b} \int R^2 e^{\frac{2(m-a)}{b}} e^{-m^2} dm$$

$$= \frac{R^2}{b} \int_{-\infty}^a e^{\frac{2m}{b} - \frac{2a}{b}} e^{-m^2} dm = \frac{R^2}{b} e^{-\frac{2a}{b}} \int_{-\infty}^a e^{\frac{2m}{b} - m^2} dm = \frac{R^2}{b} e^{-\frac{2a}{b}} \int_{-\infty}^a e^{-\left(m - \frac{1}{b}\right)^2} d\left(m - \frac{1}{b}\right) = \frac{R^2}{b} e^{-\frac{2a}{b}} \left(\int_{-\infty}^0 e^{-\sigma^2} d\sigma + \int_0^{\frac{a-1/b}{b}} e^{-\sigma^2} d\sigma \right)$$

$$U(x) = \frac{1}{2} - \frac{e^{-\frac{x^2}{2\sigma^2}}}{\sqrt{\pi}\sigma} \left[\frac{\sqrt{\pi}}{2} + \frac{\sqrt{\pi}}{2} \operatorname{erf}\left(a - \frac{x}{\sigma}\right) \right]$$

$$U(x) = \frac{1}{2} - \frac{1}{\sigma} e^{-\frac{x^2}{2\sigma^2}} \left[1 + \operatorname{erf}\left(a - \frac{x}{\sigma}\right) \right] = \frac{1}{2} - \frac{1}{\sigma} e^{-\frac{x^2}{2\sigma^2}} \left[1 - \operatorname{erf}\left(\frac{x-a}{\sigma}\right) \right]$$

$$U(x) = \frac{1}{2} - \frac{1}{\sigma} e^{-\frac{x^2}{2\sigma^2}} \left[1 - \operatorname{erf}\left(\frac{x-a}{\sigma}\right) \right]$$

$$\text{if } a=0 \Rightarrow U(x) = \frac{1}{2} - \frac{1}{\sigma} e^{-\frac{x^2}{2\sigma^2}} \left[1 - \operatorname{erf}\left(\frac{x}{\sigma}\right) \right]$$

Book: $U(x) = \frac{1}{2} \left[1 + \exp\left(\frac{x^2}{2\sigma^2}\right) \left(1 - \operatorname{erf}\left(\frac{x}{\sigma}\right) \right) \right]$ for $a=0$

$b = 10 \log_{10} \frac{\sigma}{\sigma_0}$ $U(x) = \frac{1}{2} \left(1 - \operatorname{erf}\left(\frac{x}{\sigma}\right) + \exp\left(\frac{x^2}{2\sigma^2}\right) \left[1 - \operatorname{erf}\left(\frac{x-a}{\sigma}\right) \right] \right)$ $a \neq 0$

$$\textcircled{1} = \int_0^R r e^{-(a+b \ln \frac{r}{R})^2} dr = \left| \begin{array}{l} u = v \quad du = dr \\ v = \int e^{-(a+b \ln \frac{r}{R})^2} dr \end{array} \right| \textcircled{A}$$

$$\textcircled{1} = \left| \begin{array}{l} u = a + b \ln \frac{r}{R} \quad r = R e^{\frac{u-a}{b}} \\ du = \frac{b}{r} \cdot \frac{1}{b} dr = \frac{1}{r} dr \end{array} \right| = \int e^{-u^2} \frac{r}{b} du = \frac{1}{b} \int e^{-u^2} \cdot R e^{\frac{u-a}{b}} du$$

$$= \frac{R}{b} \int e^{-u^2} e^{\frac{u}{b}} e^{-\frac{a}{b}} du =$$

Ex. 3.9 $d_0 = 100 \text{ m}$, $d_1 = 200 \text{ m}$, $d_2 = 1 \text{ km}$, $d_3 = 3 \text{ km}$

$$\overline{PL}(d) = \overline{PL}(d_0) + 10 \log_{10} \left(\frac{d}{d_0} \right) + X_G$$

① MMSE (minimum mean square error) = ? for h

② $\sigma = ?$

③ $P_r = ?$ AT $d = 2 \text{ km}$

④ $P_r [P_r(2 \text{ km}) > -60 \text{ dBm}]$

⑤ $U[\delta = -60 \text{ dBm}] = ?$

	d	received PWR	PL
0	100 m	0 dBm	0
1	200 m	-20 dBm	20
2	1000 m	-55 dBm	55
3	3000 m	-70 dBm	70

⑥ $\overline{PL}(d_0) = 0 \text{ dBm}$

$$\overline{PL}(d_1) = 10 \log_{10} \left(\frac{d_1}{d_0} \right) + X_G$$

$$u_1 = \frac{20 \text{ dBm} - X_G}{10 \log 2}$$

$u_2 =$

$$u_1 = \frac{\overline{PL}(d_1) - X_G}{10 \log \left(\frac{d_1}{d_0} \right)}$$

$$u_2 = \frac{35 - X_G}{10 \log 10} \quad ; \quad u_3 = \frac{70 - X_G}{10 \log 30}$$

$$|X_B| = \emptyset \quad u_1 = 6,64 \quad u_2 = 3,5 \quad u_3 = 4,73$$

$$u_{\text{avg}}^2 = \frac{1}{3} (u_1^2 + u_2^2 + u_3^2) \quad \bar{u} = 4,96 \quad u_{\text{avg}} = 5,127$$

$$\textcircled{c} \quad \sigma^2 = \frac{1}{3} \left[(\bar{u} - u_1)^2 + (\bar{u} - u_2)^2 + (\bar{u} - u_3)^2 \right] = (1,2930)^2$$

$$\sigma = 1,2930$$

$$P_R = \frac{P_T \cdot G_1 \cdot G_2 \cdot \lambda^2}{(4\pi)^2 \cdot d^2 \cdot L}$$

$$d_i = [100, 200, 1000, 3000]$$

$$p_i = [0, -20, -35, -70]$$

$$20 = 10 \log 2 + x_B$$

$$35 = 10 \log 10 + x_B$$

$$70 = 10 \log 30 + x_B$$

④ p_i - power at distance d_i

\hat{p}_i - estimate of p_i using $\left(\frac{d}{d_0}\right)^n$ path loss model

$$J(n) = \sum_{i=1}^4 (p_i - \hat{p}_i)^2 \quad \frac{dJ(n)}{dn} = 0 \Rightarrow n =$$

$$P_L(\text{dB}) = P_L(d_0) + 10n \log \left(\frac{d}{d_0}\right)$$

$$\hat{p}_i = p_i(d_0) - 10n \log \frac{d}{d_0} \quad \hat{p}_1 = -10n \log \left(\frac{d_1}{d_0}\right) =$$

$$\hat{p}_1 = -10n \log \left(\frac{100}{100}\right) = 0 \quad \hat{p}_2 = -10n \log \frac{200}{100} = -3n$$

$$\hat{p}_3 = -10n \log 10 = -10n \quad \hat{p}_4 = -14,77n$$

$$J(n) = (0 - 0)^2 + (-20 + 3n)^2 + (-35 + 10n)^2 + (-70 + 14,77n)^2$$

$$J(n) = 327,2 n^2 - 2887,8 n + 6525$$

$$\frac{d}{dn} [J(n)] = 654,3 n - 2887,8 = 0 \Rightarrow \boxed{n = 4,41}$$

$$\textcircled{b} \quad x_B(0) = 0 \quad x_B(1) = 20 - 10 \log 2 = 6,7246$$

$$x_B(2) = 35 - 10 \log 10 = -9,1$$

$$x_B(3) = 70 - 10 \log 30 = -4,85$$

$$x_B = -1,97 \text{ dB} \quad u_{\text{avg}} = 5,127$$

$$\sigma^2 = \frac{1}{4} (327,2 n^2 - 2887,8 n + 6525) = 38,075$$

$$\sigma = \sqrt{38,075} = \underline{\underline{6,17 \text{ dB}}}$$

a) $P_r = ?$ $d = 2 \text{ km}$
 $P_r(d) = P_r(0) - 10 \log \left(\frac{d}{d_0} \right) = 0 - 10 \log \frac{2 \cdot 10^3}{10^2} = -10 \cdot 4,4 \cdot \log(20)$
 $P_r(d) = -57,4 \text{ dB} + X_G = -57,4 \text{ dB} + 6,17 \cdot \text{randn}(1,1) = -62,9 \text{ dB}$
 $P_r(d) = -57,4 \text{ dB} + X_G = -57,4 \text{ dB} + 6,17 \cdot \text{randn}(1,1) = -62,9 \text{ dB}$

b) $P_1 [P_r(2 \text{ km}) > -60 \text{ dBm}] = ?$
 $P_r [P_r(d) > \gamma] = \frac{1}{2} \left[1 - \text{erf} \left(\frac{\gamma - P_r(d)}{\sqrt{2} \sigma} \right) \right] = \frac{1}{2} \left(1 - \frac{2}{\sqrt{\pi}} \int_0^{\frac{\gamma - P_r(d)}{\sqrt{2} \sigma}} e^{-u^2} du \right) =$
 $= \frac{1}{2} \left(1 - \frac{2}{\sqrt{\pi}} \int_0^{0,3} e^{-u^2} du \right)$

$P_r [P_r(d) > \gamma] = 0,66$

$\frac{1}{\sqrt{2\pi}\sigma} \int_0^{-60 - \frac{P_r^2}{2\sigma^2}} e^{-\frac{P_r^2}{2\sigma^2}} dP_r = \frac{1}{\sqrt{2\pi} \cdot 6,17} \int_0^{-60} e^{-\frac{P_r^2}{2(6,17)^2}} dP_r$

c) $U[\gamma = -60 \text{ dBm}] = ?$

$a = \frac{\gamma - P_r(2 \text{ km})}{\sigma \sqrt{2}} = \frac{-60 + 57,4}{6,17 \sqrt{2}} = -0,2979 \approx -0,3$

$b = \frac{10 \text{ m}}{\sigma \sqrt{2}} \log e = 2,19$

$U(\gamma) = \frac{1}{2} \left(1 - \text{erf}(a) + \text{erf} \left(\frac{1 - 2ab}{b^2} \right) \left[1 - \text{erf} \left(\frac{1 - ab}{b} \right) \right] \right)$

$\frac{\sigma}{\sqrt{2}} = \frac{6,17}{1,41} = 4,41$; $P_r [P_r > -60] = 0,66$; $U(\gamma) = 0,9$

• OKUMURA MODEL

$L_{50}(\text{dB}) = L_f + A_{\text{max}}(f, d) - G(h_{te}) - G(h_{re}) - G_{\text{area}}$

$G(h_{te}) = 20 \log \left(\frac{h_{te}}{200} \right)$ $1000 \text{ m} > h_{te} > 30 \text{ m}$

$G(h_{re}) = 10 \log \left(\frac{h_{re}}{3} \right)$ $h_{re} \leq 3 \text{ m}$

$G(h_{re}) = 20 \log \left(\frac{h_{re}}{3} \right)$ $10 \text{ m} > h_{re} > 3 \text{ m}$

3.10 Find $L_{50} = ?$ $d = 50 \text{ km}$ $h_{te} = 100$ $h_{re} = 10$
 $EIRP = 1 \text{ kW}$ 900 MHz $G_e = 1$

$$P_r = \frac{P_t G_t G_r \lambda^2}{(4\pi)^2 d^2} = \frac{EIRP \frac{\lambda^2}{4\pi}}{(4\pi)^2 d^2} = \frac{10^3}{16\pi^2 \cdot 9 \cdot 5^2 \cdot 10^{8.5}}$$

$$P_r = \frac{1}{16 \cdot 9 \cdot 25 \cdot 7^2} \cdot 10^{-5} = 2,8 \cdot 10^{-3} \cdot 10^{-5} = 2,8 \cdot 10^{-10} = 0,28 \mu\text{W}$$

$$L_{50}(\text{dB}) = L_f + A_{nu}(f, d) - G(h_{te}) - G(h_{re}) - G_{atm} \approx 9 \text{ dB}$$

$$G(h_{te}) = 20 \log(0.9) = -6 \text{ dB}$$

$$G(h_{re}) = 20 \log\left(\frac{h_{re}}{3}\right) = 10 \text{ dB}$$

$$L_f = 20 \log \frac{P_t}{P_r} = 20 \log \frac{10^3}{2,8 \cdot 10^{-10}} = 20 \log \frac{10^{12}}{2,8} = 129 \text{ dB}$$

$$L_{50} = 129 + A_{nu}(f, d) + 6 - 10 - 9 = 121 \text{ dB} + A_{nu} - 9$$

$$L_{50} = 112 + A_{nu}(900 \text{ MHz}, 50 \text{ km}) \quad A_{nu} = 35 \text{ dB}$$

$$L_{50} = 112 + 35 = 147 \text{ dB}$$

$$P_r(\text{dB}) = EIRP(\text{dBm}) - L_{50} + G_r(\text{dB}) = 10 \log \frac{10^3}{10^3} - 150 + 9$$

$$P_r(\text{dB}) = -90 \text{ dB}$$

HATA Model

$$L_{50}(\text{urban})(\text{dB}) = 69.55 + 26.16 \log f_c - 13.82 \log h_{te} - a(h_{re}) + (44.9 - 6.55 \log h_{te}) \log d$$

$$a(h_{re}) = (1.1 \log f_c - 0.7) h_{re} - (1.56 \log f_c - 0.8) \text{ dB}$$

LARGE CITY

$$a(h_{re}) = 8.29 (\log 154 h_{re})^2 - 1.1 \text{ dB} \quad f_c \leq 300 \text{ MHz}$$

$$a(h_{re}) = 32 (\log 11.75 h_{re})^2 - 4.97 \text{ dB} \quad f_c \geq 300 \text{ MHz}$$

SUBURBAN

$$L_{50}(\text{dB}) = L_{50}(\text{urban}) - 2[\log(f_c/10)]^2 - 5.4$$

OPEN AREA

$$L_{50}(\text{dB}) = L_{50}(\text{urban}) - 4.78 (\log f_c)^2 - 18.33 \log f_c - 40.98$$

WALFISH & BERTONI Model

$$S = P_0 Q^2 P_1 \quad P_0 = \left(\frac{T}{4\pi R}\right)^2$$

$$d = 1 \text{ km} \quad \frac{P_0}{P_T} = \frac{\lambda^2}{(4\pi R)^2} = \frac{1 \cdot 300^2}{(4\pi)^2} = \frac{3}{16\pi^2 \cdot 19^2} = 1,6 \cdot 10^{-4}$$

$$P_1 = P_r(d) = 10 \log \frac{1}{1,6 \cdot 10^4} = 38 \text{ dB}$$

WIDEAREA PCC Microcell Model

$$d_f = \frac{1}{\lambda} \sqrt{(\epsilon^2 - \Delta^2)^2 - 2(\epsilon^2 + \Delta^2) \left(\frac{\Delta}{2}\right)^2 + \left(\frac{\Delta}{2}\right)^4}$$

FRESNEL I ZONE CLEARANCE DISTANCE

$$\bar{P}_L(d) = \begin{cases} 10 n_1 \log(d) + \eta_1 & 1 < d < d_f \\ 10 n_2 \log(d/d_f) + 10 n_1 \log d_f + \eta_1 & d > d_f \end{cases}$$

$$\eta_1 = PL(d_0) = \frac{P_t \cdot G_t G_r \lambda^2}{(4\pi)^2 d^2} \quad 10 \log \frac{\eta_1}{P_t} = 10 \log \frac{(0.158)^2}{(4\pi)^2}$$

$$\lambda = \frac{300}{1900} = \frac{3}{19} = 0.158 \quad ; \quad PL = 10 \log \frac{P_r}{P_t} = 38 \text{ dB}$$

• OBS case: $\bar{P}_L(d) = 10 n_1 \log(d) + \eta_1$
 3.11 Indoor Propagation Models

$$PL(dB) = PL(d_0) + 10 n_1 \log\left(\frac{d}{d_0}\right) + X_G$$

• ATTENUATION FACTOR MODEL

$$\bar{P}_L(dB) = PL(d_0) + 10 n_{eff} \log\left(\frac{d}{d_0}\right) + FAF(dB)$$

$$\bar{P}_L(d) = \bar{P}_L(d_0) + 10 \log\left(\frac{d}{d_0}\right) + \alpha d + FAF(dB)$$

Example 3.11

$n = 3.27$ 1 floor $n = 5.22$ 3 floor
 $FAF = 24.4$ 3 floors btw T & R

$$PL(30) = PL(d_0) + 10 \cdot 3.27 \log\left(\frac{30}{1}\right) + 24.4 \quad \boxed{3.94}$$

$$PL(d_0) = -10 \log \frac{\frac{1}{9}}{16\pi^2} = -10 \log \frac{1}{9 \cdot 16\pi^2} = 31 \text{ dB}$$

$$PL(30) = 31 + 48.3 + 24.4 = 103.3 \text{ dB}$$

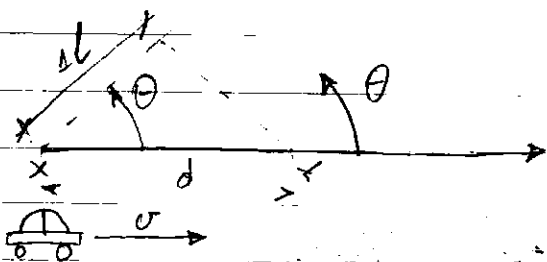
$$\boxed{3.95} \quad PL(30) = PL(d_0) + 10 \cdot 5.22 \log 30 = 108, 105 \text{ dB}$$

Ch4: Small-Scale Fading and Multipath

$$d \cdot \cos \theta = v \cdot t \cos \theta$$

$$\Delta d = \frac{2\pi \Delta d}{\lambda} = \frac{2\pi v \Delta t \cos \theta}{\lambda}$$

$$\boxed{f_d = \frac{\omega_d}{2\pi} = \frac{\Delta \theta}{2\pi \Delta t} = \frac{v}{\lambda} \cos \theta}$$



Example 4.1 $f = 1850 \text{ MHz}$
 $v = 60 \text{ mph}$

(a) RECEIVER IS MOVING TOWARDS

THE TRANSMITTER; (b) RECEIVER AWAY FROM TRANSMITTER

(c) DIRECTION PERPENDICULAR TO THE DIRECTION OF RECEIVER

(a) $f = 1850 \text{ MHz}$ $v = 60 \text{ mph} = 60 \cdot 1,61 \text{ km/h} = 26,8 \text{ m/sec}$

$f_d = \frac{v}{\lambda} \cos(\theta)$; $\lambda = \frac{300}{1850} = 0,1622$

$f_d = \frac{26,8 \frac{\text{m}}{\text{s}}}{0,1622 \text{ m}} \cos(\theta) = 165 \cos(\theta)$ $f_{d_{\text{max}}} = 165 \text{ Hz}$
 $f_{\text{min}} = f + f_{d_{\text{max}}}$

(b) $f_{d_{\text{min}}} = 165 \cos(\pi) = -165 \text{ Hz}$ $f_{\text{min}} = f - f_{d_{\text{min}}}$
 $f_{\text{max}} = 1850 \cdot 10^6 + 0,000165 \cdot 10^6 = 1850,000165 \text{ MHz}$
 $f_{\text{min}} = 1850 \cdot 10^6 - 0,000165 \cdot 10^6 = 1849,999835 \text{ MHz}$

(c) $f_d = 0$

4.2. IMPULSE RESPONSE MODEL OF A MULTIPATH CHANNEL

$x(t)$ - TRANSMITTED SIGNAL

$\gamma(d,t)$ - RECEIVED SIGNAL AT DISTANCE "d"

$\gamma(d,t) = x(t) \otimes h(t) = \int_{-\infty}^{\infty} x(\tau) h(d,t-\tau) d\tau$

FOR CAUSAL SYSTEM $h(d,t) = 0 \quad t < 0$

$\gamma(d,t) = \int_{-\infty}^t x(\tau) h(d,t-\tau) d\tau \quad d = v \cdot t$

$\gamma(vt,t) = \int_{-\infty}^t x(\tau) \cdot h(vt,t-\tau) d\tau \quad v = \text{const}$

$\gamma(t) = \int_{-\infty}^t x(\tau) h(vt,t-\tau) d\tau = x(t) \otimes h(vt,t) = x(t) \otimes h(d,t)$

$\gamma(t) = \int_{-\infty}^{\infty} x(\tau) h(t,\tau) d\tau = h(t) \otimes h(t,\tau)$

$r(t) = c(t) \otimes \frac{1}{2} h_b(t,\tau) \quad h_b(t,\tau) \Rightarrow \text{BASEBAND IMPULSE RESPONSE}$

$x(t) \triangleright h(t,\tau) = \text{Re} \{ h(t,\tau) e^{j\omega_c t} \} \quad \triangleright \gamma(t)$

$\gamma(t) = \text{Re} \{ r(t) e^{j\omega_c t} \}$

$\gamma(t) = x(t) \otimes h(t)$

$c(t) \triangleright \frac{1}{2} h_b(t,\tau)$

$\triangleright r(t)$
 $\frac{1}{2} r(t) = \frac{1}{2} c(t) \otimes \frac{1}{2} h_b(t)$

$x(t) = \text{Re} \{ c(t) e^{j\omega_c t} \} \quad \gamma(t) = \text{Re} \{ r(t) e^{j\omega_c t} \}$

$u(t) = u_m(t) \cos(\omega_c t) = u_m(t) \left[\frac{1}{2} e^{j\omega_c t} + \frac{1}{2} e^{-j\omega_c t} \right]$

$U(j\omega) = \frac{1}{2} U_m[j(\omega - \omega_c)] + \frac{1}{2} U_m[j(\omega + \omega_c)]$

$u(t) = u_m \cos(\omega_m t) \cos(\omega_c t) = \frac{u_m}{2} \cos[(\omega_c - \omega_m)t] + \frac{u_m}{2} \cos[(\omega_c + \omega_m)t]$

DFT $X(k) = \sum_{n=0}^{N-1} x(n) W_N^{nk}$ $k=0, \dots, N-1$
 $W_N = e^{-j\frac{2\pi}{N}}$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} x_1 & x_1 & x_1 \\ x_2 & x_2 & x_2 \\ x_3 & x_3 & x_3 \end{bmatrix} \quad e^{j\pi} = \cos \pi + j \sin \pi$$

$DT = 10 \cdot 10^{-6} = 10 \mu\text{sec}$ $T = 10 \cdot DT$ $T = 100 DT$
 $T = 1 \text{ msec}$ $f = \frac{1}{T} = 100 \text{ Hz}$
 $N = 100$

$\cos(\pi [0:99])$ $\cos(\omega t)$ $t = n \cdot \Delta t$
 $\cos\left(\frac{2\pi k}{N} n \Delta t\right)$

$\cos(2\pi f n \Delta t) = \cos(2\pi f t)$
 $f = 50 \text{ kHz} \Rightarrow \cos(2\pi \cdot 50 \cdot 10^3 \cdot n \cdot 10 \cdot 10^{-6}) =$
 $= \cos(100 \cdot \pi \cdot n \cdot 10^{-3}) = \cos(10^3 \pi \cdot n \cdot 10^{-3})$
 $= \cos(\pi n) = |n = [0:99]| = \cos(\pi [0:99])$

$N=100$ $[-50:50] \frac{1}{100 DT} = [-50000:50000]$

BANDPASS
 $x(t) \triangleright h(t, \tau) = \text{Re} \{ h_b(t, \tau) e^{j\omega_c t} \}$ $y(t) = \text{Re} \{ r(t) e^{j\omega_c t} \}$

BASEBAND
 $c(t) \triangleright \frac{1}{2} h_b(t, \tau) \triangleright \frac{1}{2} r(t) = \frac{1}{2} c(t) \otimes \frac{1}{2} h_b(t)$

$$\begin{aligned} x(t) &= \text{Re} \{ c(t) e^{-j\omega_c t} \} \\ y(t) &= \text{Re} \{ r(t) e^{-j\omega_c t} \} \end{aligned}$$

Average power of bandpass signal $x^2(t)$ is $\frac{1}{2} |c(t)|^2$

excess delay bins:

TIME DELAY BINS: $\tau_{i+1} - \tau_i$ $\tau_0 = 0$

τ_0 - FIRST MULTIPATH SIGNAL AT RECEIVER

$$\Delta T = \tau_i - \tau_0 \quad \tau_i = i \Delta T \quad i = 0, \dots, N-1$$

N - TOTAL NUMBER OF EQUALLY-SPACED MULTIPATH COMPONENTS

FREQUENCY SPAN OF THE MODEL: $\frac{1}{2\Delta T}$ (BANDWIDTH OF THE TRANSMITTED SIGNAL SHOULD BE $< \frac{1}{2\Delta T}$)

EXCESS DELAY δ : $\tau_i \rightarrow$ DELAY OF THE i -TH COMPONENT COMPARED TO THE FIRST ARRIVING COMPONENT

BASEBAND IMPULSE RESPONSE OF MULTIPATH CHANNEL:

$$h_b(t, \tau) = \sum_{i=0}^{N-1} a_i(t, \tau) \exp[j2\pi f_c \tau_i(t) + \phi_i(t, \tau)] \delta(\tau - \tau_i(t))$$

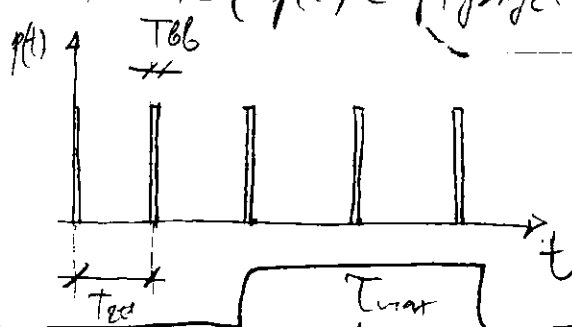
$a_i(t, \tau)$ - REAL AMPLITUDE $\tau_i(t)$ - EXCESS DELAY

IF CHANNEL IMPULSE RESPONSE IS TIME INVARIANT.

$$h_b(\tau) = \sum_{i=0}^{N-1} a_i \exp(-j\theta_i) \delta(\tau - \tau_i)$$

RELATIONSHIP BETWEEN BANDWIDTH & RX POWER

$$x(t) = \Re \{ y(t) \exp(j2\pi f_c t) \}$$



LET: $p(t) = 2\sqrt{\frac{T_{max}}{T_{bb}}} \text{rect}[t - \frac{T_{max}}{2} - \tau_i]$ $0 \leq t < T_{bb}$

$$r(t) = \frac{1}{2} \sum_{i=0}^{N-1} a_i e^{-j\theta_i} p(t - \tau_i) = \sum_{i=0}^{N-1} a_i e^{-j\theta_i} \sqrt{\frac{T_{max}}{T_{bb}}} \text{rect}[t - \frac{T_{max}}{2} - \tau_i]$$

$$|r(t_0)|^2 = \frac{1}{T_{max}} \int_0^{T_{max}} r(t) \cdot r^*(t) dt = |r(t_0)|^2 - \text{POWER PEAK VALUE} =$$

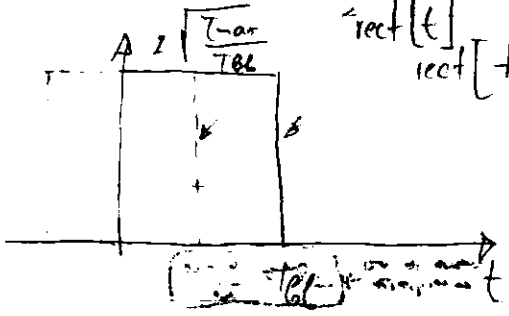
$$= \frac{1}{T_{max}} \int_0^{T_{max}} \frac{1}{4} \left[\sum_{i=0}^{N-1} a_i e^{-j\theta_i} p(t - \tau_i) \right] \left[\sum_{j=0}^{N-1} a_j e^{+j\theta_j} p(t - \tau_j) \right] dt =$$

$$= \frac{1}{4T_{max}} \int_0^{T_{max}} \left(\sum_{i=0}^{N-1} \sum_{j=0}^{N-1} a_i a_j p(t - \tau_i) p(t - \tau_j) e^{-j(\theta_i - \theta_j)} \right) dt$$

$|\tau_j - \tau_i| > T_{bb}$ for $i \neq j \rightarrow$

$$|r(t_0)|^2 = \frac{1}{4T_{max}} \int_0^{T_{max}} \left[\sum_{k=0}^{N-1} a_k^2 p^2(t - \tau_k) \right] dt =$$

$$= \frac{1}{4T_{max}} \sum_{k=0}^{N-1} a_k^2 \int_0^{T_{max}} \left[2\sqrt{\frac{T_{max}}{T_{bb}}} \text{rect}[t - \frac{T_{max}}{2} - \tau_k] \right]^2 dt$$



$$\frac{T_{max}}{4T_{bb}} \int_0^{T_{max}} \left(2\sqrt{\frac{T_{max}}{T_{bb}}} \right)^2 dt = \frac{T_{max}}{4T_{bb}} \cdot \frac{4T_{max}}{T_{bb}} = \frac{T_{max}^2}{T_{bb}^2}$$

$$= \frac{1}{4T_{max}} \sum_{k=0}^{N-1} a_k^2 \frac{4 \cdot T_{max}}{T_{bb}} \int_0^{T_{bb}} dt = \sum_{k=0}^{N-1} a_k^2$$

$$E_{avg}[P_{WB}] = E_{avg} \left[\sum_{i=0}^{N-1} |a_i e^{j\theta_i}|^2 \right] = \sum_{i=0}^{N-1} \overline{a_i^2}$$

ensemble average

• CW ^{NARROW BAND} SIGNAL AMPLITUDE $c(t) = 2$

$$r(t) = \sum_{i=0}^{N-1} a_i \exp(j\theta_i(t, \tau)) = \sum_{i=0}^{N-1} a_i e^{j\theta_i(t, \tau)}$$

PHASOR SUM

$$|r(t)|^2 = \left| \sum_{i=0}^{N-1} a_i \exp(j\theta_i(t, \tau)) \right|^2$$

AVERAGE RECEIVED POWER OVER LOCAL AREA IS:

$$E_{a,\theta}[P_{CW}] = E_{a,\theta} \left[\left| \sum_{i=0}^{N-1} a_i e^{j\theta} \right|^2 \right] \quad \overline{\{x+y\}} = \overline{x} + \overline{y}$$

$$E_{a,\theta}[P_{CW}] = \overline{(a_0 e^{j\theta_0} + a_1 e^{j\theta_1} + \dots + a_{N-1} e^{j\theta_{N-1}})}$$

$$\overline{(a_0 e^{j\theta_0} + a_1 e^{j\theta_1} + \dots + a_{N-1} e^{j\theta_{N-1}})}$$

$$\textcircled{*} = a_0 e^{j\theta_0} \cdot a_1 e^{-j\theta_1} = a_0 a_1 [\cos(\theta_0 - \theta_1) + j \sin(\theta_0 - \theta_1)]$$

$$\textcircled{+} = a_0 e^{-j\theta_0} \cdot a_1 e^{j\theta_1} = a_0 a_1 [\cos(\theta_0 - \theta_1) - j \sin(\theta_0 - \theta_1)]$$

$$\textcircled{*} + \textcircled{+} = 2 a_0 a_1 \cos(\theta_0 - \theta_1)$$

$$E_{a,\theta}[P_{CW}] = \sum_{i=0}^{N-1} \overline{a_i^2} + 2 \sum_{i=0}^{N-1} \sum_{j=0, j \neq i}^{N-1} a_i a_j \overline{\cos(\theta_i - \theta_j)}$$

$$E_{a,\theta}[P_{CW}] = \sum_{i=0}^{N-1} \overline{a_i^2} + 2 \sum_{i=0}^{N-1} \sum_{j=0, j \neq i}^{N-1} v_{ij} \overline{\cos(\theta_i - \theta_j)}$$

$v_{ij} = E[a_i a_j]$

Example 4.2 (M) $\tau_{max} = 100 \mu s$ - URBAN RADIO CHANNELS

(M) $\tau_{max} = 4 \mu s$ - MICROCELLULAR

$N = 64$ NUMBER OF MULTIPATH DMS

(a) $\Delta \tau = ?$ (b) MAXIMUM BANDWIDTH

(1) REPEAT THE EXERCISE WITH RAY CHANNEL MODEL $\tau_{max} = 500 \mu s$

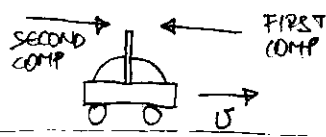
(a) $\tau_i = i \cdot \Delta \tau$ $\tau_{max} = \tau_{N-1} = (N-1) \Delta \tau$ $\Delta \tau = \frac{\tau_{max}}{N-1}$

US: $\Delta \tau = \frac{100 \mu s}{63} = 1.59 \mu s$ M: $63.5 \mu s$ I: $7.9 \mu s$

(b) $B = \frac{1}{2\Delta \tau}$ $B_0 = \frac{1}{2 \cdot 1.59} = 314 \text{ kHz}$; $B_M = 7.9 \text{ MHz}$; $B_I = 63.3 \text{ MHz}$

EXAMPLE 4.5

$v = 10 \text{ m/s}$ RECEIVES TWO MULTIPATH COMPONENTS
 $f_c = 1 \text{ GHz}$ $\tau_0 = 0$ WITH INITIAL PHASE OF 70 dBm
 SECOND COMPONENT $\tau_1 = 1 \mu\text{s}$ WITH INITIAL PHASE 0° & -73 dBm POWER
 - COMPUTE NARROWBAND INSTANTANEOUS POWER AT TIME INTERVALS $0:0.1:0.5 \text{ s}$
 - COMPUTE AVERAGE NARROWBAND & WIDEBAND POWERS OVER THE INTERVAL



$v = 10 \text{ m/s}$ $0.1 \text{ TIME INTERVAL CORRESPONDS TO SPATIAL INTERVAL OF } 1 \text{ m}$
 $\lambda = \frac{300}{1000} = 0.3 \text{ m}$ $|V(t)|^2 = \left| \sum_{i=0}^{N-1} a_i e^{j\theta_i(t, \tau_i)} \right|^2$

$-70 \text{ dBm} = 10 \log \frac{P_1}{1 \text{ mW}} = 10 \log P_1 \cdot 10^3 \Rightarrow 10^{-7} = P_1 \cdot 10^3 \Rightarrow P_1 = 10^{-10} \text{ W}$
 $P_1 = 100 \cdot 10^{-12} = 100 \text{ pW}$
 $-73 \text{ dBm} = 10 \log \frac{P_2}{1 \text{ mW}} \Rightarrow P_2 = 10^{-7.3} \text{ W} = 50 \text{ pW}$
 $|V(t)|^2 = \left| \sqrt{100 \text{ pW}} e^{j\theta} + \sqrt{50 \text{ pW}} e^{j0} \right|^2 = 2.9 \cdot 10^{-10} = 290 \text{ pW}$

$\theta_1 = \frac{2\pi v t}{\lambda} = \frac{2\pi \cdot 10 \cdot t}{0.3}$ $t = 0.1 \text{ s}$ $\theta_1 = \frac{2\pi \cdot 10 \cdot 0.1}{0.3} = \frac{20\pi}{3} \text{ rad}$
 $\theta_1 = \frac{20\pi}{3} \cdot \frac{180}{\pi} = \text{REM} \left(\frac{1200^\circ}{360} \right) \cdot 360 = \frac{360^\circ}{3} = 120^\circ$
 $t = 0.1 \text{ s} : \theta_1 = 2.09 \quad \theta_2 = -2.01$
 $\frac{20\pi}{3} = 2\pi \cdot \frac{10}{3} = 2\pi \cdot 3.33 = 2\pi \cdot 3 + \frac{2\pi}{3} = 2,094 \text{ rad}$

$t = 0:0.1:0.5$ $P_2 = 10^{-9} \cdot [0.2914, 0.0793, 0.0793, 0.2914, 0.0793, 0.0793]$
 $\theta = [0; 120; 240; 0; 120; 240]$

AVERAGE NARROWBAND:
 $\text{mean}(P_2) = \frac{(2 \cdot 291.4 + 4 \cdot 79.3) \cdot 10^{-12}}{6} = 150 \text{ pW}$

WIDEBAND POWER: $E_{a,\theta}[P_{WB}] = E_{a,\theta} \left[\sum_{i=0}^{N-1} |a_i e^{j\theta_i}|^2 \right] = \sum_{i=0}^{N-1} a_i^2$
 $E_{a,\theta}[P_{WB}] = 100 \text{ pW} + 50 \text{ pW} = 150 \text{ pW}$

$\bar{y} = \iint x y p_{xy}(x, y) dx dy$ $F_y(x) = \int p(x) dx$
 $F_{xy}(x, y) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} p(x, y) dx dy$ $F_g(x) = \int \int p(x, y) dx dy$
 $\frac{dF_g(x)}{dx} = \int_{-\infty}^{\infty} p(x, y) dy = p_g(x)$

TIME DISPERSION PARAMETERS

$\sigma_f^2 = \left(\bar{f}^2 - \bar{f}^2 \right) = \bar{f}^2 - \bar{f}^2$

$\bar{\tau} = \frac{\sum_k a_k^2 \tau_k}{\sum_k a_k^2} = \frac{\sum_k P(\tau_k) \cdot \tau_k}{\sum_k P(\tau_k)}$

$\bar{\tau}$ IS FIRST MOMENT OF THE POWER DENSITY PROFILE

$\sigma_\tau = \sqrt{\tau^2 - \bar{\tau}^2}$ IRMS DELAY SPREAD

$$\tau^2 = \frac{\sum a_k^2 \tau_k^2}{\sum a_k^2} = \frac{\sum P(\tau_k) \tau_k^2}{\sum P(\tau_k)}$$

- MAXIMUM EXCESS DELAY (X dB)
- $\tau_x - \tau_0$; τ_0 - FIRST ARRIVING SIGNAL
- τ_x - MAXIMUM DELAY AT WHICH MULTIPATH COMPONENT IS WITHIN X dB OF THE STRONGEST ARRIVING MULTIPATH COMPONENT.

~~CONCEPT~~ BANDWIDTH - BCS

$B_c = \frac{1}{50\sigma_\tau}$

$B_c = \frac{1}{5\sigma_\tau}$

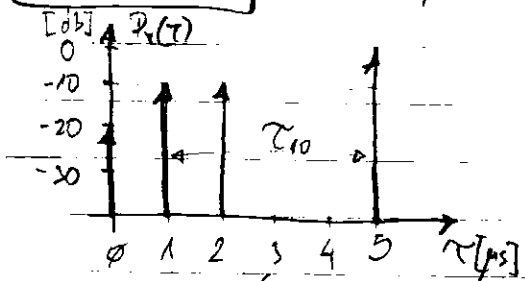
FOR THE FREQ. CORRELATION FUNCTION ABOVE 0.9

FOR THE TIME CORRELATION FUNCTION ABOVE 0.5

EXAM. 4.4

$\bar{\tau}, \sigma_\tau, \tau_x = ?$ X=10dB

Estimate 50% coherent BANDW. OF THE CHANNEL



$$\bar{\tau} = \frac{\sum a_k^2 \tau_k}{\sum a_k^2} = \frac{\sum P(\tau_k) \tau_k}{\sum P(\tau_k)}$$

$$\bar{\tau} = \frac{-20 \cdot 0 - 10 \cdot 1 - 10 \cdot 2 - 0.5}{-20 - 10 - 10 + 0 + 0 - 0}$$

$\bar{\tau} = \frac{-30}{-40} = 0.75 \mu s$

$\tau^2 = \frac{\sum P(\tau_k) \tau_k^2}{\sum P(\tau_k)} = \frac{-20 \cdot 0^2 - 10 \cdot 1^2 - 10 \cdot 4 - 0.5^2}{-40} = \frac{-50}{-40} = 1.25 \mu s^2$

$\sigma_\tau = \sqrt{(1.25)^2 - (0.75)^2} = 1 \mu s$; $\tau_{10} = 4 \mu s$

$B_c = \frac{1}{5\sigma_\tau} = 0.2 \cdot 10^6 = 200 \text{ kHz}$

OK

$10/\log P(0) = -20$; $10^{-2} = P(0)$; $P(0) = 0.01$; $P(1) = P(2) = 0.1$; $P(5) = 1$

$\bar{\tau} = \frac{0.01 \cdot 0 + 0.1 \cdot 1 + 0.1 \cdot 2 + 1 \cdot 5}{0.01 + 0.1 + 0.1 + 1} = \frac{0.3 + 5}{1.21} = \frac{5.3}{1.21} = 4.38 \mu s$

$\tau^2 = \frac{0.1 \cdot 1^2 + 0.1 \cdot 4 + 25}{1.21} = \frac{0.5 + 25}{1.21} = \frac{25.5}{1.21} = 21.074 \mu s^2$

$\sigma_\tau = \sqrt{21.074 - (4.38)^2} = 1.375 \mu s$; $\tau_{10} = 4 \mu s$

$B_c = \frac{1}{5\sigma_\tau} = 0.145 \cdot 10^6 = 145 \text{ kHz}$

AMPS : 300kHz < 145kHz OK

GSM : 200kHz > 145kHz NOT OK

EQUALIZER NEEDED

$d_c = d \cdot \cos \theta$; $\Delta \phi = \frac{2\pi R}{\lambda}$; $\frac{2\pi}{\lambda} \cdot d \cdot \cos \theta = \frac{2\pi}{\lambda} \cdot d \cdot \cos \theta$

$f_d = \frac{\omega_d}{2\pi} = \frac{1}{\Delta t} = \frac{1}{\Delta t} \cdot \frac{\lambda}{\lambda} \cdot \frac{2\pi}{\lambda} \cdot d \cdot \cos \theta = \frac{d}{\lambda} \cdot \cos \theta$

① FREQUENCY DISPERSION

• COHERENCE TIME: T_c

$T_c = \frac{1}{f_m}$

$f_m = f_{max}$ (MAXIMUM DOPPLER SHIFT)

IF TIME CORRELATION FUNCTION > 0.5 THEN

$T_c = \frac{9}{16\pi f_m}$

$f_m = \frac{v}{\lambda}$

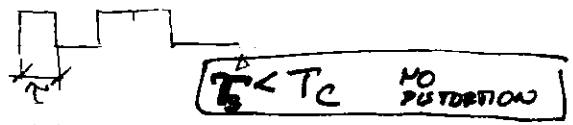
281.5 : 209.8

144 : 105

SYMBOL PERIOD

GEOMETRICAL MEAN OF : ① & ②

① $T_c = \frac{9}{16\pi f_m^2}$



EXAMPLE: $v = 60 \text{ mph}$ $f_c = 300 \text{ MHz}$ $\lambda = 0.333 \text{ m}$

$f_m = \frac{v}{\lambda} = \frac{60 \cdot 1.61 \cdot 10^3}{0.33 \cdot 3600} = 81.3 \text{ Hz}$

② $T_c = 2.2 \text{ msec}$
 $1/T_c = 454 \text{ bps}$

① $T_c = 5.2 \text{ msec}$
 $1/T_c = 192 \text{ bps}$

EXAMPLE 4.5 DOPPLER & SPATIAL SAMPLING INTERVAL = ?

"HIGHLY CORRELATED SAMPLES IN TIME; $f_c = 1900 \text{ MHz}$ "

$v = 50 \text{ m/s}$, HOW LONG IT WILL TAKE TO MOVE THE MEASUR?

DOPPLER SHIFT $\Delta f = ?$

$\lambda = \frac{300}{1900} = \frac{3}{19} = 0.16 \text{ m}$; $\Delta f = f_m = \frac{v}{\lambda} = 316 \text{ Hz}$ (DOPPLER SHIFT)

$T_c = \sqrt{\frac{9}{16\pi f_m^2}} = 1.34 \text{ msec}$

$d = v \cdot T_c = 50 \cdot 1.34 \cdot 10^{-3} = 6.68 \text{ cm}$

SPATIAL SAMPLING $< 6.68 \text{ cm}$

• CONSERVATIVE APPROACH (SMALLEST T_c)

$T_c = \frac{9}{16\pi f_m^2} = 569.42 \mu\text{s}$ $d \leq v \cdot \frac{T_c}{2} = 1.41 \text{ cm}$

10m TRAVEL DISTANCE: $N = \frac{10\text{m}}{0.0141} = 709 \text{ SAMPLES}$

TIME FOR MEASUREMENT = $N \cdot T_c / 2 = 0.2 \text{ sec}$

TYPES OF SMALL SCALE FADING

SMALL SCALE FADING (BASED ON MULTIPATH TIME DELAY SPREAD) TIME DISPERSION

FLAT FADING

FREQUENCY SELECTIVE FAD.

1. BW of signal $<$ BW of channel (flat) 1.) BW signal $>$ BW of channel
2. Delay spread $<$ Symbol period ($T_s \gg T_{sp}$) 2.) Delay spread $>$ Symbol period

SMALL SCALE FADING (BASED ON DOPPLER SPREAD) FREQ. DISPERSION

FAST FADING

SLOW FADING

1. High DOPPLER SPREAD
2. COHERENCE TIME $<$ SYMBOL PERIOD
3. CHANNEL VARIATION FASTER THAN THE DATA SYMBOL RATE
1. Low DOPPLER SPREAD
2. COHERENCE TIME $>$ SYMBOL PERIOD
3. CHANNEL VARIATION SLOWER THAN THE DATA SYMBOL RATE

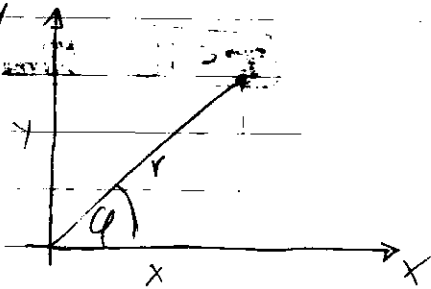
$$y(t) = x(t) \cos(\omega_0 t) - y(t) \sin(\omega_0 t)$$

$$y(t) = r(t) \cos(\omega_0 t + \varphi(t))$$

$$r(t) = \sqrt{x^2(t) + y^2(t)}$$

$$\varphi(t) = \arctan \frac{y(t)}{x(t)}$$

~~$$x(t) = \frac{x(t)}{2} (e^{+j\omega t} + e^{-j\omega t}) - \frac{y(t)}{2} (e^{+j\omega t} - e^{-j\omega t})$$~~



$$x = r \cdot \cos(\varphi)$$

$$y = r \cdot \sin(\varphi)$$

$$\varphi = \arctan \frac{y}{x}$$

$$y(t) = r \cos \varphi \cdot \cos(\omega_0 t) - r \sin \varphi \cdot \sin(\omega_0 t) = r \cos(\omega_0 t + \varphi)$$

2.

FREQUENCY SELECTIVE FADING

FREQUENCY SELECTIVE CHANNELS = WIDE BAND CHANNELS

$$B_s > B_c$$

AND

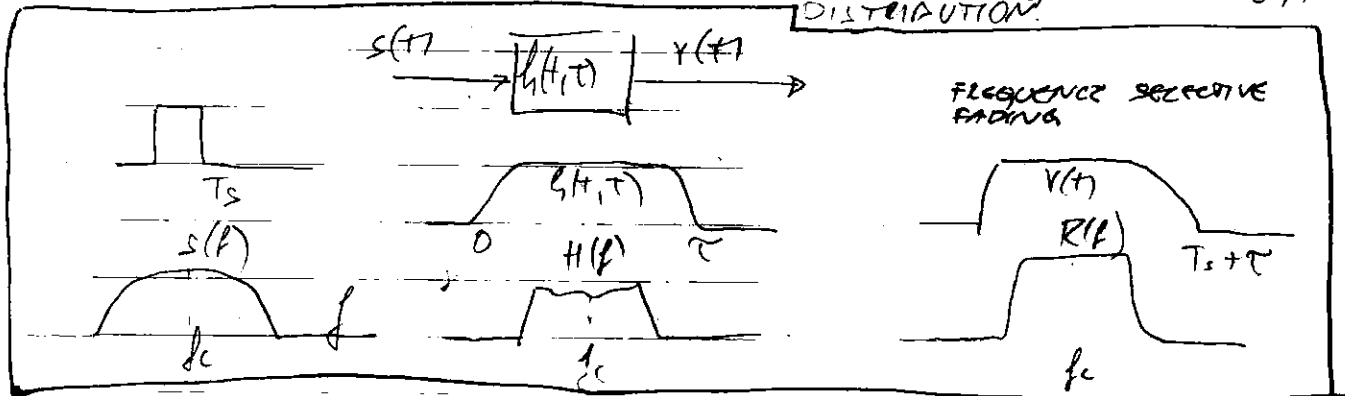
$$T_s < 6\tau$$

RAYLEIGH DISTRIBUTION:

2023-2024

$$P(r) = \int_0^{2\pi} P(r, \varphi) d\varphi = \int_0^{2\pi} \frac{r}{2\pi \sigma^2} e^{-\frac{r^2}{2\sigma^2}} d\varphi = \frac{r}{\sigma^2} e^{-\frac{r^2}{2\sigma^2}}$$

AMPLITUDE DISTRIBUTION IN FAST FADING FOLLOWS RAYLEIGH DISTRIBUTION.



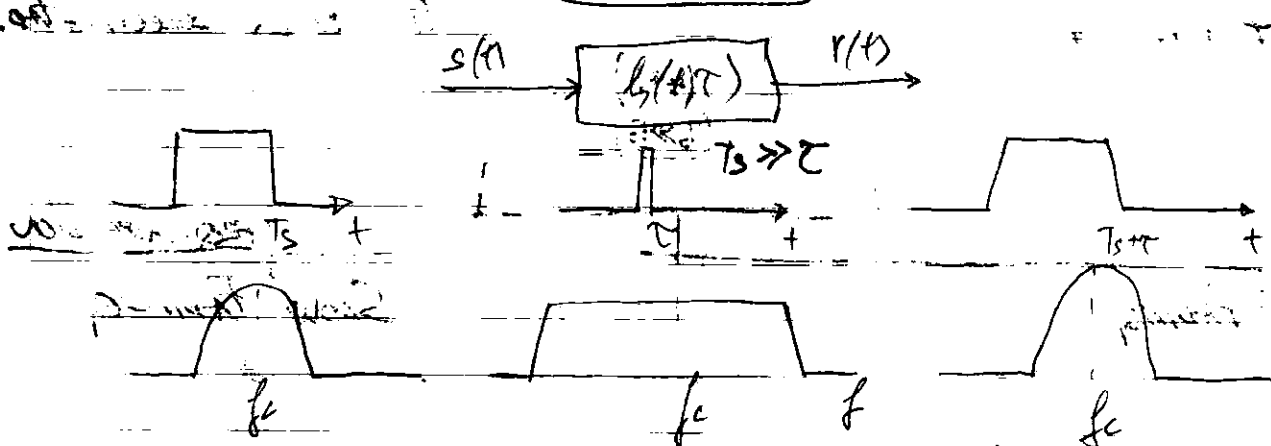
Rule of thumb: CHANNEL CHANGE IS FREQUENCY SELECTIVE IF: $T_s \leq 10B_c$

1. FAST FADING

$$B_s \ll B_c$$

AND

$$T_s \gg \tau$$



FSF NA BANDWIDTH !!!

FADING EFFECTS DUE TO DOPLER SPREAD

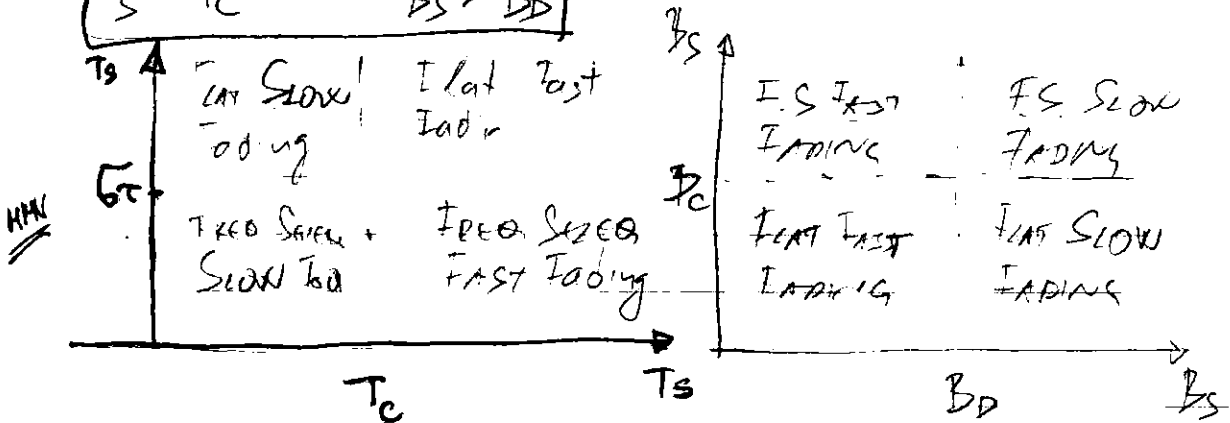
① FAST FADING, THE CHANNEL IMPULSE RESPONSE CHANGES RAPIDLY WITHIN SYMBOL DURATION

$$f_s > f_c \quad B_s < B_D$$

OCCURS FOR VERY LOW MOBILE SPEEDS

② SLOW FADING

$$f_s < f_c \quad B_s > B_D$$



DESCRIBE STATISTICAL TIME VARYING NATURE OF RECEIVED ENVELOPE OF RECEIVED PLAT FADING

RAYLEIGH FADING DISTRIBUTION

$$f(r) = \frac{r}{\sigma^2} e^{-\frac{r^2}{2\sigma^2}} \quad 0 \leq r < \infty$$

σ - rms VALUE OF THE RECEIVED VOLTAGE SIGNAL BEFORE ENVELOPE DETECTION

$$F(r) = F_r(r \leq R) = \int_0^R f(r) dr = -e^{-\frac{r^2}{2\sigma^2}} \Big|_0^R = -e^{-\frac{R^2}{2\sigma^2}} + 1$$

$$\int \frac{r}{\sigma^2} e^{-\frac{r^2}{2\sigma^2}} dr = \frac{1}{2} \int e^{-\frac{r^2}{2\sigma^2}} d\left(\frac{r^2}{\sigma^2}\right) = \int e^{-x} d\left(\frac{r^2}{2\sigma^2}\right) = \int e^{-x} dx = -e^{-x} = -e^{-\frac{r^2}{2\sigma^2}}$$

$$F(r) = F_r(r \leq R) = 1 - e^{-\frac{r^2}{2\sigma^2}}$$

THE PROBABILITY THAT THE ENVELOPE OF THE RECEIVED SIGNAL DOES NOT EXCEED SPECIFIED VALUE R IS GIVEN BY CORRESPONDING CDF.

• MEAN VALUE

$$\bar{r} = E(r) = \int_0^{\infty} r f(r) dr = \int_0^{\infty} r \frac{r}{\sigma^2} e^{-\frac{r^2}{2\sigma^2}} dr = \int_0^{\infty} \frac{r^2}{\sigma^2} e^{-\frac{r^2}{2\sigma^2}} dr$$

$$\sigma = \int \frac{r^2}{\sigma^2} e^{-\frac{r^2}{2\sigma^2}} dr = -e^{-\frac{r^2}{2\sigma^2}} = -r \cdot e^{-\frac{r^2}{2\sigma^2}} - \int e^{-\frac{r^2}{2\sigma^2}} dr$$

$$r = -r e^{-\frac{r^2}{2\sigma^2}} + \int e^{-\frac{r^2}{2\sigma^2}} dr \quad (*)$$

$$\int_{-\infty}^{\infty} e^{-x^2} dx = \sqrt{\pi}$$

$$\int e^{-x} dx = \left| \frac{1}{2x} = \frac{1}{2} \right| \quad dx = \frac{dx}{2x} = \int e^{-\frac{1}{2x}} \frac{dx}{2x}$$

$$\bar{r} = \int_0^{\infty} \frac{r^2}{\sigma^2} e^{-\frac{r^2}{2\sigma^2}} dr = 2 \int_0^{\infty} \frac{r^2}{2\sigma^2} e^{-\frac{r^2}{2\sigma^2}} dr$$

$$u = e^{-\frac{r^2}{2\sigma^2}} \quad du = e^{-\frac{r^2}{2\sigma^2}} \left(-\frac{2r}{2\sigma^2} \right) dr = -\frac{r}{\sigma^2} e^{-\frac{r^2}{2\sigma^2}} dr$$

$$\sigma = \int \frac{r^2}{2\sigma^2} dr = \frac{1}{2\sigma^2} \frac{r^3}{3}$$

$$r = \frac{r^2}{2\sigma^2} \quad dr = \frac{2r}{2\sigma^2} dr = \frac{r}{\sigma^2} dr \quad dr = \frac{\sigma^2}{r} du$$

$$r = \sigma \sqrt{2u} \quad ; \quad dr = \frac{\sigma^2}{\sigma \sqrt{2u}} du = \frac{\sigma}{\sqrt{2u}}$$

$$\bar{r} = -r e^{-\frac{r^2}{2\sigma^2}} \Big|_0^{\infty} + \int_0^{\infty} e^{-\frac{r^2}{2\sigma^2}} dr = -\lim_{r \rightarrow \infty} \frac{r}{e^{\frac{r^2}{2\sigma^2}}} + \int_0^{\infty} e^{-u} \frac{\sigma}{\sqrt{2u}} du$$

$$\bar{r} = \sigma \sqrt{2} \int_0^{\infty} e^{-u} \frac{1}{\sqrt{2u}} du = \sigma \sqrt{2} \frac{\Gamma(\frac{1}{2})}{2} = \sigma \frac{\Gamma(\frac{1}{2})}{\sqrt{2}} \quad \boxed{\bar{r} = \sigma \sqrt{\frac{\pi}{2}} = 1.25\sigma}$$

• VARIANCE:

$$\sigma_r^2 = E(r^2) - E^2(r) = \int_0^{\infty} \frac{r^3}{\sigma^2} e^{-\frac{r^2}{2\sigma^2}} dr - \left(\sigma \sqrt{\frac{\pi}{2}} \right)^2$$

$$E(r^2) = \int_0^{\infty} r^2 \frac{r}{\sigma^2} e^{-\frac{r^2}{2\sigma^2}} dr, \quad u = \int \frac{r}{\sigma^2} e^{-\frac{r^2}{2\sigma^2}} dr = -e^{-\frac{r^2}{2\sigma^2}}$$

$$E(r^2) = -r^2 \cdot e^{-\frac{r^2}{2\sigma^2}} \Big|_0^{\infty} + \int_0^{\infty} 2r e^{-\frac{r^2}{2\sigma^2}} dr = \dots$$

$$= 2\sigma^2 \int_0^{\infty} \frac{r}{\sigma^2} e^{-\frac{r^2}{2\sigma^2}} dr = 2\sigma^2$$

$$\boxed{\sigma_r = 2\sigma^2 - \sigma^2 \frac{\pi}{2}}$$

$$\boxed{\sigma_r = \sigma^2 \left(2 - \frac{\pi}{2} \right)}$$

• MEDIAN

$$\frac{1}{2} = \int_0^{r_m} p(r) dr$$

$$\boxed{r_m = 1.177\sigma}$$

$$\int_0^{r_m} \frac{r}{\sigma} e^{-\frac{r^2}{2\sigma^2}} dr = \int_0^M \frac{M}{12\sigma} du$$

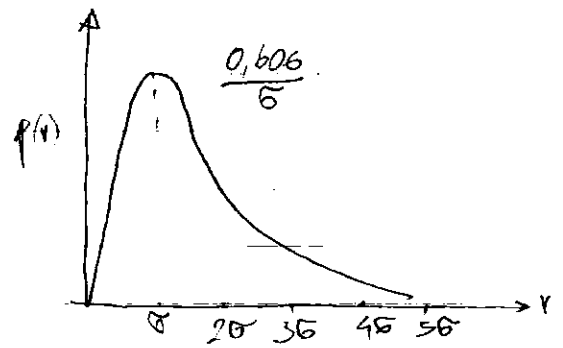
$$\frac{r_m}{\sigma} = M = \frac{r_m}{12\sigma} \int_0^M u e^{-u} du = 1.81157$$

$$\bar{r} = 1.25 \sigma \quad r_{med} = 1.177 \sigma$$

$$20 \log \frac{\bar{r}}{r_{med}} = 0.52 \text{ dB}$$

$$p(r) = \frac{r}{\sigma^2} e^{-\frac{r^2}{2\sigma^2}}$$

$$p(\sigma) = \frac{1}{\sigma} e^{-\frac{1}{2}} = \frac{1}{\sigma \sqrt{e}} = \frac{0.606}{\sigma}$$



• Rician fading distribution

If there is a dominant (non-fading) signal component present, such as line-of-sight propagation path, small-scale fading envelope distribution is **RICIAN**.

$$p(r) = \begin{cases} \frac{r}{\sigma^2} e^{-\frac{(r^2 + A^2)}{2\sigma^2}} I_0\left(\frac{Ar}{\sigma^2}\right) & A \geq 0, r \geq 0 \\ 0 & r < 0 \end{cases}$$

A - PDC AMPLITUDE OF DOMINANT SIGNAL
 I_0 - BESSEL FUNCTION OF FIRST KIND AND ZERO ORDER

$$I_0\left(\frac{Ar}{\sigma^2}\right) = \frac{1}{2\pi} \int_0^{2\pi} e^{\frac{Ar}{\sigma^2} \cos \phi} d\phi$$

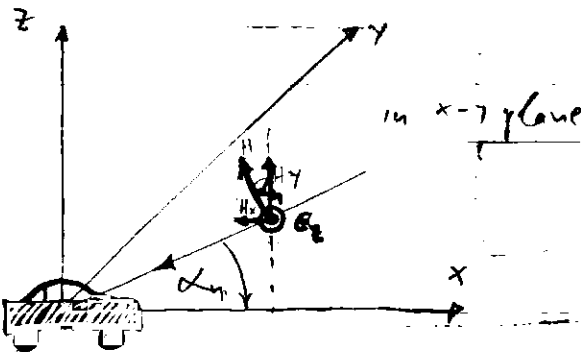
$$K = \frac{A^2}{2\sigma^2}$$

RATIO BETWEEN DETERMINISTIC SIGNAL POWER AND "VARIANCE" OF THE MULTIPATH.

$$K \text{ (dB)} = 10 \log \frac{A^2}{2\sigma^2} \text{ [dB]} \quad \text{RICIAN FACTOR}$$

STATISTICAL MODELS FOR MULTIPATH FADING CHANNELS

• CHANNEL MODEL FOR ~~PLAT~~ **PLAT**



$$d = v \cdot \Delta t \cos(\alpha_n)$$

$$\Delta \phi = \frac{2\pi d}{\lambda} = \frac{2\pi v \cdot \Delta t \cos(\alpha_n)}{\lambda}$$

$$\omega_{dn} = \frac{\Delta \phi}{\Delta t} = \frac{2\pi v}{\lambda} \cos(\alpha_n)$$

$$f_{dn} = \frac{\omega_{dn}}{2\pi} = \frac{v}{\lambda} \cos(\alpha_n)$$

$$H_y = H \cdot \cos(\alpha_n) \quad H_x = H \cdot \sin(\alpha_n)$$

$$E_z = E_0 \sum_{n=1}^N C_n \cos(2\pi f_n t + \theta_n)$$

$$H_x = -\frac{E_0}{\eta} \sum_{n=1}^N C_n \sin(\alpha_n) \cos(2\pi f_n t + \theta_n)$$

$$H_y = -\frac{E_0}{\eta} \sum_{n=1}^N C_n \cos(\alpha_n) \cos(2\pi f_n t + \theta_n)$$

C_n - REAL RANDOM VARIABLE REPRESENTING AMPLITUDES OF INDIVIDUAL WAVES

η - INTRINSIC IMPEDANCE OF FREE SPACE (377 Ω)

θ_n - RANDOM PHASE OF n -TH ARRIVING COMPONENT

$$\theta_n = 2\pi f_n t + \phi_n$$

- AMPLITUDES OF E_x & E_y ARE NORMALIZED SUCH THAT ESTIMATE AVERAGE OF C_n^2 IS GIVEN BY

$$\sum_{n=1}^N C_n^2 = 1$$

• THREE COMPONENT E_x , E_y & E_z CAN BE APPROXIMATED AS GAUSSIAN RANDOM VARIABLES IF N IS SUFFICIENTLY LARGE.

• PHASE ANGLES ARE WITH UNIFORM PDF $[0, 2\pi]$

$$E_z = T_c(t) \cos(2\pi f_c t) - T_s(t) \sin(2\pi f_c t)$$

$$E_z = E_0 \sum_{n=1}^N C_n \cos(2\pi f_c t + \theta_n) = E_0 \sum_{n=1}^N C_n \cos(\omega_c t) \cos \theta_n -$$

$$- E_0 \sum_{n=1}^N C_n \sin(\omega_c t) \sin \theta_n = \left[\sum_{n=1}^N C_n \cos(\omega_c t + \theta_n) \right] \cos(\omega_c t) -$$

$$- E_0 \left[\sum_{n=1}^N C_n \sin(\omega_c t + \theta_n) \right] \sin(\omega_c t)$$

$$E_z = T_c(t) \cos(2\pi f_c t) - T_s(t) \sin(2\pi f_c t)$$

$$T_c(t) = E_0 \sum_{n=1}^N C_n \cos(2\pi f_c t + \theta_n) \quad T_s(t) = E_0 \sum_{n=1}^N C_n \sin(2\pi f_c t + \theta_n)$$

$T_c(t)$ & $T_s(t)$ ARE GAUSSIAN RANDOM PROCESSES DERIVED FROM T_c & T_s AT ANY TIME t . T_c & T_s ARE UNCORRELATED ZERO MEAN GAUSSIAN RANDOM VARIABLES WITH VARIANCE:

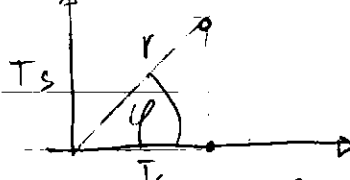
$$\overline{T_c^2} = \overline{T_s^2} = \overline{E_z^2} = \frac{E_0^2}{2} \quad ?$$

$$E_z = V(t) \cdot \cos(\varphi(t)) \cdot \cos(2\pi f_c t) - V(t) \sin(\varphi(t)) \sin(2\pi f_c t) = V(t) \cdot \cos(2\pi f_c t + \varphi(t))$$

$$T_c(t) = V(t) \cos \varphi(t)$$

$$T_s(t) = V(t) \sin \varphi(t)$$

$$\varphi(t) = \arctan \frac{T_s(t)}{T_c(t)}$$



$$V(t) = \sqrt{T_c^2(t) + T_s^2(t)}$$

• SO KONSTENZIE NA ZAKONIAN KORO VO DIGITALNI TK (RAPON MORE NA VEJODITAZEN IUM) \Rightarrow SLUCHAJNI PRAVNI SIGNAL IMA ANGLENA $V = V_0$ IMA PIZIVKA IZVREDEKA NA SLOZIK NA VEJODITAZEN.

$$P(r) = \frac{1}{\sigma^2} e^{-\frac{r^2}{2\sigma^2}} \quad 0 \leq r < \infty \quad \text{KADE } \sigma^2 = \frac{E_0^2}{2}$$

$$P_{T_c, T_s}(T_c, T_s) = P(T_c) \cdot P(T_s) = \frac{1}{2\sigma^2} e^{-\frac{T_c^2}{2\sigma^2}} \cdot \frac{1}{2\sigma^2} e^{-\frac{T_s^2}{2\sigma^2}}$$

$$P(T_c, T_s) = \frac{1}{2\sigma^2} e^{-\frac{T_c^2 + T_s^2}{2\sigma^2}} \quad \begin{matrix} T_c = r \cdot \cos \varphi \\ T_s = r \cdot \sin \varphi \end{matrix} \quad J = \begin{vmatrix} \frac{\partial T_c}{\partial r} & \frac{\partial T_c}{\partial \varphi} \\ \frac{\partial T_s}{\partial r} & \frac{\partial T_s}{\partial \varphi} \end{vmatrix}$$

$$D = \begin{vmatrix} r \cos \varphi & -r \sin \varphi \\ \sin \varphi & r \cos \varphi \end{vmatrix} = r \cos^2 \varphi + r \sin^2 \varphi = r$$

$$\left| \frac{dr}{dt} \frac{dt_s}{ds} = |D| \frac{dr}{d\varphi} \frac{d\varphi}{ds} \right|$$

$$\boxed{\gamma(r, \varphi) = |D| \gamma(r_c, \varphi_s)}$$

$$p(r, \varphi) = \frac{1}{2\pi b^2} e^{-\frac{r^2}{2b^2}}$$

$$p(r) = \int_0^{2\pi} p(r, \varphi) \cdot |D| \cdot d\varphi$$

$$p(r) = \int_0^{2\pi} \frac{1}{2\pi b^2} e^{-\frac{r^2}{2b^2}} \cdot r \cdot d\varphi = \frac{r}{2\pi b^2} e^{-\frac{r^2}{2b^2}} \cdot 2\pi$$

$$\boxed{p(r) = \frac{r}{b^2} e^{-\frac{r^2}{2b^2}}}$$

$$p(r_c, \varphi_c) \frac{dr_c}{dt} \frac{dt_s}{ds} = p(r, \varphi) \cdot dr \cdot d\varphi$$

$$p(r, \varphi) = \frac{p(r_c, \varphi_s)}{\frac{dr_c}{dt} \frac{dt_s}{ds}} = \frac{p(r_c, \varphi_s)}{|D|}$$

$$\boxed{p(r, \varphi) = |D| \gamma(r_c, \varphi_s)}$$

$$p(r, \varphi) = r \cdot \frac{1}{2\pi b^2} e^{-\frac{r^2}{2b^2}}$$

$$p(r) = \int_0^{2\pi} p(r, \varphi) \cdot d\varphi$$

$$\overline{T_c^2} = \int_0^{\infty} T_c p(T_c) dT_c \quad !!$$

$$|\epsilon_c|^2 = \frac{\int_0^{\infty} (r \cos \varphi \cdot \cos(2\pi f c t) - r \sin \varphi \cdot \sin(2\pi f c t))^2 =$$

$$= \underbrace{r^2 \cos^2 \varphi \cos^2(2\pi f c t)}_{\textcircled{1}} - \underbrace{2 r \cos \varphi \sin \varphi \cdot \cos(2\pi f c t) \cdot \sin(2\pi f c t)}_{\textcircled{2}} + \underbrace{r^2 \sin^2 \varphi \cdot \sin^2(2\pi f c t)}_{\textcircled{3}}$$

$$\textcircled{1} = \cos^2(\varphi) \int_0^{\infty} r^2 \cos^2 \varphi \frac{r}{b^2} e^{-\frac{r^2}{2b^2}} dr = 2b^2 \cos^2(\varphi) \cos^2 \varphi \quad \textcircled{2} = 2b^2 \sin^2 \varphi \cdot \sin^2 \varphi$$

$$\textcircled{1} + \textcircled{3} = 2b^2 \quad \textcircled{2} = 0 \quad \textcircled{3} = 0 \quad \textcircled{4} = 0$$

SPECTRUM STATE DUE TO POWER SPREAD IN CARRIER MODE

- $p(\alpha) d\alpha$ - FRACTION OF TOTAL INCOMING POWER WITHIN $d\alpha$ OF THE ANGLE
- AVERAGE RECEIVED POWER WITH RESPECT TO POLARIC ANGLE
- $G(\alpha)$ ANTENNA GAIN WITHIN OF ANGLE ANTENNA

$$P_r = \int_0^{2\pi} A G(\alpha) \cdot p(\alpha) d\alpha \quad \rightarrow \text{TOTAL RECEIVED POWER WITH ANGLE}$$

$$\textcircled{1} f(\alpha) = f = \frac{f}{2} \cos(\alpha) + f_c = f_m \cos \alpha + f_c \quad f_m - \text{MAXIMUM POWER SPREAD}$$

$$\boxed{p(\alpha) = p(-\alpha)}$$

$$S(f) - \text{POWER SPECTRUM}$$

$S(f) df$ → DIFFERENTIAL VARIATION OF RECEIVED POWER WITH FREQUENCY

$$\textcircled{2} S(f) df = A [p(\alpha) G(\alpha) + p(-\alpha) G(-\alpha)] |d\alpha|$$

$$\textcircled{3} \rightarrow df = f_m |\sin \alpha| \cdot d\alpha$$

$$\textcircled{4} \rightarrow \cos \alpha = \frac{f - f_c}{f_m} \quad \alpha = \cos^{-1} \frac{f - f_c}{f_m} = \arccos \frac{f - f_c}{f_m}$$

$$\sin \alpha = \sqrt{1 - \cos^2 \alpha} = \sqrt{1 - \left(\frac{f - f_c}{f_m}\right)^2}$$

$$\textcircled{5} \rightarrow S(f) = f_m \sin \alpha \cdot d\alpha = A [p(\alpha) G(\alpha) + p(-\alpha) G(-\alpha)] d\alpha$$

$$\boxed{S(f) = \frac{A [p(\alpha) \cdot G(\alpha) + p(-\alpha) \cdot G(-\alpha)]}{f_m \cdot \sqrt{1 - \left(\frac{f - f_c}{f_m}\right)^2}}$$

$$S(f) = 0 \quad \text{if } |f - f_c| > f_m$$

• IN CASE OF GP ANTENNA ($\lambda/4$) AND UNIFORM DISTRIBUTION $G(\alpha) = 1.5$
 $\psi(\alpha) = \frac{1}{2\pi} [0 \dots 2\pi]$

4.78 $S_{\text{eff}}(f) = \frac{1 \left[\frac{1}{2\pi} \cdot 1.5 + \frac{1}{2\pi} \cdot 1.5 \right]}{\pi f \sqrt{1 - \left(\frac{f-f_c}{f_m}\right)^2}} = \frac{1.5}{\pi f \sqrt{1 - \left(\frac{f-f_c}{f_m}\right)^2}}$

4.79 $S_{\text{eff}}(f) = \frac{1}{8\pi f_m} K \left[\sqrt{1 - \left(\frac{f}{2f_m}\right)^2} \right]$ $K[\cdot]$ - elliptical integral of first kind

$10 \text{ dB} = 10 \log \frac{x}{1}$ $\log \frac{x}{1} = 1$ $\frac{x}{1} = 10 \Rightarrow x = 10$

$X[\text{dB}] = 10 \log \frac{X(100)}{1\text{W}} = 10 \log \frac{0.15\text{dB}}{1\text{W}} = -8.2 \text{ dB}$

$Y[\text{dB}] = 10 \log \frac{Y(100)}{1\text{W}} = 10 \log \frac{0.2644}{1\text{W}} = -5.77 \text{ dB}$

COMPLEX GAUSSIAN DISTRIBUTION

$z = x + jy$ u_x, u_y $u_z = u_x + ju_y = \epsilon(z)$

$\sigma^2 = E[(x-u_x)^2] = E[(y-u_y)^2] = \frac{1}{2} E[(z-u_z)^2]$

- PROBABILITY DENSITY FUNCTION OF 2D RANDOM VARIABLE (x,y)

$p(x,y) = \frac{1}{2\pi\sigma^2} e^{-\frac{(x-u_x)^2 + (y-u_y)^2}{2\sigma^2}}$

$p(z) = \frac{1}{2\pi\sigma^2} e^{-\frac{|z-u_z|^2}{2\sigma^2}}$

$|z-u_z|^2 = z^2 - 2zu_z + u_z^2 = (x+jy)^2 - 2(x+jy)(u_x+ju_y) + (u_x+ju_y)^2$

$= x^2 + 2jxy - y^2 - 2(xu_x + jyuy + ju_xy - yu_y) + u_x^2 + 2ju_xu_y - u_y^2$

$|z-u_z|^2 = |x+jy - u_x - ju_y|^2 = |(x-u_x) + j(y-u_y)|^2 = (x-u_x)^2 + (y-u_y)^2$

$E[(z-u_z)^2] = E[(x-u_x)^2 + (y-u_y)^2] = E[(x-u_x)^2] + E[(y-u_y)^2]$

$2\sigma^2 = E[(z-u_z)^2]$ $\sigma^2 = \frac{1}{2} E[(z-u_z)^2]$

$\cos(2\pi f \cdot 4 \text{DT})$ $f = 50 \text{ kHz} = 5 \cdot 10^4$ $\Delta t = 10^{-5}$
 $\cos(2\pi \cdot 5 \cdot 10^4 \cdot 4 \cdot 10^{-5}) = \cos(4000) = \cos(50\pi \cdot 10^{-1}) = \cos(5\pi)$

$\begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 2 & 2 & 2 & 2 \\ 3 & 3 & 3 & 3 \\ 4 & 4 & 4 & 4 \end{bmatrix}$

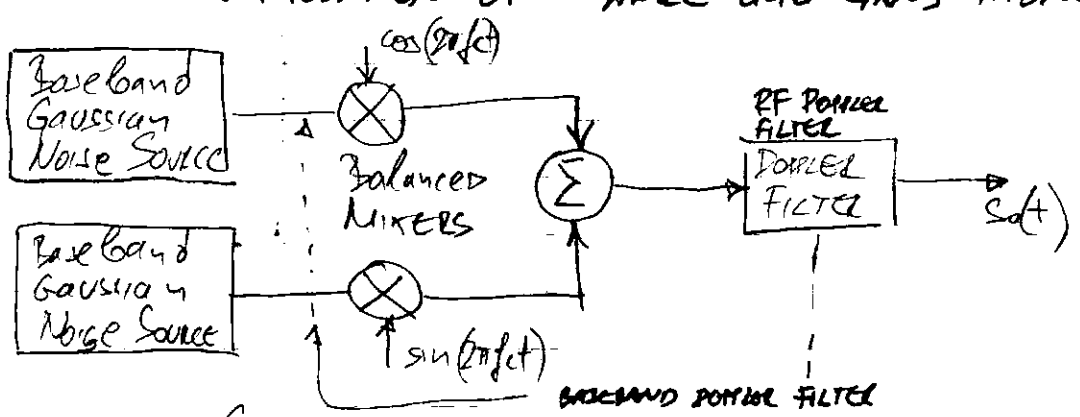
$T = \frac{1}{5 \cdot 10^4} = 0.2 \cdot 10^{-4} = 2 \cdot 10^{-5}$
 $N \cdot \Delta t = 10^3 \cdot 10^{-5} = 10^{-2}$

$T = \frac{1}{5} \cdot 10^{-3} = 0.2 \cdot 10^{-3} = 2 \cdot 10^{-4}$

$N = 1000 \quad \Delta t = 10^{-4}$
 $f = 100 \text{ Hz} \quad c(t) = \cos(2\pi f \cdot \Delta t) = \cos(2\pi \cdot 10^2 \cdot 10^{-4}) = \cos(2 \cdot 10^{-2} \pi)$
 $e(t) = \cos(0.002\pi)$
 $T = \frac{1}{10^2} = 0.01 \text{ sec}$

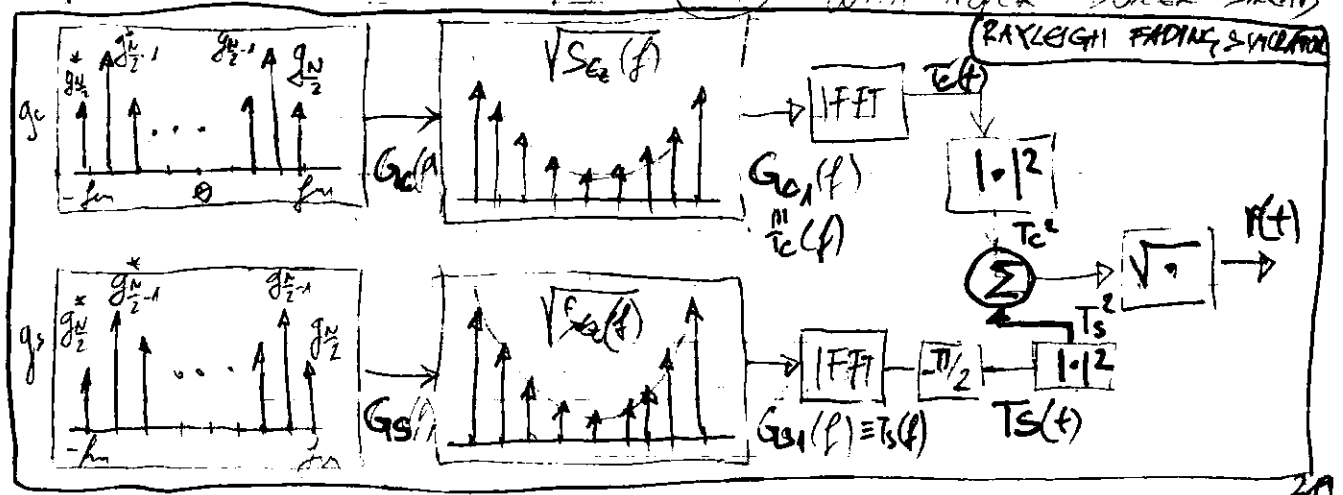
$t = [0 : N-1] \cdot \Delta t$
 $f = [0 : N-1] / (N \cdot \Delta t)$
 $\frac{1}{\Delta t} = 10 \text{ kHz}$

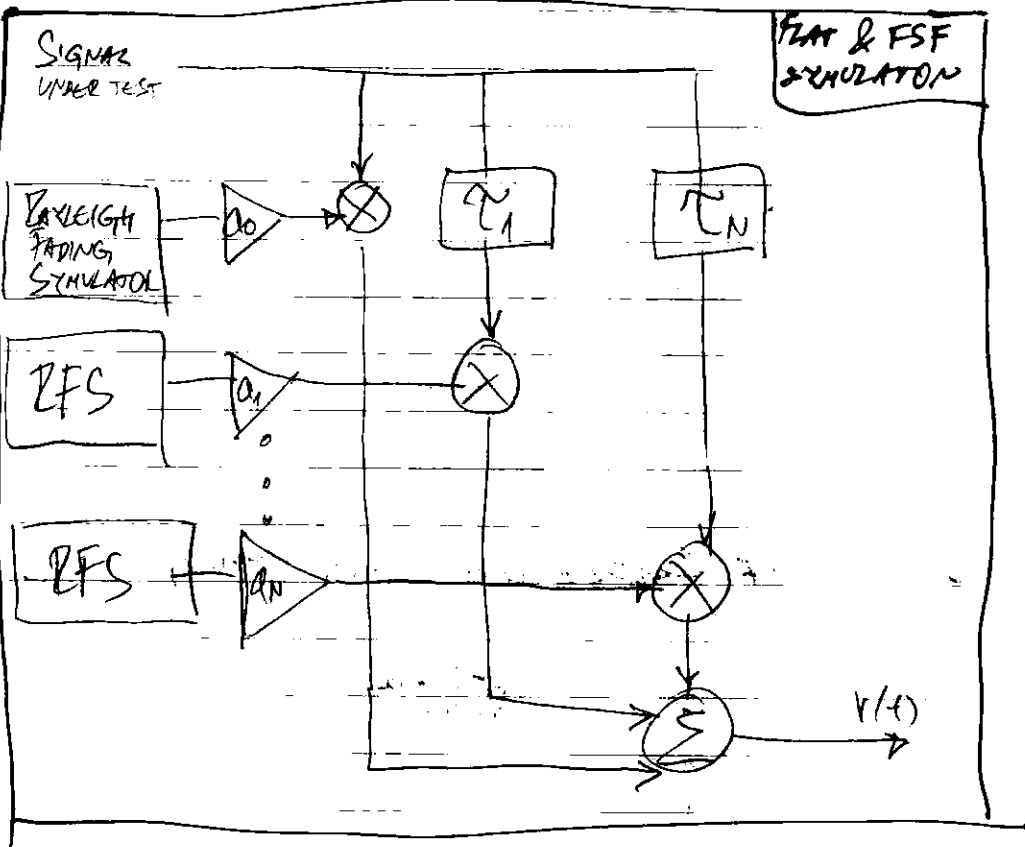
SIMULATION OF CARROLL AND GANS FADING MODELS



IMPLEMENT SMITH SIMULATOR.

- 1) SPECIFY N FREQ. DOMAIN POINTS.
- 2) f_m - DEFINE MAX DOPPLER FREQ. $T = \frac{1}{\Delta f}$ } TIME DURATION OF ~~STATIONARY~~ WAVELENGTH
- 3) GENERATE GAUSSIAN RANDOM VARIABLES FOR EACH OF THE $N/2$ POSITIVE FREQ. COMPONENTS
- 4) CONSTRUCT THE NEGATIVE FREQ. COMPONENTS OF NOISE SOURCE BY CONJUGATING POSITIVE VALUES ($\frac{V_{R1}}{OTK \text{ AMISO}}$)
- 5) MULTIPLEX IN-PLACE AND QUADRATURE NOISE BY $\sqrt{S_{cc}(f)}$
- 6) PERFORM IFFT $+ |T_s|^2 + |T_c|^2$
- 7) $\sqrt{\dots}$ ORDER TO GET $(Y(t))$ RAYLEIGH FADING SIGNAL WITH PROPER DOPPLER SKEW





$2 \cdot f_c \cdot Dt = 0.02$ $f_c = \frac{0.02}{2 \cdot Dt}$ $f_c = 100 \text{ Hz}$

$f = 900 \text{ MHz}$ $\lambda = \frac{300}{900} = 0,33$ $v = 100 \text{ km/h} = 27,7 \text{ m/s}$
 $f_m = \frac{v}{\lambda} = \frac{27,7}{0,33} = 83,33 \text{ Hz}$

$f_m = 100 \text{ Hz} \Rightarrow v = f_m \cdot \lambda = 100 \cdot \frac{1}{3} = 33,3 \frac{\text{m}}{\text{s}} = 120 \frac{\text{km}}{\text{h}}$

$f_c = 900 \text{ MHz}$ $v = 120 \text{ km/h} = 33,33 \text{ m/s} \Rightarrow f_m = 100 \text{ Hz}$

$T_c = \frac{1}{9 \cdot 10^8} = 0,111 \cdot 10^{-8} = 1,11 \cdot 10^{-9} = 1,11 \text{ nsec}$

$N = 1000$

$N \cdot Dt = T_c \Rightarrow N = 10000 \Rightarrow Dt = \frac{T_c}{N} = 1,11 \text{ psec}$

$k = 2 f_c \cdot Dt$ $k = 2 \cdot 9 \cdot 10^8 \cdot 1,11 \cdot 10^{-12} = 20 \cdot 10^{-4} = 2 \cdot 10^{-3}$

$\cos(0.002 \cdot \pi \cdot t)$
 $N = 10.000$ $N \cdot Dt = T_c$ $Dt = \frac{T_c}{N} = \frac{1.111 \cdot 10^{-9}}{10^4} = 1.111 \cdot 10^{-13} = 0,111 \cdot 10^{-12} \text{ sec}$

$k = 2 \cdot 9 \cdot 10^8 \cdot 0,11 \cdot 10^{-12} = 2 \cdot 10^{-4} = 0,2 \cdot 10^{-3}$

• DOPPLER FILTER

$S_{eff}(f) = \frac{1.5}{f_m \sqrt{1 - \left(\frac{f - f_c}{f_m}\right)^2}}$

$f_c = 0$ BANDWIDTH
 $f_m = 100 \text{ Hz}$

$T = \frac{1}{f_m} = 10^{-2} = 0,01 \text{ sec}$

$f_{max} = 100 \text{ Hz}$ $\cos(2\pi f_m \cdot Dt)$
 $Dt = 10^{-4}$ $k = 2 \cdot 10^2 \cdot 10^{-4} = 2 \cdot 10^{-2} = 0,02$

$$DT = 10^{-4}; N = 5000;$$

$$0.02 = 2 \cdot f_c \cdot DT$$

$$\cos(0.02\pi n)$$

$$f_c = \frac{0.02}{2 \cdot DT} = 0.01 \cdot 10^4 = \underline{\underline{10^2}}$$

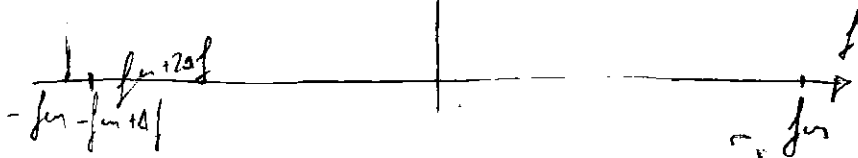
$$s(f) = \cos(2\pi f t)$$

$$s(f) = \cos(2\pi f \cdot 10^{-4} n)$$

$$B = 2f_c$$

$$\Delta f = \frac{2f_c}{N-1}$$

$$k = \frac{0.0735 - 0.0534}{\Delta f}$$



$$s(f) - s(f-2\Delta f) = \frac{0.0735 - 0.0534}{-f + \Delta f - (-f + 2\Delta f)} (f + f - 2\Delta f)$$

$$s(f) - 0.0534 = \frac{0.0221}{-f + \Delta f + f - 2\Delta f} (f + f - 2\Delta f)$$

$$s(f) - 0.0534 = -\frac{0.0221}{\Delta f} (f + f - 2\Delta f)$$

$$s(f) = -\frac{0.0221}{\Delta f} (f + f - 2\Delta f) + 0.0534$$

$$s\left(\frac{f}{2}\right) = -\frac{0.0221}{\Delta f} (-f + f - 2\Delta f) + 0.0534 = +2 \cdot 0.0221 + 0.0534 = 0.0976$$

$$e^{fj\frac{\pi}{2}} = \cos\left(\frac{\pi}{2}\right) + j\sin\left(\frac{\pi}{2}\right) = 0 + j$$

$$g_x + jg_y = \sqrt{g_x^2 + g_y^2} e^{j \arctan\left(\frac{g_y}{g_x}\right)}$$

$$z = 1 + j1$$

$$|z| = 1.4142 + 0.3426j$$

$$|z| = \sqrt{1^2 + 1^2} = \sqrt{2} = 1.4142$$

$$\angle z = \arctan\left(\frac{1}{1}\right) = \frac{\pi}{4} = 0.7854$$

$$z = \sqrt{2} e^{j\frac{\pi}{4}} = 1.4142 e^{j0.7854}$$

$$c = \cos(2\pi fct)$$

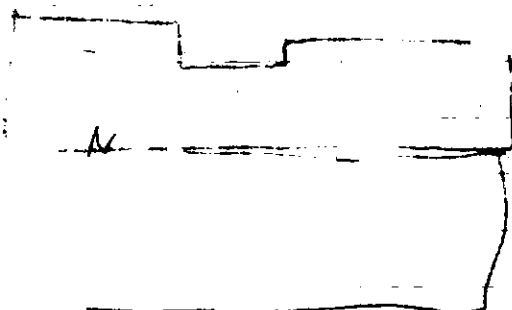
$$c_t = r \cdot \cos(2\pi fct + \varphi(t))$$

$$\cos\left(\alpha - \frac{\pi}{2}\right) = \cos\left(\frac{\pi}{2} - \alpha\right) = \sin\alpha$$

$$\mathcal{F}\{f(t-\tau)\} = F(j\omega) \cdot e^{-j\omega\tau}$$

$$F(k) = \sum_{n=1}^N f(n) e^{-j\frac{2\pi nk}{N}}, k=1$$

$$\mathcal{F}[f(n-m)] = F(k) e^{-j\frac{2\pi km}{N}}$$



$$\text{sawtooth}_h(20 \times \pi \times t) = \text{sawtooth}(20 \times \pi \times \frac{1}{2} \times Dt) = \text{sawtooth}(0,002 \pi t)$$

$$Dt = 10^{-4} \text{ sec} \quad 2 f_c Dt = 0,002 \quad f_c = \frac{0,002 \cdot 10^9}{2} = 0,001 \cdot 10^9 = 10^6 \text{ Hz}$$

$$\cos(0,2 \pi \times 4) \quad f_c = 900 \text{ MHz}$$

$$2 \cdot f_c \cdot Dt = 0,2 \quad f_c = \frac{0,1}{Dt} \quad Dt = \frac{0,1}{f_c} = 0,11 \cdot 10^{-12} \text{ sec}$$

$$Dt = 1,11 \cdot 10^{-12} \rightarrow f_c = \frac{0,1}{1,11 \cdot 10^{-12}} = 90 \text{ GHz}$$

$$0,1 \cdot 10^{-8} = 10^{-1} \cdot 10^{-8} = 10^{-9} \approx 1 \mu\text{s} \quad T_c = 1 \mu\text{s}$$

$$f_c = 900 \text{ MHz} = 9 \cdot 10^8 \Rightarrow T_c = \frac{1}{f_c} \approx 1,11 \text{ ns}$$

Level Crossing and Fading Statistics

- **LCR** - EXPECTED RATE AT WHICH THE RAYLEIGH FADING-ENVELOPE, NORMALIZED TO A LOCAL RMS SIGNAL LEVEL, CROSSES A SPECIFIED LEVEL IN POSITIVE-GOING DIRECTION OF LEVEL CROSSINGS PER SECOND ARE:

$$N_L = \int_0^{\infty} v p(r, v) dv = \sqrt{2\pi} f_m \rho e^{-\rho^2}$$

v - TIME DERIVATIVE OF $r(t)$ (i.e., the slope)

$p(r, v)$ - JOINT DENSITY FUNCTION OF r AND v AT $v=r$

f_m - MAXIMUM DOPPLER FREQUENCY

$\rho = R/R_{rms}$ VALUE OF THE SPECIFIED LEVEL R (NORMALIZED)

Ex. 26 RAYLEIGH FADING SIGNAL LCR=? for $\rho=1$ $f_m=20 \text{ kHz}$

$\sigma_{max}=?$ if $f_c=900 \text{ MHz}$

$$LCR = N_L = \sqrt{2\pi} f_m \rho e^{-\rho^2} = \sqrt{2\pi} \cdot 20 \cdot 1 \cdot e^{-1} = 18,443$$

$$f_m = \frac{\sigma_{max}}{\lambda}$$

$$\sigma_{max} = f_m \lambda = 20 \cdot 0,33 = 6,6 \frac{\text{m}}{\text{s}} = 24 \frac{\text{km}}{\text{h}}$$

- **AVERAGE FADE DURATION** - AVERAGE DURATION OF TIME FOR WHICH RECEIVED SIGNAL IS BELOW SPECIFIED LEVEL R FOR RAYLEIGH FAD.:

$$\tau = \frac{1}{N_L} P_r[V \leq R]$$

$$P_r[V \leq R] = \frac{1}{T} \sum \tau_i$$

$$P_r[V \leq R] = \int_0^R \frac{v}{\sigma} e^{-\frac{v^2}{2\sigma^2}} dv = -e^{-\frac{v^2}{2\sigma^2}} \Big|_0^R = -e^{-\frac{R^2}{2\sigma^2}} + 1 = 1 - e^{-\frac{R^2}{2\sigma^2}}$$

$$P_r[V \leq R] = 1 - e^{-\rho^2}$$

$$\rho = \frac{R}{\sigma} = \frac{R}{\frac{\sigma}{\sqrt{2}}} = \frac{R\sqrt{2}}{\sigma}$$

$$\tau = \frac{1}{\sqrt{2\pi} f_m \rho e^{-\rho^2}} \cdot (1 - e^{-\rho^2}) = \frac{e^{\rho^2} - 1}{\sqrt{2\pi} f_m \rho}$$

Ex. 4.7. $\rho = 0.01$ $\rho = 0.1$ $\rho = 1$ $f_m = 200 \text{ Hz}$

$$\tau = \frac{e^{\rho^2} - 1}{\sqrt{2\pi} f_m \rho}$$

$\rho = 0.01 \quad \bar{\tau} = 1.19 \cdot 10^{-6} = 1.19 \mu\text{s}$
 $\rho = 0.1 \quad \bar{\tau} = 2005 \mu\text{s} = 2005 \cdot 10^{-6}$
 $\rho = 1 \quad \bar{\tau} = 3.5 \text{ ms}$

Ex. 4.8. $\bar{\tau} = ?$ $\rho = 0.707$ $f_m = 20 \text{ Hz}$ binary digital mod. with bit duration 50 bits FAST/SLOW = ?

- Average number of bit errors/sec = ?
 BIT ERROR = FADE $\beta < 0.1$

$$\tau = \frac{\rho^2 - 1}{\sqrt{2\pi} f_m \rho} = 0.0187 = 18 \text{ msec}$$

$$T_s = \frac{1}{50} = 0.02 = 20 \text{ msec}$$

FAST FADING $T_c < T_s$ $T_c = \frac{9}{16\pi f_m} = 2.95 \text{ msec} \approx 3 \text{ msec}$
 $T_s = 20 \text{ msec} > T_c = 3 \text{ msec} \Rightarrow$ FAST FADING

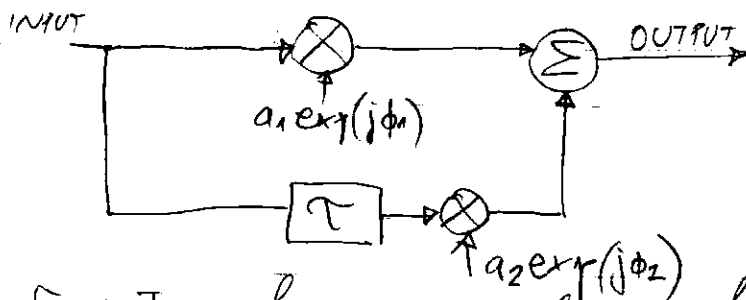
$\rho = 0.1 \Rightarrow \tau_c = 2 \text{ msec}$

$$N_e = \sqrt{2\pi} f_m \rho e^{-\rho^2} = 5.06 \text{ level crossings/sec}$$

$$\text{BER} = N_e / \text{bits} = \frac{5.06}{50 \text{ bits}} = \frac{1}{10} = 0.1 = 10\%$$

TWO-PATH RAYLEIGH FADING MODEL

- Used to model the MULTIPATH DELAY SPREAD



$$h_b(t) = a_1 \exp(j\phi_1) \delta(t) + a_2 \exp(j\phi_2) \delta(t - \tau)$$

SPECIAL CASE: $a_2 = 0$

$$h_b(t) = a_1 \exp(j\phi_1) \delta(t) \quad \text{FLAT RAYLEIGH FADING}$$

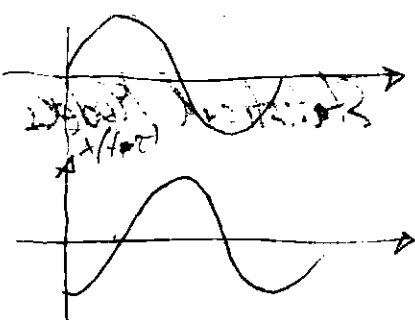
$\tau > T_s$ frequency selective fading
 $\tau \leq T_s$ flat fading

-20 dBW = $10 \log \frac{WGN}{1 \text{ W}}$

-60 dBW \Rightarrow 10^{-6} W

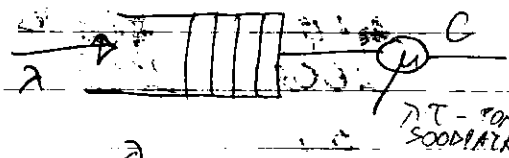
$WGN = 10^{-2} = 0.01 \text{ W} = 10 \text{ mW}$

$WGN = 10^{-6} = 1 \mu\text{W}$



$$\Delta T = \frac{T_{max}}{N-1} = \frac{T_{max}}{2}$$

• exponential distribution of inter-arrival times

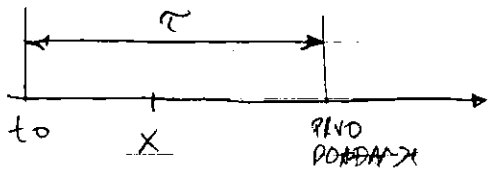


λ - SREDEN BRZ NA POKETI VO 1 SEC
 μ - " " OPSLUZEM VO 1 SEC
 C - KAPACITET NA VASKOTI

$\rho = \frac{\lambda}{\mu}$ INTENZITET NA SODRANAJ

• VELOZATNOSTA PENA VO INTERVALOT, T JE SE SLUCAT K MASTANI E SOLLASIO QUASIDONAVATA VASKOPREDA

$P(k) = \frac{(\lambda T)^k}{k!} e^{-\lambda T}$ $E(k) = \sum_{k=0}^{\infty} k P(k) = \lambda T$



$P(\tau > x) = \frac{(\lambda T)^0}{0!} e^{-\lambda x} = e^{-\lambda x}$
 $P(\tau \leq x) = 1 - e^{-\lambda x}$

• FUNKCIJA NA GUSTINA NA VELOZATNOST

$f(x) = \frac{dP(\tau \leq x)}{dx} = \lambda \cdot e^{-\lambda x}$

MRAB: $f(x|\mu) = \frac{1}{\mu} e^{-\frac{x}{\mu}}$ $f(2|2) = \frac{1}{2} e^{-\frac{2}{2}} = 0.184$
 $f(2|2) = \frac{1}{2} e^{-\frac{2}{2}} = 0.112$

$G(x) = \sum_{i=0}^{\infty} x \cdot f(x) = \sum_{i=0}^{\infty} \frac{x}{\mu} e^{-\frac{x}{\mu}}$ } NE VOCA!!
 LE EXODOT ZA KONTINUVALA DISTRIBUCIJA

$I = \int_0^{\infty} x e^{-\frac{x}{\mu}} dx = \int_0^{\infty} x e^{-\frac{x}{\mu}} dx$
 $u = x$
 $v = \int e^{-\frac{x}{\mu}} dx = -\mu e^{-\frac{x}{\mu}}$
 $I = \frac{1}{\mu} \left(-x \cdot \mu e^{-\frac{x}{\mu}} + \int \mu e^{-\frac{x}{\mu}} dx \right) = \frac{1}{\mu} \left(-\lim_{x \rightarrow \infty} x e^{-\frac{x}{\mu}} + \mu e^{-\frac{x}{\mu}} \right)$
 $I = \frac{1}{\mu} \left(-\mu e^{-\frac{x}{\mu}} \right) = -\mu e^{-\frac{x}{\mu}} \Big|_0^{\infty} = -(0 - \mu e^0) = \mu$

• SRCIM WO SRCIM Indoor & Outdoor Statistical Models

$h_b(t, x_r, s_r, p_r, p_n) = \sum A_i(t, x_r, s_r, p_r, p_n) e^{j\theta_i(t, x_r, s_r, p_r, p_n)} \delta(t - t_i(x_r, s_r, p_r, p_n))$

x_r - receiver spacing
 s_r - topography (LOS or OLOS)
 p_n - PARTICULAR MEASUREMENT LOCATION

$$Y(\omega) = \sum_{k=0}^{N-1} x(k) h(\omega - k) \quad n=0,1,\dots,\infty$$

$$h_b(t, \tau) = \sum_{i=0}^{N-1} a_i(t, \tau) \exp[j(\omega_i \tau + \phi_i(t, \tau))] \delta(\tau - \tau_i(t))$$

$$h_b(\tau) = \sum_{i=0}^{N-1} a_i \exp(-j\omega_i \tau) \cdot \delta(\tau - \tau_i) \quad \text{TIME INVARIANT}$$

PROBABILITIES FOR MULTISTEP APPROXIMATING AT A PARTICULAR EXCESS DELAY

$$P_e(T_i, S_1) = \begin{cases} 1 - \frac{T_i}{367} & T_i < 110 \mu s \\ 0,65 - \frac{T_i - 110}{360} & 110 \mu s < T_i < 200 \mu s \\ 0,22 - \frac{T_i - 200}{1360} & 200 \mu s < T_i < 500 \mu s \end{cases}$$

$$P_e(T_i, S_2) = \begin{cases} 0,55 + \frac{T_i}{667} & T_i < 100 \mu s \\ 0,08 + 0,62 \exp\left(\frac{T_i - 100}{75}\right) & 100 \mu s < T_i < 500 \mu s \end{cases}$$

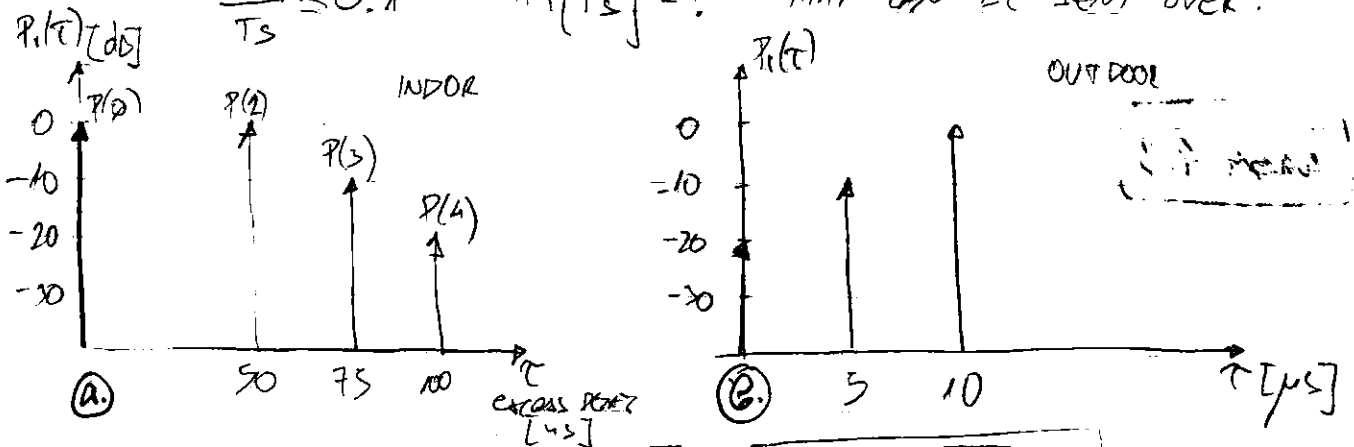
PROBLEM 4.2

SUITABLE BER PERFORMANCE WHENEVER

$$\frac{\bar{\sigma}}{T_s} \leq 0,1$$

$$\min\{T_s\} = ?$$

THAT CAN BE SENT OVER:



$$T_s \geq 10 \bar{\sigma}_\tau$$

$$\bar{\sigma}_\tau = \sqrt{\bar{\tau}^2 - \bar{\tau}^2} = \sqrt{(\tau - \bar{\tau})^2}$$

$$(a) \bar{\tau} = \frac{\sum P_k \tau_k}{\sum P_k}$$

$$0 \text{ dB} = 10 \log \frac{P_k}{1 \text{ W}} \quad P(0) = 10^{\frac{0}{10}} \text{ W} = 1 \text{ W} \quad P(2) = 1 \text{ W}$$

$$P(3) = 10^{-1} = 0,1 \text{ W} \quad P(4) = 10^{-2} = 0,01 \text{ W}$$

$$\bar{\tau} = \frac{0 \cdot 0 + 1 \cdot 50 \cdot 10^{-9} + 0,1 \cdot 75 \cdot 10^{-9} + 0,01 \cdot 10^{-9}}{1 + 1 + 0,1 + 0,01} = \frac{50 \cdot 10^{-9} + 7,5 \cdot 10^{-9} + 0,01 \cdot 10^{-9}}{2,11}$$

$$\bar{\tau} = \frac{57,51 \cdot 10^{-9}}{2,11} = 27,256 \mu s$$

$$\bar{\sigma}_\tau^2 = \frac{(0 - 51,81 \cdot 10^{-9})^2 + [(50 - 51,81) \cdot 10^{-9}]^2 + [(75 - 51,81) \cdot 10^{-9}]^2 + [(100 - 51,81) \cdot 10^{-9}]^2}{4}$$

$$= 0,25 (27 \cdot 10^3 + 3 \cdot 28 + 537,8 + 2,3 \cdot 10^3) \cdot 10^{-18} = 1,385 \cdot 10^{-15}$$

$$\sigma_{\tau} = \sqrt{1,385 \cdot 10^{-15}} = 37,22 \mu\text{s}$$

$$\overline{\tau^2} = \frac{\sum P(v) \tau_c^2}{\sum P(v)} = \frac{0 \cdot 0 + 1 \cdot 50^2 + 0,1 \cdot 75^2 + 0,01 \cdot 100^2}{2,11} \cdot 10^{-12}$$

$$\overline{\tau^2} = 0,17 (2500 + 562,5 + 100) \cdot 10^{-18} = 1,4986 \cdot 10^{-15}$$

$$\sigma_{\tau} = \sqrt{\overline{\tau^2} - \bar{\tau}^2} = \sqrt{1,4986 \cdot 10^{-15} - (27,256 \cdot 10^{-9})^2} = 27,49 \mu\text{s}$$

$$\boxed{\sigma_{\tau} = 27,49 \mu\text{s}}$$

$$\cdot T_s \geq 10 \sigma_{\tau} \quad T_s \geq 275 \cdot 10^{-9} \quad \left[f_s \leq 3,6 \text{ MHz} \right] \quad f_s \leq 3,6 \text{ MHz}$$

$$\textcircled{b} \quad \bar{\tau} = \frac{0,1 \cdot 5 + 1 \cdot 10}{0,01 + 0,1 + 1} = \frac{10,5}{1,11} = 9,46 \mu\text{s}$$

$$\overline{\tau^2} = \frac{0,1 \cdot 25 + 1 \cdot 100}{1,11} = \frac{102,5}{1,11} = 92,34 \mu\text{s}^2$$

$$\sigma_{\tau} = \sqrt{\overline{\tau^2} - \bar{\tau}^2} = \sqrt{92,34 - 9,46^2} = 1,688 \mu\text{s}$$

$$T_s \geq 10 \sigma_{\tau} = 16,88 \mu\text{s} \quad f_s \leq \frac{1}{T_s} = 59,24 \text{ KBps}$$

Problem 4.3 For the power delay profiles from 4.2 estimate 90% coherence and 50% coherence bandwidths

$$\text{COHERENCE} > 0,5 \quad T_c = \frac{9}{16\pi f_m}$$

$$\textcircled{a} \quad |s(t_0)|^2 = \sum_{k=0}^{N-1} a_k(t_0) = 1 + 1 + 0,1 + 0,01 = 2,11 \text{ W}$$

$$B_c = \frac{1}{5T_c} = \frac{1}{5 \cdot 27,49 \cdot 10^{-9}} = 7,28 \text{ MHz} \quad \text{COHERENCE} > 0,5$$

$$B_c = \frac{1}{50T_c} = 0,728 \text{ MHz} \quad \text{COHERENCE} > 0,9$$

$$\textcircled{b} \quad B_c = \frac{1}{5T_c} = \frac{1}{5 \cdot 1,688 \cdot 10^{-6}} = 118 \text{ kHz} \quad \text{COHERENCE} > 0,5$$

$$B_c = \frac{1}{50T_c} = 11,8 \text{ kHz} \quad \text{COHERENCE} > 0,9$$

Problem 4.4 a) $R_B = 25 \text{ KBps}$ BPSK MODULATED SIGNAL
RMS = ?

$$\textcircled{b} \quad 8\text{-PSK} \quad R_B = 75 \text{ KBps}$$

а) $B_{max} = 25 \text{ kHz}$ $T_s = \frac{1}{25 \text{ kHz}} = 40 \mu\text{s}$

$\sigma_r \leq 0.1 T_s$ $\sigma_r \leq 0.1 \cdot 40 \mu\text{s} = 4 \mu\text{s}$

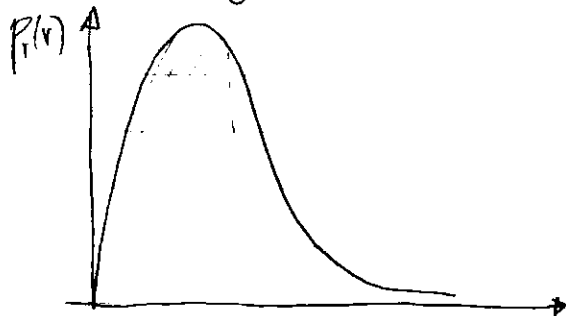
б) $B_{max} = \frac{1}{3} 25 \text{ kHz} = 8.33 \text{ kHz}$

$\sigma_r \leq 0.1 T_s = 0.1 \cdot \frac{1}{8.33 \text{ kHz}} = 0.1 \cdot 120 \mu\text{s} = 12 \mu\text{s}$

Пример 4.5

$f(r) = \frac{1}{\sigma^2} e^{-\frac{r^2}{2\sigma^2}}$

σ^2 - variance; $F(r < R)$



$F(r < R) = \int_0^R f(r) dr$

$F(r < R) = \int_0^R \frac{1}{\sigma^2} e^{-\frac{r^2}{2\sigma^2}} dr$

$m = \frac{r^2}{2\sigma^2}$ $dm = \frac{2r}{2\sigma^2} dr = \frac{r}{\sigma^2} dr$ $r = 0 \rightarrow m = 0$ $r = R \rightarrow m = \frac{R^2}{2\sigma^2}$

$\int_0^{\frac{R^2}{2\sigma^2}} e^{-m} dm = -e^{-m} \Big|_0^{\frac{R^2}{2\sigma^2}} = -\left(e^{-\frac{R^2}{2\sigma^2}} - 1\right) = 1 - e^{-\frac{R^2}{2\sigma^2}}$

~~$10 \text{ dB} = 20 \log R$~~ ~~$R = 10^{\frac{1}{2}} = \sqrt{10} = 3.16$~~

$-10 \text{ dB} = 10 \log \frac{R^2}{2\sigma^2}$ $\frac{R}{\sigma} = 10^{-\frac{1}{2}} = 0.316$

$F\left(\frac{R}{\sigma} < 0.316\right) = 1 - e^{-\frac{(0.316)^2}{2}} = 1 - e^{-0.1} = 1 - 0.904 = 0.095 = 9.5\%$

процент на параметр во вре сирот ле аде -10 dB помал од σ е 9.5%

Пример 4.6

$LCR = \sqrt{2\pi} f_m \rho e^{-\rho^2}$ $f_m = \frac{v}{\lambda} = \frac{13.8}{0.333} = 41.67$

а) $\frac{d LCR}{d \rho} = 0$ $\frac{d}{d \rho} (\sqrt{2\pi} f_m \rho e^{-\rho^2}) = \sqrt{2\pi} \frac{d}{d \rho} (\rho e^{-\rho^2}) =$

$= \rho' e^{-\rho^2} + \rho \cdot (e^{-\rho^2})' = e^{-\rho^2} + \rho e^{-\rho^2} (-2\rho) = e^{-\rho^2} - 2\rho^2 e^{-\rho^2} = 0$

б) $\sigma = 50 \text{ km/h} = 13.8 \text{ m/s}$ $f_c = 900 \text{ MHz}$ $T_c = \frac{1}{f_c} = 1.11 \text{ ns}$
 $LCR = \sqrt{2\pi} f_m \rho e^{-\rho^2} = \sqrt{2\pi} \cdot 41.67 \cdot 0.707 e^{-0.707^2} = 44.8 \text{ crossing/s} = 267 \text{ crossing/}\mu\text{s}$

c) $\rho = 0,707$ $\tau = \frac{e^{\rho^2} - 1}{\sqrt{2\pi} f_m \rho} = \frac{e^{\frac{1}{2}} - 1}{\sqrt{2\pi} 41,67 \cdot 0,707} = 8,8 \text{ us}$

PROBLEM 4.7

$f_c = 900 \text{ MHz}$; $v = 10 \text{ s}$; $\tau_{\text{fade}} = 1 \text{ ms}$

- $d = ?$ for 10s interval?

- LCR = ? AT RMS THRESHOLD LEVEL DURING 10s

• $10 \log \rho = -10 \text{ dB}$ $\rho = 10^{-1} = 0,1$

$10^{-3} = \frac{e^{0,01} - 1}{\sqrt{2\pi} f_m \cdot 0,1}$ $f_m = \frac{e^{0,01} - 1}{\sqrt{2\pi} \cdot 10^{-3}} = 4 \cdot 10^3 \cdot 10 = 4 \cdot 10^4 = 40 \text{ kHz}$

$f_m = \frac{v}{\lambda}$ $v = f_m \lambda = 40 \cdot \frac{1}{3} = 133 \frac{\text{m}}{\text{s}} = 48 \frac{\text{km}}{\text{h}}$
 $d = v \cdot t = 133 \text{ m}$

• LCR = $\sqrt{2\pi} f_m \rho e^{-\rho^2} = \sqrt{2\pi} \cdot 40 \cdot 0,1 \cdot e^{-0,01} = 9,93 \frac{\text{cross}}{\text{sec}}$
 $T = 10 \text{ s}$ LCR/10s = 99,3 cross / 10 sec. } $\rho = 0,1$

$\rho = 1$ LCR = $\sqrt{2\pi} f_m \rho e^{-1} = \sqrt{2\pi} \cdot 40 \cdot 0,1 \cdot e^{-1} = 3,7 \frac{\text{cross}}{\text{sec}}$

▶ SELAK NB TERATA PA SE-TRATERA KAND SIKSA TUKU KAND NIKU

$\rho = \sqrt{\text{RMS}}$ ROOT MEAN SQUARE !!!

• $10 \log \rho = -10 \text{ dB}$ $\rho = 10^{-\frac{1}{2}} = \frac{1}{\sqrt{10}} = 0,316$

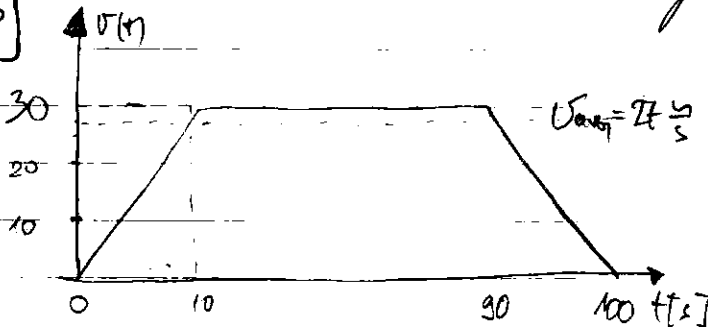
$f_m = \frac{e^{0,1} - 1}{\sqrt{2\pi} \cdot 0,316 \cdot 10^{-3}} = 0,133 \cdot 10^3 = 133 \text{ Hz}$ $f_m = \frac{v}{\lambda}$

$v = f_m \cdot \lambda = \frac{133}{3} = 443 \frac{\text{m}}{\text{sec}} = 160 \frac{\text{km}}{\text{sec}}$ $d = v \cdot 10 \text{ s} = 443 \text{ m}$

• $\rho = 1$ LCR = $\sqrt{2\pi} \cdot 133 \cdot 1 \cdot e^{-1} = 122,6 \frac{\text{cross}}{\text{sec}}$

10s : LCR $\cdot 10 \text{ sec} = 1226 \text{ crossings}$

PROBLEM 4.8



$f_c = 900 \text{ MHz}$, $\rho = 0,1$
 LCR = ?
 FADE DURATION $\tau = ?$ } 100s PERIOD

$LCR = \sqrt{2\pi} f_m \rho e^{-\rho^2}$

$f_m = \frac{v}{\lambda}$

$t = 0 \dots 10 \text{ s}$ $v = 3t$

$t = 10 \dots 90 \text{ s}$ $v = 30 \frac{\text{m}}{\text{s}}$

$t = 90 \dots 100$ $v = 3(x - 100) = -3t + 300$

$U_{\text{avg}} = \frac{1}{b-a} \int_a^b v(t) dt = \frac{1}{100} \left[\int_0^{10} 3t dt + \int_{10}^{90} 30 dt + \int_{90}^{100} (-3t + 300) dt \right]$

$$V_{avg} = \frac{1}{100} \left[3 \frac{t^2}{2} \Big|_0^{10} + 30(90-10) + \left(-\frac{3t^2}{2} + 300t \right) \Big|_{90}^{100} \right] =$$

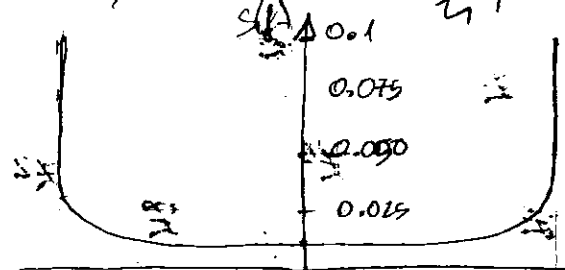
$$= \frac{1}{100} \left[3 \left(\frac{100^2}{2} - 0 \right) + 2400 - \frac{3}{2} (10^2 - 8100) + 300(10) \right] =$$

$$= \frac{1}{100} (150 + 2400 - 2850 + 3000) = \frac{2700}{100} = \underline{\underline{27 \frac{m}{s}}}$$

$$N_c = 20,101 \frac{\text{cross}}{\text{sec}} \approx 2010 \frac{\text{crossings}}{\text{sec}}$$

$$e^{-2} = 0.1353 \Rightarrow \tau = \frac{1}{2010} = 497.5 \mu s \approx \underline{\underline{495 \mu s}}$$

Problem 4.9: $f_c = 860 \text{ MHz}$ $\lambda = \frac{300}{860} = 0.35 \text{ m}$
 $f_m = \frac{v}{\lambda} = \frac{100 \text{ km}}{0.35} = 27,78 \text{ kHz}$ $f_m = 79,36 \approx 80 \text{ kHz}$



$$S(f) = \frac{1.5 \times 10^{-6}}{\pi f \sqrt{1 - \left(\frac{f - f_c}{f_m} \right)^2}}$$

$$860 \text{ MHz} - 80 \text{ kHz} \quad 860 \text{ MHz} \quad 860 \text{ MHz} + 80 \text{ kHz} \quad [\text{Hz}]$$

$$P_{bb} = -20 \text{ dB} = 10 \log P \Rightarrow P = 10^{-2} = 0.01$$

$$N_c = \frac{1}{\tau} \int P e^{-\tau|f-f_c|} df = 19.85 \frac{\text{cross}}{\text{sec}} \quad \tau = \frac{1}{19.85} = 50.4 \times 10^{-6} \text{ sec}$$

Problem 4.10

MAXIMUM RMS DELAY SPREAD = ?

SYSTEM	RF DATA RATE	MODULATION	SPECTRAL EFFICIENCY
1 USDC	48.6 kbps	1/4 DQPSK	2.65 / Hz
2 GSM	170.833 kbps	0.3 GMSK	3.33 / Hz
3 PECT	1152 kbps	0.3 GMSK	3.33 / Hz

$$T_s \geq 105 \tau \quad T_{s1} = \frac{2}{48.6 \cdot 10^3} = 4.115 \cdot 10^{-6} = 4.115 \mu \text{sec}$$

$$\tau_{e1} \leq 4.115 \mu \text{sec}$$

$$T_{s2} = \frac{1}{0.3 \cdot 270.833 \cdot 10^3} = 12.38 \mu \text{sec} \quad \tau_{e2} \leq 12.38 \mu \text{sec}$$

$$T_{s3} = \frac{1}{0.3 \cdot 1152 \cdot 10^3} = 2.89 \mu \text{sec} \quad \tau_{e3} \leq 2.89 \mu \text{sec}$$

Prob 4.11 RF Doppler Spectrum = ?

$$f_m = \frac{v}{\lambda}$$

$\frac{5}{8} \lambda$ VERTICAL MONODER

$$S(f) = \frac{1.75 \times 10^{-6}}{\pi f_m \sqrt{1 - \left(\frac{f - f_c}{f_m} \right)^2}} \quad S_{sub}(f) = \frac{1}{80 f_m} K \left[\sqrt{1 - \left(\frac{f - f_c}{2 f_m} \right)^2} \right]$$

5/8 lambda VERTICAL MONODER (K) = 4.75
 FIRST KIND
 BUNTIKAL INTEGRAL OF FIRST KIND

4.12

SHOW THAT THE MAGNITUDE OF THE SUM OF TWO INDEPENDENT IDENTICALLY DISTRIBUTED COMPLEX (QUADRATURE) GAUSSIAN SOURCES IS RAYLEIGH DISTRIBUTED

$$f_{X,Y}(x,y) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{x^2}{2\sigma^2}} \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{y^2}{2\sigma^2}}$$

X, Y - TWO INDEPENDENT, ZERO MEAN, GAUSSIAN RANDOM VARIABLES WITH EQUAL VARIANCE σ^2

$$f_{X,Y}(x,y) = \frac{1}{2\pi\sigma^2} e^{-\frac{x^2+y^2}{2\sigma^2}}$$

$$\begin{aligned} x &= z \cos \phi & x^2 + y^2 &= z^2 \\ y &= z \sin \phi & \phi &= \arctan \frac{y}{x} \end{aligned}$$

$$|J| = \begin{vmatrix} \frac{\partial x}{\partial z} & \frac{\partial x}{\partial \phi} \\ \frac{\partial y}{\partial z} & \frac{\partial y}{\partial \phi} \end{vmatrix} = \begin{vmatrix} \cos \phi & -z \sin \phi \\ \sin \phi & z \cos \phi \end{vmatrix} = z \cos^2 \phi + z \sin^2 \phi = z$$

$$f_{z,\phi}(z,\phi) = |J| \cdot f_{X,Y}(x,y) = \frac{z}{2\pi\sigma^2} e^{-\frac{z^2}{2\sigma^2}}$$

$$f_z(z) = \int_0^{2\pi} f_{z,\phi}(z,\phi) d\phi = \int_0^{2\pi} \frac{z}{2\pi\sigma^2} e^{-\frac{z^2}{2\sigma^2}} d\phi = \frac{z}{\sigma^2} e^{-\frac{z^2}{2\sigma^2}}$$

z - REPRESENTS MAGNITUDE (ENVELOPE) OF THE SUM OF TWO INDEPENDENT IDENTICALLY DISTRIBUTED COMPLEX (QUADRATURE) GAUSSIAN SOURCES

$$F_z(z) = \int_{-\infty}^z p_z(x) dx$$

$$p_z(x) = \frac{dF_z(x)}{dx}$$

ALTERNATIVELY: $F_z(z) = \iint_{x^2+y^2 \leq z^2} f_{X,Y}(x,y) dx dy =$

$$= \int_0^{2\pi} \int_0^z \frac{1}{2\pi\sigma^2} e^{-\frac{r^2}{2\sigma^2}} r dr d\phi = \frac{1}{\sigma^2} \int_0^z r e^{-\frac{r^2}{2\sigma^2}} dr$$

$$= \int_0^z e^{-\frac{r^2}{2\sigma^2}} \frac{r}{\sigma^2} dr = \int_0^z e^{-u} du = -e^{-u} \Big|_0^z = 1 - e^{-\frac{z^2}{2\sigma^2}}$$

$$f_z(z) = \frac{dF_z(z)}{dz} = + e^{-\frac{z^2}{2\sigma^2}} \frac{z}{\sigma^2} = \frac{z}{\sigma^2} e^{-\frac{z^2}{2\sigma^2}} \quad z \geq 0$$

COMPLEX GO SAJA ZA SINUSOM SO QUADRATURE ŽE TO, HICE DA SE RAZLOŽI NA VEKTORE KAKO: $z = x + jy = v \cdot e^{j\phi}$
 ŽE TO ŽIVOTAJA ŽENA I NAPOKAR KUŽATI !!!

Pr. 4.13 GENERATE TIME SEQUENCE OF 2192 SAMPLE VALUES OF RAYLEIGH FADING SIGNAL FOR:

(a) $f_m = 20\text{Hz}$ (b) $f_m = 200\text{Hz}$

$$\Delta f = \frac{2f_m}{N-1} = 4\text{kHz} \quad T = \frac{1}{\Delta f} = 20\mu\text{s}$$

Pr. 4.14 GENERATE 100 sample functions based on Pr 4.13 AND COMPUTE THEORETICAL & SIMULATED VALUES FOR

R_{RMS} , N_R , and $\bar{\tau}$ for $\rho = 1, 0.1, 0.01$

$$N_R = \sqrt{2\pi} f_m \rho e^{-\rho^2} \quad \bar{\tau} = \frac{e^{-\rho^2} - 1}{12\pi f_m \rho}$$

(a) $f_m = 20\text{Hz}$

$\rho = 1 \quad N_R = 18.44 \quad \bar{\tau} = 3.4\text{msec}$

$\rho = 0.1 \quad N_R = 4.96 \quad \bar{\tau} = 2\text{msec}$

$\rho = 0.01 \quad N_R = 0.5 \quad \bar{\tau} = 0.2\text{msec}$

$$\rho = \frac{R}{R_{RMS}}$$

(b) $f_m = 200\text{Hz}$

$\rho = 1 \quad N_R = 184.4 \quad \bar{\tau} = 3.4\text{msec}$

$\rho = 0.1 \quad N_R = 49.6 \quad \bar{\tau} = 0.2\text{msec}$

$\rho = 0.01 \quad N_R = 5.01 \quad \bar{\tau} = 0.02\text{msec}$

ufs - example 3. m

$\Delta t = 0.111 \cdot 10^{-9} \quad N = 1000 \quad \Delta t > \tau$

$$\Delta f = \frac{2f_m}{N-1} = \frac{2 \cdot 100}{1000-1} = 0.2\text{Hz}$$

$$\Delta t_{1000} = \frac{1}{f_s} = \frac{\Delta t}{N} = \frac{1}{N \cdot \Delta f} = \underline{5 \cdot 10^{-3}}$$

$$\rho = \frac{1}{\sqrt{2}} = 0.707 \quad \frac{R}{R_{RMS}} = 0.707 \quad 20 \log \frac{R}{R_{RMS}} = -3\text{dB}$$

SIMULATION OF FADING USING MATLAB FOR CLASSROOM INSTRUCTIONS

ufs - example 4

$f_m = 200\text{Hz}$

$T_c = \frac{9}{16\pi f_m} = 1.8\text{ms}$

$T_s = 11.1\text{ms}$

$T_s \ll T_c \Rightarrow$ SLOW FADING

ufs - fast fading

$T_c = 1.8\text{ms}$

$T_s = 11.1\text{ms}$

$T_s > T_c \Rightarrow$ FAST FAD

LQR FROM GOLDSMITH

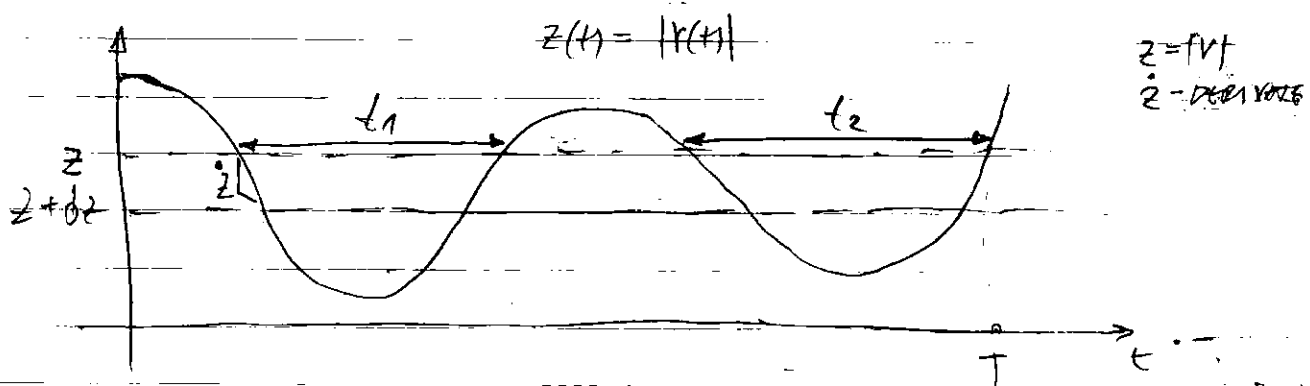
$z = |r| \quad \dot{z}, P(z, \dot{z})$

\hookrightarrow SIGNAL ENVELOPE

L_z

$\dot{z} \rightarrow$ DERIVATIVE OF SIGNAL ENVELOPE

$q(z, \dot{z})$ JOINT DISTRIBUTION



EXPECTED AMOUNT OF TIME THAT SIGNAL ENVELOPE SPENDS IN INTERVAL z TO $z + dz$ WITH ENVELOPE SLOPE WITHIN RANGE $[\dot{z}, \dot{z} + d\dot{z}]$ OVER THE DURATION dt IS:

$$A = p(z, \dot{z}) dz d\dot{z} dt$$

TIME TO CROSS FROM z TO $z + dz$ ONCE FOR GIVEN ENVELOPE SLOPE \dot{z} IS:

$$B = \frac{dz}{\dot{z}}$$

EXPECTED CROSSINGS OF THE ENVELOPE z WITHIN INTERVAL $(z, z + dz)$ FOR A GIVEN ENVELOPE SLOPE \dot{z} OVER dt IS:

$$\frac{A}{B} = \frac{p(z, \dot{z}) dz d\dot{z} dt}{\frac{dz}{\dot{z}}} = \dot{z} p(z, \dot{z}) d\dot{z} dt$$

• THE EXPECTED NUMBER OF CROSSINGS OF ENVELOPE LEVEL z FOR SLOPES BETWEEN $\dot{z} \div \dot{z} + d\dot{z}$ IN INTERVAL $[0, T]$ IN DOWNWARD DIRECTION IS:

$$\int_0^T \dot{z} p(z, \dot{z}) d\dot{z} dt = \dot{z} p(z, \dot{z}) d\dot{z} T$$

$$N_z = T \int_0^{\infty} \dot{z} p(z, \dot{z}) d\dot{z} \quad \left. \begin{array}{l} \text{EXPECTED CROSSINGS OF ENVELOPE} \\ z \text{ WITH NEGATIVE SLOPE OVER} \\ \text{INTERVAL } [0, T] \end{array} \right\}$$

$$L_z = \frac{N_z}{T} = \int_0^{\infty} \dot{z} p(z, \dot{z}) d\dot{z} \quad \left. \begin{array}{l} \text{LEVEL CROSSING RATE} \end{array} \right\}$$

$$L_z = \sqrt{2\pi(k+1)} \int_0^{\infty} p e^{-k - (k+1)p^2} I_0(2p \sqrt{k(k+1)}) dp$$

↑ FOR RICEAN FADING

FOR RAYLEIGH FADING $k=0$

$$L_z = \sqrt{2\pi} \int_0^{\infty} p e^{-p^2} dp$$

AVERAGE ENVELOPE LEVEL

• AVERAGE FADE DURATION

$$\bar{t}_z = \frac{1}{L_z} \sum_i t_i = \frac{P(z(t) < z)}{L_z}$$

$$\bar{t}_z = \frac{1}{L_z} \sum_i t_i = \frac{P(z(t) < z)}{L_z}$$

$$\bar{t}_z = \frac{e^{p^2} - 1}{p \sqrt{2\pi}}$$

SIMULATION OF PEPING USING MATLAB FOR CLASSROOM INSTRUCTION

$$s(t) = \sum_{i=1}^N a_i \cos(\omega_i t + \phi_i) \quad \text{v.o.t.} \quad P_0(\theta) = \frac{1}{2\pi} \quad \theta=0 \quad \pi$$

$$\Delta \phi_D = \frac{2\pi \Delta S}{\lambda} = \frac{2\pi d \cos \alpha}{\lambda} = \frac{2\pi d}{\lambda} \cos \alpha \quad \omega_D = \frac{\phi_D}{\Delta t} = \frac{2\pi v \cos \alpha}{\lambda}$$

$$f_D = \frac{\omega_D}{2\pi} = \frac{1}{2\pi} \frac{2\pi v}{\lambda} \cos \alpha = \frac{v}{\lambda} \cos \alpha$$

$$P(x, \lambda) = \frac{e^{-\lambda} \lambda^k}{k!} = \frac{e^{-\lambda} \lambda^k}{k!} \quad \lambda = \frac{v}{c}$$

$$\omega_{di} = \frac{\omega_c v}{c} \cos \psi_i \rightarrow \text{ANGLE OF ARRIVAL}$$

$$\omega_c = 2\pi f_c \quad \omega_{di} = 2\pi f_d \quad f_{di} = \frac{f_c v}{c} \cos \psi_i$$

$$v = d \omega \Delta t \quad \phi_D = \frac{2\pi \Delta S}{\lambda} = \frac{2\pi \Delta S \cos \psi_i}{\lambda}$$

$$\omega_{di} = \frac{\phi_{di}}{\Delta t} = \frac{2\pi d \cos \psi_i}{\Delta t \lambda} = \frac{2\pi v \cos \psi_i}{\Delta t \lambda}$$

$$f_{di} = \frac{\omega_{di}}{2\pi} = \frac{v}{\lambda} \cos \psi_i \quad f_{di} = \frac{\frac{v}{\lambda} v}{v} \cos \psi_i = \frac{v}{\lambda} \cos \psi_i$$

$$s(t) = \sum_{i=1}^N a_i \cos(\omega_c t + \omega_{di} t + \phi_i) \quad \text{DOPPLER MULTIPATH}$$

$$s(t) = \sum_{i=1}^N a_i \cos \omega_c t \cos(\omega_{di} t + \phi_i) - \sum_{i=1}^N a_i \sin \omega_c t \sin(\omega_{di} t + \phi_i)$$

$$s(t) = \left(\sum_{i=1}^N a_i \cos(\omega_{di} t + \phi_i) \right) \cos(\omega_c t) - \left(\sum_{i=1}^N a_i \sin(\omega_{di} t + \phi_i) \right) \sin(\omega_c t)$$

$$I(t) = \sum_{i=1}^N a_i \cos(\omega_{di} t + \phi_i) \quad \text{I(t) - in-phase} \quad Q(t) = \sum_{i=1}^N a_i \sin(\omega_{di} t + \phi_i) \quad \text{Q(t) - quadrature}$$

$$R = \sqrt{I^2(t) + Q^2(t)} \quad f(r) = \frac{r}{\sigma^2} \exp\left(-\frac{r^2}{2\sigma^2}\right) \quad \text{PDF FOR RCF}$$

I(t) & Q(t) ARE DISTRIBUTED NORMALLY WHEN N IS LARGE

$$f_c = 900 \text{ MHz} \quad \lambda = \frac{c}{f} = \frac{300}{900} = 0.33 \quad c = \lambda f_c = \frac{\lambda}{T_c}$$

$$T_c = \frac{1}{f_c} = \frac{1}{9 \cdot 10^8} = \frac{1}{9} \cdot 10^{-9} = 1.11 \cdot 10^{-9} = 1.11 \text{ nsec}$$

1250 WAVELENGTHS : 1250 = T_c = 1.1 nsec

a_i - Weibull distributed

$$f(x, \kappa, \lambda) = \frac{\kappa}{\lambda} \left(\frac{x}{\lambda}\right)^{\kappa-1} e^{-\left(\frac{x}{\lambda}\right)^\kappa} \quad x > 0$$

$\kappa > 0$ - shape parameter $\lambda > 0$ - scale parameter

COMPLEMENTARY CUMULATIVE DISTRIBUTION IS SKETCHED ATTACHED

vešbrnd; unšbrnd; demod

$$e^{j\omega t} = \cos \omega t + j \sin \omega t$$

$$e^{-j\omega t} = \cos \omega t - j \sin \omega t$$

OTK MODULACII

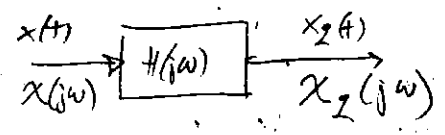
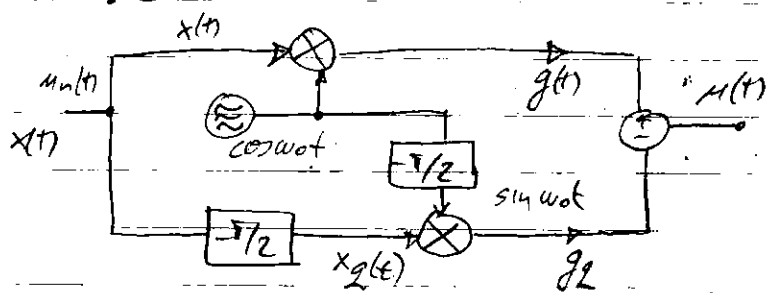
• KAH SIGNAL

$$u(t) = U_0 \cos \omega_0 t + k u_m(t) \cos \omega_0 t = [U_0 + k u_m(t)] \cos \omega_0 t$$

$$u(t) = U_0 \left[1 + \frac{k u_m(t)}{U_0} \right] \cos \omega_0 t \quad u_m(t) = \frac{u_m(t)}{U_0}$$

AMPLITUDA NA MODULIRANOT SIGNAL ST MERNA: $U_0 + k u_m(t)$; $U_0 + k u_m(t)$

• AMISO

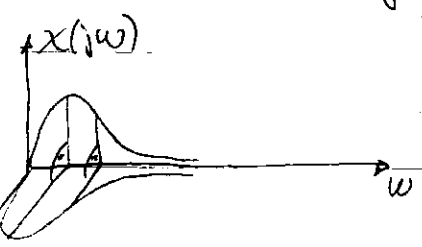


$$g(t) = x(t) \cdot \cos(\omega_0 t)$$

$$G(j\omega) = \frac{1}{2} X[j(\omega - \omega_0)] + \frac{1}{2} X[j(\omega + \omega_0)]$$

$$x_2(t) \rightarrow X_2(j\omega)$$

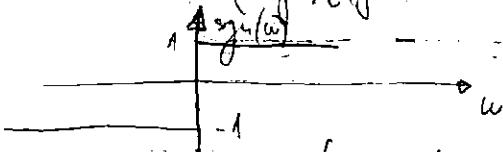
$$H(j\omega) = \begin{cases} 1 \cdot e^{j\frac{\omega}{2}} = j & \omega > 0 \\ 1 \cdot e^{j\frac{\omega}{2}} = j & \omega < 0 \end{cases}$$



$f(t) = \sin(\omega_0 t) = \cos(\omega_0 t - \frac{\pi}{2})$
 $F(j\omega) = \mathcal{F}[\cos(\omega_0 t - \frac{\pi}{2})]$
 $= \mathcal{F}[f(\omega_0 t - \frac{\pi}{2})] = G(j\omega) \cdot e^{-j\frac{\pi}{2}}$
 $G(j\omega) = \mathcal{F}\{\cos(\omega_0 t)\}$
 $G(j\omega) = \mathcal{F}[\frac{1}{2} e^{j\omega_0 t} + \frac{1}{2} e^{-j\omega_0 t}] = \frac{2\pi}{2} \delta(\omega - \omega_0) + \frac{2\pi}{2} \delta(\omega + \omega_0)$
 $\mathcal{F}\{f(t) \cdot e^{j\omega_0 t}\} = \mathcal{F}[f(\omega + \omega_0)]$
 $\mathcal{F}\{e^{-j\omega_0 t}\} = 2\pi \delta(\omega - \omega_0)$
 $\mathcal{F}\{\sin \omega_0 t\} = \frac{1}{j} [\pi \delta(\omega - \omega_0) + \pi \delta(\omega + \omega_0)] \cdot e^{-j\frac{\pi}{2}} = -j\pi \delta(\omega - \omega_0) - j\pi \delta(\omega + \omega_0)$
 $\mathcal{F}\{k\} = \int_{-\infty}^{\infty} k \cdot e^{j\omega t} dt = \delta(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{j\omega t} d\omega$
 $\delta(\omega) = -\frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-j\omega t} dt$
 $\int_{-\infty}^{\infty} e^{-j\omega t} d\omega = 2\pi \delta(t)$
 $\mathcal{F}\{k\} = k \int_{-\infty}^{\infty} e^{-j\omega t} dt = 2k\pi \delta(\omega)$
 $\mathcal{F}\{\sin \omega_0 t\} = \frac{1}{2j} \mathcal{F}\{e^{-j\omega_0 t} - e^{j\omega_0 t}\} = \frac{1}{2j} [2\pi \delta(\omega - \omega_0) - 2\pi \delta(\omega + \omega_0)]$
 $= -\pi j \delta(\omega - \omega_0) + \pi j \delta(\omega + \omega_0)$

$$X_g(j\omega) = \begin{cases} -jX(j\omega) & \omega > 0 \\ jX(j\omega) & \omega < 0 \end{cases}$$

$$X_g(j\omega) = -j \operatorname{sgn}(\omega) \cdot X(j\omega)$$



$$g_2(t) = x_2(t) \cdot \sin(\omega_0 t)$$

$$G_2(j\omega) = \mathcal{F} \left\{ x_2(t) \cdot \frac{1}{2} (e^{j\omega_0 t} - e^{-j\omega_0 t}) \right\} = \frac{1}{2} X[j(\omega - \omega_0)] - \frac{1}{2} X[j(\omega + \omega_0)]$$

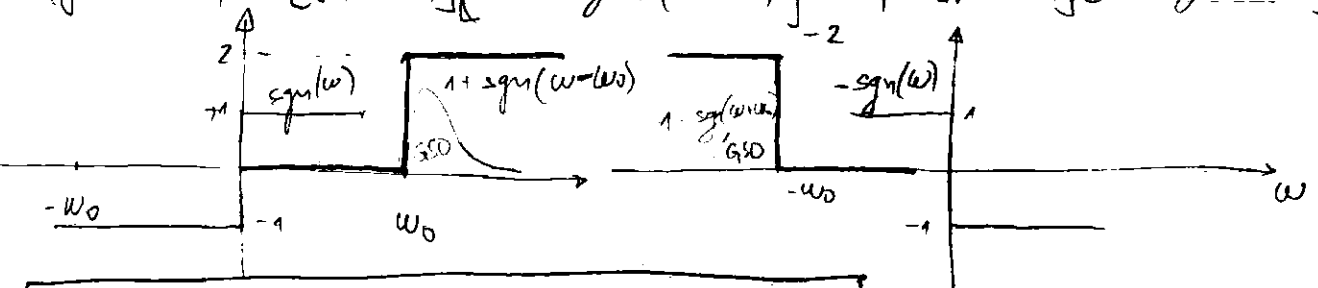
$$G_2(j\omega) = -\frac{1}{2} X(j(\omega - \omega_0)) \operatorname{sgn}(\omega - \omega_0) + \frac{1}{2} X(\omega + \omega_0) \operatorname{sgn}(\omega + \omega_0)$$

$$u(t) = \frac{1}{2} g(t) + \frac{1}{2} g_2(t) = \frac{1}{2} x(t) \cos(\omega_0 t) + \frac{1}{2} x_2(t) \sin(\omega_0 t)$$

$$U(j\omega) = \frac{1}{2} G(j\omega) + \frac{1}{2} G_2(j\omega) = \frac{1}{4} X[j(\omega - \omega_0)] + \frac{1}{4} X[j(\omega + \omega_0)] +$$

$$\left\{ \frac{1}{4} X(\omega + \omega_0) \operatorname{sgn}(\omega + \omega_0) - \frac{1}{4} X[j(\omega - \omega_0)] \operatorname{sgn}(\omega - \omega_0) \right\}$$

$$U(j\omega) = \frac{1}{4} X[j(\omega - \omega_0)] [1 \oplus \operatorname{sgn}(\omega - \omega_0)] + \frac{1}{4} X[j(\omega + \omega_0)] [1 \oplus \operatorname{sgn}(\omega + \omega_0)]$$



$$u(t) = \frac{1}{2} x(t) \cos(\omega_0 t) + \frac{1}{2} x_2(t) \sin(\omega_0 t)$$

$$x_2(t) = ? \quad x(t) \xrightarrow{-j \operatorname{sgn}(\omega)} x_2(t)$$

$$x_2(t) = \int_{-\infty}^{\infty} x(\tau) \cdot h(t - \tau) d\tau$$

$$h(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} -j \operatorname{sgn}(\omega) e^{j\omega t} d\omega =$$

$$= \frac{1}{2\pi} \left[-j \int_{-\infty}^0 e^{j\omega t} d\omega - j \int_0^{\infty} e^{j\omega t} d\omega \right] = \frac{1}{2\pi} \left[\int_{-\infty}^0 e^{j\omega t} d\omega - \int_0^{\infty} e^{j\omega t} d\omega \right]$$

$$\mathcal{F} \{ \operatorname{sgn}(t) \} = \int_{-\infty}^{\infty} \operatorname{sgn}(t) e^{-j\omega t} dt = -\int_{-\infty}^0 e^{-j\omega t} dt + \int_0^{\infty} e^{-j\omega t} dt = \frac{2}{j\omega}$$

$$\left. \begin{matrix} \omega \rightarrow t \\ t \rightarrow -\omega \end{matrix} \right\} \mathcal{F} \{ \operatorname{sgn}(\omega) \} = + \int_{-\infty}^0 e^{j\omega t} d\omega + \int_0^{\infty} e^{j\omega t} d\omega = \int_{-\infty}^0 e^{j\omega t} d\omega - \int_0^{\infty} e^{j\omega t} d\omega$$

$$= - \int_0^{\infty} e^{j\omega t} d\omega + \int_{-\infty}^0 e^{j\omega t} d\omega = \int_{-\infty}^0 e^{j\omega t} d\omega - \int_0^{\infty} e^{j\omega t} d\omega = \textcircled{*} = \frac{2}{jt}$$

$$h(t) = \frac{j}{2\pi} \cdot \textcircled{*} = \frac{j}{2\pi} \cdot \frac{2}{jt} = \frac{1}{\pi t} \quad h(t - \tau) = \frac{1}{\pi(t - \tau)}$$

$$x_2(t) = \int_{-\infty}^{\infty} \frac{x(\tau)}{\pi(t - \tau)} d\tau = \frac{1}{\pi} \int_{-\infty}^{\infty} \frac{x(\tau)}{t - \tau} d\tau = \widehat{x}(t) \quad \text{Hilbert transform}$$

HILBERT TRANSFORM:

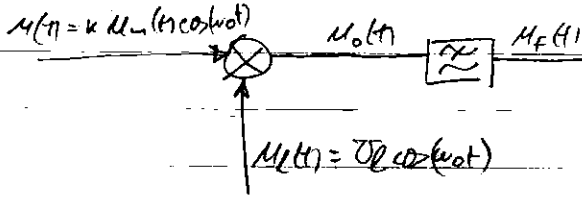
$$F(s) = \frac{1}{\pi} \int_a^{\infty} \frac{f(t)}{t-s} dt$$

AMPSO

$$u(t) = \frac{1}{2} \times [u \cos(\omega_0 t) + \hat{u}(t) \sin(\omega_0 t)] = k M_m(t) \cos(\omega_0 t) + k \hat{M}_m(t) \sin(\omega_0 t)$$

3. DEMODULACIJA NA AMPSO

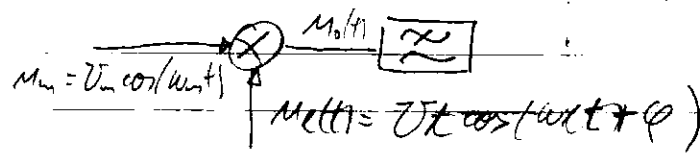
SINTIČNA DEMODULACIJA NA AMPSO



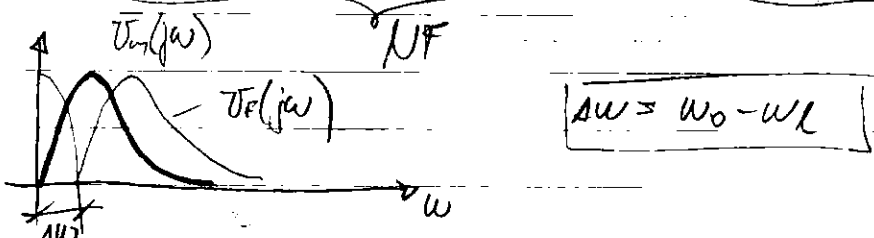
$$M_0(t) = k M_m(t) \cos(\omega_0 t) \cdot U_L \cos(\omega_0 t) = k M_m(t) \cdot U_L \left[\frac{1}{2} \cos[(\omega_0 - \omega_0)t] + \frac{1}{2} \cos[(\omega_0 + \omega_0)t] \right]$$

$$= \frac{k}{2} M_m(t) \cdot U_L + \frac{k}{2} M_m(t) \cdot U_L \cdot \cos[2\omega_0 t]$$

• Ako nosilac nije se svodi u signal



$$M_0(t) = \frac{k}{2} M_m(t) \cdot U_L \cos[(\omega_0 - \omega_0)t - \varphi] + \frac{k}{2} M_m(t) \cdot U_L \cos[(\omega_0 + \omega_0)t + \varphi]$$



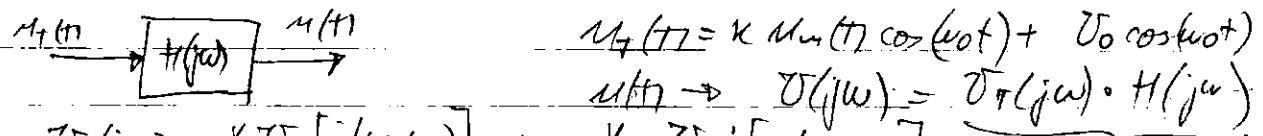
AMPSO
$$u(t) = \frac{1}{2} M_m(t) \cos(\omega_0 t) + \frac{1}{2} \hat{M}_m(t) \sin(\omega_0 t)$$

SINTIČNA DEMODULACIJA:
$$M_F(t) = M(t) \cdot U_L \cos(\omega_0 t)$$

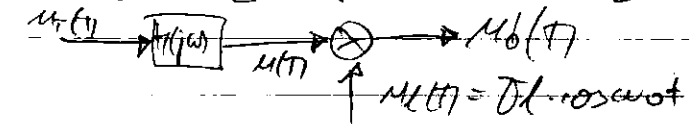
$\Delta \omega = 0 \Rightarrow M_F(t) = \frac{1}{4} U_L M_m(t) \cos \varphi + \frac{1}{4} U_L \hat{M}_m(t) \sin \varphi$

$\varphi = 0 \Rightarrow M_F(t) = \frac{1}{4} U_L M_m(t) \cos \varphi = k M_m(t)$

SINTIČNA DEMODULACIJA NA AMPSO



$$U_F(j\omega) = \frac{k}{2} U_m [j(\omega - \omega_0)] + \frac{k}{2} U_m [j(\omega + \omega_0)]$$



$$U_0(j\omega) = \frac{U_L}{2} U [j(\omega - \omega_0)] + \frac{U_L}{2} U [j(\omega + \omega_0)]$$

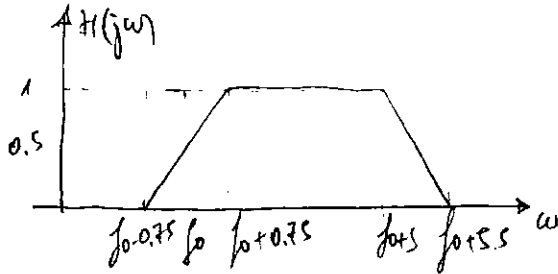
NE GO OPERIRATI SA NEGATIVNIM FREKVENCIJAMA !!

$$U_d(j\omega) = \frac{\sigma_L}{2} U_T(j\omega)_{\omega_0} + \frac{\sigma_L}{2} U_T(j(\omega+\omega_0)) + H[j(\omega-\omega_0)] =$$

$$= \frac{\sigma_L}{2} H[j(\omega-\omega_0)] \left\{ \frac{k}{2} U_m[j(\omega-\omega_0)] + \frac{k}{2} U_m[j(\omega+\omega_0)] \right\} +$$

$$+ \frac{\sigma_L}{2} H[j(\omega+\omega_0)] \left\{ \frac{k}{2} U_m[j(\omega-\omega_0)] + \frac{k}{2} U_m[j(\omega+\omega_0)] \right\}$$

$$U[j(\omega-\omega_0)] = U_T(j\omega)_{\omega_0} + H[j(\omega-\omega_0)] \left\{ \frac{k}{2} U_m[j(\omega-\omega_0)] + U_m[j(\omega+\omega_0)] H[j(\omega-\omega_0)] \right\}$$



$$\omega - \omega_0 + \omega - \omega_0 = \omega - 2\omega_0$$

$$\omega - \omega_0 + \omega_0 = \omega$$

$$U[j(\omega-\omega_0)] = \frac{k}{2} U_m[j(\omega-2\omega_0)] H[j(\omega-\omega_0)] + \frac{1}{2} k U_m(j\omega) H[j(\omega-\omega_0)]$$

$$U[j(\omega+\omega_0)] = \frac{k}{2} U_m(j\omega) H[j(\omega+\omega_0)] + \frac{k}{2} U_m[j(\omega+2\omega_0)] H[j(\omega+\omega_0)]$$

$$U_d(j\omega) = \frac{k}{4} \sigma_L U_m(j\omega) \left\{ H[j(\omega-\omega_0)] + H[j(\omega+\omega_0)] \right\} +$$

$$\frac{k}{4} \sigma_L \left\{ U_m[j(\omega-2\omega_0)] H[j(\omega-\omega_0)] + \frac{1}{2} U_m[j(\omega+2\omega_0)] H[j(\omega+\omega_0)] \right\}$$

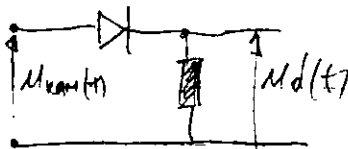
OUT FILTER
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RE (4)

$$M_F(t) = \frac{k \sigma_L}{4} u_m(t)$$

$$\cos(\omega_0 t) \cdot \cos(\omega_0 t) = \frac{1}{2} \cos(2\omega_0 t) + \frac{1}{2} \cos(0) = \frac{1}{2} \cos(2\omega_0 t) + \frac{1}{2}$$

3.6) ДЕТЕКЦИЯ НА КАМ СИГНАЛИ

• ДЕТЕКЦИЯ НА КАМ СО НЕЗНАКОМ ДЕТЕКТОР



$$M_d(t) = a_1 M_{\text{max}}(t) + a_2 M_{\text{kam}}^2(t)$$

$$M_{\text{kam}}(t) = U_0 [1 + u_0 \cos(\omega_0 t)] \cos \omega_0 t$$

$u(t) = \frac{u_{\text{max}}(t)}{U_0}$
 $u_0 = \frac{U_m}{U_0}$

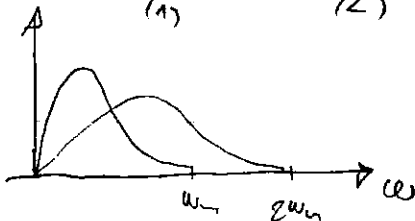
$$a_2 M_{\text{kam}}^2(t) = a_2 U_0^2 [1 + u_0 \cos(\omega_0 t)]^2 \cos^2 \omega_0 t = a_2 U_0^2 [1 + 2u_0 \cos(\omega_0 t) + u_0^2 \cos^2(\omega_0 t)] \cos^2 \omega_0 t$$

$$\cos^2 \omega_0 t = \cos(\omega_0 t) \cos(\omega_0 t) = \frac{1}{2} \cos[(\omega_0 - \omega_0)t] + \frac{1}{2} \cos 2\omega_0 t = \frac{1}{2} (1 + \cos 2\omega_0 t)$$

$$a_2 M_{\text{kam}}^2(t) = \frac{a_2 U_0^2}{2} [1 + 2u_0 \cos(\omega_0 t) + u_0^2 \cos^2(\omega_0 t)] + \frac{a_2 U_0^2}{2} [\dots] \cos 2\omega_0 t$$

FILTERED

$$M_F(t) = \underbrace{\frac{a_2 U_0^2}{2}}_{(1)} + \underbrace{a_2 U_0^2 u_0 \cos(\omega_0 t)}_{(2)} + \underbrace{\frac{a_2 U_0^2 u_0^2 \cos^2(\omega_0 t)}{2}}_{(3)} \quad \begin{matrix} (2) - \text{ВОЗБУЖДЕН СИГНАЛ} \\ (3) - \end{matrix}$$



$$u_1(t) = \cos(\omega_0 t)$$

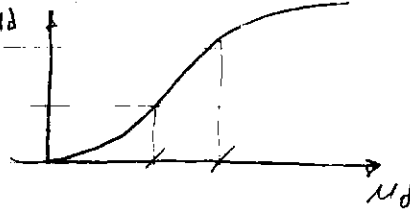
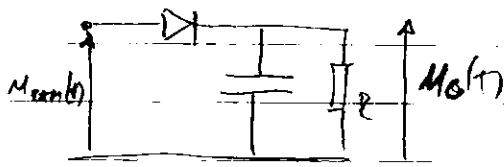
$$\frac{a_2 U_0^2}{2} u_0^2 u_1^2(t) = \frac{a_2 U_0^2}{2} u_0^2 (1 + \cos 2\omega_0 t) \frac{1}{2}$$

$$= \frac{a_2 U_0^2}{4} u_0^2 + \frac{a_2 U_0^2}{4} \cos(2\omega_0 t)$$

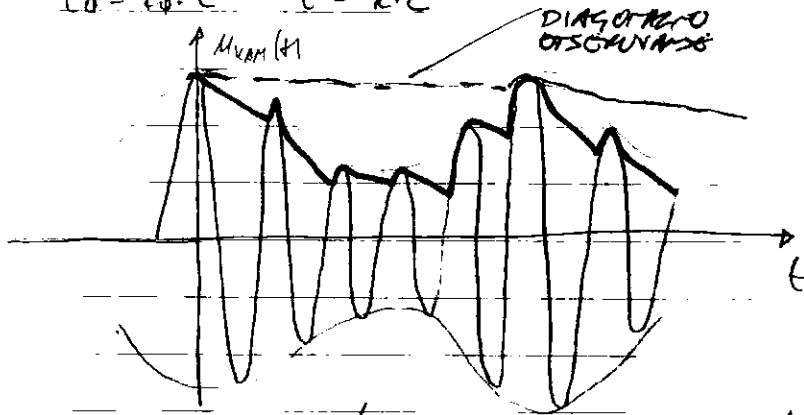
ОТРАБА

$$\sigma_2 = \left(\frac{q_2 \sigma_0^2 \omega_0^2}{4} \right) = \left(\frac{\omega_0}{4} \right)^2 \quad \omega_{H2} = 20 \log \frac{4}{\omega_0} \quad \text{STABILITE NA HARMONICNOJ (ZODRZLJIVOST OD II RED) POBUJENJO SLOJENJE NA HARM. POBUJENJE}$$

LINEARNI DETEKTOR NA INVEZICIA



$$\tau_d = R_d \cdot C \quad \tau = R \cdot C$$



ZA DA NE POJE DO DIAZ
OTSEKIVANJE
 $S_a(t_0) = S_{ce}(t_0)$

$$M_{in}(t) = U_0(1 + m \cos \omega_m t) \cos \omega_c t$$

$$M_a(t) = U_0(1 + m \cos \omega_m t)$$

$$M_c(t) = U e^{-\frac{t-t_0}{RC}}$$

$$S_a(t) = \left. \frac{dM_a(t)}{dt} \right|_{t=t_0} \quad S_{ce}(t_0) = \left. \frac{dM_c(t)}{dt} \right|_{t=t_0}$$

NEKA: $u(t) = \cos(\omega_m t)$ - TEST TON

$$S_a(t_0) = [U_0(1 + m \cos \omega_m t)]' = -U_0 m \omega_m \sin(\omega_m t_0) \cdot \omega_m = -U_0 m \omega_m^2 \sin(\omega_m t_0)$$

$$S_{ce}(t_0) = \frac{U}{RC} e^{-\frac{t-t_0}{RC}} \cdot (-1) = -\frac{U}{RC} \cdot e^0 = -\frac{U}{RC}$$

$$U = M_a(t_0) = U_0(1 + m \cos(\omega_m t_0)) = U_0 [1 + m \cos(\omega_m t_0)]$$

$$-\frac{U_0}{RC} (1 + m \cos(\omega_m t_0)) = -U_0 m \omega_m^2 \sin(\omega_m t_0)$$

$$\tau = RC = \frac{1 + m \cos(\omega_m t_0)}{m \omega_m^2 \sin(\omega_m t_0)} \quad \frac{d\tau}{dt_0} = 0$$

$$-m \omega_m \sin(\omega_m t_0) \cdot m \omega_m^2 \sin(\omega_m t_0) = (1 + m \cos(\omega_m t_0)) m \omega_m^2 \cos(\omega_m t_0) = 0$$

$$m^2 \omega_m^2 \sin^2(\omega_m t_0)$$

$$-m^2 \omega_m^2 \sin^2(\omega_m t_0) - m \omega_m^2 \cos(\omega_m t_0) - m^2 \omega_m^2 \cos^2(\omega_m t_0) = 0 = 0$$

$$(-m^2 \omega_m^2 \sin^2(\omega_m t_0) - m \omega_m^2 \cos(\omega_m t_0) - m^2 \omega_m^2 \cos^2(\omega_m t_0)) = 0 \quad \text{--- } m^2 \omega_m^2 \sin^2(\omega_m t_0) = m^2 \omega_m^2 \cos^2(\omega_m t_0)$$

$$-m \omega_m [m \omega_m \sin^2(\omega_m t_0) + m \cos(\omega_m t_0) + m \omega_m \cos^2(\omega_m t_0)] = 0 \quad \text{(A)}$$

$$\frac{0}{m^2 \omega_m^2 \sin^2(\omega_m t_0)} = -1 - \frac{m \omega_m \cos(\omega_m t_0) + m^2 \omega_m \cos^2(\omega_m t_0)}{m^2 \omega_m^2 \sin^2(\omega_m t_0)} =$$

$$= -1 - \frac{\cos(\omega_m t_0) [1 + m \cos(\omega_m t_0)]}{m \omega_m \sin^2(\omega_m t_0)} = 0$$

$$-\cos(\omega_m t_0) [1 + m \cos(\omega_m t_0)] = m \omega_m \sin^2(\omega_m t_0)$$

$$-\cos(\omega_m t_0) + m \cos^2(\omega_m t_0) + m \omega_m \sin^2(\omega_m t_0) = 0$$

$$m_0 [\omega_m \sin^2(\omega_m t_0) + \cos^2(\omega_m t_0)] = -\cos(\omega_m t_0)$$

$$\boxed{m_0 = \frac{-\cos(\omega_m t_0)}{\omega_m \sin^2(\omega_m t_0) + \cos^2(\omega_m t_0)}}$$

1570

$$\textcircled{1} \Rightarrow m_0 [\omega_m \sin^2(\omega_m t_0) + \cos^2(\omega_m t_0)] = -\cos(\omega_m t_0)$$

$$\textcircled{1} \Rightarrow m_0 \omega_m \sin^2(\omega_m t_0) + \omega_m \cos^2(\omega_m t_0) + m_0 \omega_m \cos^2(\omega_m t_0) = 0$$

$$m_0 \omega_m (\sin^2(\omega_m t_0) + \cos^2(\omega_m t_0)) = -\omega_m \cos^2(\omega_m t_0)$$

$$\boxed{m_0 = -\cos^2(\omega_m t_0)}$$

$$T_{max} = 2C_{max} = \frac{1 + \cos^2(\omega_m t_0)}{-\cos(\omega_m t_0) \cdot \omega_m \cdot \sin(\omega_m t_0)} \cdot \frac{\sin^2(\omega_m t_0)}{\cos(\omega_m t_0) \cdot \omega_m \cdot \sin(\omega_m t_0)}$$

$$T_{max} = - \frac{\sin(\omega_m t_0)}{\omega_m \cos(\omega_m t_0)} = - \frac{1}{\omega_m} \tan(\omega_m t_0)$$

$$T_{max} = - \frac{\sqrt{1 - \cos^2(\omega_m t_0)}}{\omega_m \cos(\omega_m t_0)} = - \frac{1}{\omega_m} \sqrt{\frac{1}{\cos^2(\omega_m t_0)} - 1} = - \frac{1}{\omega_m} \sqrt{\frac{1}{m_0^2} - 1}$$

$$\boxed{T_{max} = - \frac{1}{\omega_m} \sqrt{\frac{1}{m_0^2} - 1}}$$

• Derivata na AMNSO so DA

- AMNSO me more da se odredi so DA

DOVAZ:

$$M(t) = M_1(t) \cos(\omega t) + \hat{M}_1(t) \sin(\omega t)$$

$$M(t) = M_0(t) \cos(\omega t + \varphi(t))$$

$$M_0(t) = \sqrt{M_1^2(t) + \hat{M}_1^2(t)} \neq M_1(t)$$

($\hat{M}_1(t)$)

$$m_1(t) = U_m \cos(\omega_m t)$$

$$u(t) = \cos(\omega_m t)$$

$$M(t) = U_0 (1 + m_0 u(t)) \cos(\omega t) =$$

$$= U_0 (1 + m_0 \cos(\omega_m t)) \cos(\omega t) =$$

$$= U_0 \cos \omega t + \frac{U_0 m_0}{2} \cos[(\omega_0 - \omega_m)t] + \frac{U_0 m_0}{2} \cos[(\omega_0 + \omega_m)t] \quad m_0 = \frac{U_m}{U_0}$$

$$M_F(t) = U_0 \cdot H_0 \cos(\omega t) + \frac{U_0 m_0}{2} H^+ \cos[(\omega_0 - \omega_m)t] + \frac{U_0 m_0}{2} H^- \cos[(\omega_0 + \omega_m)t]$$

$$M_F(t) = A \cos(\omega_0 t) + B \sin(\omega_0 t) = M_0(t) \cos(\omega_0 t + \varphi)$$

$$M_0(t) = \sqrt{A^2 + B^2} = ?$$

$$M_F(t) = U_0 H_0 \cos(\omega_0 t) + \frac{U_0 m_0 H^+}{2} \cos(\omega_0 t) \cos \omega_m t + \frac{U_0 m_0 H^-}{2} \sin(\omega_0 t) \sin \omega_m t +$$

$$+ \frac{U_0 m_0}{2} H^- \cos \omega_0 t \cdot \cos \omega_m t - \frac{U_0 m_0 H^+}{2} \sin \omega_0 t \cdot \sin \omega_m t$$

$$M_F(t) = U_0 \left(H_0 + \frac{m_0 H^+}{2} \cos \omega_m t + \frac{m_0 H^-}{2} \cos \omega_m t \right) \cdot \cos(\omega_0 t) +$$

$$+ U_0 \left(\frac{m_0 H^+}{2} \sin \omega_m t - \frac{m_0 H^-}{2} \sin \omega_m t \right) \cdot \sin(\omega_0 t)$$

$$u_{\pm}(t) = U_0 \left[H_0 + \frac{u_0}{2}(H^+ + H^-) \cos \omega_0 t \right] \cos \omega_0 t + \frac{U_0 u_0}{2} (H^+ - H^-) \sin \omega_0 t \sin(\omega_0 t)$$

$$u_{\pm}(t) = U_0 \left[\left(H_0 + \frac{u_0}{2}(H^+ + H^-) \cos \omega_0 t \right)^2 + \left(\frac{1}{2} u_0 (H^+ - H^-) \sin \omega_0 t \right)^2 \right]$$

$$u_{\pm}(t) = U_0 + U_{A1} \cos(\omega_0 t) + U_{A2} \cos(2\omega_0 t)$$

$$d_2 = \frac{U_{A2}^2}{U_{A1}^2} = \left[\frac{u_0 (H^+ - H^-)^2}{4} \right]^2 \quad H^+ - H^- = 1 \quad \text{max case}$$

$$d_2 = \left(\frac{u_0}{4} \right)^2$$

$$d_{dB} = 10 \log \left(\frac{4}{u_0} \right)^2 = 20 \log \frac{4}{u_0}$$

• SINKA NA SLOZEN SIGNAL

$$\textcircled{1} x(t) = U_1 \cos(\omega_0 t) + U_2 \cos(\omega_0 t)$$

$$P_{\pm} = \frac{U_1^2}{2R} + \frac{U_2^2}{2R}$$

$$\textcircled{2} x(t) = U_1 \cos(\omega_0 t) + U_2 \cos(\omega_0 t)$$

$$P_{\pm} = \frac{(U_1 + U_2)^2}{2R}$$

$$\textcircled{3} x(t) = U_1 \cos(\omega_0 t + \varphi_1) + U_2 \cos(\omega_0 t + \varphi_2) =$$

$$U_1 \cos(\omega_0 t) \cos \varphi_1 - U_1 \sin(\omega_0 t) \sin \varphi_1 + U_2 \cos(\omega_0 t) \cos \varphi_2 - U_2 \sin(\omega_0 t) \sin \varphi_2$$

$$= \underbrace{(U_1 \cos \varphi_1 + U_2 \cos \varphi_2)}_A \cos(\omega_0 t) - \underbrace{(U_1 \sin \varphi_1 + U_2 \sin \varphi_2)}_B \sin(\omega_0 t)$$

$$x(t) = \sqrt{A^2 + B^2} \cdot \cos(\omega_0 t + \varphi) \quad \varphi = \arctg \frac{B}{A}$$

$$A = k \cos \varphi \quad B = k \sin \varphi, \quad k = \sqrt{A^2 + B^2}, \quad \frac{B}{A} = \tan \varphi \Rightarrow \varphi = \arctg \frac{B}{A}$$

$$U_1 = U_2 \quad \underline{x(t)} = \sqrt{U_1^2 (\cos \varphi_1 + \cos \varphi_2)^2 + U_1^2 (\sin \varphi_1 + \sin \varphi_2)^2} \cdot \cos(\omega_0 t + \varphi)$$

$$\textcircled{4} = U_1^2 (\cos^2 \varphi_1 + 2 \cos \varphi_1 \cos \varphi_2 + \cos^2 \varphi_2 + \sin^2 \varphi_1 + 2 \sin \varphi_1 \sin \varphi_2 + \sin^2 \varphi_2) =$$

$$= 2 U_1^2 (1 + \underbrace{\cos \varphi_1 \cos \varphi_2 + \sin \varphi_1 \sin \varphi_2}_{\cos(\varphi_1 - \varphi_2)}) =$$

$$= \left[1 + \cos \Delta \right] \quad \cos \left(\frac{\Delta}{2} + \frac{\Delta}{2} \right) = \cos \frac{\Delta}{2} \cdot \cos \frac{\Delta}{2} - \sin \frac{\Delta}{2} \cdot \sin \frac{\Delta}{2}$$

$$= \cos^2 \frac{\Delta}{2} - \sin^2 \frac{\Delta}{2}$$

$$1 + \cos \Delta = 1 + \cos^2 \frac{\Delta}{2} - \sin^2 \frac{\Delta}{2} = 2 \cos^2 \frac{\Delta}{2}$$

$$= 2 U_1^2 \cdot 2 \cos^2 \left(\frac{\varphi_1 - \varphi_2}{2} \right) = \boxed{4 U_1^2 \cdot \cos^2 \frac{\varphi_1 - \varphi_2}{2}}$$

$$x(t) = 2 U_1 \cdot \cos \frac{\varphi_1 - \varphi_2}{2} \cdot \cos(\omega_0 t + \varphi)$$

$$\text{• max: } \varphi_1 = \varphi_2 \quad P = \frac{(2U_1)^2}{2R} = 4 \frac{U_1^2}{2R}$$

$$\text{• min: } \varphi_1 - \varphi_2 = \pi \Rightarrow \pi = 0 \quad \text{• } \varphi_1 - \varphi_2 = \frac{\pi}{2} \quad \cos \frac{\pi}{4} = \frac{\sqrt{2}}{2}$$

$$P = \frac{\left(2 U_1 \cdot \frac{\sqrt{2}}{2} \right)^2}{2R} = \frac{2 U_1^2}{2R} = 2 \frac{U_1^2}{2R}$$

4. SUM

• SPECTRALNA GUSTINA NA SREDNA SIAGA NA PRAVICI SUM

$$P_n(f) = \frac{h \cdot f}{e^{-\frac{h \cdot f}{kT}} - 1}$$

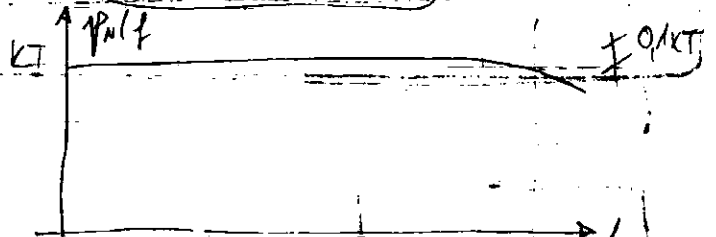
$$h = 6.62 \cdot 10^{-34} \text{ J}\cdot\text{s} \quad \frac{h \cdot f}{kT} \ll 1$$

$$k = 1.38 \cdot 10^{-23} \text{ J/K} \quad kT$$

$$e^x = 1 + \frac{x}{1!} + \frac{x^2}{2!} + \dots$$

$$e^{-\frac{h \cdot f}{kT}} \approx 1 - \frac{h \cdot f}{kT}$$

$$P_n(f) = \frac{h \cdot f}{\frac{h \cdot f}{kT}} = k \cdot T$$



• PASIOLAZIVA SREDNA SIAGA

$$P_n(f) = \frac{dP_{RN}}{df}$$

$$P_{RN} = \int_{f_1}^{f_2} P_n(f) df = k \cdot T \cdot B \quad [\text{W/Hz}]$$

Pr. $B = 1 \text{ Hz}$ $P_{RN} = k \cdot T \cdot B = 4 \cdot 10^{-21} \text{ [W/Hz]}$

$$T = \frac{4 \cdot 10^{-21}}{1.38 \cdot 10^{-23}} = 290 \text{ K}$$

$$10 \cdot \log_{10} \frac{P_{RN}}{1 \mu\text{W}} = -179 \text{ dB}$$

$$B = 4 \text{ kHz} \quad P_{RN} = 1.656 \cdot 10^{-18} \frac{\text{W}}{\text{Hz}} = -158 \text{ dB}$$

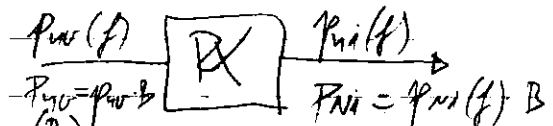
$$E_{\text{NEFF}} = \sqrt{4 P_{RN} \cdot R} = \sqrt{4 R k T B}$$

• ANOMALNA CA RELI SUM SO PP SIGNALI

$$e(t) = \sum_{i=1}^N E_i \cos(\omega_i t + \varphi_i)$$

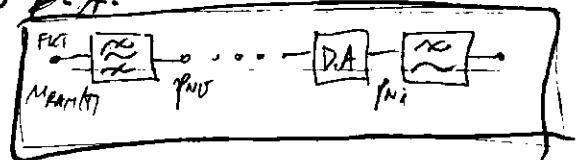
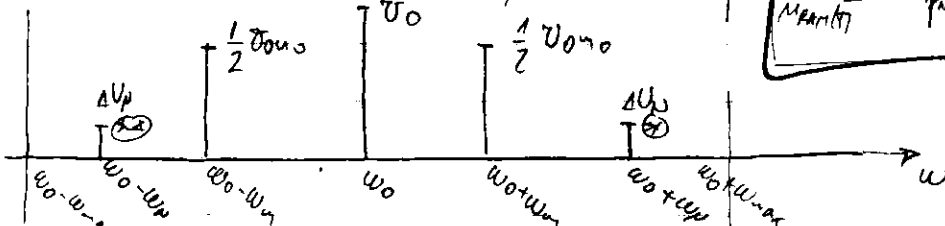
• ODROS SIGNAL SUM

$$F = \frac{P_{ni}}{P_{no}} \left(\frac{P_s}{P_n} \right)_i \quad 10 \log \left(\frac{P_s}{P_n} \right)_i$$



• S/N KAD POKRENIK NA KAM SO D.A.

$$u_{\text{cam}} = U_0 (1 + m \cos \omega_m t) \cos \omega_c t$$



$$u(t) = U_0 (1 + m \cos \omega_m t) \cos \omega_c t + \Delta U_n \cdot \cos((\omega_c + \omega_n)t + \varphi_n) =$$

$$= U_0 (1 + m \cos \omega_m t) \cos \omega_c t + \Delta U_n \cos(\omega_c t) \cos(\omega_n t + \varphi_n) - \Delta U_n \sin(\omega_c t) \sin(\omega_n t + \varphi_n)$$

$$= \underbrace{[U_0 (1 + m \cos \omega_m t) + \Delta U_n \cos(\omega_n t + \varphi_n)]}_{A} \cos \omega_c t - \underbrace{\Delta U_n \sin(\omega_n t + \varphi_n)}_{B} \sin(\omega_c t)$$

$$u_{\text{eff}}(t) = \sqrt{A^2 + B^2} = \left\{ U_0^2 (1 + m \cos \omega_m t)^2 + 2 U_0 (1 + m \cos \omega_m t) \cdot \Delta U_n \cos(\omega_n t + \varphi_n) + \Delta U_n^2 (\cos^2(\omega_n t + \varphi_n) + \sin^2(\omega_n t + \varphi_n)) \right\}^{1/2}$$

$\Delta U_n \ll U_0 \quad \Delta U_n^2 \rightarrow 0$

$$u_a(t) = \left[V_0^2 (1 + u_0 \cos \omega_m t)^2 + 2 V_0 u_0 \cos \omega_m t \cos(\omega_c t + \varphi_N) \right]^{1/2}$$

$$u_a(t) = V_0 (1 + u_0 \cos \omega_m t) \sqrt{1 + \frac{2 u_0 \cos(\omega_c t + \varphi_N)}{V_0 (1 + u_0 \cos \omega_m t)}}$$

$$\sqrt{1+x} \approx 1 + \frac{x}{2}$$

$$u_a(t) = V_0 (1 + u_0 \cos \omega_m t) \left(1 + \frac{u_0 \cos(\omega_c t + \varphi_N)}{V_0 (1 + u_0 \cos \omega_m t)} \right) \approx$$

$$u_a(t) = V_0 (1 + u_0 \cos \omega_m t) + u_0 \cos(\omega_c t + \varphi_N) \quad \text{①}$$

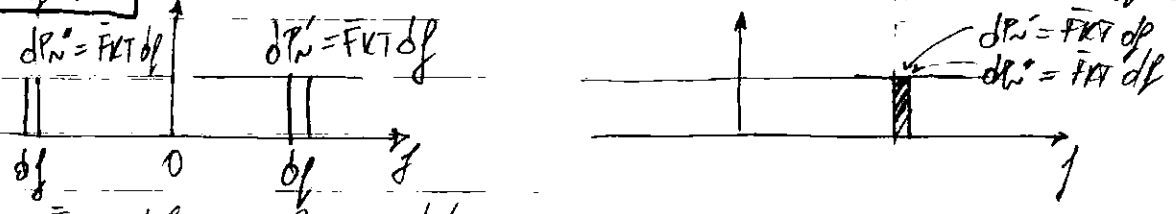
$$u_d(t) = V_0 + V_0 u_0 \cos \omega_m t + u_0 \cos(\omega_c t + \varphi_N) \quad \text{MMV}$$

$$P_{Nd} = \Delta P_{N1} \cos(\omega_c t + \varphi_N) + \Delta P_{N2} \cos(\omega_c t + \varphi_N)$$

$$P_N = \sum_{i=1}^n \Delta P_{Ni}$$

$$\Delta N = \Delta P_{N1} + \Delta P_{N2}$$

$P_{Nd} = P_{Nd1} + P_{Nd2}$
 $\Delta P_{N1} \sim U_{N1}^2 \quad \omega_0 + \omega_m$
 $\Delta P_{N2} \sim U_{N2}^2 \quad \omega_0 - \omega_m$



$$\Delta P_{Ni} = 2 FKT df = 2 P_{N1} df$$

$$P_{sv} = \left(\frac{1}{2} V_0 u_0 \right)^2 \frac{1}{2L} + \left(\frac{1}{2} V_0 u_0 \right)^2 \frac{1}{2L} = 2 P_{N1}$$

even symmetric cont
 $\left(\frac{1}{2} V_0 u_0 \right)^2 \frac{1}{2L}$
 ①

$$P_{N1} = \int_{f_0}^{f_{max}} P_{N1}(f) df = FKT B_{VF}$$

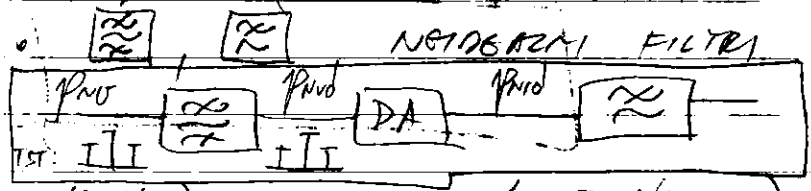
$$P_{s1} = (u_0 V_0)^2 \frac{1}{2R} = 4 P_{N1}$$

$$P_{N1} = \int_{f_0}^{f_{max}} 2 P_{N1} df = 2 FKT \cdot B_{VF}$$

$$B_{VF} = 2 B_{VF}$$

$$\left(\frac{P_s}{P_{N1}} \right) = \frac{2 P_{N1}}{2 FKT B_{VF}} = \frac{2 P_{N1}}{2 FKT B_{VF}} = \frac{P_{N1}}{FKT B_{VF}}$$

$$\left(\frac{P_s}{P_{N1}} \right) = \frac{4 P_{N1}}{2 FKT B_{VF}} = \frac{2 P_{N1}}{FKT B_{VF}} = 2 \left(\frac{P_s}{P_{N1}} \right)$$



$P_{N1} \neq P_{N2}$

$$V_0 A(\omega_0) \sim \text{positive}, \quad \frac{1}{2} \omega_0 V_0 A(\omega_0 + \omega_m) \quad \text{GSO}, \quad \frac{1}{2} \omega_0 V_0 A(\omega_0 - \omega_m) \quad \text{DSO}$$

$$P_{N1} = \left(\frac{1}{2} \omega_0 V_0 A(\omega_0 + \omega_m) \right)^2 \frac{1}{2R}$$

$$P_{N2} = \left(\frac{1}{2} \omega_0 V_0 A(\omega_0 - \omega_m) \right)^2 \frac{1}{2R}$$

$$P_{svd} = P_{N1} + P_{N2}$$

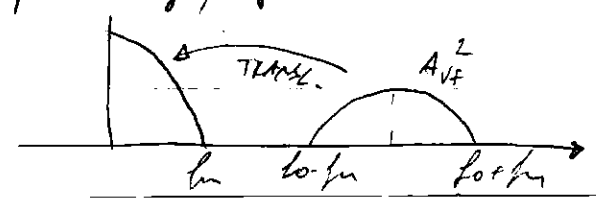
$$P_{N1} = P_{N1V} A^2(\omega_0 + \omega_m) \quad P_{N2} = P_{N2V} A^2(\omega_0 - \omega_m)$$

$$P_{N1V} = P_{N1} \cdot A_{VF}^2(\omega)$$

$$P_{N1V} = \int_{f_1}^{f_2} P_{N1} A_{VF}^2(f) df$$

$$P_{svd} = FKT \int_{f_1}^{f_2} A_{VF}^2(f) df$$

$f_c = \omega_0 + \omega_m$
 $f_1 = f_0 + f_{max}$



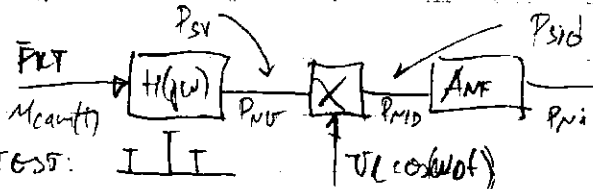
$$P_{nid} = 2FKT A_{in}^2(f) \quad P_{ni} = P_{nid} A_{VF}^2(f)$$

$$P_{ni} = \int_0^{f_{max}} P_{nid} A_{VF}^2(f) df = \int_0^{f_{max}} 2 P_{nid} A_{VF}^2(f) df$$

$$P_{sid} = \int_0^{f_{max}} \left[u_0 V_0 [A_{VF}(f_0 - f) + A_{VF}(f_0 + f)] \right]^2 \frac{1}{2R} \quad P_{si} = P_{sid} A_{VF}^2(f) \frac{1}{2R}$$

$$\left(\frac{S}{N}\right)_V = \frac{P_{svd}}{P_{nvd}} \quad \left(\frac{S}{N}\right)_A = \frac{P_{sia}}{P_{nia}}$$

• SNR KAS SISTEM DEMODULASI



$$M(t) = U_0 \cos \omega_c t + \frac{1}{2} u_0 U_0 \cos(\omega_0 \pm \omega_c) t$$

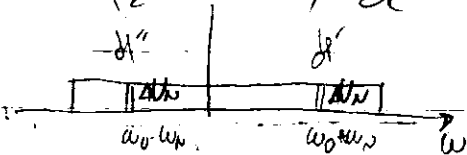
$$M_d(t) = M(t) \cdot M_L(t) = (VF) + \frac{1}{2} U_0 U_0 u_0 \cos(\omega_c t) + \frac{U_0 U_0}{2}$$

$$P_{ni} = P_{nl} = \left(\frac{1}{2} u_0 U_0\right)^2 \frac{1}{2R} \quad P_{sv} = 2 P_{ni}$$

$$M(t) \cdot U_L \cos \omega_c t = \frac{U_0 U_L}{2} [\cos(\omega_0 - \omega_c) t + \cos(\omega_0 + \omega_c) t] + \frac{U_0 u_0 U_0}{2} \cos(\omega_c t) \cos \omega_c t + \frac{U_0 u_0 U_0}{2} \cos(\omega_0 - \omega_c) t \cos \omega_c t$$

$$= \frac{U_0 U_L}{2} + \frac{U_0 U_L}{2} \cos 2\omega_c t + \frac{U_0 u_0 U_0}{4} [\cos(\omega_0 + \omega_c) t + \cos(\omega_0 - \omega_c) t] + \frac{U_0 u_0 U_0}{4} [\cos(\omega_c t) + \cos(2\omega_c t)] = (VF) + \frac{U_0 U_L}{2} + \frac{U_0 u_0 U_0}{2} \cos \omega_c t$$

$$P_{sid} = \left(\frac{1}{2} u_0 U_0 U_L\right)^2 \frac{1}{2R} = \left(\frac{1}{2} U_L\right)^2 \left(u_0 U_0\right)^2 \frac{1}{2R} = 4 DP P_{ni} = 2 DP P_v$$



$$U_L \cos(\omega_0 - \omega_c) t \cdot U_0 \cos \omega_c t = \frac{U_0 U_L}{2} \cos(\omega_c t + \omega_0) + (VF)$$

$$\Delta P' = \frac{\Delta U_L^2}{2R} \quad \text{TRANSKRIPSI}$$

$$\Delta P_{ni}' = \left(\frac{\Delta U_L U_0}{2}\right)^2 \frac{1}{2R} = \left(\frac{U_0}{2}\right)^2 \Delta U_L^2 \frac{1}{2R}$$

$$\Delta P'' = \frac{\Delta U_L^2}{2R} \quad \text{NF}$$

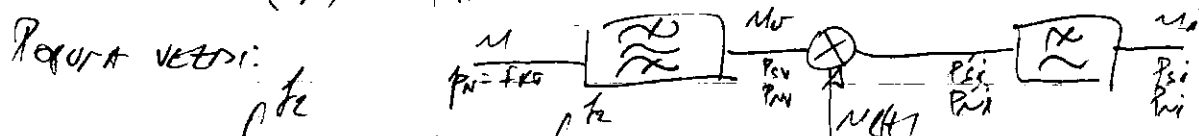
$$\Delta P_{ni}'' = DP \Delta U_L^2 \frac{1}{2R}$$

$$\Delta P_{ni} = \Delta P_{ni}' + \Delta P_{ni}'' = 2 DP \Delta U_L^2 \frac{1}{2R} = 2 \Delta P'$$

$$dP_{ni} = DP \cdot dP_{NV} \quad dP_{ni} = DP \cdot P_{NV} df \quad P_{sv} = 2 P_{ni} \quad P_{si} = 4 DP P_{ni} = 2 DP P_{sv}$$

$$\left(\frac{P_s}{P_n}\right)_A = \frac{2 DP \cdot P_{sv}}{2 FKT \cdot DP \cdot BNF} = \frac{2 P_{sv}}{FKT \cdot BNF} = 2 \frac{P_{sv}}{P_{nv}} = 2 \left(\frac{P_s}{P_n}\right)_V$$

$$\text{AM ISO} \quad \left(\frac{P_s}{P_n}\right)_A = \left(\frac{P_s}{P_n}\right)_V$$



$$P_{NV} = \int_{-f_c}^{f_c} P_{NV} df = \int_{-f_c}^{f_c} P_N \cdot A_{VF}^2(f) df$$

$$P_{SI} = 2D_p \cdot P_{SV} \quad P_{ni} = 2D_p \cdot \gamma_n \cdot A_{VF}^2(f)$$

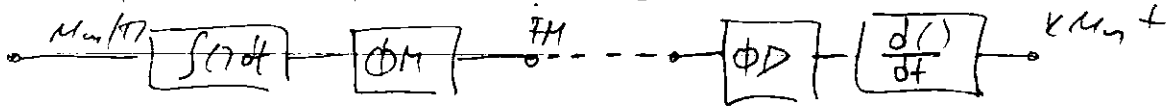
$$P_{ni} = P_{ni} \cdot A_{VF}^2(f) = 2D_p \gamma_n \cdot A_{VF}^2 \cdot A_{VF}^2$$

$$P_{ni} = \int_0^{f_m} 2D_p \gamma_n \cdot A_{VF}^2 \cdot A_{VF}^2 df = 2D_p \gamma_n \int_0^{f_m} A_{VF}(f+f_0) A_{VF}^2(f) df$$

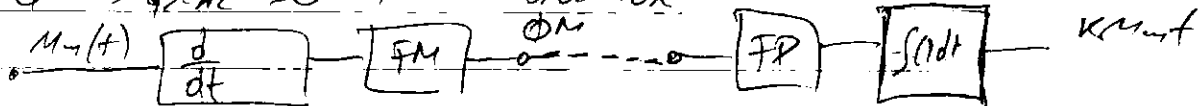
$$dP_{ni} = \gamma_n df$$

OTK AGLONA MODULACIJA

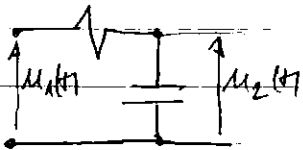
- FM signal iz FM modulatora



- ΦM signal iz FM modulatora

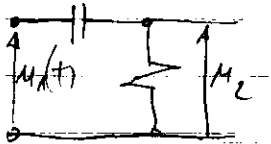


$$M_1(t) = U_0 \cos(\omega_0 t + k_f M_1(t)) \quad M_{FM}(t) = U_0 \cos(\omega_0 t + k_{\Phi} \int M_1(t) dt)$$



$$M_2(t) = \frac{1}{RC} \int M_1(t) dt \quad \left[\frac{1}{\omega_0 RC} \ll 1 \right]$$

$$i = RC \frac{dM_2(t)}{dt} \Rightarrow \frac{V}{RC}$$



$$M_2(t) = RC \frac{dM_1(t)}{dt} \quad \left[\frac{1}{\omega_0 RC} \gg 1 \right]$$

- Naveda $M_2(t) = U_0 \cos(\omega_0 t)$

$$M_{FM}(t) = U_0 \cos(\omega_0 t + k_f U_m \cos(\omega_m t)) = U_0 \cos(\omega_0 t + \Delta\phi_0 \cos(\omega_m t))$$

$$\delta\phi_i = \Delta\phi_0 \cos(\omega_m t) \quad \delta\omega_i = -\Delta\phi_0 \sin(\omega_m t) \quad \omega_i = \frac{d\phi_i}{dt}$$

$$M_{FM}(t) = U_0 \cos(\omega_0 t + k_{\Phi} U_m \int \cos(\omega_m t) dt) = U_0 \cos(\omega_0 t + \frac{k_{\Phi} U_m}{\omega_m} \sin(\omega_m t))$$

$$M_{FM}(t) = U_0 \cos(\omega_0 t + \frac{\Delta\omega_0}{\omega_m} \sin(\omega_m t)) \quad \Delta\omega_0 = \frac{\Delta\omega_0}{\omega_m} \omega_m$$

$$M_{FM}(t) = U_0 \cos(\omega_0 t + \frac{\Delta\omega_0}{\omega_m} \cos(\omega_m t - \frac{\pi}{2}))$$

$$\delta\omega_i = \frac{d}{dt} (\delta\phi_i) = \frac{\Delta\omega_0}{\omega_m} (-\sin(\omega_m t - \frac{\pi}{2})) = \Delta\omega_0 (-1) \sin(\frac{\pi}{2} - \omega_m t)$$

$$\delta\omega_i = \Delta\omega_0 \cos(\omega_m t)$$

- Specijal na ΦM, FM signali

$$\cos(0.2\pi n) = \cos(2\pi f t) \quad t = 4 \mu s \quad \omega = 2\pi f$$

$$\cos(\omega t) = \cos(2\pi \cdot 4 \cdot 10^6 \cdot 4 \cdot 10^{-6}) = \cos(0.2 \cdot 2\pi \cdot 4)$$

$$M_{FM}(t) = U_0 \cos(\omega_0 t + k_f U_m \cos(\omega_m t)) = U_0 \cos(\omega_0 t + m \cos(\omega_m t))$$

$$m = \Delta\phi_0 = k_f U_m$$

$$e^{j \text{argument}} = \sum_{n=-\infty}^{\infty} J_n(m) e^{jn\omega_m t}$$

$$u_{FM}(t) = U_0 \cos\left\{\omega_0 t + \frac{\Delta\omega_0}{\omega_m} \cos(\omega_m t - \frac{\pi}{2})\right\} = U_0 \cos\left\{\omega_0 t + m \cos(\omega_m t - \frac{\pi}{2})\right\}$$

$$m = \frac{\Delta\omega_0}{\omega_m} = \frac{k_v \cdot U_m}{\omega_m} = \frac{k_v \cdot U_m}{f_m}$$

• Mod & Mod(t) ist periodische Funktion ist Mod PA & Erzeugt VO Fred

$$\begin{aligned} \cos(\alpha + m \cos \beta) &= \sum_{n=-\infty}^{\infty} J_n(m) \cdot \cos\left(\alpha + n\beta + \frac{n\pi}{2}\right) \\ \cos(\alpha + m \sin \beta) &= \sum_{n=-\infty}^{\infty} J_n(m) \cos(\alpha + n\beta) \\ \sin(\alpha + m \cos \beta) &= \sum_{n=-\infty}^{\infty} J_n(m) \sin\left(\alpha + n\beta + \frac{n\pi}{2}\right) \\ \sin(\alpha + m \sin \beta) &= \sum_{n=-\infty}^{\infty} J_n(m) \sin(\alpha + n\beta) \end{aligned}$$

$$F_n = \frac{1}{T} \int_{-T/2}^{T/2} \cos(\alpha + m \cos \beta) \cdot e^{-jn\omega_0 t} dt = ? \Rightarrow \text{NE SE LEHRA VO ZUTVOER A FORMA \Rightarrow BERECHN FUNKT}$$

$$u_{FM}(t) = U_0 \cos(\omega_0 t + m \cos \omega_m t) = \sum_{n=-\infty}^{\infty} J_n(m) \cdot \cos(\omega_0 t + n \cdot \omega_m t + \frac{n\pi}{2})$$

$$e^{j(\omega_0 t + m \cos \omega_m t)} = \sum_{n=-\infty}^{\infty} J_n(m) \cdot e^{jn\omega_0 t}$$

$$J_n(m) = \frac{1}{T} \int_{-T/2}^{T/2} e^{j(m \cos \omega_m t)} \cdot e^{-jn\omega_0 t} dt$$

$$m \ll 1 \Rightarrow J_n(m) \approx \frac{m^n}{2^n n!}$$

$$d(\omega t) = 2\pi f dt = \frac{2\pi}{T} dt$$

$$J_n(x) = \frac{1}{2\pi} \int_{-\pi}^{\pi} e^{-j(n\tau - x \sin \tau)} d\tau = \begin{cases} \tau = \omega_0 t \\ d\tau = \omega_0 dt = \frac{2\pi}{T} dt \\ \omega_0 = 2\pi f = \frac{2\pi}{T} \end{cases}$$

$$= \frac{1}{2\pi} \cdot \frac{2\pi}{T} \int_{-T/2}^{T/2} e^{-jn\omega_0 t} e^{jx \sin(\omega_0 t)} dt = \frac{1}{T} \int_{-T/2}^{T/2} e^{jx \sin(\omega_0 t)} e^{-jn\omega_0 t} dt$$

$$\textcircled{*} = U_0 \left[J_0(m) \cos \omega_0 t + \sum_{n=1}^{\infty} J_n(m) \cdot \cos(\omega_0 t + n\omega_m t + \frac{n\pi}{2}) + \sum_{n=1}^{\infty} J_n(m) \cos(\omega_0 t + n\omega_m t + \frac{n\pi}{2}) \right]$$

$$J_{-n}(m) = (-1)^n J_n(m)$$

$$\textcircled{*} = \sum_{n=1}^{\infty} J_{-n}(m) \cos(\omega_0 t - n\omega_m t - \frac{n\pi}{2}) = \left| \begin{aligned} \cos(\omega_0 t - n\omega_m t - \frac{n\pi}{2}) &= (-1)^n \cdot \cos(\omega_0 t - n\omega_m t + \frac{n\pi}{2}) \\ \cos(\alpha - \pi) &= \cos \alpha \cdot \cos \pi + \sin \alpha \cdot \sin \pi = -\cos \alpha \\ \cos(\alpha - \frac{\pi}{2}) &= \cos \alpha \cdot \cos \frac{\pi}{2} + \sin \alpha \cdot \sin \frac{\pi}{2} = \sin \alpha \end{aligned} \right.$$

$$\begin{aligned} \cos(\alpha - \frac{n\pi}{2}) &= \cos \alpha \cdot \cos(\frac{n\pi}{2}) - \sin \alpha \cdot \sin(\frac{n\pi}{2}) \\ n = 2, 4, 6 & \cos(\alpha - \frac{n\pi}{2}) = \cos(\alpha) \\ n = 1, 3, 5, 7 & \cos(\alpha - \frac{n\pi}{2}) = -\sin \alpha \cdot (-1)^{n-1} \\ \cos(\alpha - \frac{n\pi}{2}) &= \sin(\frac{\pi}{2} - \alpha) \cos(\frac{n\pi}{2}) - \sin \alpha \cdot \sin(\frac{n\pi}{2}) \end{aligned}$$

$$n = 0, 1, 2, 3, \dots$$

$$\cos(n\pi/2) = [1, 0, -1, 0, 1, 0, -1, \dots]$$

$$\sin(n\pi/2) = [0, 1, 0, -1, 0, 1, 0, \dots]$$

$$\cos(\alpha - \frac{y\pi}{2}) = \cos(\alpha) \cos \frac{y\pi}{2} + \sin(\alpha) \sin \frac{y\pi}{2} =$$

$$= [\cos(\alpha), \sin(\alpha), -\cos(\alpha), -\sin(\alpha), \cos(\alpha), \sin(\alpha), -\cos(\alpha), -\sin(\alpha), \cos(\alpha), \sin(\alpha), \dots]$$

$$\cos(\alpha - \frac{y\pi}{2}) = (-1)^y \sin(\alpha) \quad ? \quad y=1 \quad \cos(\alpha - \frac{\pi}{2}) = -\sin(\alpha) \quad \#$$

$$\cos(\alpha + \frac{y\pi}{2}) = [\cos(\alpha), -\sin(\alpha), \cos(\alpha), \sin(\alpha), \cos(\alpha), -\sin(\alpha), \cos(\alpha), \sin(\alpha), \dots]$$

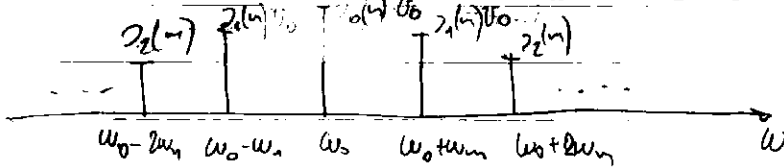
$$= (-1)^y \cos(\alpha - \frac{y\pi}{2}) = \cos(\alpha), \sin(\alpha), \cos(\alpha), \sin(\alpha), \cos(\alpha), -\sin(\alpha), \dots$$

$$\textcircled{*} \sum_{n=1}^{\infty} J_n \cos(\omega_0 t - n\omega_1 t - \frac{n\pi}{2}) = \sum_{n=1}^{\infty} (-1)^n J_n \cos(\omega_0 t - n\omega_1 t + \frac{n\pi}{2}) =$$

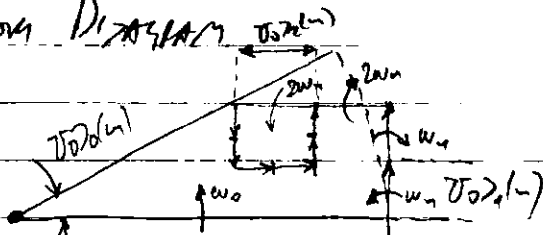
$$\left(J_n^{(-)} = (-1)^n J_n \right) \quad \left(\cos(\alpha - \frac{y\pi}{2}) = (-1)^y \cos(\alpha + \frac{y\pi}{2}) \right)$$

$$= \sum_{n=1}^{\infty} J_n^{(-)} \cos(\omega_0 t - n\omega_1 t + \frac{n\pi}{2})$$

$$u(t) = U_0 \cdot J_0 \cos \omega_0 t + U_0 \sum_{n=1}^{\infty} J_n^{(-)} \left[\cos((\omega_0 - n\omega_1)t + \frac{n\pi}{2}) + \cos((\omega_0 + n\omega_1)t + \frac{n\pi}{2}) \right]$$



• FREQUENCY DIAGRAM



$$\bullet \text{ NOTE: } u(t) = U_0 \cos[\omega_0 t + \omega_1 \cos \omega_1 t + \omega_2 \cos \omega_2 t] =$$

$$= U_0 \cos[\frac{\omega_0 t}{2} + \omega_1 \cos \omega_1 t + \frac{\omega_0 t + \omega_2 \cos \omega_2 t}{2}] =$$

$$= U_0 \cos(\frac{\omega_0 t}{2} + \omega_1 \cos \omega_1 t) \cos(\frac{\omega_0 t}{2} + \omega_2 \cos \omega_2 t) - U_0 \sin(\frac{\omega_0 t}{2} + \omega_1 \cos \omega_1 t) \sin(\frac{\omega_0 t}{2} + \omega_2 \cos \omega_2 t)$$

$$= U_0 \sum_{p=0}^{\infty} J_p \cos(\frac{\omega_0 t}{2} + p\omega_1 t + \frac{p\pi}{2}) \sum_{q=0}^{\infty} J_q \cos(\frac{\omega_0 t}{2} + q\omega_2 t + \frac{q\pi}{2}) - U_0 \sum_{p=0}^{\infty} J_p \sin(\frac{\omega_0 t}{2} + p\omega_1 t + \frac{p\pi}{2}) \sum_{q=0}^{\infty} J_q \sin(\frac{\omega_0 t}{2} + q\omega_2 t + \frac{q\pi}{2})$$

$$= U_0 \sum_{p=0}^{\infty} \sum_{q=0}^{\infty} J_p J_q \cos[\omega_0 t + (p\omega_1 + q\omega_2)t + \frac{p+q}{2}\pi]$$

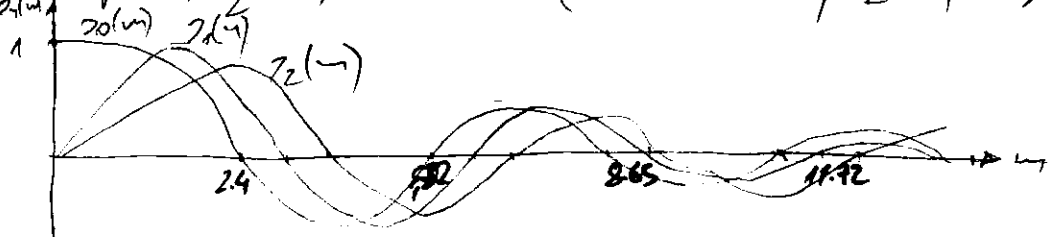
$p=0, q=0$	\rightarrow	$U_0 J_0 J_0$	ω_0
$p=0, q=1$	\rightarrow	$U_0 J_0 J_1$	$\omega_0 + \omega_2$
$p=1, q=0$	\rightarrow	$U_0 J_1 J_0$	$\omega_0 + \omega_1$

.....

$$\left. \begin{array}{l} \omega_0 + \omega_1 + \omega_2 \\ \omega_0 + \omega_1 - \omega_2 \\ \omega_0 - \omega_1 + \omega_2 \\ \omega_0 - \omega_1 - \omega_2 \end{array} \right\}$$

• ZNAČAJNI KOMPONENTI OD SVEKUPNOG NA KLJUČNOJ FREKVENCIJI SINTAZI

- 1) $J_0(\omega) \leq 1$ (samo $J_0(0) = 1$)
- 2) $J_2(\omega_1) J_2(\omega_2) \leq 1$ ($J_1(\omega_1) \leq 1, J_2(\omega_2) \leq 1$)



$$y(t) = \sigma_0 \cos(\omega_0 t) + \sigma_0 \sum_{n=1}^{\infty} J_n(\omega) \left\{ \cos(\omega_0 t + n\omega t + \frac{n\pi}{2}) + \cos(\omega_0 t - n\omega t + \frac{n\pi}{2}) \right\}$$

$$J_n(\omega) = \frac{\omega^n}{2^n n!} \left[1 - \frac{\omega^2}{2(2+n)} + \frac{\omega^4}{2 \cdot 2^2 (2+n)(4+2)} - \dots + \frac{(-1)^p \omega^{2p}}{p! 2^{2p} (2+n) \dots (2+n+p)} \right]$$

• $\omega < 1$ $J_n(\omega) \approx \frac{\omega^n}{2^n n!}$ $J_0(\omega) \approx 1$; $J_1(\omega) \approx \frac{\omega}{2}$; $J_2 \approx \frac{\omega^2}{8}$; $J_3 \approx \frac{\omega^3}{48}$

• KARLSONOV KRITERIJUM ZA ZNAČAJNI KOMPONENTI

TRJEBA DA SE ODRŽATI SVE USLOJEVI TI SU SVEGA ≥ 11 OD REKONSTRUKCIJE NOSIČKE

$100 \frac{\sigma_0^2 J_n(\omega)}{2L} < \frac{\sigma_0^2}{2L}$

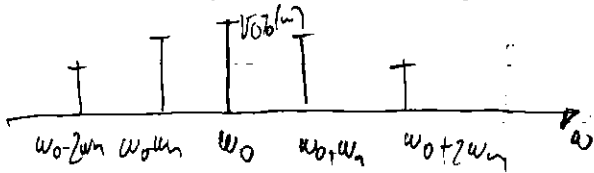
→ KOMPONENTA NE E ZNAČAJNA

$$\sigma_0 J_0(\omega) = \sigma_0 \quad \sigma_0 J_1(\omega) = \frac{\sigma_0 \omega}{2} \quad \sigma_0 J_2(\omega) = \frac{\sigma_0 \omega^2}{8}$$

$$\frac{\sigma_0^2}{2L} > 100 \frac{\sigma_0^2}{2L} \cdot \frac{\omega^4}{64} \quad \left(\frac{\omega^2}{8}\right)^2 < \frac{1}{100} = \left(\frac{1}{10}\right)^2$$

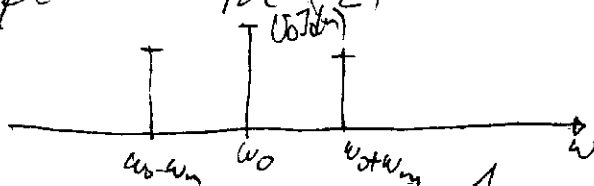
$$\frac{\omega^2}{8} < \frac{1}{10} \quad \omega^2 < \frac{8}{10} \quad \omega \leq \sqrt{0.8} \rightarrow \text{KOMPONENTA NE E ZNAČAJNA}$$

ZA: $\omega \leq 0.9$ SAMA PRVA DVA KOMPONENTI SE ZNAČAJE,



$B_{VF} = 4 f_m$

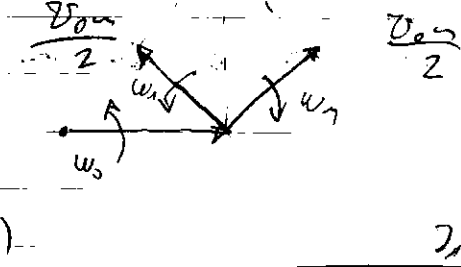
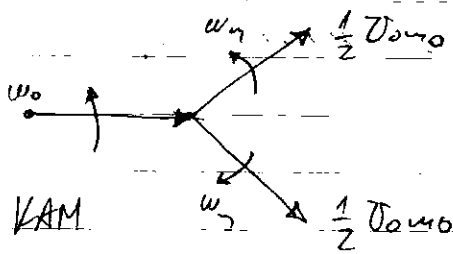
$$\frac{\sigma_0^2}{2L} > 100 \frac{\sigma_0^2}{2L} \left(\frac{\omega}{2}\right)^2 \quad \omega \leq \frac{2}{100} = \frac{1}{50} = 0.02$$



$$B_{VF} = 2 f_m$$

$$y(t) = \sigma_0 \cos(\omega_0 t) + \sigma_0 \sum_{n=1}^1 J_n(\omega) \left\{ \cos\left[(\omega_0 + n\omega)t + \frac{n\pi}{2}\right] + \cos\left[(\omega_0 - n\omega)t + \frac{n\pi}{2}\right] \right\}$$

$$= \sigma_0 \cos(\omega_0 t) + \sigma_0 J_1(\omega) \cos\left[(\omega_0 + \omega)t + \frac{\pi}{2}\right] + \sigma_0 J_1(\omega) \cos\left[(\omega_0 - \omega)t + \frac{\pi}{2}\right]$$



$$u(t) = U_0 \cos \omega_0 t + \frac{U_0 m}{2} \cos \left[(\omega_0 + \omega_m) t + \frac{\pi}{2} \right] + \frac{U_0 m}{2} \cos \left[(\omega_0 - \omega_m) t + \frac{\pi}{2} \right]$$

Enlargement of oscillation $\gamma = 0.3 = 0.4$

KAM: $[U_0 + \frac{U_0 m}{2} e^{j\omega_m t} + \frac{U_0 m}{2} e^{-j\omega_m t}] \cdot e^{j\omega_0 t}$

FM: $[U_0 \cos \left(\frac{U_0 m}{2} e^{j(\omega_m t + \frac{\pi}{2})} \right) \frac{U_0 m}{2} e^{-j(\omega_m t - \frac{\pi}{2})}] e^{j\omega_0 t}$

$$Z_0(\omega) = \frac{1}{2\pi} \int_0^{2\pi} e^{j\omega \cos \varphi} d\varphi$$

$$Z_1(\omega) = \frac{1}{T} \int_{-T/2}^{T/2} e^{j\omega \cos(\omega_0 t)} e^{-j\omega t} dt$$

$$Z_2(\omega) = \frac{1}{2\pi} \int_0^{2\pi} e^{j\omega \cos \varphi} e^{-j\omega \varphi} d\varphi$$

$$Z_3(\omega) = \frac{1}{T} \int_{-T/2}^{T/2} e^{j\omega \cos(\omega_0 t)} e^{-j\omega t} dt = \frac{1}{T} \frac{1}{\omega_0} \int_{-T/2}^{T/2} e^{j(\omega \cos(\omega_0 t) - \omega t)} d(\omega_0 t)$$

$\varphi = \omega_0 t$ $d\varphi = \omega_0 dt = 2\pi f dt = \frac{2\pi}{T} dt$ $dt = \frac{T}{2\pi} d\varphi$
 $t = \frac{T}{2}$ $\varphi = \frac{2\pi}{T} \cdot \frac{T}{2} = \pi$ $t = -\frac{T}{2}$ $\varphi = \frac{2\pi}{T} \cdot (-\frac{T}{2}) = -\pi$

$$Z_3(\omega) = \frac{1}{T} \frac{1}{2\pi f} \int_{-\pi}^{\pi} e^{j(\omega \cos \varphi - \omega \varphi)} d\varphi = \frac{1}{2\pi} \int_{-\pi}^{\pi} e^{j\omega \cos \varphi} e^{-j\omega \varphi} d\varphi$$

$$Z_3(\omega) = \frac{1}{2\pi} \int_{-\pi}^{\pi} e^{j\omega \cos \varphi} e^{-j\omega \varphi} d\varphi$$

$m > 1$ $Z_3(\omega) = \sqrt{\frac{2}{\pi m}} \cos \left(\omega - \frac{\omega \pi}{2} - \frac{\pi}{4} \right)$

$Z_3 > 0.1$ $Z_3 > 0.1$

$$\left[\frac{U_0 Z_3 > 0.1(\omega)}{2R} \right]^2 < 0.01 P_0$$

\Rightarrow $m+1$ harmonics 18V0 1.2620 as ω_0

$B_{VF} = 2(m+1) f_m$

at $m \rightarrow 1$ $B_{VF} = 2m f_m$

• Прямая огибающая ФМ

$$M_{FM} = U_0 \cos(\omega_0 t + k_f U_m \cdot \cos(\omega_m t))$$

$$\omega = k_f U_m$$

$$U_m \uparrow \Rightarrow \omega \uparrow$$

$$\Rightarrow B_{VF} = 2(m+1) \cdot f_{max}$$

$$B_{VF} = 2(m+1) \cdot f_{max}$$

• Прямая огибающая ФМ

$$\Delta f_0 = k_f \cdot U_m \quad \Delta \omega_0 = k_{\omega} U_m$$

$$M_{FM} = U_0 \cos(\omega_0 t + \frac{\Delta \omega_0}{\omega_m} \sin \omega_m t)$$

$$m = \frac{\Delta \omega_0}{\omega_m} = \frac{k_{\omega} U_m}{\omega_m}$$

$$B_{VF} = 2(m+1) f_m = 2 \left(\frac{\Delta f_0}{f_m} \cdot f_m + f_m \right) = 2(\Delta f_0 + f_m) = 2(k_f U_m + f_m)$$

$$B_{VF}^{FM} = 2(\Delta f_0 + f_m) \quad \text{в диапазоне } \Delta f_0 = 140 \text{ кГц}$$

• Следила следящая ФМ & ФМ

$$M(t) = U_0 \cos[\omega_0 t + m \cdot \cos(\omega_m t)] = U_0 \sum_{n=-\infty}^{\infty} J_n(m) \cdot \cos[(\omega_0 + n\omega_m)t + \frac{n\pi}{2}]$$

↳ огибающая ФМ

Парсеваля теорема: $P = \frac{1}{R} \sum_{n=-\infty}^{\infty} |F_n|^2$

$$[I_{eff} f(t)]^2 = \frac{1}{T} \int_{-T/2}^{T/2} f^2(t) dt = \sum_{n=-\infty}^{\infty} |F_n|^2$$

$$P = \frac{U_0^2}{2R} \sum_{n=-\infty}^{\infty} J_n^2(m) = P_0 \sum_{n=-\infty}^{\infty} J_n^2(m)$$

$$\sum_{n=-\infty}^{\infty} J_n^2(m) = 1 \quad \Rightarrow \text{всех модовая составляющая } P = P_0$$

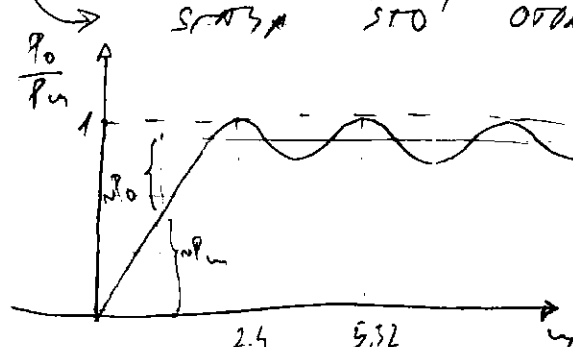
$$P_0 = P_m + \frac{U_0^2 J_0^2(m)}{2R} = P_m + P_0 \cdot J_0^2(m)$$

$$P_m = P_0 (1 - J_0^2(m))$$

$$\begin{matrix} m = 2.4 \\ m = 5.32 \\ m = \dots \end{matrix}$$

$$\begin{matrix} P_m = P_0 \\ P_m = P_0 \end{matrix}$$

результат согласен с теорией



$$\frac{P_m}{P_0} = 1 - J_0^2(m)$$

$$m \uparrow \Rightarrow P_m \uparrow$$

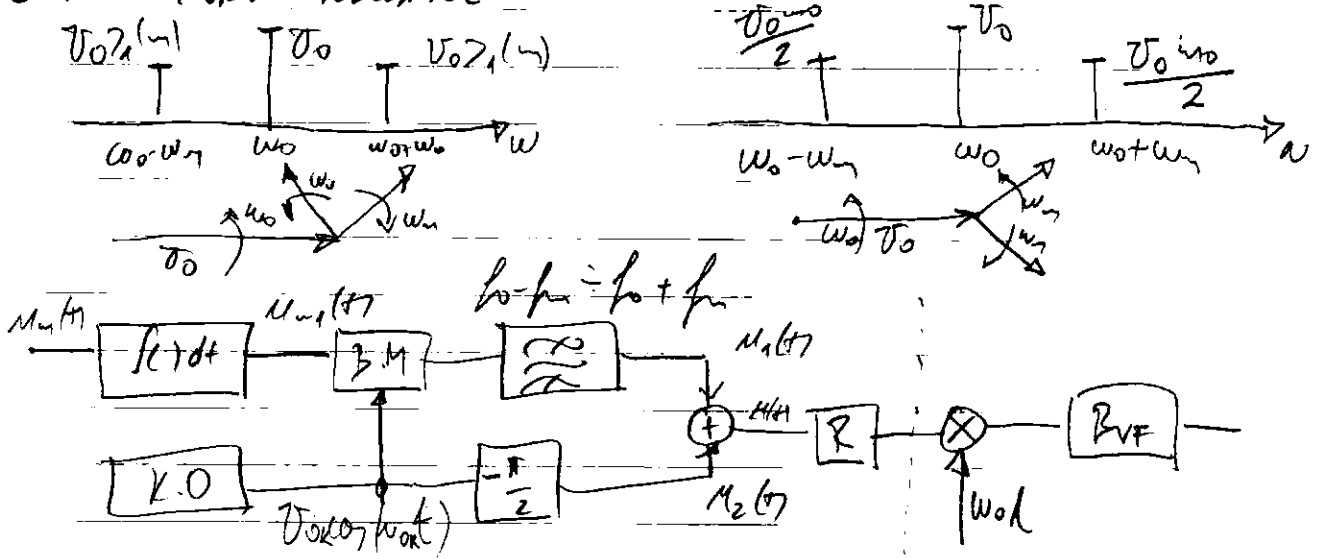
VAM $M(t) = U_0 (1 + m_0 \cos(\omega_m t)) \cos \omega_0 t = U_0 (1 + \frac{U_m}{U_0} \cos \omega_m t) \cos \omega_0 t$

$$= U_0 \cos \omega_0 t + \frac{U_0 U_m}{2R} \cos(\omega_0 - \omega_m)t + \frac{U_0 U_m}{2R} \cos(\omega_0 + \omega_m)t$$

$$P = \frac{U_0^2}{2R} + \frac{U_0^2 U_m^2}{4R} + \frac{U_0^2 U_m^2}{4R} = \frac{U_0^2}{2R} + \frac{U_0^2 U_m^2}{2R} = \frac{U_0^2}{2R} (1 + \frac{U_m^2}{2})$$

$$m_0 = 1 \quad \max(M(t)) = U_0 (1+1) = 2U_0 \quad P = \frac{4U_0^2}{2R} = 4P_0$$

① AMSTRONG'S MODULATOR



$$M_{FM}(t) = V_0 \cos \omega_0 t + \frac{\omega_m V_0}{2} \left\{ \cos \left[(\omega_0 - \omega_m)t + \frac{\pi}{2} \right] + \cos \left[(\omega_0 + \omega_m)t + \frac{\pi}{2} \right] \right\}$$

$$M_{AM}(t) = V_0 \cos \omega_0 t + \frac{\omega_m V_0}{2} \cos(\omega_0 - \omega_m)t + \frac{\omega_m V_0}{2} \cos(\omega_0 + \omega_m)t$$

$$M_1(t) = k_0 M_m(t) \cos(\omega_0 t) \quad | \quad M_m(t) = V_m \cdot \cos(\omega_m t)$$

$$M_2(t) = V_{0k} \sin(\omega_0 t)$$

$$M_{sum}(t) = \frac{1}{RC} \int M_m(t) dt = \frac{V_m}{RC \omega_m} \sin(\omega_m t) = \frac{V_{m1}}{\omega_m} \sin(\omega_m t) \quad V_{m1} = \frac{V_m}{RC} = k_2 V_m$$

$$M_1(t) = \frac{k_1 V_{m1}}{\omega_m} \sin(\omega_m t) = \frac{k V_m}{\cos(\omega_0 t) \omega_m} \sin(\omega_m t) \cdot \cos(\omega_0 t)$$

$$u(t) = V_{0k} \sin(\omega_0 t) + \frac{k V_m}{\omega_m} \sin(\omega_m t) \cos(\omega_0 t) = V(t) \sin(\omega_0 t + \varphi(t))$$

① $A \cos \alpha + B \sin \alpha = \sqrt{A^2 + B^2} \cdot \cos \left(\alpha + \arctan \frac{-B}{A} \right)$

$$A = C \cos \varphi$$

$$B = -C \sin \varphi$$

$$\varphi = \arctan \frac{-B}{A}$$

$$A^2 + B^2 = C^2 (\cos^2 \varphi + \sin^2 \varphi)$$

$$C \cos \varphi \cos \alpha - C \sin \varphi \sin \alpha = C \cos(\alpha + \varphi)$$

② $A \sin \alpha + B \cos \alpha = \sqrt{A^2 + B^2} \sin \left(\alpha + \arctan \frac{B}{A} \right)$

$$A = C \cos \varphi$$

$$B = C \sin \varphi$$

$$\varphi = \arctan \frac{B}{A}$$

$$A^2 + B^2 = C^2$$

$$C = \sqrt{A^2 + B^2}$$

$$C \cos \varphi \sin \alpha + C \sin \varphi \cos \alpha = C \sin(\alpha + \varphi)$$

$$V(t) = \sqrt{V_{0k}^2 + \left(\frac{k V_m}{\omega_m} \right)^2 \sin^2(\omega_m t)}$$

$$\varphi(t) = \arctan \frac{B}{A} = \arctan \left[\frac{\frac{k V_m}{\omega_m} \sin(\omega_m t)}{V_{0k}} \right] = \frac{\left(\frac{k V_m}{\omega_m} \right) \sin(\omega_m t)}{V_{0k}}$$

$$\varphi(t) = k_w \frac{V_m}{\omega_m} \sin(\omega_m t)$$

$$V(t) = V_{0k} \sqrt{1 + \left(\frac{k V_m}{V_{0k} \omega_m} \right)^2 \sin^2(\omega_m t)} \approx \left| \frac{k V_m}{\omega_m} \ll 1 \right| = V_{0k}$$

$$u(t) = \frac{\partial \phi}{\partial x} \sin \left[\omega_0 t + k_w \frac{v_m}{\omega_m} \sin(\omega_m t) \right] \Rightarrow \text{FM signal}$$

$$r \omega_i = r \omega_0 + r \delta \omega_i \quad \omega_i = \frac{d\phi_i}{dt} = \omega_0 + \frac{k_w v_m \cos(\omega_m t)}{\delta \omega_i}$$

$$r \omega_i = r \omega_0 + r \cdot k_w \cdot v_m \cdot \cos(\omega_m t) \quad \Delta \omega_{02} = r \cdot \Delta \omega_{01} \quad \omega_{02} = r \omega_{01}$$

$$m_1 = \frac{\Delta \omega_{01}}{\omega_{01}} \quad m_2 = \frac{\Delta \omega_{02}}{\omega_{02}} = r \cdot m_1$$

$$\left[\frac{k_w v_m}{\omega_{01}} \ll 1 \right] \Rightarrow \text{ΜΑΧΙΜΑΖΙΟΤ ΚΩΔΕΣ ΤΑ ΜΟΔΥΛΑΚΙΑ} \ll 1$$

$$\omega_{02} = r \cdot \omega_{01} \quad r \omega_{02} \oplus \omega_{01} = \omega_0 \quad \omega_0 = \omega_0 - r \omega_{02}$$

$$B_{FM} = 2(m+1) f_m$$

• ΔΑΔΕΛΟΥ ΝΕ ΕΙΣΡΟΔΕΤΟ $\omega_m \ll 1$

$$\phi(t) = \arctg \left[\frac{k_w v_m}{\omega_{0x}} \sin(\omega_m t) \right] = \arctg(\Delta \phi_{0x} \sin(\omega_m t))$$

$$\delta \omega_i = \frac{d\phi(t)}{dt} = \frac{\Delta \phi_{0x} \cdot \omega_m \cos(\omega_m t)}{1 + \Delta \phi_{0x}^2 \sin^2(\omega_m t)} = \sum_{n=-\infty}^{\infty} a_n \cos(n \omega_m t)$$

$$y = \arctg x \quad x = \tan y \quad \frac{dx}{dy} = \frac{\cos^2(y) - \sin^2(y)}{\cos^2(y)} = \frac{1}{\cos^2(y)}$$

$$= 1 + \tan^2(y) = 1 + x^2 \quad \frac{dx}{dy} = 1 + x^2 \quad \boxed{\frac{dy}{dx} = \frac{1}{1+x^2}}$$

$$a_n = \frac{2}{T} \int_{-T/2}^{T/2} f(t) \cdot \cos(n \omega_m t) dt \quad n=0,1,2, \dots$$

$$a_n = \frac{2}{T} \int_{-T/2}^{T/2} \delta \omega_i \cos(n \omega_m t) dt = \frac{2}{T} \int_{-T/2}^{T/2} \frac{\Delta \phi_{0x} \omega_m \cos(\omega_m t) \cos(n \omega_m t)}{1 + \Delta \phi_{0x}^2 \sin^2(\omega_m t)} dt$$

$$n=1 \quad a_1 = \frac{2 \Delta \phi_{0x} \omega_m}{T} \int_{-T/2}^{T/2} \frac{\cos^2(\omega_m t)}{1 + \Delta \phi_{0x}^2 \sin^2(\omega_m t)} dt$$

$$I = \omega_m \int_{-T/2}^{T/2} \frac{\cos^2(\omega_m t)}{1 + \Delta \phi_{0x}^2 \sin^2(\omega_m t)} dt = \left| \begin{array}{l} u = \omega_m t \\ du = \omega_m dt \\ t = \frac{T}{2} \quad u = \frac{2\pi \cdot \frac{T}{2}}{2} = \pi \\ t = -\frac{T}{2} \quad u = -\pi \end{array} \right.$$

$$I = \omega_m \int_{-\pi}^{\pi} \frac{\cos^2(u)}{1 + \Delta \phi_{0x}^2 \sin^2(u)} du = \frac{2\pi}{\Delta \phi_{0x}^2} (\sqrt{1 + \Delta \phi_{0x}^2} - 1)$$

$$a_1 = \frac{2 \Delta \phi_{0x}}{T} \cdot \frac{2\pi}{\Delta \phi_{0x}^2} (\sqrt{1 + \Delta \phi_{0x}^2} - 1) = \frac{4\pi}{T \Delta \phi_{0x}} (\sqrt{1 + \Delta \phi_{0x}^2} - 1)$$

$$A = \frac{1}{f_m} = \frac{1}{\omega_m / 2\pi} = \frac{2\pi}{\omega_m} \quad \boxed{a_1 = \frac{2 \omega_m}{\Delta \phi_{0x}} (\sqrt{1 + \Delta \phi_{0x}^2} - 1)}$$

$$S_{U_{12}} = \frac{2u_m}{\Delta \phi_{ox}} \left[\sqrt{1 + \Delta \phi_{ox}^2} - 1 \right] \cos(2\omega t) + \frac{2u_m}{\Delta \phi_{ox}} \left[\sqrt{1 + \Delta \phi_{ox}^2} - 1 \right]^3 \cos(6\omega t) + \dots$$

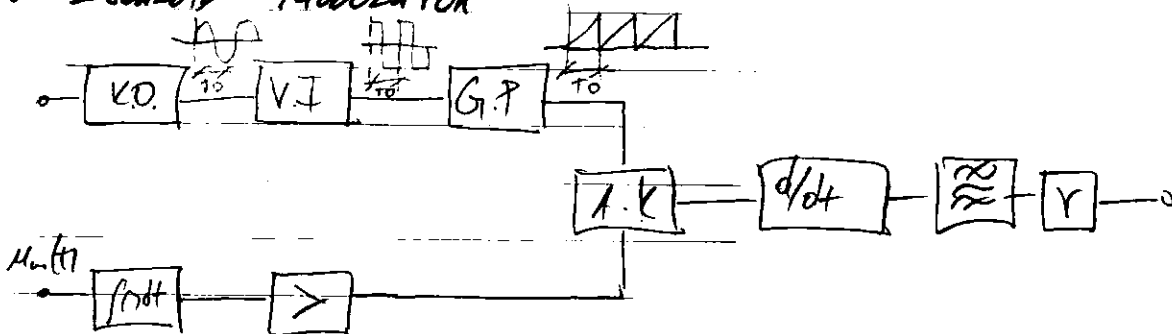
$$d_3 = \left(\frac{\Delta u_{12}}{\Delta u_{11}} \right)^2 = \left(\frac{\left[\sqrt{1 + \Delta \phi_{ox}^2} - 1 \right]^2}{\Delta \phi_{ox}^2} \right)^2 = \frac{\Delta \phi_{ox} = u_m < 1}{\sqrt{1 + \Delta \phi_{ox}^2} = 1 + \frac{\Delta \phi_{ox}^2}{2}}$$

$$d_3 = \left(\frac{\left(1 + \frac{\Delta \phi_{ox}^2}{2} - 1 \right)^2}{\Delta \phi_{ox}^2} \right)^2 = \left(\frac{\Delta \phi_{ox}^4}{4 \cdot \Delta \phi_{ox}^2} \right)^2 = \left(\frac{\Delta \phi_{ox}^2}{4} \right)^2$$

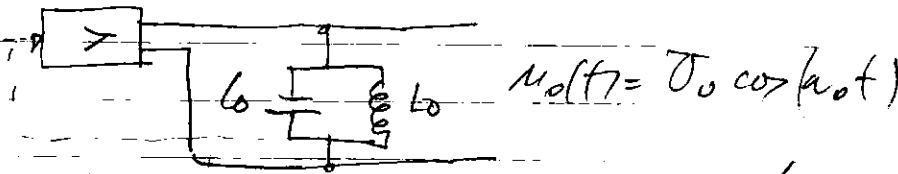
$$A_{d_3} = 10 \log \frac{1}{d_3} = 20 \log \frac{4}{\Delta \phi_{ox}^2} = 40 \log \frac{2}{\Delta \phi_{ox}}$$

$\Delta \phi_{ox} = u_m \uparrow \Rightarrow$ POZOLEMI MODULOVANJA

• SEMI-CONDUCTOR MODULATOR



• PRIMERNA KONTAKA ZA PODVARNJE FM SIGNALA



$$\omega_0 = \frac{1}{\sqrt{L_0 C_0}} ; \omega_n = \frac{1}{\sqrt{L_0 C(t)}} = \frac{1}{\sqrt{L_0 (C_0 + \delta C(t))}} = \frac{1}{\sqrt{L_0 C_0}} \frac{1}{\sqrt{1 + \frac{\delta C(t)}{C_0}}}$$

$$\frac{\delta C(t)}{C_0} \ll 1 ; f(t) = f(0) + \frac{f'(0)}{1!} \cdot x + \frac{f''(0)}{2!} \cdot x^2 + \dots$$

$$f(x) = \frac{1}{1+x} ; f(0) = 1 ; f'(x) = -\frac{1}{2} (1+x)^{-2} = -\frac{1}{2 \sqrt{1+x}}$$

$$f'(0) = -\frac{1}{2} ; \boxed{f(x) = 1 - \frac{1}{2} \cdot x}$$

$$\omega_n = \omega_0 \left(1 - \frac{1}{2} \frac{\delta C(t)}{C_0} \right) = \omega_0 - \frac{1}{2} \omega_0 \frac{\delta C(t)}{C_0} = \omega_0 + \delta \omega_n$$

$$\delta \omega_n = -\frac{1}{2} \omega_0 \frac{\delta C(t)}{C_0} \quad \text{" } C \uparrow \Rightarrow \omega \downarrow$$

$$\delta \omega_n = -\frac{1}{2} \frac{\omega_0}{C_0} \cdot \delta C(t) = -\frac{1}{2} \frac{\omega_0}{C_0} \cdot U_m \cdot u(t) \quad \Delta \omega_0 = -\frac{1}{2} \frac{\omega_0}{C_0} \cdot U_m$$

• PRIMERNA MODULATOR SO KONTAKTNI SLOJ

$$I = I_p + I_a = \frac{U}{R + \frac{1}{j\omega C}} + S U_g ; U_g = \frac{U R}{R + \frac{1}{j\omega C}}$$

$$Y = \frac{I}{U} = \frac{1}{R + \frac{1}{j\omega C}} + \frac{SR}{R + \frac{1}{j\omega C}} = \frac{1 + SR}{R + \frac{1}{j\omega C}} \quad Z = Y^{-1}$$

$$Z = \frac{R}{1 + SR} + \frac{1}{j\omega C(1 + SR)} = R_e + \frac{1}{j\omega C_e}$$

- $SR \gg 1 \quad R_e = \frac{1}{S} \quad C_e = SR C \quad s(t) = s_0 + \delta s(t)$

$\delta s(t) = k M_m(t) \quad C_e = RC s_0 + RC \delta s(t) = RC s_0 + RC k M_m(t)$

AA' $C = \underbrace{C_0 + RC s_0}_{C_{stat}} + \underbrace{RC k M_m(t)}_{\delta C(t)}$

$$\omega_0 = \frac{1}{\sqrt{L_0(C_0 + RC s_0)}} \quad \omega_a = \omega_0 + \delta \omega_a = \omega_0 - \frac{1}{Z} \omega_0 \frac{RC k M_m(t)}{C_0 + RC s_0}$$

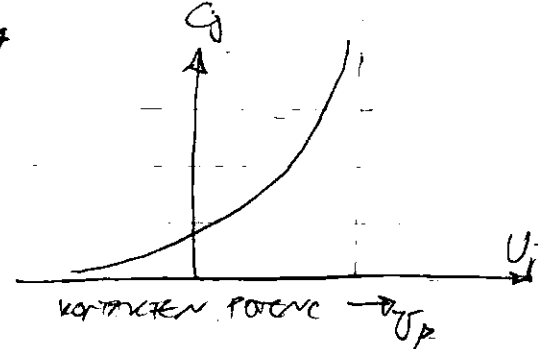
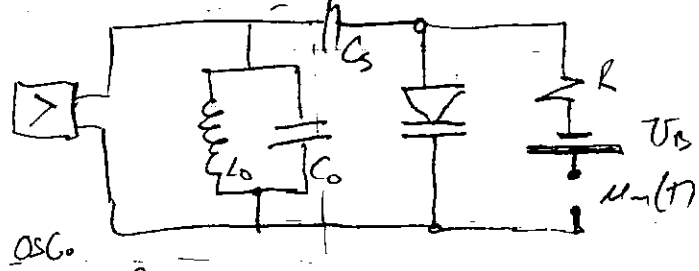
$$\omega_a = \frac{1}{\sqrt{L_0(C_0 + RC s_0 + RC k M_m(t))}} = \frac{1}{\sqrt{L_0(C_0 + RC s_0)}} \frac{1}{\sqrt{1 + \frac{RC k M_m(t)}{C_0 + RC s_0}}}$$

$$\omega_a = \omega_0 \left(1 - \frac{1}{Z} \frac{RC k M_m(t)}{C_0 + RC s_0} \right) = \omega_0 - \underbrace{\frac{\omega_0}{Z} \frac{RC k M_m(t)}{C_0 + RC s_0}}_{\delta \omega_a}$$

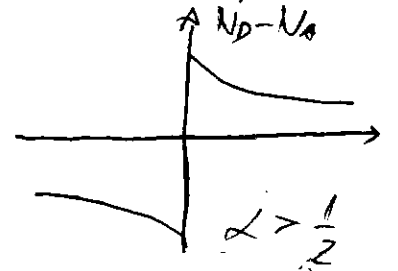
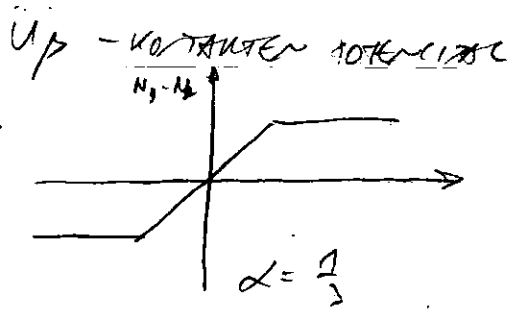
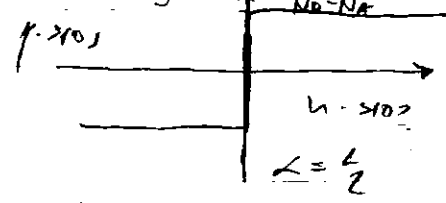
$$\delta \omega_a = - \frac{\omega_0}{Z} \frac{RC k M_m(t)}{C_0 + RC s_0} \cdot v(t)$$

$$M_m(t) = \sigma_0 \cos(\omega_0 t + \int k M_m(t) dt)$$

• FM MODULATOR SO VARICAP DIODA



$$C_j = \frac{C_k}{(U_p - U_j)^\alpha}$$



• $M_m(t) = \sigma$

$$C_{p0} = \frac{C_k}{(U_p - U_b)^\alpha} = C_k U_b^{-\alpha}$$

$$U_b = U_p - U_b$$

$$M_j = U_b - U_m(t)$$

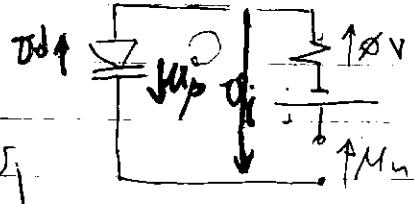
$$U = U_p - M_j = U_b + U_m(t)$$

$$C_j = \frac{C_k}{(U_p - U_j)^\alpha} = \frac{C_k}{(U_b + U_m(t))^\alpha}$$

$$C_j = C_k [U_b + U_m(t)]^{-\alpha} \quad C_{stat} = C_0 + C_j \quad C_j \gg C_0 \quad C_{stat} \approx C_j$$

$$\omega_i = \frac{1}{(L_0 C_0)^{1/2}} = (L_0 C_0)^{-1/2} = \frac{L_0^{-1/2} C_0^{-1/2}}{L_0^{1/2} C_0^{1/2}} [\overline{V}_0 + M_n(t)]^{1/2} = k [\overline{V}_0 + M_n(t)]^{1/2}$$

$$C_{j0} = k \cdot \overline{V}_0 \quad \omega_0 = (L_0 C_0)^{-1/2} = L_0^{-1/2} C_0^{-1/2} \cdot \overline{V}_0^{1/2} = k \overline{V}_0^{1/2}$$



$$V_D = V_p - V_j$$

$$M_p + 0V - V_D + M_n = V_p - V_D + M_n$$

$$C_j = \frac{C_0}{V_p - M_n} \quad M_j = +V_D - M_n$$

$$C_j = \frac{C_0}{M_p - V_D + M_n(t)} = \frac{C_0}{\overline{V}_0 + M_n}$$

$$\delta\omega_i = \omega_i - \omega_0 = k [\overline{V}_0 + M_n(t)]^{1/2} - k \overline{V}_0^{1/2} = k \left\{ [\overline{V}_0 + M_n(t)]^{1/2} - \overline{V}_0^{1/2} \right\}$$

$$(a+b)^n = \binom{n}{0} a^n + \binom{n}{1} a^{n-1} b + \binom{n}{2} a^{n-2} b^2 + \dots + \binom{n}{n-1} a b^{n-1} + \binom{n}{n} b^n$$

$$\delta\omega_i = k \left\{ \binom{1/2}{0} \overline{V}_0^{1/2} - \overline{V}_0^{1/2} + \binom{1/2}{1} \overline{V}_0^{-1/2} M_n + \binom{1/2}{2} \overline{V}_0^{-3/2} M_n^2 + \dots \right\}$$

$$\binom{n}{k} = \frac{n!}{k!(n-k)!} = \frac{n \cdot (n-1) \cdot (n-2) \cdot \dots \cdot (n-k+1)}{k!}$$

$$\binom{1/2}{0} = \frac{1!}{0!1!} = 1; \quad \binom{1/2}{1} = \frac{1/2}{1} = \frac{1}{2}; \quad \binom{1/2}{2} = \frac{1/2 \cdot (1/2 - 1)}{2} = \frac{1}{4} \left(\frac{1}{2} - 1 \right)$$

$$\delta\omega_i = k \left\{ \overline{V}_0^{1/2} - \overline{V}_0^{1/2} + \frac{1}{2} \overline{V}_0^{-1/2} M_n + \frac{1}{4} \left(\frac{1}{2} - 1 \right) \overline{V}_0^{-3/2} M_n^2 + \dots \right\}$$

$$\binom{1/2}{1} = \frac{1/2}{(1/2 - 1)!} = \frac{1/2}{1} = \frac{1}{2}; \quad \binom{n}{1} = \frac{n!}{(n-1)!} = \frac{n \cdot (n-1) \cdot \dots \cdot 1}{1 \cdot \dots \cdot (n-1)} = n$$

$$\binom{1/2}{2} = \frac{1/2 \cdot (1/2 - 1)}{2! \cdot (1/2 - 2)!} = \frac{1}{2} \cdot \left(\frac{1}{2} - 1 \right) \cdot \frac{1}{2}$$

$$\delta\omega_i = k \left\{ \frac{1}{2} \overline{V}_0^{-1/2} M_n(t) + \frac{1}{4} \left(\frac{1}{2} - 1 \right) \overline{V}_0^{-3/2} M_n^2 + \dots \right\}$$

$$\alpha = 2 \quad \delta\omega_i = k \left\{ \frac{2}{2} \overline{V}_0^0 \cdot M_n(t) + 0 \right\} = k M_n(t) = k \omega_i M_n(t)$$

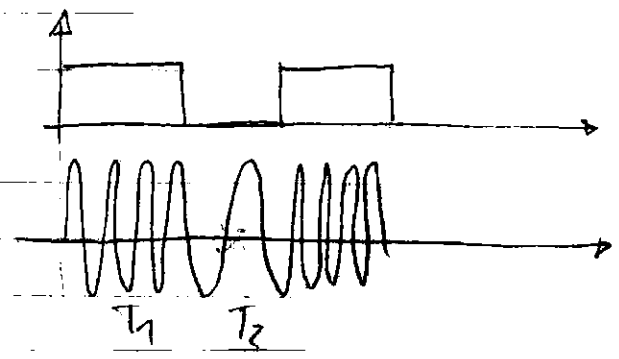
• DEVENČIA NA FM SĽAŽKI

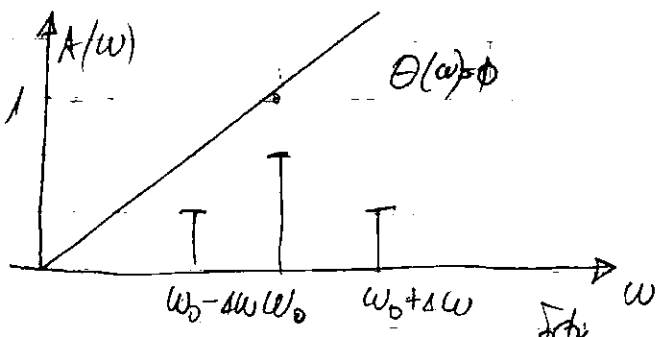
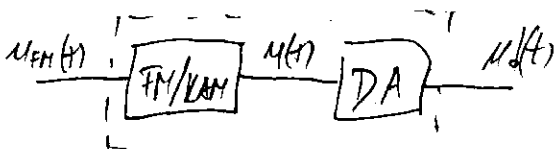
$$M_p(t) = k_0 \delta\omega_i$$

• BLOKNA ČA KLENKI

$$T_1 = \frac{1}{f_0 + \Delta f} \quad T_2 = \frac{1}{f_0 - \Delta f}$$

254 (DIGITÁLNA MODULÁCIA) SĽAŽKI





$\omega_0 \rightarrow U_0$
 $\omega_0 + \Delta\omega \rightarrow U_0 A(\omega_0 + \Delta\omega)$
 $\omega_0 - \Delta\omega \rightarrow U_0 A(\omega_0 - \Delta\omega)$

- идеален свик

$$U = U_0 + D \Delta\omega_A$$

$$M(t) = (U_0 + D \Delta\omega_A) \cos[\omega_0 t + K_w \int M_m(t) dt]$$

$$M_A(t) = U_0 \left(1 + \frac{D \Delta\omega_A}{U_0} \right)$$

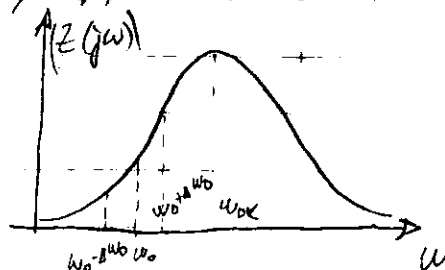
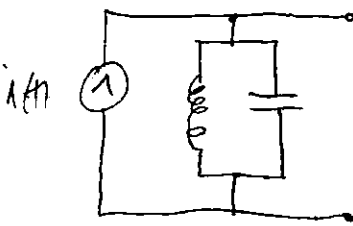
$$\Delta\omega_A = \frac{d \Delta\phi_A}{dt} = K_w M_m(t)$$

$$M_A(t) = U_0 \left(1 + \frac{D K_w M_m(t)}{U_0} \right) = U_0 \left(1 + \frac{D K_w U_m}{U_0} m(t) \right)$$

$$U_0 = \frac{D K_w U_m}{U_0} \quad M_A = U_0 (1 + k_{FM} m(t))$$

$$u_d(t) = K_d \cdot \Delta\omega_A = K_d K_w \cdot M_m(t) = K_d M_m(t)$$

• РЕАЛИЗАЦИЯ НА FM/KAM УОРВЕРСОДЕЛ



$$f_0 \gg 2\Delta f_0$$

$$i(t) = I(t) \cos(\omega_0 t + K_w \int m(t) dt) = I_0 \cos(\omega_0 t + \varphi)$$

$$i(t) = I_0 \cos(\omega_0 t + \varphi) \xrightarrow{\text{COMPLEX PLAYS}} I(t) = I_0 e^{j(\omega_0 t + \varphi)} \quad I(j\omega) = \mathcal{F}\{I(t)\}$$

$$\omega_s = \omega_0 + \frac{d\varphi}{dt} = \omega_0 + \varphi'(t) \quad \Delta\omega_s = \frac{d\varphi(t)}{dt} = \varphi'(t)$$

$$Z(j\omega) = Z(j\omega_0) + \frac{Z'(j\omega_0)}{1!} \cdot j(\omega - \omega_0) + \frac{Z''(j\omega_0)}{2!} j^2(\omega - \omega_0)^2 + \dots$$

$$\mathcal{F}\{f(t)\} = j\omega F(j\omega) \quad F(j\omega) = \int_{-\infty}^{\infty} f(t) e^{-j\omega t} dt$$

$$f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(j\omega) e^{j\omega t} d\omega$$

$$f'(t) = \frac{1}{2\pi} j\omega \int_{-\infty}^{\infty} F(j\omega) e^{j\omega t} d\omega = j\omega \frac{1}{2\pi} \int_{-\infty}^{\infty} F(j\omega) e^{j\omega t} d\omega$$

~~$$f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(j\omega) e^{j\omega t} d\omega$$

$$f'(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} j\omega F(j\omega) e^{j\omega t} d\omega$$~~

$$\mathcal{F}\{f'(t)\} = j\omega \cdot F(j\omega)$$

$$\mathcal{F}\left\{\int_{-\infty}^x f(x) dx\right\} = (*)$$

$$f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(j\omega) e^{j\omega t} d\omega$$

$$\frac{1}{2\pi} \int_{-\infty}^x \left(\int_{-\infty}^{\alpha} F(j\omega) e^{j\omega x} d\omega \right) dx = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(j\omega) d\omega \int_{-\infty}^x e^{j\omega x} dx$$

$$I = \int_{-\infty}^x e^{j\omega x} dx = \frac{1}{j\omega} \int_{-\infty}^x d(e^{j\omega x}) = \frac{1}{j\omega} e^{j\omega x} \Big|_{-\infty}^x = \frac{1}{j\omega} (e^{j\omega x} - 0)$$

$$I = \frac{e^{j\omega x}}{j\omega}; (*) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(j\omega) \frac{e^{j\omega t}}{j\omega} d\omega = \frac{1}{j\omega} F(j\omega)$$

kontakt@centar@stb.com.mk

MARINA VEZICKOVA

OPREMA OD 17001 ZA VOJNE TRANSMISORNE SURETKE.

$$I(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} I(j\omega) e^{j\omega t} d\omega; I_1(t) = I'(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} j\omega I(j\omega) e^{j\omega t} d\omega$$

$$I_1(t) = \frac{dI(t)}{dt}$$

$$I(t) = I_0 e^{j\omega_0 t + \varphi(t)}$$

$$U(t) = \left[Z(j\omega_0) + \frac{Z'(j\omega_0)}{1!} \left(\frac{d}{dt} - j\omega_0 \right) + \frac{Z''(j\omega_0)}{2!} \left(\frac{d}{dt} - j\omega_0 \right)^2 + \dots \right] I_0 e^{j(\omega_0 t + \varphi(t))}$$

$$U(t) = \mathcal{F}^{-1}\{Z(j\omega) \cdot I(j\omega)\}$$

$$\left(\frac{d}{dt} - j\omega_0 \right) e^{j(\omega_0 t + \varphi(t))} = (j\omega_0 + \varphi'(t) - j\omega_0) e^{j(\omega_0 t + \varphi(t))} = j\varphi'(t) e^{j(\omega_0 t + \varphi(t))}$$

$$\left(\frac{d}{dt} - j\omega_0 \right)^2 e^{j(\omega_0 t + \varphi(t))} = \left(\frac{d}{dt} - j\omega_0 \right) j\varphi'(t) e^{j(\omega_0 t + \varphi(t))} = j[\varphi''(t) - \varphi'^2(t)] e^{j(\omega_0 t + \varphi(t))}$$

$$= j[\varphi''(t) \cdot e^{jx} + \varphi'(t) [j\omega_0 \varphi'(t)] e^{jx} - j\omega_0 e^{jx} \varphi'(t)] =$$

$$= j[\varphi'' + \cancel{j\omega_0 \varphi'} + j\omega_0 \varphi' + j\varphi'^2 - j\omega_0 \varphi'] e^{j(\omega_0 t + \varphi(t))}$$

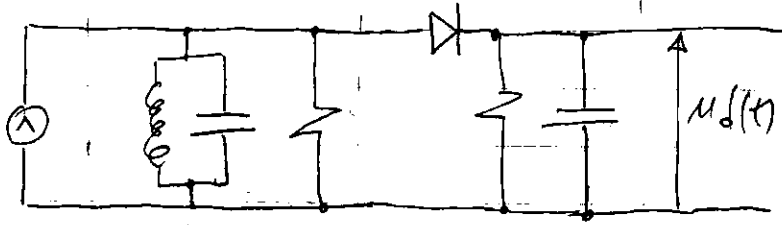
$$= [j\varphi''(t) - \varphi'^2(t)] e^{j(\omega_0 t + \varphi(t))}$$

$$U(t) = \left\{ Z(j\omega_0) + Z'(j\omega_0) j\varphi' + \frac{Z''(j\omega_0)}{2} [j\varphi''(t) - \varphi'^2(t)] \right\} I_0 e^{j(\omega_0 t + \varphi(t))}$$

$Z'', Z'' \rightarrow 0$

$$u(t) = (a + b \cdot \delta u_i) I_0 e^{j(\omega_0 t + \varphi(t))}$$

• КОМПЛЕКСНЫЙ ДЕТЕРМИНАНТ НА ФМ С ЧАСТИ



$$\frac{1}{Z(j\omega)} = \frac{1}{j\omega L} + \frac{1}{R} + j\omega C$$

↳ ИМПЕДАНСА НА ОК

FM/KAM КОМПЛЕКСИЗМА
СТАЦИОНАРЕН РЕЖИМ:
 $\omega_c = \frac{1}{\sqrt{LC}}$

D.A.
 $L = 2C \cdot R^2$ $|U| = |Z(j\omega)| \cdot |I|$
 $Z(j\omega) = \frac{R + j\omega L + \omega^2 CLR}{j\omega LR}$

$$Z(j\omega) = \frac{j\omega LR}{(R - \omega^2 LC) + j\omega L}$$

$$|Z| = \frac{WLR}{\sqrt{(R - W^2LC)^2 + W^2L^2}}$$

$$|Z| = \frac{WLR}{\sqrt{R^2(1 - W^2LC)^2 + W^2L^2}}$$

$$= \frac{WLR}{\sqrt{1 - 2W^2LC + W^4L^2C^2 + \frac{W^2L^2}{R^2}}}$$

$$|Z| = \frac{WLR}{\sqrt{R^2(1 - 2W^2LC + W^4L^2C^2) + W^2L^2}}$$

$$= \frac{WL}{\sqrt{1 + W^4L^2C^2}}$$

$$|Z| = \frac{WL}{\sqrt{1 + \frac{W^4}{W_c^4}}}$$

$\left(\frac{W}{W_c}\right) < 1$
 $Z(j\omega) \approx WL \left(1 - \frac{W^4}{2W_c^4}\right) = A(W)$
 $A(W) = L \left(W - \frac{W^5}{2W_c^4}\right)$

$$\delta W_i = W_i \cdot U_{in} \cos \omega t$$

$$W_i = W(t) = W_0 + \delta W$$

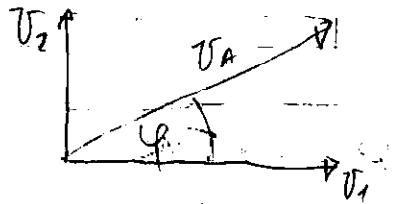
$$\delta W_i = W_i - W_0 = W(t) - W_0$$

$$A(W) = A(W_0) + \frac{A'(W_0)}{1!} \delta W_i + \frac{A''(W_0)}{2!} \delta W_i^2 + \frac{A'''(W_0)}{3!} \delta W_i^3 + \dots$$

$$|Z(j\omega)| = L \left(W_0 - \frac{W_0^5}{2W_c^4}\right) + L \left(1 - \frac{5}{2} \frac{W_0^4}{W_c^4}\right) \cdot \delta W_i - \frac{L}{2} \cdot 10 \frac{W_0^3}{W_c^4} \cdot \delta W_i^2 - \frac{30L}{3!} \frac{W_0^2}{W_c^4} \cdot \delta W_i^3 - \dots$$

$$|U| \approx U_d(t) = I \cdot L \left\{ \left(W_0 - \frac{W_0^5}{2W_c^4}\right) + \left(1 - \frac{5}{2} \frac{W_0^4}{W_c^4}\right) \cdot W_0 U_{in} \cos(\omega t) - \frac{10}{2!} \frac{W_0^3}{W_c^4} (W_0 U_{in})^2 \cos^2(\omega t) - \frac{30}{3!} \frac{W_0^2}{W_c^4} (W_0 U_{in})^3 \cos^3(\omega t) - \dots \right\}$$

• ФОРМА СИГНАЛА ПИСКЛИМА АВДЕ



$$U_A = U_1 \cos \omega t + U_2 \sin \omega t$$

$$U_1 = U_A \cos \varphi \quad \varphi = \arctg \frac{U_2}{U_1}$$

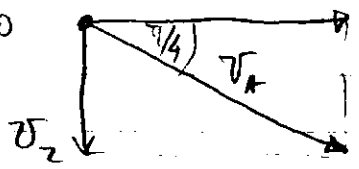
$$U_2 = -U_A \sin \varphi$$

$$U_A = U_1 (\cos \omega t - \cos \varphi - \sin \omega t \sin \varphi) = U_1 \cos(\omega t + \varphi)$$

АКО: $U_1 = U_2 \Rightarrow \varphi = \arctg(-1) \quad \text{tg } \varphi = -1 \quad \left(\varphi = -\frac{\pi}{4}\right)$

$$U_A = U_1 \cos\left(\omega t - \frac{\pi}{4}\right)$$

РЕЗУЛТО



$$U_A = \sqrt{U_1^2 + U_2^2}$$

• Dönüş S(N) için FM, FM sığırzı

QTS 200777



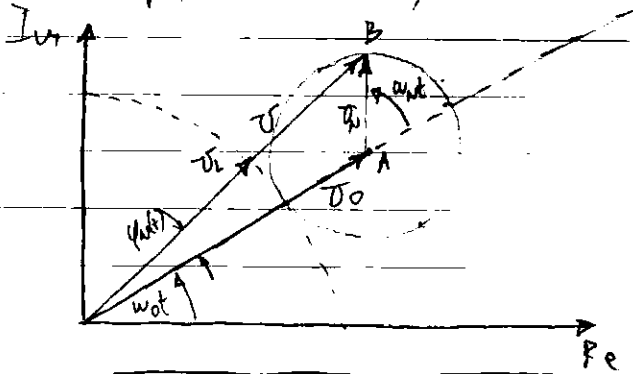
• NA VLEK NEBOLUCUKAN KONTEZ + 1 PA PLEKKA

$$u(t) = U_0 \cos \omega_0 t + U_N \cos(\omega_0 + \omega_N)t = U_0 \cos \omega_0 t + U_N \cos \omega_0 t \cdot \cos \omega_N t - U_N \sin \omega_0 t \cdot \sin \omega_N t = \underbrace{(U_0 + U_N \cos \omega_N t)}_A \cos \omega_0 t - \underbrace{U_N \sin \omega_0 t \sin \omega_N t}_B$$

$$A = C \cdot \cos \varphi_N \quad C = \sqrt{A^2 + B^2}$$

$$B = C \cdot \sin \varphi_N \quad \varphi_N = \arctan \frac{B}{A} = \arctan \frac{U_N \sin \omega_N t}{U_0 + U_N \cos \omega_N t}$$

$$u(t) = \sqrt{(U_0 + U_N \cos \omega_N t)^2 + U_N^2 \sin^2 \omega_N t} \cdot \cos(\omega_0 t + \varphi_N)$$



$$U(t) = \sqrt{U_0^2 + 2U_0 U_N \cos \omega_N t + U_N^2 \cos^2 \omega_N t + U_N^2 \sin^2 \omega_N t}$$

$$= U_0 \sqrt{1 + \frac{2U_0 U_N \cos \omega_N t}{U_0} + \frac{U_N^2}{U_0^2}}$$

LIMITA $\Rightarrow U(t) = U_{LO} \quad u(t) = U_{LO} \cdot \cos(\omega_0 t + \varphi_N)$

$$U_0 \gg U_N \quad \arctan \frac{U_N \sin \omega_N t}{U_0 + U_N \cos \omega_N t} \approx \frac{U_N}{U_0} \sin \omega_N t$$

$$u(t) = U_{LO} \cos(\omega_0 t + \frac{U_N}{U_0} \sin \omega_N t)$$

INDEX NA MODULASYON

$$m_0 = \frac{U_N}{U_0}$$

$$u_{FM} = D_f \cdot \delta f_i \quad D_w \delta \omega_i = D_w \cdot \frac{U_N}{U_0} \cos(\omega_N t) = \left(D_f \cdot \frac{U_N}{U_0} f_N \right) \cos(\omega_N t)$$

$$u_{FM} = D_\phi \cdot \delta \phi_i = D_\phi \cdot \frac{U_N}{U_0} \sin \omega_N t$$

• SIRA SIRA NA SIRA NA 1200777 FM K...



$$u(t) = D_f \cdot \delta f_i$$

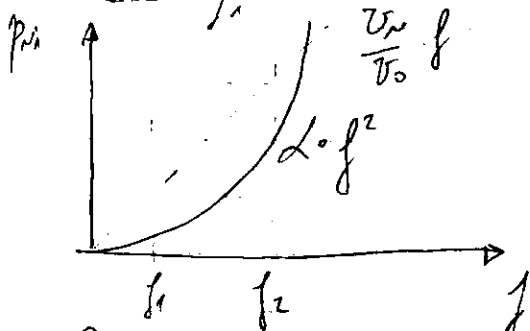
$$\delta f_{FM} = \frac{U_N}{U_0} f_N \cos(\omega_N t + \varphi_N) \quad P_{FM} = 2 P_F^2 \frac{U_N^2}{U_0^2} f_N^2$$

$$P_{FM} = 2 P_F^2 \frac{1}{P_0} f_N^2 \quad \text{REDUKCJA NA SIRA NA SIRA NA SUM}$$

$$P_{FM} \rightarrow \delta P_{FM} = \text{KRT. OF} \quad P_{FF} = P_F^2$$

$$dP_{in} = 2D_{eff} \frac{FKT}{P_0} f^2 df$$

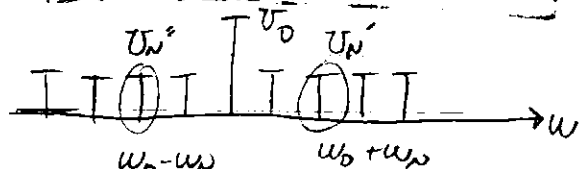
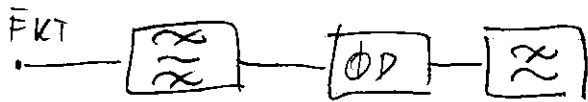
$$P_{in} = \int_{f_1}^{f_2} p_{in} df = 2D_{eff} \frac{FKT}{P_0} \int_{f_1}^{f_2} f^2 df$$



$$P_{in} = 2D_{eff} \frac{FKT}{P_0} f^2 = L f^2$$

$$\int_{f_1}^{f_2} f^2 df = 2D_{eff} \frac{FKT}{P_0} \frac{f^3}{3} \Big|_{f_1}^{f_2}$$

• Sledra srazu na sum na kcez od Φ_M Φ_X



$$\delta\phi_n = \frac{v_n}{v_0} \cos \omega t = \Delta\phi_n \cos \omega t \quad M(t) = D_0 \frac{v_n}{v_0}$$

$$\delta\phi_n' = \frac{v_n'}{v_0} \cos(\omega t + \phi_n)$$

$$\delta\phi_n'' = \frac{v_n''}{v_0} \cos(\omega t + \phi_n)$$

$$\Delta P_{in} \sim (v_n')^2$$

$$\Delta P_{in} \sim (v_n'')^2$$

$$\Delta P_{in} \sim \left(D_0 \frac{v_n'}{v_0} \right)^2$$

$$\Delta P_{in} \sim \left(D_0 \frac{v_n''}{v_0} \right)^2$$

$$\Delta P_{in} = \Delta P_{in}' + \Delta P_{in}''$$

$$\Delta P_{in} = \frac{D_0^2}{v_0^2} (v_n'^2 + v_n''^2) = D_{eff} \left(\frac{P_{in}'}{P_0} + \frac{P_{in}''}{P_0} \right)$$

$$dP_{in} = FKT df$$

$$dP_{in} = D_{eff} \frac{FKT}{P_0} df$$

$$\Delta P_{in} = 2D_{eff} \Delta P_{in}$$

$$\Delta P_{in} = D_{eff} \frac{FKT}{P_0} df$$

$$P_{in} = FKT$$

$$dP_{in} = 2D_{eff} \frac{FKT}{P_0} df = p_{in} df$$

$$P_{in} = p_{in} \cdot BNF$$

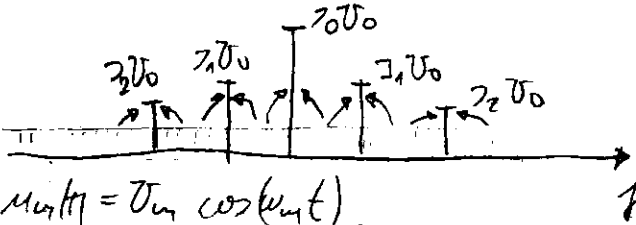
$$P_{in} = \int_{f_1}^{f_2} 2D_{eff} \frac{FKT}{P_0} df = 2D_{eff} \frac{FKT}{P_0} (f_2 - f_1)$$

$$P_{in} = FKT \cdot BNF$$

$$P_{in} = 2D_{eff} \frac{FKT}{P_0} \cdot BNF$$

• SUM NA IZKAZ OD KJENIKOT VO MISCANO NA SIGMA.

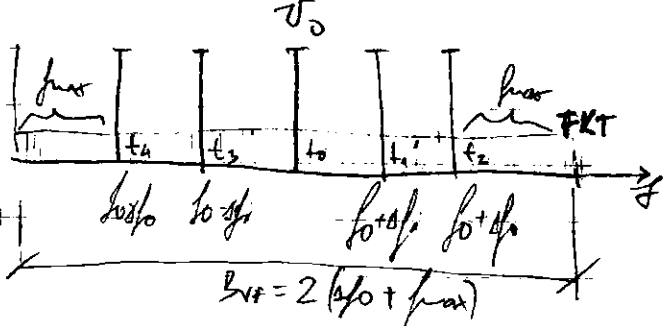
$$M(t) = v_m \cos \omega t$$



$$M(t) = v_m \cos \omega t$$

$$M(t) = -v_m \rightarrow f_0 \text{ sto}$$

$$M(t) = 0 \rightarrow f_0 + f_0$$



$$P_{sv} = P_0$$

$$P_{NL} = FKT \cdot P_{VF} = P_{NV}$$

$$\left(\frac{S}{N}\right) = \frac{P_{sv}}{P_{NL}} = \frac{P_0}{FKT \cdot P_{VF}}$$

$$\left(\frac{S}{N}\right)_i = ?$$

$$\Delta \phi_{os} = k_p U_m \quad U_i = D_F \Delta \phi_{os} \quad M_{di}(t) = D_F \delta \phi_i$$

$$M_{di}(t) = D_F \Delta \phi_{os} \cos \omega_m t \quad P_{si} \sim D_F^2 \Delta \phi_{os}^2 = P_{sv} \Delta \phi_{os}^2$$

$$P_{si} = D_F^2 \frac{FKT}{P_0}$$

$$P_{ni} = 2 D_F^2 \frac{FKT}{P_0} P_{VF}$$

$$\frac{P_{si}}{P_{ni}} = \frac{D_F^2 \Delta \phi_{os}^2}{2 D_F^2 \frac{FKT}{P_0} P_{VF}} = \frac{\Delta \phi_{os}^2}{2} \cdot \frac{P_0 \cdot P_{VF}}{(FKT \cdot P_{VF}) P_{NV}} = \frac{\Delta \phi_{os}^2}{2} \frac{P_{VF}}{P_{NV}} \cdot \frac{P_0}{P_{NV}}$$

$$\frac{P_{si}}{P_{ni}} = \frac{\Delta \phi_{os}^2}{2} \frac{P_{VF}}{P_{NV}} \frac{P_0}{P_{NV}}$$

$$\left(\frac{S}{N}\right)_i = \frac{\Delta \phi_{os}^2}{2} \frac{P_{VF}}{P_{NV}} \frac{P_0}{P_{NV}} = \frac{\Delta \phi_{os}^2}{2} \frac{P_{VF}}{P_{NV}}$$

• Ako se zrači samo P_{NL} uva uopisna rje NF FKT =

$$\frac{P_{si}}{P_{ni}} = \frac{\Delta \phi_{os}^2}{2} \frac{P_0 \cdot P_{VF}}{(FKT \cdot P_{VF}) P_{NV}} = \Delta \phi_{os}^2 \frac{P_0}{P_{NV}} = \Delta \phi_{os}^2 \frac{P_{sv}}{P_{NV}}$$

$$P_{ni} = 2 FKT \cdot P_{VF}$$

$$\left(\frac{S}{N}\right)_i^{FM} = ? \quad \delta f_i = \Delta f_{os} \cos \omega_m t = v_f U_m \quad M_{di}(t) = D_F \delta f_i$$

$$M_{di}(t) = D_F \Delta f_{os} \cos \omega_m t$$

$$P_{si} = D_F^2 \Delta f_{os}^2 = D_F^2 \Delta^2 f_{os}$$

$$P_{ni} = 2 D_F^2 \frac{FKT}{P_0} \int_{f_1}^{f_2} f^2 df$$

$$\frac{P_{si}}{P_{ni}} = \frac{D_F^2 \Delta^2 f_{os}}{2 D_F^2 \frac{FKT}{P_0} \int_{f_1}^{f_2} f^2 df}$$

$$\frac{P_{si}}{P_{ni}} = \frac{\Delta^2 f_{os} P_{VF}}{2 \int_{f_1}^{f_2} f^2 df} \cdot \frac{P_0}{P_{NV}}$$

$$\left(\frac{S}{N}\right)_i = \frac{\Delta^2 f_{os} P_{VF}}{2 \int_{f_1}^{f_2} f^2 df}$$

• Praz na ulazu na sistemu za FM

$$B_{VF} = 2(\Delta f_{os} + f_c) \quad P_{NL} = FKT \cdot P_{VF}$$

SUM: $20 \log \frac{U_m}{U_{eff}} = 13 \text{ dB}$ $PR: 20 \log \frac{U_m}{U_{eff}} = 30 \text{ dB}$

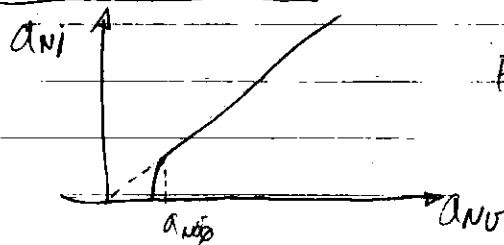
$$10 \log \frac{P_{si}}{P_{ni}} = 10 \log \frac{\Delta f_{os}^2 P_{VF}}{2 \int_{f_1}^{f_2} f^2 df} + 10 \log \frac{P_{sv}}{P_{NL}} = V + a_{NV}$$

$$a_{NV} = V + a_{NV}$$

V - faktor na porobnacu na S/N

a_{NV0} - gub na ulazu

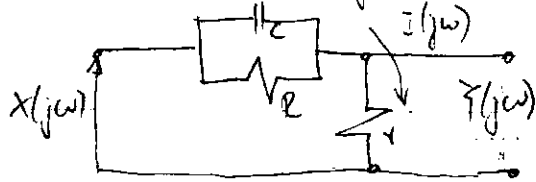
$$FM: a_{NV0} = 10 \text{ dB} \quad t.e. P_0 = 10 P_{NL}$$



• PODOBNAVAŽE NA S/N SO PREDPIS, DECENTPIS



• Klasično $H_p(jw)$ za MOTRIKI SIGNALI



$$Y(jw) = r \cdot I(jw)$$

$$H_p(jw) = \frac{Y(jw)}{X(jw)}$$

$$I(jw) = \frac{X(jw)}{R + \frac{1}{jwC}}$$

$$Y(jw) = \frac{r X(jw)}{R + \frac{1}{jwC}}$$

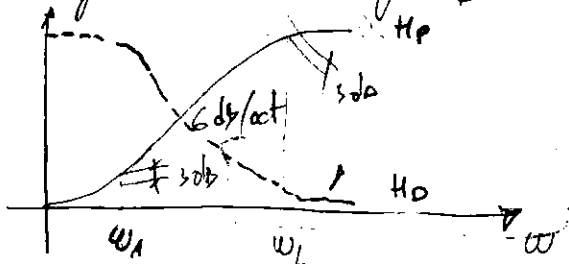
$$H_p(jw) = \frac{Y(jw)}{X(jw)} = \frac{r(jwRC + 1)}{R + jwRC}$$

$$R \gg r \quad H_p(jw) = \frac{r(jwRC + 1)}{R(1 + jwRC)} = \frac{r}{R} (1 + jwRC)$$

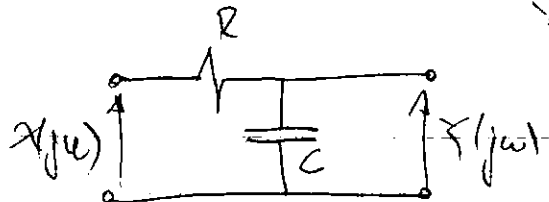
$$H_p(jw) = \frac{r}{R} \sqrt{1 + \omega^2 R^2 C^2} = \frac{r}{R} \sqrt{1 + \frac{\omega^2}{\omega_n^2}} \quad \omega_n = \frac{1}{RC}$$

$$|H_p(jw)| = H_p(\omega) = \frac{r}{R} \sqrt{1 + \frac{\omega^2}{\omega_n^2}}$$

$$20 \log H_p(\omega) = 20 \log \frac{r}{R} + 10 \log \left(1 + \frac{\omega^2}{\omega_n^2} \right)$$



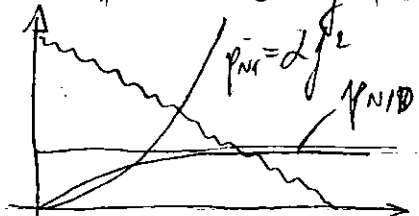
• Klasično $H_d(jw)$ KOLD



$$H_d(jw) = \frac{jwC}{R + \frac{1}{jwC}} = \frac{1}{1 + jwRC} = \frac{1}{1 + j \frac{\omega}{\omega_n}} \quad \omega_n = \frac{1}{RC}$$

$$|H_d(jw)| = H_d(\omega) = \frac{1}{\sqrt{1 + \frac{\omega^2}{\omega_n^2}}} \quad 20 \log H_d(\omega) = -10 \log \left(1 + \frac{\omega^2}{\omega_n^2} \right)$$

$$\omega \gg \omega_n \quad 20 \log H_d(\omega) = -10 \log \frac{\omega}{\omega_n}$$



$$P_{ni}(f) = \frac{20 \cdot FKT}{T_0} f^2 = \alpha \cdot f^2 \quad \left. \begin{array}{l} \text{SGSS} \\ \text{BEE Hd} \end{array} \right\}$$

$$P_{nid} = |H(jw)|^2 \cdot P_{ni} = \frac{\alpha f^2}{1 + \frac{f^2}{f_n^2}}$$

AVO: $\frac{f}{f_1} < 1 \Rightarrow \left(\frac{f}{f_1}\right)^2 < 1 \quad P_{MID} = \alpha \cdot f^2$

AVO: $\frac{f}{f_1} > 1 \Rightarrow \left(\frac{f}{f_1}\right)^2 \geq 1 \quad P_{MID} = \frac{2f^2}{f_1^2} = \alpha \cdot f_1^2$

$P_{Ni} = \int_0^{f_{max}} P_{MID}(f) df = 2 P_{eff} \frac{FKT}{P_0} \frac{f_{max}^3}{3}$

$P_{MID} = \int_{f_{max}}^{\infty} \frac{2f^2}{1 + \frac{f^2}{f_1^2}} df = \int_0^{f_{max}} \frac{2 \cdot f_1^2 f^2}{f_1^2 + f^2} df = \alpha \cdot f_1^2 \int_0^{f_{max}} \frac{f^2 df}{f_1^2 + f^2}$

$I = \int_0^{f_{max}} \frac{df}{f_1^2 + f^2} - \int_0^{f_{max}} \frac{f^2 df}{f_1^2 + f^2} = f_{max} - \int_0^{f_{max}} \frac{df \cdot \frac{d(f/f_1)}{1 + (f/f_1)^2}}$

$I = f_{max} - f_1 \arctan \frac{f_{max}}{f_1} \quad P_{MID} = \alpha \cdot f_1^2 \left[f_{max} - \arctan \frac{f_{max}}{f_1} \right]$

$P_{MID} = 2 P_{eff} \frac{FKT}{P_0} f_1^3 \left[\frac{f_{max}}{f_1} - \arctan \frac{f_{max}}{f_1} \right]$

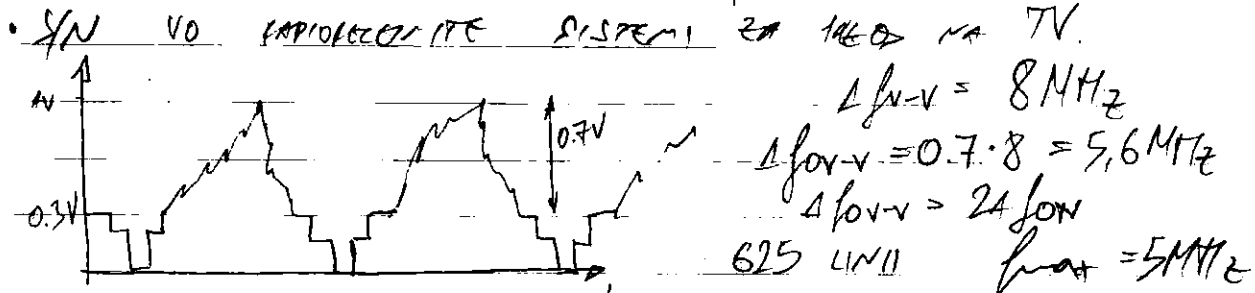
$Q = \frac{P_{Ni}}{P_{MID}} = \frac{\frac{f_{max}^3}{3}}{f_1^3 \left[\frac{f_{max}}{f_1} - \arctan \frac{f_{max}}{f_1} \right]} = \frac{(S/N)_{id}}{(S/N)_i}$

MUZICKI SIGNAL: $f_{max} = 15 \text{ kHz} \quad f_1 = 2.1 \text{ kHz}$
 $Q = \frac{1}{3} \left(\frac{f_{max}}{f_1}\right)^2 = 20 \quad 10 \log 20 = \dots 10(\log 10 + \log 2) = 13 \text{ dB}$

$\Delta f_{os} = 75 \text{ kHz} \quad f_{max} = 15 \text{ kHz}$
 $P_{Ni} = 2 P_{eff} \frac{FKT}{P_0} \frac{f_{max}^3}{3} \quad P_{si} = P_{eff} (\Delta f_{os})^2$

$\frac{P_{si}}{P_{Ni}} = \frac{P_{eff} (\Delta f_{os})^2}{2 P_{eff} \frac{FKT}{P_0} \frac{f_{max}^3}{3}} = \frac{3 \Delta f_{os} P_0}{2 FKT f_{max}^3} = \left(\frac{S}{N}\right)_i$

So $\frac{P_{si}}{P_{MID}} = \frac{P_{si}}{P_{Ni}/Q} = Q \frac{P_{si}}{P_{Ni}}$



$\left(\frac{S}{N}\right)_i = \frac{U_{ov-v}}{U_{eff}} = \frac{U_{ov-v}}{U_{eff}}$

$$a_{NA} = 20 \log \frac{U_{sv-v}}{U_{eff}} = 10 \log A_{NI} = 10 \log \left(\frac{U_{sv-v}}{U_{eff}} \right)^2$$

• $U_{eff} = ?$ $P_{Ni} = 2D_{FF} \frac{F_{KT}}{P_0} \int_0^{f_{max}} f^2 df$

$$P_{Ni} = \frac{U_{eff}^2}{R_0} ; U_{eff}^2 = P_{Ni} \cdot R_0 = 2D_{FF} R_0 \frac{F_{KT}}{P_0} \int_0^{f_{max}} f^2 df$$

• P_{Ni} REMODULACIJA $U_{sv-v} = (A_{fov-v}) \cdot D_{FF}$

$$\frac{P_{Ni}}{W} = \frac{D_{FF} \cdot A_{fov-v}}{\left[2D_{FF} R_0 \cdot \frac{F_{KT}}{P_0} \int_0^{f_{max}} f^2 df \right]^{1/2}} = \frac{U_{sv-v}}{U_{eff}}$$

$$U_s = D_{FF} \cdot A_{fo} \quad (M_{skt} = D_{FF} A_{fo} \cos(\omega t) = D_{FF} \cdot \delta f_i)$$

$$U_s^2 = D_{FF}^2 \cdot A_{fo}^2$$

$$\frac{D_{FF}^2 \cdot A_{fo}^2}{2 \cdot R_0} = \frac{U_s^2}{2R_0} = \frac{D_{FF}^2 A_{fo}^2}{\left(D_{FF} = \frac{D_{FF}}{2R_0} \right)}$$

$$a_{NA} = 10 \log \frac{D_{FF}^2 A_{fov-v}^2}{2D_{FF} R_0 \frac{F_{KT}}{P_0} \int_0^{f_{max}} f^2 df} = 10 \log \frac{A_{fov-v}^2}{\frac{F_{KT}}{P_0} \int_0^{f_{max}} f^2 df}$$

$$= 10 \log \frac{A_{fov-v}^2}{\frac{F_{KT}}{P_0} \frac{f_{max}^3}{3}} = 10 \log \frac{(A_{fov-v})^2}{f_{max} \frac{F_{KT}}{P_0}}$$

$F_{KT} = 4 \cdot 10^{-21} \text{ W/Hz}$; $A_{fov-v} = 3,6 \text{ MHz}$; $f_{max} = 5 \text{ MHz}$

$$a_{NA} = 10 \log 3 \cdot \left(\frac{3,6}{5} \right)^2 \cdot \frac{1}{4 \cdot 10^{-21} \cdot 5 \cdot 10^6} + 10 \log F + 10 \log \frac{P_0}{1 \text{ mW}} + 10 \log 10^3$$

$$= 10 \log 3,7632 \cdot \frac{1}{20 \cdot 10^{-15}} + (-30) - 10 \log F + 4_{P_0} =$$

$$= 142,75 - 30 - 10 \log F + 4_{P_0} = \boxed{112,75 - 10 \log F + 4_{P_0}}$$

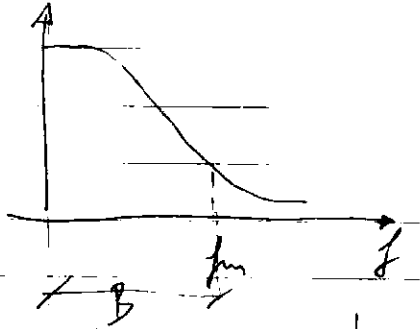
- PREGLED NA AUDIO (GOVOR) NIJE TOJAKI KAKO JE OD TV SITEMOTA
- RADIOELEKTRICNI SIGNALI ZA MERENJE NA PUA SIGNALI

$$\left(\frac{P_s}{P_n} \right)_{10 \text{ dB}} = \frac{A_{fo}^2 \cdot P_0}{2 F_{KT} \int_{f_1}^{f_2} f^2 df} = \left| \frac{f = \frac{f_1 + f_2}{2} = f_c}{f_c = f_2 - f_1} \right| = \frac{A_{fo}^2 \cdot P_0}{2 F_{KT} f_c B} = \left(\frac{A_{fo}}{f_c} \right)^2 \frac{P_0}{2 F_{KT} B}$$

• Ako se stvarni i imaginarni delovi

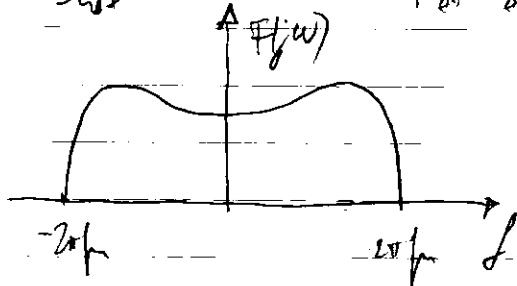
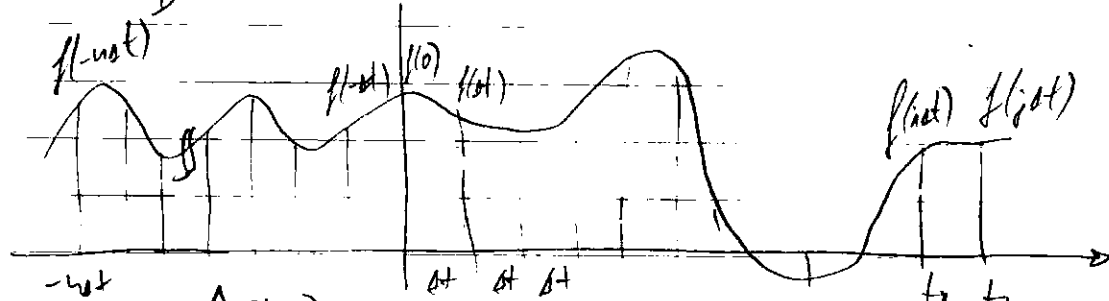
$$\frac{P_{SD}}{P_{WD}} = A^2(f) \frac{P_s}{P_r}$$

• Diskretizacija na kontinuelnu signal

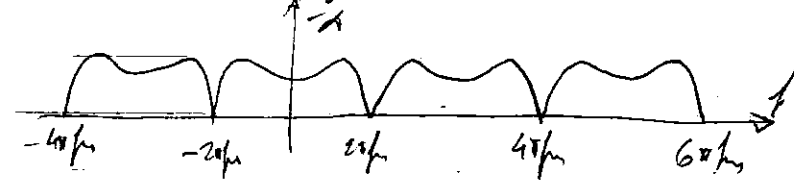


$$f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(j\omega) e^{j\omega t} d\omega = \frac{1}{2\pi} \int_{-\omega_H}^{\omega_H} F(j\omega) e^{j\omega t} d\omega$$

$$\Delta t = t_j - t_i \leq \frac{1}{2f_H}$$



$$F(j\omega) = \int_{-\infty}^{\infty} f(t) e^{-j\omega t} dt = \mathcal{F}\{f(t)\}$$



$$F_s(j\omega) = \sum_{n=-\infty}^{\infty} F_n e^{jn \frac{2\pi}{T} \omega} = \sum_{n=-\infty}^{\infty} F_n e^{jn \frac{1}{2T} \omega} \quad T = 40 \mu s$$

$$F_n = \frac{1}{40 \mu s} \int_{-20 \mu s}^{20 \mu s} F(j\omega) e^{-j \frac{n}{2T} \omega} d\omega = \frac{1}{40 \mu s} \int_{-20 \mu s}^{20 \mu s} F(j\omega) e^{-j \frac{n}{2T} \omega} d\omega$$

$$f(t) = \frac{1}{2\pi} \int_{-20 \mu s}^{20 \mu s} F(j\omega) e^{j\omega t} d\omega \quad t = -40 \mu s = -\frac{n}{2T} \quad f(t) = ?$$

$$f\left(-\frac{n}{2T}\right) = \frac{1}{2\pi} \int_{-20 \mu s}^{20 \mu s} F(j\omega) e^{-j \frac{n}{2T} \omega} d\omega \quad \textcircled{*} = 2\pi \int\left(-\frac{n}{2T}\right)$$

$$F_n = \frac{1}{40 \mu s} \cdot f\left(-\frac{n}{2T}\right) \cdot 2\pi \quad \left[F_n = \frac{1}{2T} \cdot f\left(-\frac{n}{2T}\right) \right]$$

$$f\left(-\frac{n}{2T}\right) = 2T F_n; \quad F_s(j\omega) = \sum_{n=-\infty}^{\infty} \frac{1}{2T} f\left(-\frac{n}{2T}\right) e^{jn \frac{1}{2T} \omega}$$

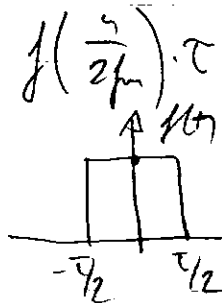
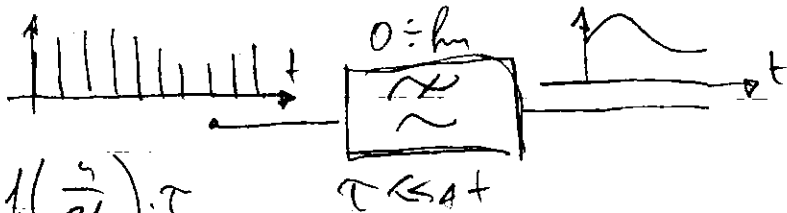
$$f(t) = \frac{1}{2\pi} \int_{-20 \mu s}^{20 \mu s} \sum_{n=-\infty}^{\infty} \frac{1}{2T} f\left(-\frac{n}{2T}\right) e^{jn \frac{1}{2T} \omega} e^{j\omega t} d\omega = \frac{1}{2\pi} \int_{-20 \mu s}^{20 \mu s} F(j\omega) e^{j\omega t} d\omega$$

$$f(t) = \frac{1}{2\pi} \sum_{\omega=-\infty}^{\infty} \frac{1}{2T} f\left(-\frac{\omega}{2T}\right) \int_{-2\pi f}^{2\pi f} e^{j\omega\left(t + \frac{\omega}{2T}\right)} d\omega$$

$$\textcircled{*} = \frac{1}{j\left(t + \frac{\omega}{2T}\right)} e^{j\omega\left(t + \frac{\omega}{2T}\right)} \Big|_{-2\pi f}^{2\pi f} = \frac{1}{j\left(t + \frac{\omega}{2T}\right)} \left[e^{j2\pi f\left(t + \frac{\omega}{2T}\right)} - e^{-j2\pi f\left(t + \frac{\omega}{2T}\right)} \right]$$

$$f(t) = \sum_{\omega=-\infty}^{\infty} f\left(-\frac{\omega}{2T}\right) \frac{e^{j2\pi f\left(t + \frac{\omega}{2T}\right)} - e^{-j2\pi f\left(t + \frac{\omega}{2T}\right)}}{4Tf\left(t + \frac{\omega}{2T}\right)} = \sum_{\omega=-\infty}^{\infty} f\left(-\frac{\omega}{2T}\right) \frac{\sin\left(2\pi f\left(t + \frac{\omega}{2T}\right)\right)}{2\pi f\left(t + \frac{\omega}{2T}\right)}$$

$$f(t) = \sum_{\omega=-\infty}^{\infty} f\left(\frac{\omega}{2T}\right) \frac{\sin\left(2\pi f\left(t - \frac{\omega}{2T}\right)\right)}{2\pi f\left(t - \frac{\omega}{2T}\right)}$$

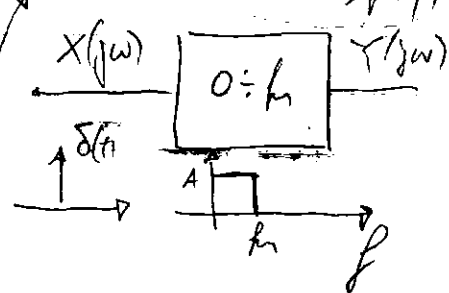


AP $\mathcal{F}\{f(t)\} = \text{FT} \frac{\sin \frac{\omega T}{2}}{\omega T} = F(j\omega)$

$$f(t) = \sum_{\omega=-\infty}^{\infty} e \cdot d \cdot \frac{\sin(\omega T/2)}{(\omega T/2)} e^{j\omega t}$$

$$f(t) = e \cdot d + 2e \sum_{\omega=1}^{\infty} \frac{\sin \frac{\omega T}{2}}{\frac{\omega T}{2}} \cdot \cos(\omega t)$$

$$y_u(t) = 2\pi f t f\left(\frac{\omega}{2T}\right) A$$



$$Y(j\omega) = \begin{cases} A \cdot X(j\omega) & 0 \leq \omega \leq 2\pi f \\ 0 & \omega > 2\pi f \end{cases}$$

$$Y(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} A \cdot e^{j\omega t} d\omega = \frac{A}{2\pi} \frac{1}{jt} e^{j\omega t} \Big|_{-2\pi f}^{2\pi f}$$

$$= 2 \frac{A}{2\pi \cdot t} \cdot \sin(2\pi f t) = 2A f \frac{\sin(2\pi f t)}{2\pi f t}$$

$$Y(t) = \frac{A}{2\pi} \frac{1}{jt} \frac{e^{j2\pi f t} - e^{-j2\pi f t}}{2} = 2 \frac{A}{2\pi \cdot t} \cdot \sin(2\pi f t)$$

$$Y(t) = 2A f \frac{\sin(2\pi f t)}{2\pi f t}$$

$$y(t) = \sum_{n=-\infty}^{\infty} 2\mu T f\left(\frac{y}{2\mu}\right) \frac{\sin 2\mu\pi(t-t_0 - \frac{y}{2\mu})}{2\mu(t-t_0 - \frac{y}{2\mu})}$$

$$y(t) = 2\mu T \sum_{n=-\infty}^{\infty} f\left(\frac{y}{2\mu}\right) \frac{\sin 2\mu\pi(t-t_0 - \frac{y}{2\mu})}{2\mu(t-t_0 - \frac{y}{2\mu})} = 2\mu T \cdot f(t-t_0)$$

• OTSODRAVAVANJE NA ISI

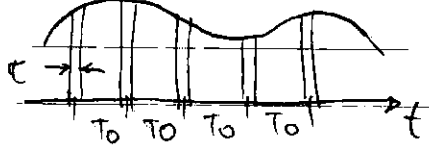
$$f_y(t-t_0 + \frac{y}{2\mu}) = kA \quad t-t_0 + \frac{y}{2\mu} = \frac{k}{2\mu}$$

$$t = t_0 - \frac{y}{2\mu} + \frac{k}{2\mu} \quad \frac{1}{2\mu} = \frac{\Delta t}{N} = \frac{1}{2\mu N}$$

$$f_y = N \cdot \mu$$

• KMOLEKO ANICITANO MODULIRAN SIGNAL

① AM so POKROVO ZEMAZE TA PRIMEROCI



$$M(t) = \begin{cases} M_m(t) & nT_0 - \frac{T}{2} \leq t \leq nT_0 + \frac{T}{2} \\ 0 & \text{elsewhere} \end{cases}$$

$$M_{AM}(t) = k M_m(t) s(t) \quad s(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT_0)$$

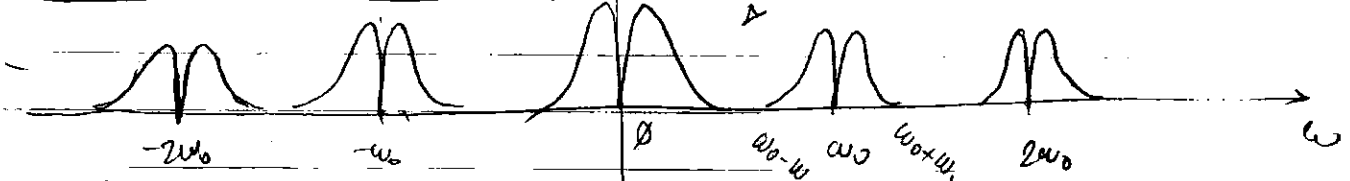
$$M_m(t) \rightarrow U_m(j\omega) \quad \text{OZNAČEN SO } \mu$$

$$M_0(t) = \left[\frac{T}{T_0} + 2 \frac{T}{T_0} \sum_{n=1}^{\infty} \frac{\sin \frac{n\omega T}{2}}{\frac{n\omega T}{2}} \cos(n\omega t) \right] U_0$$

$$M_{AM}(t) = k M_m(t) \frac{T U_0}{T_0} + 2k M_m(t) \frac{T U_0}{T_0} \sum_{n=1}^{\infty} \frac{\sin \frac{n\omega T}{2}}{\frac{n\omega T}{2}} \cos(n\omega t)$$

$$U(j\omega) = k \frac{T U_0}{T_0} U_m(j\omega) + 2k \frac{T U_0}{T_0} \sum_{n=1}^{\infty} \frac{\sin \frac{n\omega T}{2}}{\frac{n\omega T}{2}} \left[U_m(j\omega - n\omega_0) + U_m(j\omega + n\omega_0) \right]$$

$$M_{AM} = k M_m(t) \sum_{n=-\infty}^{\infty} U_0 \delta(t - nT_0)$$



② AM so REGULIRANO ZEMAZE PRIMEROCI I NEGON STENJAZ

$$\delta_T(t) = \lim_{T \rightarrow 0} \frac{1}{T} \sum_{n=-\infty}^{\infty} \frac{\sin \frac{n\omega T}{2}}{\frac{n\omega T}{2}} e^{jn\omega t} = \frac{1}{T} \sum_{n=-\infty}^{\infty} e^{jn\omega t}$$

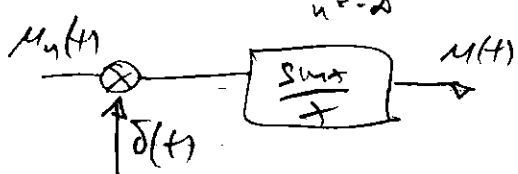
$$T \rightarrow 0 \quad s(t) \rightarrow \delta(t) \quad M(t) = k M_m(t) \cdot \delta_T(t) = k M_m(t) \sum_{n=-\infty}^{\infty} \delta(t - nT_0)$$

$$\delta_T(t) = \frac{1}{T} \sum_{n=-\infty}^{\infty} e^{jn\omega_0 t}$$

$$M(t) = k M_1(t) \cdot \frac{1}{T} \sum_{n=-\infty}^{\infty} e^{jn\omega_0 t}$$

$$D(j\omega) = \frac{k}{T} D_1[j(\omega - n\omega_0)] + \frac{k}{T} D_2[j(\omega + n\omega_0)] \quad n=0, \dots, \infty$$

$$D(j\omega) = k_1 \sum_{n=-\infty}^{\infty} D_1[j(\omega - n\omega_0)] \quad M(t) = k \sum_{n=-\infty}^{\infty} M_1(t) \delta(t - nT)$$

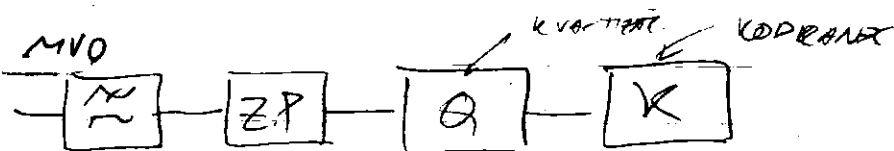


$$M(t) = k \sum_{n=-\infty}^{\infty} M_1(t) \delta(t - nT)$$

$$D(j\omega) = \frac{\sum_{n=-\infty}^{\infty} e^{jn\omega_0 t}}{\omega T} \sum_{n=-\infty}^{\infty} D_1[j(\omega - n\omega_0)]$$

• КВАТИЗАЦИЯ ПО МВО

$$q = \frac{V}{\Delta M}$$



$$q = 2^4$$

q - число на кват. нивоа

$$n = \text{ld } q$$

$$q = 8$$

$$n = \text{ld } 8 = 3$$

$$M_N(t) = M(t) - M_q(t)$$

• ПАРОМЕТРА КВАТИЗАЦИЯ

$$M_i < M < M_{i+1}$$

$$\overline{M_{Ni}^2} = \int_{M_{2i} - \frac{\Delta M_i}{2}}^{M_{2i+1}} (M - M_{2i})^2 p(M) dM$$

$$\overline{M_{Ni}^2} = \int_0^{\Delta M_i} (M - M_{2i})^2 dM = \frac{1}{3} \frac{\Delta M_i^3}{2} = \frac{\Delta M_i^3}{6}$$

$$\overline{M_N^2} = \sum_{i=1}^q \overline{M_{Ni}^2} = \frac{1}{12} \sum_{i=1}^q \Delta M_i^3 = \frac{\Delta M^2}{12} \sum_{i=1}^q \frac{\Delta M_i}{\Delta M} = \frac{\Delta M^2}{12}$$

$$\overline{M_N^2} = \frac{\Delta M^2}{12}$$

$$\overline{M_N^2} = \frac{\Delta M^2}{12}$$

СРЪКА НА СУМА НА КВАТИЗАЦИЯ

$$P_s = \int_{-V/2}^{V/2} M^2 p(M) dM = \frac{1}{3} \frac{M^3}{3} \Big|_{-V/2}^{V/2} = \frac{1}{9} \left(\frac{2 \cdot V^3}{8} \right) = \frac{V^3}{12}$$

$$p_0 V = 1$$

$$P_s = \frac{V^2}{12}$$

$$2 \cdot \Delta M = V$$

$$P_s = \frac{q^2 \Delta M^2}{12}$$

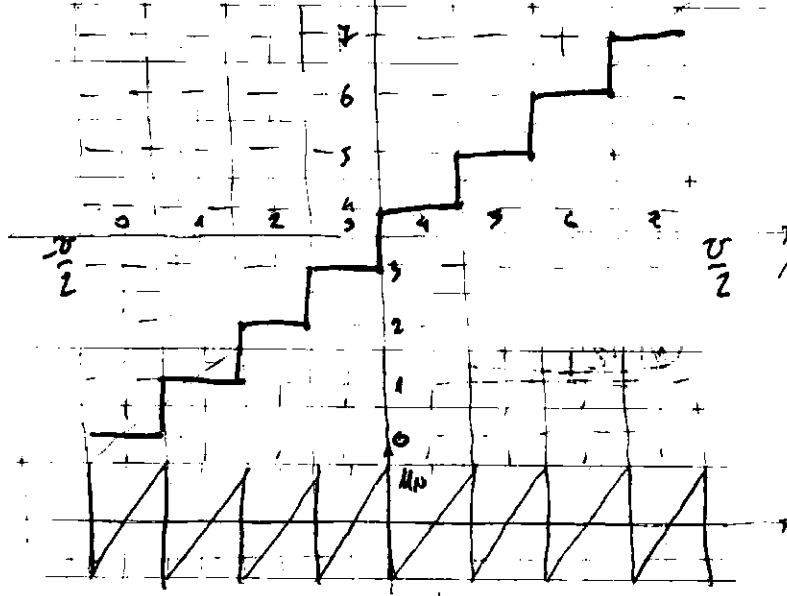
• СРЪКА НА КВАТИЗИРАНИ СИГНАЛ

$$P = \frac{1}{V} (f_1^2 + f_2^2 + \dots + f_n^2) = \frac{1}{V} \sum_{i=1}^n f_i^2$$

$$\Delta t = \frac{1}{2f_n}$$

$f_1, f_2, \dots, f_n \rightarrow$ параметри во 1MT (табл.)

$$+ \frac{qM}{2} + \frac{3qM}{2} + \frac{5qM}{2} + \dots + \frac{(2-1)qM}{2}$$



$$P_2 = \frac{1}{2} \frac{\Delta M^2}{4} [1^2 + 3^2 + 5^2 + \dots + (2-1)^2]$$

$$S = \sum_{i=1}^{N-1} x^2 = \frac{1}{6} N^3 - \frac{1}{6} N$$

$$P_2 = \frac{1}{2} \frac{\Delta M^2}{4} \left[\frac{1}{6} 2^3 - \frac{1}{6} 2 \right]$$

$$P_2 = \frac{\Delta M^2}{12} [2^2 - 1]$$

$$S = \frac{n(n+1)(2n+1)}{6}$$

$$S = 1 + q + q^2 + \dots + q^{n-1}$$

$$qS = q + q^2 + q^3 + \dots + q^n$$

$$S - qS = 1 - q^{n+1} \quad S = \frac{1 - q^{n+1}}{1 - q}$$

$$\lim_{n \rightarrow \infty} \frac{1 - 2^{n+1}}{1 - 2} = \frac{1}{1 - 2} \quad (2 < 1)$$

$$S = a_1 + a_2 + a_3 + \dots + a_n$$

$$a_2 = a_1 + d \quad a_3 = a_1 + 2d$$

$$a_n = a_1 + (n-1)d$$

$$S = a_1 + a_1 + d + a_1 + 2d + \dots + a_1 + (n-1)d =$$

$$= a_1 + a_1 + d + a_1 + d + \dots + a_1 + d$$

$$= \underbrace{a_1 + a_1 + \dots + a_1}_{S} + (n-1)d = S + (n-1)d - a_1 + a_1$$

$$S = S + a_1 - a_n + (n-1)d \quad a_n = a_1 + (n-1)d$$

$$S = a_1 + a_2 + a_3 + \dots + a_n$$

$$S = a_n + a_{n-1} + a_{n-2} + \dots + a_1$$

$$2S = (a_1 + a_n) + (a_2 + a_{n-1}) + (a_3 + a_{n-2}) + \dots + (a_{n-1} + a_2) + (a_n + a_1)$$

$$= [a_1 + a_1 + (n-1)d] + [a_1 + d + a_1 + (n-2)d] + \dots + [a_1 + (n-1)d + a_1]$$

$$= [2a_1 + (n-1)d] + [2a_1 + (n-1)d] + \dots + [2a_1 + (n-1)d]$$

$$2S = n \cdot (2a_1 + (n-1)d) \quad S = a_1 n + \frac{n(n-1)d}{2}$$

$$\sum_{i=1}^n i = \frac{n(n+1)}{2}$$

$$\sum_{i=0}^{q-1} (2i+1)^2 = \frac{q^3}{6} - \frac{q}{6} \quad \left| \begin{array}{l} 2q-2+1 = 2q-1 \\ 2(\frac{2}{2}-1)+1 = 2-2+1 = 1 \end{array} \right.$$

$$P_{N2} = \frac{\Delta M^2}{12}$$

$$P_{S2} = \frac{q^2 \Delta M^2}{12}$$

$$P_2 = \frac{\Delta M^2}{12} [q^2 - 1]$$

$$P_2 = P_{S2} - P_{N2}$$

$$A_{N2} = \frac{S}{N} = \frac{P_2}{P_{N2}} = \frac{\frac{\Delta M^2}{12} [q^2 - 1]}{\frac{\Delta M^2}{12}} = q^2 - 1 = q^2$$

$$10 \log_{10} A_{N2} = 90 \log_{10} 2$$

$$q = 2^8 = 256$$

$$20 \log q = 48,16 \text{ dB}$$

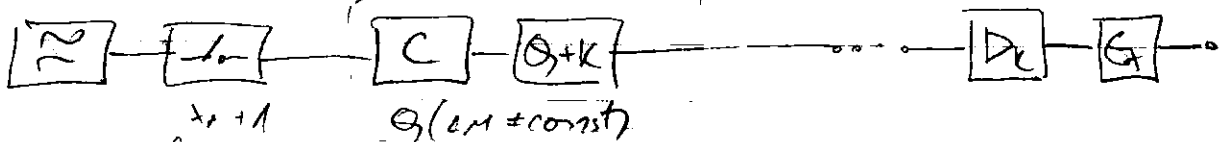
• НЕОБРАТКА

КВАТИРАЦИТА

$$q(M) \neq \text{const}$$

$$\Delta M \neq \text{const}$$

КОМКОСИТА



$$\overline{M_N^2} = \int (x - \gamma_i)^2 p(x) dx \quad \text{and} \quad x_i = \bar{x}_i - \frac{\Delta x_i}{2} \quad x_{i+1} = \bar{x}_i + \frac{\Delta x_i}{2}$$

$$p(x) = p(x_i) \quad \bar{x}_i = M q_i = \gamma_i$$

$$\overline{M_{Ni}^2} = p(\bar{x}_i) \int_{\bar{x}_i - \frac{\Delta x_i}{2}}^{\bar{x}_i + \frac{\Delta x_i}{2}} (x - \gamma_i)^2 dx = p(\bar{x}_i) \frac{1}{3} \left[\left(\bar{x}_i + \frac{\Delta x_i}{2} - \gamma_i \right)^3 - \left(\bar{x}_i - \frac{\Delta x_i}{2} - \gamma_i \right)^3 \right]$$

$$\overline{M_{Ni}^2} = p(\bar{x}_i) \cdot \frac{1}{3} \left[2 \frac{\Delta x_i^3}{8} \right] = \frac{1}{12} p(\bar{x}_i) \frac{\Delta x_i^3}{12}$$

$$\Delta x_i = \frac{\Delta M_i}{F(x)} \quad \overline{M_{Ni}^2} = \frac{1}{12} p(\bar{x}_i) \frac{\Delta M_i^3}{[F(x)]^3} \Delta x_i = \frac{1}{12} \frac{\Delta M_i^3}{[F(x)]^3} p(\bar{x}_i) \Delta x_i$$

$$\frac{1}{2} U = \frac{1}{2} X \quad q = \frac{U}{\Delta M} \quad \Delta M = \frac{U}{q}$$

$$\overline{M_{Ni}^2} = \frac{1}{12} \frac{U^3}{q^3} p(\bar{x}_i) \cdot \Delta x_i \cdot \frac{1}{[F(x)]^3}$$

$$\overline{M_N^2} = \sum_{i=0}^{q-1} \overline{M_{Ni}^2} = \frac{1}{12} \frac{U^3}{q^3} \sum_{i=1}^{q-1} \frac{p(\bar{x}_i) \Delta x_i}{[F(x)]^3}$$

$M = F(x) \Rightarrow$ CONTINUAKA FUNKCIJA

$$\overline{M_N^2} = \frac{1}{12} \frac{U^3}{q^3} \int_{-U/2}^{U/2} \frac{p(x)}{[F(x)]^3} dx$$

РАСКОМ. КВАНТ $F(x) = 1$

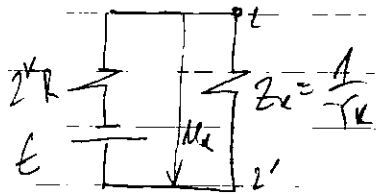
$$\overline{M_N^2} = \frac{1}{12} \frac{U^3}{q^3} = \frac{\Delta M^3}{12} \int_{-U/2}^{U/2} p(x) dx = 1$$

$$\overline{M_N^2} = \frac{1}{12} \frac{U^3}{q^3} \left[\int_{-U/2}^{U_2} \frac{p(x) dx}{(C_7)^2} + \int_{U_2}^{U_6} \frac{p(x) dx}{(C_6)^2} + \dots + \int_{U_6}^{U_0} \frac{p(x) dx}{(C_7)^2} \right]$$

• КОДЕК I ДЕККОДЕ

$$\gamma = \frac{1}{2^0 R} + \frac{1}{2^1 R} + \dots + \frac{1}{2^k R} + \dots + \frac{1}{2^{M-1} R} = \frac{1}{R} (2 - 2^{-M})$$

$$S = \frac{1 - \frac{1}{2^{M+1}}}{1 - \frac{1}{2}} = 2 - \frac{1}{2^M} \approx (2 - 2^{-M}) \quad M' = \frac{1}{T} \cdot \Delta$$



$$Y_k = \sum_{r=0}^{\infty} \frac{1}{2^r R} = Y - \frac{1}{2^k R}$$

$Y \neq k$

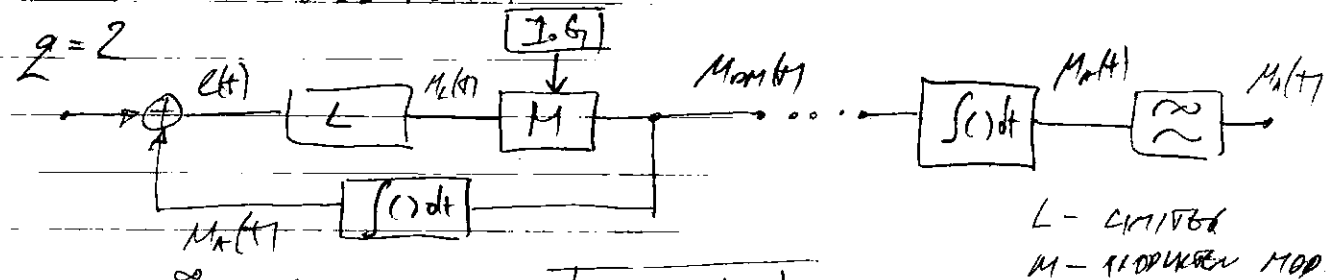
$$M_k = \frac{E}{2^k R + \frac{1}{Y_k}} \cdot \frac{1}{Y_k} = \frac{E}{2^k R \left(Y - \frac{1}{2^k R} \right) + 1} = \frac{E}{2^k R Y - 1 + 1} = \frac{E}{2^k R Y}$$

$$M = M' - M = \frac{1}{Y} - \frac{E}{2^k R Y} = \frac{1}{Y} \left(1 - \frac{E}{2^k R} \right)$$

ЧАСТИ РЕГУЛЯТОРА: $M = \frac{1}{Y} \left(1 - \frac{E}{2^k R} - \frac{E}{2^k R} \right)$

DELTA МОДУЛЯЦИЯ

$$q=2$$



L - ОГРАНИЧИТЕЛЬ
M - МОДУЛЯТОР

$$u_0(t) = \sum_{k=-\infty}^{\infty} \delta(t - kT_s) \quad T_s = \frac{1}{f_s}$$

$$M_k(t) = A \operatorname{sgn}[M_r(t) - M_k(t)] = \begin{cases} +A & e(t) > 0 \\ -A & e(t) < 0 \end{cases}$$

$$e(t) = M_r(t) - M_k(t)$$

$$M_{mod}(t) = \sum_k A \operatorname{sgn}[M_r(kT_s) - M_k(kT_s)] \delta(t - kT_s)$$

$$\frac{1}{2\pi} \int_{-\infty}^{\infty} j\omega e^{j\omega t} d\omega = \frac{j}{2\pi} \int_{-\infty}^{\infty} \omega e^{j\omega t} d\omega \quad \omega = \omega \quad \sigma = \int e^{j\omega t} d\omega = \frac{e^{j\omega t}}{j}$$

$$j = \left(\omega \cdot \frac{e^{j\omega t}}{jt} - \frac{1}{jt} \int e^{j\omega t} d\omega \right) \Big|_{-\infty}^{\infty} = \left(\omega \frac{e^{j\omega t}}{jt} - \frac{e^{j\omega t}}{(jt)^2} \right) \Big|_{-\infty}^{\infty}$$

$$= \left(\omega \frac{e^{j\omega t}}{jt} + \frac{e^{j\omega t}}{t^2} \right) \Big|_{-\infty}^{\infty} = \frac{e^{j\omega t}}{t} \left(\frac{1}{t} - j\omega \right) \Big|_{-\infty}^{\infty}$$

$$\lim_{x \rightarrow 0} \left[\frac{e^{jxt}}{t} \left(\frac{1}{t} - jx \right) - \frac{e^{jxt}}{t} \left(\frac{1}{t} + jx \right) \right]$$

НЕВИСЯЩАЯ

$$M_k(t) = \sum_k A \operatorname{sgn}[M_r(kT_s) - M_k(kT_s)] u_M(t - kT_s)$$

$$T_s \ll AT \quad AT = \frac{1}{2f_m}$$

ГЛАВНА ТО РАДИ РЕГУЛЯЦИЯ E:

$$e(t) = M_r(t) - M_k(t)$$

$e(t) \downarrow$ рно $T_s \downarrow$ $\sigma \downarrow$ $\Delta \downarrow$

• УСЛОВИЯ РА МБ ПОДРОБНО ОДОБРАЖАНИЕ

$$|M_{\omega}(t+T_s) - M_{\omega}(t)| \leq \Delta \quad \left| \frac{M_{\omega}(t+T_s) - M_{\omega}(t)}{T_s} \right| \leq \frac{\Delta}{T_s} = f_s \Delta$$

$$\left| \frac{M_{\omega}(t+T_s) - M_{\omega}(t)}{T_s} \right| \leq \left| \frac{dM_{\omega}(t)}{dt} \right|_{\max} \quad \boxed{\left| \frac{dM_{\omega}(t)}{dt} \right|_{\max} \leq \Delta \cdot f_s}$$

ЗА РА СЕ ПОДСКАЗЫВАЮТ СИМ ОИТОВ ПЕРДА КИ А ↑ ИЛИ f_s ↑
 НЕКА: $M_{\omega}(t) = U_m \cos(\omega_m t)$ $\left| \frac{dM_{\omega}(t)}{dt} \right|_{\max} = U_m \omega_m$

$U_m \omega_m \leq \Delta \cdot f_s$

• СИГНАЛ СИГНАЛ

$\boxed{20 \text{ пр. } U_m \leq \Delta \cdot f_s}$

• ГРАДУАЦИЯ СИГНАЛ

$e(t) = M_{\omega}(t) - M_{\omega}(t)$ $|R(t)| \leq \Delta$
 f_c - ГРАДУАЦИЯ ПРЯМО $\boxed{\infty}$

$P_{NG} = CA^2 \frac{f_c}{f_s}$

$p(e) = \text{const} \quad (-\Delta, \Delta)$

$f(e) = \begin{cases} \frac{1}{2\Delta} & -\Delta < e(t) < \Delta \\ 0 & \text{НАВНЕ} \end{cases}$

$\bar{e}(t) = \bar{e}^2 = \int_{-\Delta}^{\Delta} e^2 p(e) de = \frac{1}{2\Delta} \int_{-\Delta}^{\Delta} e^2 de = \frac{1}{2\Delta} \frac{e^3}{3} \Big|_{-\Delta}^{\Delta} = \frac{1}{\Delta} \frac{\Delta^3}{3} = \frac{\Delta^2}{3}$

$\boxed{P_{NG} = \frac{1}{3} \Delta^2 \frac{f_c}{f_s}}$

$\Delta \downarrow \Rightarrow P_{NG} \downarrow$ НО ЛОЖЕ ДА РАДИКАТЕ СТРАЖИШО ИДОБРАЖАНИЕ

• АДАПТИВНА ДИМОУАЦИЯ (ADPCM)

M-EN SIGNAL

$f_b = f_d \cdot \log_2 M$

$M=4$

$\boxed{f_b = 2 \cdot f_d}$

2 БИТ/2 ПИДКА

$\hat{x}_k(t) = U_x \cdot \tau$

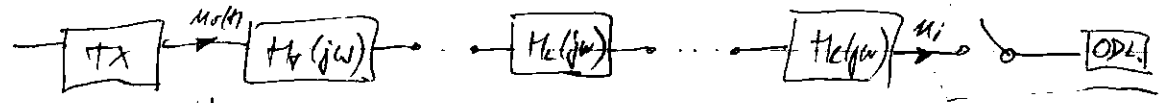
$y(t) = 2 f_c \cdot e^{j\omega_c t} \cdot A \cdot \frac{e^{j\omega_c(t-t_0)} - e^{-j\omega_c(t-t_0)}}{2j\omega_c(t-t_0)}$

$\omega_c(t-t_0) = \pi \left[t - t_0 + \frac{1}{2k} \right]$

$2 f_c \cdot T_s = \pi \quad \boxed{T_s = \frac{1}{2 f_c}}$ \otimes

\otimes НАЗНАЧЕНИЕ КРИТЕРИУМ РА ИДЕАЛЕН СП ПЛОТНОСТ $\frac{1}{T_s} = f_s \Rightarrow$ НАЗНАЧЕНИЕ МЕРА

• НАЗНАЧЕНИЕ КРИТЕРИУМ



$M_{\omega}(t) = \sum_{k=-N}^N a_k x(t-kT)$; $a_k = s_1, s_2, \dots, s_M$ БИНАРИИ $a_k = 0, 1$

$x(t) =$ СТАЦИОНАРЕН СИГНАЛ $(S(t) \sim IL)$
 $X_{\omega}(j\omega) = \sum_{k=-N}^N a_k X(j\omega) e^{-j\omega kT}$ $\hat{X}(j\omega) = H(j\omega) X(j\omega)$

$$H(j\omega) = H_1(j\omega) \cdot H_2(j\omega) \cdot H_3(j\omega) \quad \mathcal{D}_i(j\omega) = \sum_{k=-N}^N a_k H(j\omega) X(j\omega) e^{-j\omega kT}$$

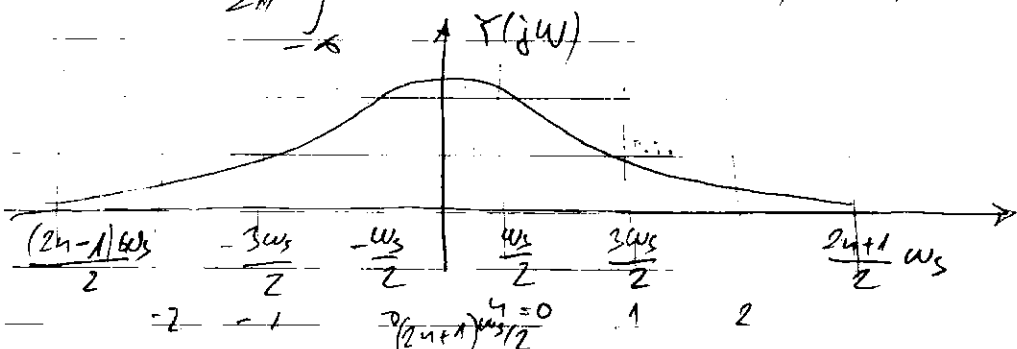
$$u_i(t) = \sum_{k=-N}^N a_k \gamma(t-kT) \quad \gamma(t-kT) = \int_{-\infty}^{\infty} \left\{ \gamma(j\omega) \right\}$$

$$\boxed{\gamma(kT) = \gamma_0 \delta_{k,0} \quad \delta_{i,j} = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases} \quad \delta_{i,j} = \text{KONKRETNÁ KONSTANTA (PŘEVA FUNKCE)}}$$

$i=j \Rightarrow$ ZA SOUVISLÉ SIGNALIZACE I NĚKDY. $i \neq j$ ZA DRUGÉ

$$\gamma(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} H(j\omega) X(j\omega) e^{j\omega t} d\omega \quad \gamma(kT) = \frac{1}{2\pi} \int_{-\infty}^{\infty} H(j\omega) X(j\omega) e^{j\omega kT} d\omega$$

$$\gamma(kT) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \gamma(j\omega) e^{j\omega kT} d\omega = \gamma_0 \delta_{k,0}$$



$$\gamma(kT) = \sum_{n=-\infty}^{\infty} \frac{1}{2\pi} \int_{\frac{(2n-1)\omega_s}{2}}^{\frac{(2n+1)\omega_s}{2}} \gamma(j\omega) e^{j\omega kT} d\omega = \begin{cases} \omega = \nu + n\omega_s \\ d\omega = d\nu \\ \omega = (2n+1)\frac{\omega_s}{2} \Rightarrow \nu = \frac{\omega_s}{2} + n\omega_s - n\omega_s \\ \omega = (2n-1)\frac{\omega_s}{2} \Rightarrow \nu = n\omega_s - \frac{\omega_s}{2} - n\omega_s \end{cases}$$

$$\gamma(kT) = \sum_{n=-\infty}^{\infty} \frac{1}{2\pi} \int_{\omega_s/2}^{\omega_s/2 + 2\pi n} \gamma(j\nu + jn\omega_s) e^{j\nu \cdot kT} \cdot e^{jn \cdot \omega_s \cdot kT} d\nu$$

$T \cdot \omega_s = T \cdot \frac{2\pi}{T} = 2\pi$

$$\boxed{T = \frac{2\pi}{\omega_s} \quad \omega_s = \frac{2\pi}{T}}$$

$$\gamma(kT) = \sum_{n=-\infty}^{\infty} \frac{1}{2\pi} \int_{-\omega_s/2}^{\omega_s/2} \gamma(j\nu + jn\omega_s) e^{j\nu kT} e^{j2\pi n k} d\nu$$

$$\gamma(kT) = \frac{1}{2\pi} \int_{-\omega_s/2}^{\omega_s/2} \sum_{n=-\infty}^{\infty} \gamma(j\nu + jn\omega_s) e^{j\nu kT} d\nu$$

$$\gamma(kT) = \frac{1}{2\pi} \int_{-\omega_s/2}^{\omega_s/2} e^{j\nu kT} \left(\sum_{n=-\infty}^{\infty} \gamma(j\nu + jn\omega_s) \right) d\nu \quad \nu = \omega \Rightarrow$$

$$\boxed{\gamma(kT) = \frac{1}{2\pi} \int_{-\omega_s/2}^{\omega_s/2} e^{j\omega kT} \left(\sum_{n=-\infty}^{\infty} \gamma(j\omega + jn\omega_s) \right) d\omega = \gamma_0 \delta_{k,0}}$$

$\delta_{0,0} = 1$
 $\delta_{1,0} = 0$

$$\sum_{k=-\infty}^{\infty} Y(j(\omega + k\omega_s)) = K = \frac{2\pi}{\omega_s} \cdot \gamma_0 = T \cdot \gamma_0 \quad |\omega| \leq \frac{\omega_s}{2}$$

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POV-22: $Y(\omega) = \frac{1}{2\pi} \int_{-\omega_s/2}^{\omega_s/2} \frac{2\pi}{\omega_s} \gamma_0 e^{j\omega \frac{2\pi}{\omega_s} \omega} d\omega$

$$\int_{-\omega_s/2}^{\omega_s/2} e^{j\omega \omega \frac{2\pi}{\omega_s}} d\omega = \frac{e^{j\omega \omega \frac{2\pi}{\omega_s}}}{j\omega \frac{2\pi}{\omega_s}} \Big|_{-\omega_s/2}^{\omega_s/2} = \frac{1}{j\omega \frac{2\pi}{\omega_s}} \left(e^{j\omega \frac{\omega_s}{2} \frac{2\pi}{\omega_s}} - e^{-j\omega \frac{\omega_s}{2} \frac{2\pi}{\omega_s}} \right)$$

$$= \frac{2}{\omega \frac{2\pi}{\omega_s}} \sin \omega \pi$$

$$Y(\omega) = \frac{1}{2\pi} \cdot \frac{2\pi}{\omega_s} \cdot \gamma_0 \cdot \frac{2}{\omega \frac{2\pi}{\omega_s}} \sin(\omega \pi) = \gamma_0 \cdot \frac{\sin \omega \pi}{\omega \pi} = \gamma_0 \cdot \text{sinc}(\omega \pi)$$

$\omega \rightarrow 0 \quad Y(\omega) = \gamma_0$

$\delta_{\omega,0} = 1$
 $\delta_{\omega,0} = 0$

• Nama: $x(t) = \delta(t)$ $H(j\omega) = A(j\omega) \cdot e^{j\omega x(t)} = A(j\omega) [\cos x(\omega) + j \sin x(\omega)]$

$$\sum_{k=-\infty}^{\infty} H(j(\omega + k\omega_s)) = K \quad |\omega| \leq \frac{\omega_s}{2}$$

I NYQUIST CRITERIA

1. $\sum_{k=-\infty}^{\infty} A(\omega + k\omega_s) \cos(x(\omega) + k\omega_s) = K \quad |\omega| \leq \frac{\omega_s}{2}$

2. $\sum_{k=-\infty}^{\infty} A(\omega + k\omega_s) \sin(x(\omega) + k\omega_s) = 0 \quad |\omega| \leq \frac{\omega_s}{2}$

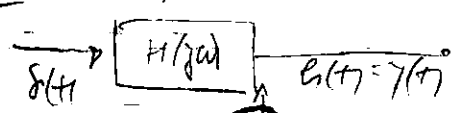
$\frac{1}{2} \cdot \frac{3\omega_s}{2} = 3\omega_s \quad x = \pi \cdot 60 = \frac{\pi}{2} \quad x = \frac{1}{120} = \frac{1}{3 \cdot 40}$

$x \cdot \pi \cdot \frac{N}{2} = \frac{\pi}{2} \Rightarrow \left[x = \frac{1}{N} \right] \quad f_s = 2 \text{ km}$

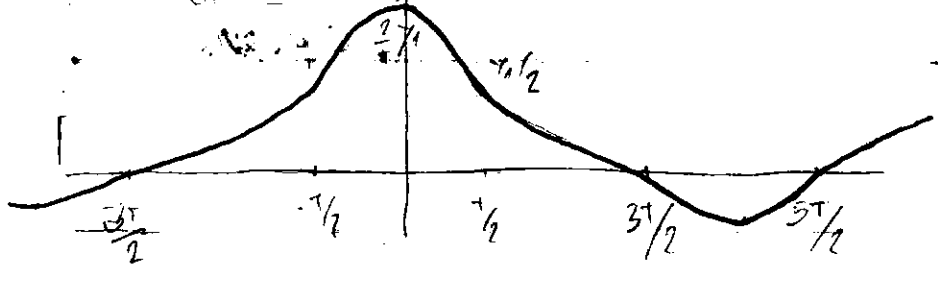
$$\sum_{k=-\infty}^{\infty} A(\omega + k\omega_s) \cos[x(\omega + k\omega_s)] = K \quad |\omega| \leq \frac{\omega_s}{2}$$

$\omega_{\text{limit}} = \frac{\omega_s}{2} \rightarrow$ NO MORE IN X VALUE \neq SP (IDENTICAL SYSTEM TO THEM)

II NYQUIST CRITERION



$$G(t) = 2\pi \cdot f_s \frac{\sin 2\pi f_s t}{2\pi f_s}$$



$$1 - \frac{2\pi}{2} \cdot \frac{2\pi \cdot \frac{1}{2}}{2} = \frac{2\pi \cdot \frac{1}{2}}{2} = \frac{2\pi}{4} = \frac{\pi}{2}$$

$$1 - \frac{1}{2} \cdot \frac{2\pi \cdot \frac{1}{2}}{2} = \frac{2\pi \cdot \frac{1}{2}}{4} = \frac{\pi}{2}$$

$$Y\left[\left(2m-1\right)\frac{T}{2}\right] = \frac{1}{2} \left[\delta_{m,0} + \delta_{m,1} \right]$$

$$Y\left[\frac{T}{2}\right] = \frac{1}{2} \left[\delta_{m,0} + \delta_{m,1} \right] = \frac{1}{2}$$

$$Y\left[\frac{T}{2}\right] = \frac{1}{2} \left[\delta_{m,0} + \delta_{m,1} \right] = \frac{1}{2}$$

$$Y\left[\left(2m-1\right)\frac{T}{2}\right] = 0$$

$$Y(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} Y(j\omega) e^{j\omega t} d\omega; \quad t = (2m-1)\frac{T}{2}$$

$$Y\left[\left(2m-1\right)\frac{T}{2}\right] = \frac{1}{2\pi} \int_{-\infty}^{\infty} Y(j\omega) e^{j\omega(2m-1)\frac{T}{2}} d\omega = \left| \begin{array}{l} \omega_s = \frac{2\pi}{T} \\ T = \frac{2\pi}{\omega_s} \\ f_s = \frac{1}{T} \end{array} \right| =$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} Y(j\omega) e^{j\omega(2m-1)\frac{2\pi}{\omega_s}} d\omega = \int_{-\omega_s/2}^{\omega_s/2} Y(j\omega) e^{j\omega(2m-1)\frac{\pi}{\omega_s}} d\omega$$

$$Y(j\omega) = X(j\omega) \cdot H(j\omega)$$

$$Y\left[\left(2m-1\right)\frac{T}{2}\right] = \frac{1}{2\pi} \sum_{n=-\infty}^{\infty} \int_{-\omega_s/2}^{\omega_s/2} Y(j\omega) e^{j\omega(2m-1)\frac{\pi}{\omega_s}} d\omega = \left| \begin{array}{l} v + n\omega_s = \omega \\ d\omega = n\omega_s \\ \omega = n\omega_s + \frac{\omega_s}{2} \quad v = \frac{\omega_s}{2} \\ \omega = n\omega_s - \frac{\omega_s}{2} \quad v = -\frac{\omega_s}{2} \end{array} \right|$$

$$= \frac{1}{2\pi} \sum_{n=-\infty}^{\infty} \int_{-\omega_s/2}^{\omega_s/2} Y(j(v+n\omega_s)) e^{jv\frac{\pi}{\omega_s}(2m-1)} e^{jn\pi(2m-1)} dv = \int_{-\omega_s/2}^{\omega_s/2} Y(jv) e^{jv\frac{\pi}{\omega_s}(2m-1)} dv = \int_{-\omega_s/2}^{\omega_s/2} Y(jv) e^{jv\frac{\pi}{\omega_s}(2m-1)} dv$$

$$j\omega(2m-1)\frac{T}{\omega_s} = j(v+n\omega_s)(2m-1)\frac{T}{\omega_s} = jv\frac{\pi}{\omega_s}(2m-1) + jn\pi(2m-1)$$

$$= \frac{1}{2\pi} \sum_{n=-\infty}^{\infty} \int_{-\omega_s/2}^{\omega_s/2} Y(j(v+n\omega_s)) e^{jv\frac{\pi}{\omega_s}(2m-1)} e^{jn\pi(2m-1)} dv = \int_{-\omega_s/2}^{\omega_s/2} Y(jv) e^{jv\frac{\pi}{\omega_s}(2m-1)} dv$$

$$Y\left[\left(2m-1\right)\frac{T}{2}\right] = \frac{1}{2\pi} \int_{-\omega_s/2}^{\omega_s/2} e^{jv\frac{\pi}{\omega_s}(2m-1)} \sum_{n=-\infty}^{\infty} (-1)^n Y(j(v+n\omega_s)) dv$$

Za pa: $Y\left[\left(2m-1\right)\frac{T}{2}\right] = \frac{1}{2} \left[\delta_{m,0} + \delta_{m,1} \right]$ $\$$ FLER ON ANDS :

$$\sum_{n=-\infty}^{\infty} (-1)^n Y(j(v+n\omega_s)) = \frac{2\pi}{\omega_s} Y_1 \cos \frac{\pi v}{\omega_s} = Y_1 \cdot T \cos \frac{\pi v}{\omega_s} \quad |v| \leq \frac{\omega_s}{2}$$

II NIKONIST

$$Y\left[\left(2m-1\right)\frac{T}{2}\right] = \frac{1}{2\pi} \int_{-\omega_s/2}^{\omega_s/2} Y_1 T \cos \frac{\pi v}{\omega_s} e^{jv\frac{\pi}{\omega_s}(2m-1)} dv = \frac{Y_1}{2} \left[\delta_{m,0} + \delta_{m,1} \right]$$

$$x(t) \rightarrow \delta(t) \quad \Gamma(j\omega) = H(j\omega)$$

$$\sum_{n=-\infty}^{\infty} (-1)^n \delta(\omega + n\omega_s) = \frac{1}{T} \cos \frac{\pi\omega}{\omega_s} \quad |\omega| \leq \frac{\omega_s}{2}$$

$$1) \sum_{n=-\infty}^{\infty} (-1)^n A(\omega + n\omega_s) \cdot \cos 2\pi(\omega + n\omega_s) = \frac{1}{T} \cos \frac{\pi\omega}{\omega_s} \quad |\omega| \leq \frac{\omega_s}{2}$$

$$2) \sum_{n=-\infty}^{\infty} (-1)^n A(\omega + n\omega_s) \sin 2\pi(\omega + n\omega_s) = 0 \quad |\omega| \leq \frac{\omega_s}{2}$$

• Normal moduli modulen casey za $\omega=0$:

$$A(\omega) \cdot \cos 2\pi(\omega) = \frac{1}{T} \cos \frac{\pi\omega}{\omega_s} \quad |\omega| \leq \frac{\omega_s}{2}$$

$$A(\omega) \cdot \sin 2\pi(\omega) = 0$$

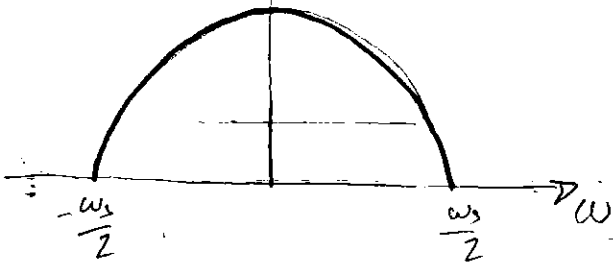
$$T = \frac{1}{f_s} = \frac{T_0}{\omega_s}$$

$$A(\omega) = \begin{cases} \frac{1}{T} \cos \frac{\pi\omega}{\omega_s} & |\omega| \leq \frac{\omega_s}{2} \\ 0 & |\omega| > \frac{\omega_s}{2} \end{cases}$$

$$|\omega| \leq \frac{\omega_s}{2}$$

$$|\omega| > \frac{\omega_s}{2}$$

$$f_{\text{min}} = \frac{\omega_s}{2}$$



$$|H(f)| = \frac{1}{T} \int_{-\omega_c}^{\omega_c} \frac{1}{T} \cos \frac{\pi\omega}{\omega_s} e^{j\omega t} d\omega = \frac{2}{T} \frac{\cos \omega_c t}{1 - \left(\frac{\omega_c t}{\omega_s}\right)^2}$$

$\omega_s = 2\omega_c$ $\omega_c = \frac{\omega_s}{2}$

$$\begin{aligned} \textcircled{*} &= \frac{1}{2} \int_{-\omega_c}^{\omega_c} \left(e^{j\frac{\pi\omega}{\omega_s}} + e^{-j\frac{\pi\omega}{\omega_s}} \right) e^{j\omega t} d\omega = \frac{1}{2} \int_{-\omega_c}^{\omega_c} e^{j\left(\frac{\pi}{\omega_s} + t\right)\omega} d\omega + \frac{1}{2} \int_{-\omega_c}^{\omega_c} e^{-j\left(\frac{\pi}{\omega_s} - t\right)\omega} d\omega \\ &= \frac{1}{2} \frac{e^{j\left(\frac{\pi}{\omega_s} + t\right)\omega_c} - e^{-j\left(\frac{\pi}{\omega_s} + t\right)\omega_c}}{j\left(\frac{\pi}{\omega_s} + t\right)} + \frac{1}{2} \frac{e^{-j\left(\frac{\pi}{\omega_s} - t\right)\omega_c} - e^{j\left(\frac{\pi}{\omega_s} - t\right)\omega_c}}{-j\left(\frac{\pi}{\omega_s} - t\right)} \\ &= \frac{\sin\left(\frac{\pi}{\omega_s} + t\right)\omega_c}{\frac{\pi}{\omega_s} + t} + \frac{\sin\left(\frac{\pi}{\omega_s} - t\right)\omega_c}{\frac{\pi}{\omega_s} - t} = \frac{\left(\frac{\pi}{\omega_s} - t\right)\sin\left(\frac{\pi}{\omega_s} + t\right)\omega_c + \left(\frac{\pi}{\omega_s} + t\right)\sin\left(\frac{\pi}{\omega_s} - t\right)\omega_c}{\left(\frac{\pi}{\omega_s}\right)^2 - t^2} \\ &= \frac{\left(\frac{\pi}{2\omega_c} - t\right)\sin\left(\frac{\pi}{2} + \omega_c t\right) + \left(\frac{\pi}{2\omega_c} + t\right)\sin\left(\frac{\pi}{2} - t\omega_c\right)}{\left(\frac{\pi}{\omega_s}\right)^2 \left[1 - \left(\frac{t\omega_s}{\pi}\right)^2\right]} = \frac{\frac{2\pi}{2\omega_c} \cdot \cos \omega_c t}{\left(\frac{\pi}{2\omega_c}\right)^2 \left[1 - \left(\frac{2t\omega_c}{\pi}\right)^2\right]} \\ &= \frac{4\omega_c}{\pi} \frac{\cos \omega_c t}{1 - \left(\frac{t\omega_s}{\pi}\right)^2} = \frac{4\omega_c}{\pi} \frac{\cos \omega_c t}{1 - \left(\frac{t\omega_c}{\omega_s}\right)^2} = \frac{2T}{\pi} \frac{\cos \omega_c t}{1 - \left(\frac{t\omega_c}{\omega_s}\right)^2} = \frac{2T}{\pi} \frac{\cos \omega_c t}{1 - \left(\frac{t\omega_s}{\pi}\right)^2} \end{aligned}$$

$$Y(t) = \frac{2}{\pi} Y_1 \frac{\cos \omega_c t}{1 - \left(\frac{2\omega_c t}{\pi}\right)^2} \quad \omega_c = \frac{1}{2} \omega_s$$

$$\omega_c = \frac{\omega_s}{2} = \frac{\frac{2\pi}{T}}{2} = \frac{\pi}{T}$$

$$t = \frac{T}{2} \quad Y\left(\frac{T}{2}\right) = \frac{2}{\pi} Y_1 \frac{\cos \frac{\pi}{T} \cdot \frac{T}{2}}{1 - \left(\frac{2 \cdot \frac{T}{2} \cdot \frac{\pi}{T}}{\pi}\right)^2} = \frac{2}{\pi} Y_1 \frac{0}{0}$$

$$\lim_{t \rightarrow \frac{T}{2}} \frac{\cos \frac{\pi}{T} t}{1 - \left(\frac{2t}{T}\right)^2} = \lim_{t \rightarrow \frac{T}{2}} \frac{-\left(\sin \frac{\pi}{T} t\right) \frac{\pi}{T}}{-2 \left(\frac{2t}{T}\right) \cdot \frac{2}{T}}$$

$$= \lim_{t \rightarrow \frac{T}{2}} \frac{\pi \sin \left(\frac{\pi}{T} t\right)}{\frac{8t}{T}} = \frac{\pi \sin \frac{\pi}{2}}{\frac{4T}{T} \cdot \frac{T}{2}} = \frac{\pi}{4}$$

$$Y\left(\frac{T}{2}\right) = \frac{2}{\pi} Y_1 \frac{\pi}{4} = \frac{Y_1}{2} \quad \sin \frac{\pi}{T} \cdot \frac{5T}{2} = \frac{5\pi}{2}$$

• SP. KOT 41 120200VA 1 I 1 II E HODSMAE
KOSINUS :

$$A(\omega) = K \begin{cases} \frac{1}{2} + \frac{1}{2} \cos \frac{\pi \omega}{\omega_s} & |\omega| \leq \omega_s \\ 0 & |\omega| > \omega_s \end{cases} \quad \underline{\underline{MMV}}$$

$$\left. \frac{1}{2} + \frac{1}{2} \cos \left(\frac{\omega + \pi \omega}{2\omega_s + 2\omega_s} \right) \right) = \frac{1}{2} + \frac{1}{2} \cos \frac{\pi \omega}{\omega_s} \cdot \cos \frac{\pi \omega}{\omega_s} - \frac{1}{2} \sin \frac{\pi \omega}{\omega_s} \sin \frac{\pi \omega}{\omega_s}$$

$$= \frac{1}{2} \left(1 - \sin^2 \frac{\pi \omega}{\omega_s} \right) + \frac{1}{2} \cos^2 \frac{\pi \omega}{\omega_s} = \cos^2 \frac{\pi \omega}{2\omega_s}$$

$$Y = \frac{1}{2\pi} \int_{-\omega_c}^{\omega_c} \left(\frac{1}{2} + \frac{1}{2} \cos \frac{\pi \omega}{\omega_s} \right) e^{j\omega t} d\omega = \frac{1}{2\pi} \frac{1}{2} \int_{-\omega_c}^{\omega_c} e^{j\omega t} d\omega + \frac{1}{2} \frac{1}{2\pi} \int_{-\omega_c}^{\omega_c} \cos \frac{\pi \omega}{\omega_s} e^{j\omega t} d\omega$$

$$\textcircled{1} = \frac{1}{4\pi} \frac{\omega_c}{\pi} \frac{\cos \omega_c t}{1 - \left(\frac{2\omega_c t}{\pi}\right)^2} \quad \textcircled{2} = \frac{1}{4\pi} \frac{1}{\pi t} (e^{j\pi \omega_c t} - e^{-j\pi \omega_c t}) = \frac{1}{2\pi^2 t} \sin \pi \omega_c t$$

$$\textcircled{1} + \textcircled{2} = \frac{\omega_c}{\pi} \frac{\cos \omega_c t}{1 - \left(\frac{2\omega_c t}{\pi}\right)^2} + \frac{\sin \omega_c t}{2\pi t} = \frac{\omega_c}{\pi} \frac{2\pi t \cos \omega_c t + \sin \omega_c t - \frac{(2\omega_c t)^2}{\pi} \sin \omega_c t}{\left[1 - \left(\frac{2\omega_c t}{\pi}\right)^2\right] 2\pi t}$$

$$= \frac{2\omega_c t \cos \omega_c t + \sin \omega_c t - \frac{(2\omega_c t)^2}{\pi} \sin \omega_c t}{\left[1 - \left(\frac{2\omega_c t}{\pi}\right)^2\right] 2\pi t}$$

? NE ZAM KAND SE POJAVIA !!!

$$Y(t) = \frac{K}{T} \frac{1}{1 - \left(\frac{2\omega_c t}{\pi}\right)^2} \textcircled{1} \frac{2\omega_c t}{\pi} \textcircled{2}$$

- ① 120200VA INC
- ② 120200VA INC

• TRANSDUCED FILTER:

$$y(t) = A_0 \cdot x(t) + A_{-1} x(t-T) + \dots + A_0 x(t-lT) + \dots + A_l x(t-2lT)$$

$$Y(\omega) = \sum_{k=-l}^l A_k x[t - (k+l)T] = e^{-j\omega l T} \sum_{k=-l}^l A_k X(j\omega) e^{j\omega k T}$$

$$H(\omega) = \frac{Y(\omega)}{X(\omega)} = e^{-j\omega l T} \sum_{k=-l}^l A_k e^{j\omega k T}$$

$$\left[f_s = \frac{1}{T_s} = \frac{f_b}{LDM} \right]$$

$$\frac{2\omega c t}{\pi} \left(\cos \omega c t - \frac{2\omega c t}{\pi} \sin \omega c t \right) + \sin \omega c t$$

$$\frac{2\omega c t}{\pi} \cos(\omega c t - \omega c t) = \frac{2\omega c t}{\pi} [\cos \omega c t \cdot \cos \omega c t + \sin \omega c t \cdot \sin \omega c t]$$

$$\sin(2\omega c t) = 2 \sin \omega c t \cdot \cos \omega c t$$

$$\frac{2\omega c t}{\pi} \cdot (1 - \sin \omega c t) + 2 \sin \omega c t - 2 \left(\frac{2\omega c t}{\pi} \right)^2 \sin \omega c t$$

DIGITALNI TK

POVTOVANKA

• PLOŠČA VO OSROVEN OPISEY

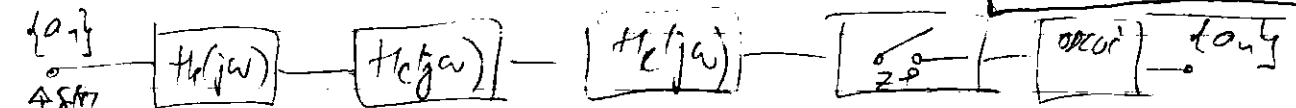
$$U_b = \frac{1}{T_b} [pA] \quad \text{DIGITALNA PLOŠČA} \quad |B| = \frac{1 \text{ PISIT}}{S}$$

$$U_b = U_b \cdot LDM$$

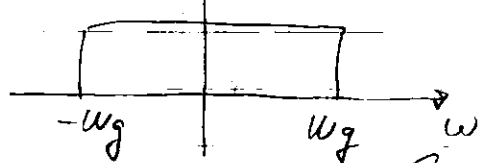
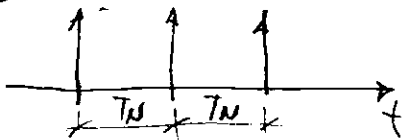
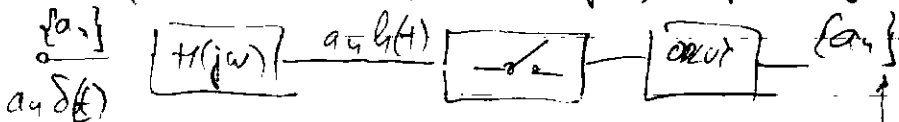
$$M = 2^N$$

• ROKAR S/N TERA MERA $F(\epsilon)$

$$F(\epsilon)_{min} = 10^{-7}$$



$$H(j\omega) = H_1(j\omega) H_2(j\omega) H_3(j\omega)$$



$$2f_g = f_s \quad f_g = \frac{1}{2} \frac{1}{T_N} = \frac{1}{2T_N}$$

• DYOIST CRITERIA

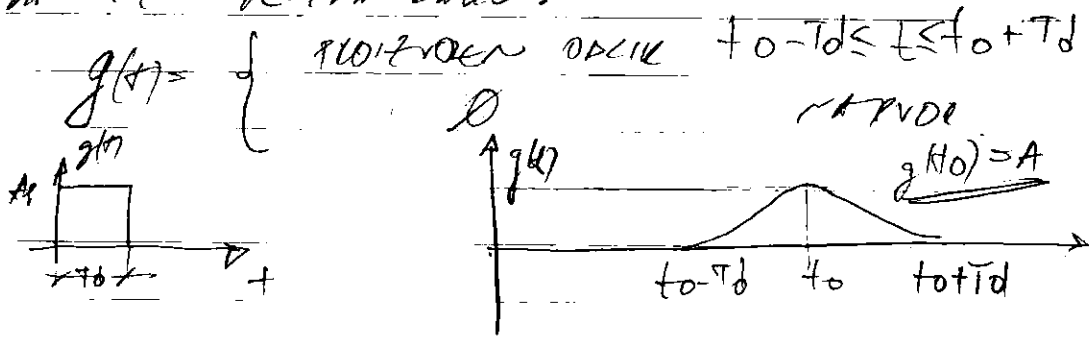
• ~~...~~

$$g_p(t) = \begin{cases} 1 & \text{AP } 0 \leq t \leq T_b \\ 0 & \text{NAPROK} \end{cases}$$

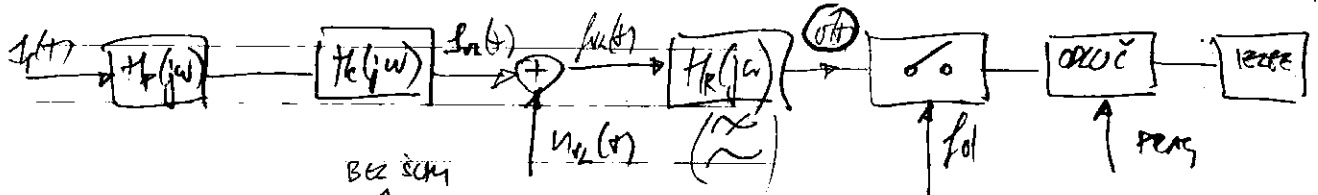
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• ~~...~~

- PRAV ULOTO ZA ZEMNJE MIMETOCIS: OVOZ II. POSE. DA NE TRAJA KALO:



- DREKCIJA ZA SIGNALNE MERESENI VO OROVEN OSEK



$$f_{vz}(t) = s_{vz}(t) + u_{vz}(t)$$

$$u(t) = s(t) + v(t)$$

$$s(t) = \sum_n a_n g(t - nT_D)$$

$a_n \in \{0, 1\}$ ZA UNIMODALNI SINUSNI SIGNAL
 DOLJAN NO OGRANICEN OD VEŠNOST FAKTOR

$$g(t) = \begin{cases} A_p & 0 \leq t \leq T_D \\ 0 & \text{NAPRVO} \end{cases}$$

$$s(t) = \sum_n a_n g(t - nT_D)$$

$$g(t) = \begin{cases} \text{POZITIVAN} & t_0 - T_D \leq t \leq t_0 + T_D \\ 0 & \text{NAPRVO} \end{cases}$$

- $P(E) = ?$ ZA UNIMODALNI AVITEN SIGNAL

$$M=2 \quad a_n \in \{0, 1\}$$

$$s(t) = A \quad a_n = 1$$

$$s(t) = 0 \quad a_n = 0$$

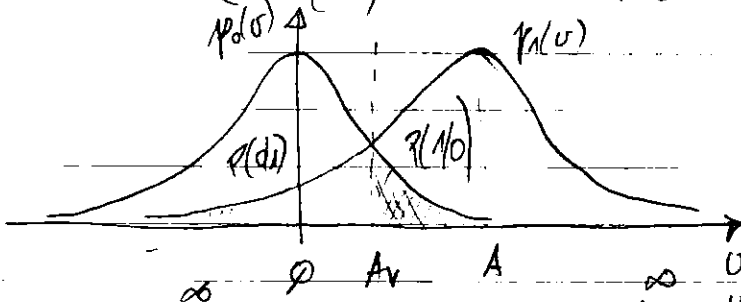
$$P(E) = P(0)P(1/0) + P(1)P(0/1)$$

$$P(x_i/y_j) = \frac{P(x_i, y_j)}{P(y_j)}$$

$$u(t) = s(t) + v(t)$$

$$u(t) = \begin{cases} A + v(t) & a_n = 1 \\ v(t) & a_n = 0 \end{cases}$$

$$A_v = \frac{A}{2} \quad P(0) = P(1)$$



$$P(1/0) = \int_{A_v}^{\infty} p_0(u) du = \frac{1}{\sqrt{2\pi}\sigma} \int_{A_v}^{\infty} e^{-\frac{u^2}{2\sigma^2}} du$$

$$t = \frac{u}{\sqrt{2\sigma^2}} \quad u = Av \quad t = \frac{Av}{\sqrt{2\sigma^2}}$$

$$dt = \frac{du}{\sqrt{2\sigma^2}}$$

$$P(1/0) = \frac{\sqrt{2\sigma^2}}{\sqrt{2\pi}\sigma} \int_{\frac{Av}{\sqrt{2\sigma^2}}}^{\infty} e^{-t^2} dt = \frac{1}{\sqrt{\pi}} \left[\int_0^{\infty} e^{-t^2} dt - \int_0^{\frac{Av}{\sqrt{2\sigma^2}}} e^{-t^2} dt \right]$$

$$\underline{P(1/0)} = \frac{1}{2} \left[1 - \frac{2}{\sqrt{\pi}} \int_0^{A/\sqrt{2\sigma_N^2}} e^{-t^2} dt \right] = \frac{1}{2} \left[1 - \Phi \left(\frac{A}{\sqrt{2\sigma_N^2}} \right) \right]$$

Wavelets aus dem orthogonalen System, Walter, Bes

$$P(0/1) = \int_{-\infty}^{A_1} P_1(u) du = \int_{-\infty}^{A_1} \frac{1}{\sqrt{2\sigma_N^2}} e^{-\frac{(u-A)^2}{2\sigma_N^2}} du \quad \begin{matrix} u-A = t \\ \frac{du}{\sqrt{2\sigma_N^2}} = dt \\ du = \sqrt{2\sigma_N^2} dt \end{matrix}$$

$$P(0/1) = \frac{1}{\sqrt{2\sigma_N^2}} \int_{-\infty}^{\frac{A_1-A}{\sqrt{2\sigma_N^2}}} e^{-t^2} dt = \frac{1}{\sqrt{\pi}} \left[\int_0^{\frac{A_1-A}{\sqrt{2\sigma_N^2}}} e^{-t^2} dt + \frac{2}{\sqrt{\pi}} \int_0^{\frac{A_1-A}{\sqrt{2\sigma_N^2}}} e^{-t^2} dt \right]$$

$$\underline{P(0/1)} = \frac{1}{2} \left[1 + \Phi \left(\frac{A_1-A}{\sqrt{2\sigma_N^2}} \right) \right] = \frac{1}{2} \left[1 - \Phi \left(\frac{A-A_1}{\sqrt{2\sigma_N^2}} \right) \right]$$

$$\hat{\sigma}^2 = \frac{A^2}{\sigma_N^2} \quad b_0 = \frac{A_1}{\sigma_N} \quad \begin{matrix} \hat{\sigma}^2 = A^2 & \sigma_N = \sigma_N \\ \text{LAWA SAGA NA KOLISIOT SISA} \end{matrix}$$

$$P(e) = P(0) \frac{1}{2} \left[1 - \Phi \left(\frac{A}{\sqrt{2\sigma_N^2}} \right) \right] + P(1) \frac{1}{2} \left[1 - \Phi \left(\frac{A-A_1}{\sqrt{2\sigma_N^2}} \right) \right]$$

$$P(0) = P(1) \Rightarrow \boxed{A_1 = \frac{A}{2}} \quad P(e) = 2 \cdot \frac{1}{2} \left[1 - \Phi \left(\frac{A}{2\sqrt{2\sigma_N^2}} \right) \right] = \frac{1}{2} \left[1 - \Phi \left(\frac{A}{2\sqrt{2\sigma_N^2}} \right) \right]$$

$$\text{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-u^2} du \quad \text{erfc}(x) = \frac{2}{\sqrt{\pi}} \int_x^{\infty} e^{-u^2} du = 1 - \text{erf}(x)$$

$$\frac{1}{\sqrt{\pi}} \int_0^{\infty} e^{-u^2} du = \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} e^{-u^2} du = \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} e^{-u^2} du$$

$$\hat{\sigma} = \frac{A_1}{\sigma_N} \quad \hat{\sigma}^2 = \frac{A^2}{\sigma_N^2} \quad P(1/0) = \frac{1}{2} \left[1 - \Phi \left(\frac{b_0}{\sqrt{2}} \right) \right]$$

$$P(0/1) = \frac{1}{2} \left[1 - \Phi \left(\frac{\hat{\sigma} - b_0}{\sqrt{2}} \right) \right] \quad P(e) = \frac{P(0)}{2} \left[1 - \Phi \left(\frac{b_0}{\sqrt{2}} \right) \right] + \frac{P(1)}{2} \left[1 - \Phi \left(\frac{\hat{\sigma} - b_0}{\sqrt{2}} \right) \right]$$

$$\Phi(x) = 2\text{erf}(x) - 1 = 2 \frac{1}{\sqrt{\pi}} \int_0^x e^{-u^2} du - \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} e^{-u^2} du = \frac{1}{\sqrt{\pi}} \int_{-\infty}^x e^{-u^2} du - \left(\frac{1}{\sqrt{\pi}} \int_{-\infty}^0 e^{-u^2} du - \frac{1}{\sqrt{\pi}} \int_0^{\infty} e^{-u^2} du \right) = \frac{1}{\sqrt{\pi}} \int_{-\infty}^x e^{-u^2} du - \frac{1}{\sqrt{\pi}} \int_0^{\infty} e^{-u^2} du$$

$$\boxed{\Phi(x) = \text{erf}(x) - \text{erfc}(x) = 1 - 2\text{erfc}(x) = 2\text{erf}(x) - 1}$$

$$P(e) = \frac{1}{2} \left[1 - \Phi\left(\frac{A}{\sqrt{2} \sqrt{2B^2}}\right) \right] = \frac{1}{2} \left[1 - \frac{1}{2} + 2 \operatorname{erfc}\left(\frac{A}{2\sqrt{2B^2}}\right) \right] = \operatorname{erfc}\left(\frac{A}{2\sqrt{2B^2}}\right)$$

UNIPOZAREN

• P(e)? ZA BIPOZAREN SIGNAL

$$u(t) = s(t) + y(t) \quad u(t_0) = \begin{cases} \frac{A}{2} + y(t_0) & a_1 = 1 \\ -\frac{A}{2} + y(t_0) & a_1 = 0 \end{cases}$$

$$P(e) = P(0)P(1/0) + P(1)P(0/1) \quad A_1 = 0$$

$$P(1/0) = \frac{1}{\sqrt{2B^2}} \int_0^{\infty} e^{-\frac{(u+\frac{A}{2})^2}{2B^2}} du \quad \left| \begin{array}{l} t = \frac{u+\frac{A}{2}}{\sqrt{2B^2}} \\ dt = \frac{du}{\sqrt{2B^2}} \\ u=0 \rightarrow t = \frac{A}{2\sqrt{2B^2}} \\ u=\infty \rightarrow t = \infty \end{array} \right.$$

$$= \frac{1}{\sqrt{\pi}} \int_{\frac{A}{2\sqrt{2B^2}}}^{\infty} e^{-t^2} dt = \frac{1}{\sqrt{\pi}} \int_0^{\infty} e^{-t^2} dt - \frac{1}{\sqrt{\pi}} \int_0^{\frac{A}{2\sqrt{2B^2}}} e^{-t^2} dt$$

$$= \frac{1}{2} \left[1 - \frac{2}{\sqrt{\pi}} \int_0^{\frac{A}{2\sqrt{2B^2}}} e^{-t^2} dt \right] = \frac{1}{2} \left[1 - \Phi\left(\frac{A}{2\sqrt{2B^2}}\right) \right]$$

$$P(0/1) = P(1/0) = \frac{1}{2} \left[1 - \Phi\left(\frac{A}{2\sqrt{2B^2}}\right) \right]$$

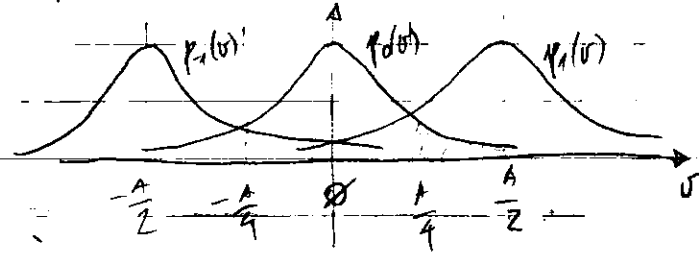
$$P(e) = \frac{1}{2} \cdot \frac{1}{2} \cdot 2 \left[1 - \Phi\left(\frac{A}{2\sqrt{2B^2}}\right) \right] = \operatorname{erfc}\left(\frac{A}{2\sqrt{2B^2}}\right) \quad A_1 = 0 \quad P(0) = P(1) = \frac{1}{2}$$

UNIPOZAREN I POLARIZOVAN SIGNAL IMAJ I STA P(e)

$$P_{SP} = \left(\frac{A}{2}\right)^2 \cdot P\left(\frac{A}{2}\right) + \left(-\frac{A}{2}\right)^2 \cdot P\left(\frac{A}{2}\right) = 2 \cdot \frac{1}{2} \cdot \frac{A^2}{4} = \frac{A^2}{4}$$

$$P_{\mu} = A^2 \cdot P\left(\frac{A}{2}\right) = \frac{A^2}{2} \quad \text{BIPOZARIZOVAN IMA 2x POMERAK POTREB SINKA}$$

• PSEUDOTERMINEN (ALTERNATIVNO BIPOZARIZOVAN) SIGNAL P(e)?



$$u(t_0) = s(t_0) + y(t_0) \quad u(t_0) = \begin{cases} \frac{A}{2} + y(t_0) & a_1 = 1 \\ y(t_0) & a_1 = 0 \\ -\frac{A}{2} + y(t_0) & a_1 = -1 \end{cases}$$

$$s(t) = \sum_{n=0}^{\infty} a_n g(t - nT_b)$$

$$P(e) = P(0) [P(1/0) + P(-1/0)] + P(1) [P(0/1) + P(-1/1)] + P(-1) [P(0/-1) + P(1/-1)]$$

$$P(0) = P(1) = P(-1) = \frac{1}{3} \quad P(1/0) = P(-1/0) = P(0/1) = P(0/-1)$$

$$P(1/1) = P(-1/1) = 0$$

$$P(e) = \frac{4}{3} [P(1/0) + P(-1/0) + P(0/1) + P(0/-1)]$$

$$P(e) = \frac{4}{3} P(1/0) = \frac{4}{3} \int_{\frac{A}{2}}^{\infty} \frac{1}{\sqrt{2B^2}} e^{-\frac{(u-\frac{A}{2})^2}{2B^2}} du \quad \left| \begin{array}{l} t = \frac{u-\frac{A}{2}}{\sqrt{2B^2}} \\ u = \frac{A}{2} \rightarrow t = 0 \\ u = \infty \rightarrow t = \infty \end{array} \right.$$

$$P(\epsilon) = \frac{4}{3} \int_0^{\infty} \frac{1}{\sqrt{\pi}} e^{-t^2} dt = \frac{4}{3} \left[\frac{1}{\sqrt{\pi}} \int_0^{\infty} e^{-t^2} dt + \frac{1}{\sqrt{\pi}} \int_0^{\infty} e^{-t^2} dt \right] =$$

$$= \frac{4}{3} \left(\frac{1}{2} - \frac{1}{2} \frac{2}{\sqrt{\pi}} \int_0^{\infty} e^{-t^2} dt \right) = \frac{2}{3} \left[1 + \Phi \left(\frac{A}{4\sqrt{2} \sigma \sqrt{2}} \right) \right]$$

$$P(\epsilon) = \frac{4}{3} P(1/0) = \frac{1}{\sqrt{2\pi} \sigma} \int_0^{\infty} e^{-\frac{v^2}{2\sigma^2}} dv \quad \frac{v}{\sqrt{2}\sigma} = t$$

$v=0 \quad t=0$
 $v=\infty \quad t=\infty$

$$P(\epsilon) = \frac{4}{3} \frac{1}{\sqrt{\pi}} \int_{\frac{A}{4\sqrt{2}\sigma}}^{\infty} e^{-t^2} dt = \frac{1}{\sqrt{\pi}} \left[\int_0^{\infty} e^{-t^2} dt - \int_0^{\frac{A}{4\sqrt{2}\sigma}} e^{-t^2} dt \right] =$$

$$P(\epsilon) = \frac{4}{3} \left[1 - \Phi \left(\frac{A}{4\sqrt{2}\sigma} \right) \right]$$

$$\Phi(x) = 1 - 2\text{erfc}(x)$$

$$P(\epsilon) = \frac{1}{2} [2\text{erfc}(x)] = \text{erfc}(x)$$

$$P(\epsilon) = \frac{4}{3} \text{erfc} \left(\frac{A}{4\sqrt{2}\sigma} \right)$$

PSUDOTEMEN

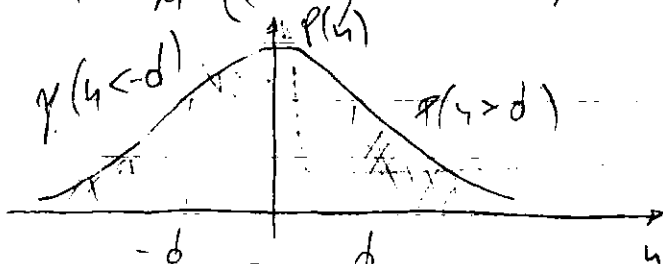
$$\text{erfc} = \frac{1}{\sqrt{\pi}} \int_x^{\infty} e^{-u^2} du$$

$$A=5 \quad \sigma=0,235 \rightarrow P(\epsilon) = 1,3 \cdot 10^{-7}$$

• **ВОПРОСЫ НА ПЕРВЫХ ЧАСТИХ М-ЕН СИСТЕМ**

$$P(u_i) = \frac{1}{M} \quad u_i = 0, 1, 2, \dots, M$$

$$P(\epsilon) = \frac{1}{M} \left\{ (M-2) P(|u| > d) + 2P(u > d) \right\} \quad P(u > d) = P(u < -d)$$



НА ПЕРВЫХ ЧАСТИХ М-ЕН СИСТЕМ

$$P(|u| > d) = P(u > d \vee u < -d) =$$

$$P(u > d) + P(u < -d) = 2P(u > d)$$

$$P(\epsilon) = \frac{1}{M} \left\{ (M-2) P(|u| > d) + P(u > d) \right\} = \frac{M-1}{M} P(u > d)$$

$$P(|u| > d) = 2P(u > d) = 2 \frac{1}{\sqrt{2\pi} \sigma} \int_d^{\infty} e^{-\frac{v^2}{2\sigma^2}} dv \quad \frac{v}{\sqrt{2}\sigma} = t$$

$v=d \quad t = \frac{d}{\sqrt{2}\sigma}$
 $v=\infty \quad t=\infty$

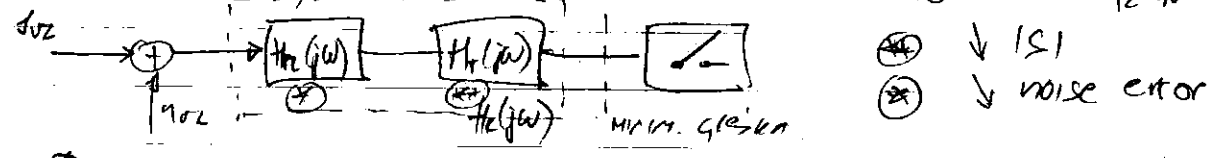
$$P(|u| > d) = 2 \frac{\sqrt{2}\sigma}{\sqrt{2\pi} \sigma} \int_{\frac{d}{\sqrt{2}\sigma}}^{\infty} e^{-t^2} dt = \frac{2}{\sqrt{\pi}} \left(- \int_0^{\frac{d}{\sqrt{2}\sigma}} e^{-t^2} dt + \int_0^{\infty} e^{-t^2} dt \right)$$

$$= \frac{2}{\sqrt{\pi}} \left[\frac{\sqrt{\pi}}{2} - \frac{\sqrt{\pi}}{2} \Phi \left(\frac{d}{\sqrt{2}\sigma} \right) \right] = \left[1 - \Phi \left(\frac{d}{\sqrt{2}\sigma} \right) \right]$$

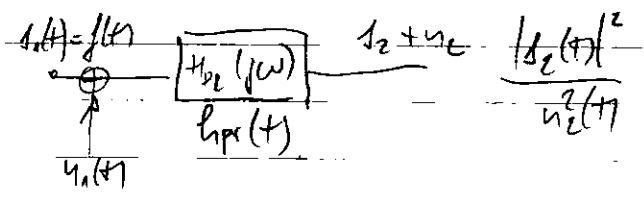
$$P(u > d) = \frac{2(M-1)}{M} \text{erfc} \frac{d}{\sqrt{2}\sigma} \quad P(|u| > d) = \frac{M-1}{M} \left[1 - \Phi \left(\frac{d}{\sqrt{2}\sigma} \right) \right]$$

$$P(e) \Big|_{m=3} = \frac{2.2}{3} \operatorname{erfc} \frac{d}{\sqrt{25.2}} = \frac{4}{3} \operatorname{erfc} \frac{d}{\sqrt{25.2}}$$

$M \rightarrow P(E) \rightarrow$ ЗАТОС ТИЗДА $\rightarrow \frac{S}{N}$ т.е. $\frac{d}{\sqrt{25.2}}$



• ПУЛГАДОН ФИЛТЕР



$$u_2(t_0) = \int_{-\infty}^{\infty} u_1(\tau) h(t_0 - \tau) d\tau$$

$$u_2(t_0) = \int_{-\infty}^{\infty} u_1(\tau) h(t_0 - \tau) d\tau$$

$$u_2(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(j\omega) H_2(j\omega) e^{j\omega t} d\omega$$

$$F(j\omega) = \mathcal{F}\{f(t)\} = \mathcal{F}\{g(t)\}$$

$$u_2(t_0) = A = \frac{1}{2\pi} \left| \int_{-\infty}^{\infty} F(j\omega) H_2(j\omega) e^{j\omega t_0} d\omega \right|$$

$u_1(t)$ - БЕЗ ГАУСОН СУМ. СО $\Phi_{u_1}(\omega) \equiv u_0$ ТОКА СЛУЧАЙНО
 СНАЧА НА СУМОТ НА ИЕЦЕ ФИЛТЕРОТ СЕ ДИДЕ

$$P_{u_2}(\theta) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \Phi_{u_2}(\omega) d\omega \quad \Phi_{u_2}(\omega) = |H(j\omega)|^2 \cdot \underbrace{\Phi_{u_1}(\omega)}_{u_0}$$

$$u_2^2(t) = P_{u_2}(\theta) = \frac{u_0}{2\pi} \int_{-\infty}^{\infty} |H(j\omega)|^2 d\omega = \sigma_N^2$$

$$\sigma_N^2 = u_2^2(t) - u_2^2$$

$$= u_2^2(t)$$

$$\sigma_2 = 0$$

$$\sigma^2 = \frac{A^2}{N^2} = \frac{1}{(4\pi)^2} \left| \int_{-\infty}^{\infty} F(j\omega) H_2(j\omega) e^{j\omega t_0} d\omega \right|^2$$

$$= \frac{1}{4\pi} \int_{-\infty}^{\infty} |H_2(j\omega)|^2 d\omega$$

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$$\left| \int_{-\infty}^{\infty} x(j\omega) Y(j\omega) d\omega \right|^2 \leq \int_{-\infty}^{\infty} |x(j\omega)|^2 d\omega \int_{-\infty}^{\infty} |Y(j\omega)|^2 d\omega$$

СТАТИВО
УСРЕДНЕНО

$$R_{ff}(t) = \int_{-\infty}^{\infty} f(t) \cdot f(t+\tau) d\tau = \int_{-\infty}^{\infty} f(t) \left[\frac{1}{2\pi} \int_{-\infty}^{\infty} F(j\omega) e^{j\omega t} e^{j\omega \tau} d\omega \right] dt$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} F(j\omega) \left[\int_{-\infty}^{\infty} f(t) e^{j\omega t} dt \right] e^{j\omega \tau} d\omega = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(j\omega) F^*(j\omega) e^{j\omega \tau} d\omega$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} |F(j\omega)|^2 e^{j\omega \tau} d\omega$$

$$E = \int_{-\infty}^{\infty} f^2(t) dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} |F(j\omega)|^2 d\omega$$

$$\frac{A^2}{\sigma_N^2 E} = \frac{1}{4\pi^2} \left| \int_{-\infty}^{\infty} F(j\omega) H_{re}(j\omega) e^{j\omega t_0} d\omega \right|^2$$

$$\frac{40}{2\pi} \int_{-\infty}^{\infty} |H(j\omega)|^2 d\omega \leq \frac{1}{2\pi} \int_{-\infty}^{\infty} |F(j\omega)|^2 d\omega$$

СИГНАЛОВА НЕОПРЕДЕЛЕНА:

$$\left| \int_{-\infty}^{\infty} F(j\omega) H_{re}(j\omega) e^{j\omega t_0} d\omega \right|^2 \leq \int_{-\infty}^{\infty} |F(j\omega)|^2 d\omega \int_{-\infty}^{\infty} |H_{re}(j\omega)|^2 d\omega$$

① $F(j\omega) = k X^*(j\omega)$ т.е. $H_{re}(j\omega) = k F^*(j\omega) e^{-j\omega t_0}$

КО ОВОД СЛУЖИТЕ ВАШЕ ЕНЕРГИЈА НА СИГНАЛОТ НЕОПРЕДЕЛЕНА

$$\frac{A^2}{\sigma_N^2 E} \leq \frac{\int_{-\infty}^{\infty} |F(j\omega)|^2 d\omega \int_{-\infty}^{\infty} |H_{re}(j\omega)|^2 d\omega}{40 \int_{-\infty}^{\infty} |H(j\omega)|^2 d\omega \int_{-\infty}^{\infty} |F(j\omega)|^2 d\omega}$$

$$\frac{A^2}{\sigma_N^2 E} \leq \frac{1}{40}$$

$$\frac{A^2}{\sigma_N^2} \leq \frac{E}{40}$$

E - ЕНЕРГИЈА НА СИГНАЛОТ НА ВХОД ОД ФИЛТОТ (ВЕННА СИГНАЛОВА СИСТЕМА)
 40 - СИСТЕМА СИГНАЛОВА ФИЛТОТ СЛУЖИ НА ВХОД ОД ФИЛТОТ

АВО Е ИЗВОРЕТО ① ТОГАШ 40 КОД ВАШЕ МАТ. ОПОНОТ S/N НА ВХОД ОД ФИЛТОТ

$$S_{max} = \frac{A^2}{\sigma_N^2} \Big|_{max} = \frac{E}{40} \quad (11)$$

ОПТИМАЛНА СИСТЕМА КОВА НА Р.Ф. Е ДАВА СО ①

• ЕНЕРГИЈА НА ВХОД ОД СС.

$$E = \int_{-\infty}^{\infty} f^2(t) dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} |F(j\omega)|^2 d\omega$$

$E^2 = A^2 \cdot T_d$ ЗА ОРАМЕН ИМПУЛС СО АМП. A , ВРЕМЕ T_d

$$f(t) = \text{erfc} \frac{A}{2\sqrt{2} \sigma_N} = \text{erfc} \frac{1}{2} \sqrt{\frac{E}{240}} = f \left(\sqrt{\frac{E}{40}} \right)$$

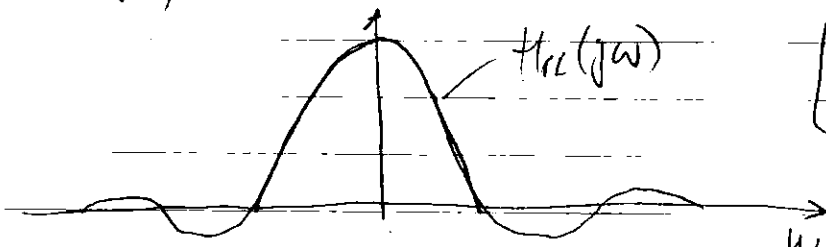
$$f(t) = \frac{2\mu-1}{\mu} \text{erfc} \left(\frac{d}{\sqrt{2} \sigma_N} \right) = \frac{4}{3} \text{erfc} \left(\frac{A}{4\sqrt{2} \sigma_N} \right) = \frac{4}{3} \text{erfc} \left(\frac{A}{4} \sqrt{\frac{A}{240}} \right)$$

$$f(t) = f \left(\sqrt{\frac{E}{40}} \right) \Rightarrow \text{ЗА АМЛ}$$

$$H_{re}(j\omega) = k F^*(j\omega) e^{-j\omega t_0}$$

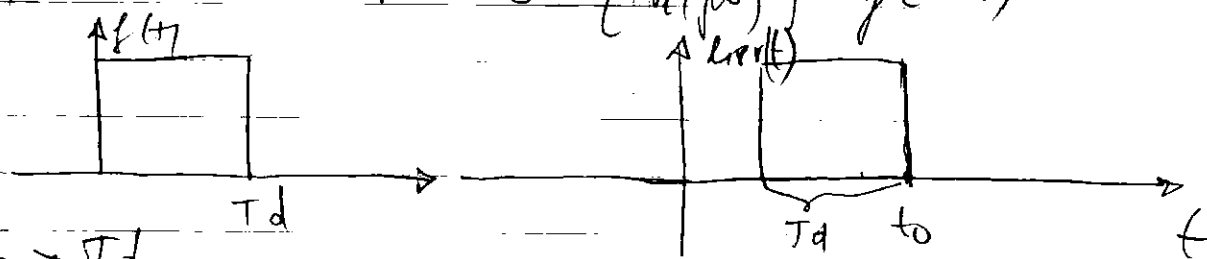
$$\mathcal{F}^{-1}\{H_{re}(j\omega)\} = h_{re}(t)$$

$$h_{re}(t) = k \cdot f(t - t_0)$$



$$\frac{1}{2\pi} \int_{-\infty}^{\infty} F^*(j\omega) e^{-j\omega t_0} e^{+j\omega t} d\omega = \left[\frac{1}{2\pi} \int_{-\infty}^{\infty} F(j\omega) e^{+j\omega(t-t_0)} d\omega \right]^* = f^*(t-t_0)$$

$$f(t) = \mathcal{F}^{-1}\{H_{re}(j\omega)\} \Rightarrow \mathcal{F}^{-1}\{H_{re}(j\omega)\} = f(t-t_0)$$



$t_0 > T_d$ \Rightarrow ~~the~~ ~~side~~ ~~is~~ ~~not~~ ~~correct~~ ~~at~~ ~~all~~

$$I_2(t_0) = A = \frac{1}{2\pi} \int_{-\infty}^{\infty} H_{re}(j\omega) \cdot F(j\omega) e^{j\omega t_0} d\omega = \frac{k}{2\pi} \int_{-\infty}^{\infty} F^*(j\omega) e^{j\omega t_0} F(j\omega) d\omega$$

$$I_2(t_0) = A = \frac{k}{2\pi} \int_{-\infty}^{\infty} |F(j\omega)|^2 d\omega = \underline{k \cdot E}$$

A^2 - MAX POWER SIGNAL IN VOLTAGE SENSE

$$N = \overline{v_d^2} = \frac{v_0}{2\pi} \int_{-\infty}^{\infty} |H_{re}(j\omega)|^2 d\omega = \frac{v_0 k^2}{2\pi} \int_{-\infty}^{\infty} |F(j\omega)|^2 d\omega = v_0 k E$$

$$\left. \frac{A}{\overline{v_d^2}} \right|_{\max} = \frac{k \cdot E}{v_0 k E} = \frac{1}{v_0 k}$$

• СЛАБЕЖЕНА НА АМПЛИТУДА НА ВЪВЕДЕНАТО ФИЛТЕР

$$P_s(t) = \frac{v}{Z_N} e^{-\frac{v^2 + A^2}{2Z_N^2}} \quad I_0\left(\frac{Av}{Z_N^2}\right)$$

$$I_0\left(\frac{Av}{Z_N^2}\right) = \frac{1}{2\pi} \int_0^{2\pi} \frac{Av}{Z_N^2} \cdot \cos \varphi \, d\varphi$$

$$P_{avg}(r, \varphi) = \frac{v}{2\pi Z_N^2} e^{-\frac{v^2 + A^2 + 2Av \cos \varphi}{2Z_N^2}}$$

$$P_{avg} = \int_0^A \frac{v}{2\pi Z_N^2} e^{-\frac{v^2 + A^2 + 2Av \cos \varphi}{2Z_N^2}} dv = \frac{1}{2\pi Z_N^2} \int_0^A v e^{-\frac{v^2}{2Z_N^2}} \cdot e^{-\frac{A^2}{2Z_N^2}} \cdot e^{-\frac{Av \cos \varphi}{Z_N^2}} dv$$

$$\rho = \frac{A \sin \phi}{2\pi b_N^2} \left(\frac{r+A \sin \phi}{2b_N} \right)^k \quad \rho = \frac{(1+2A \cos \phi + A^2 \sin^2 \phi)}{2b_N^2} \quad dr = k \int_0^A r e^{-\frac{(r+A \sin \phi)^2}{2b_N^2}} dr$$

$$U = \int_0^A e^{-\frac{(r+A \sin \phi)^2}{2b_N^2}} dr \quad t = \frac{(r+A \sin \phi)}{\sqrt{2b_N^2}} \quad r=A \quad t = \frac{A(1+\sin \phi)}{\sqrt{2b_N^2}}$$

$$r=0 \quad t = \frac{A \sin \phi}{\sqrt{2b_N^2}} \quad dt = \frac{dr}{\sqrt{2b_N^2}}$$

$$U = \sqrt{2b_N^2} \int_{\frac{A \sin \phi}{\sqrt{2b_N^2}}}^{\frac{A(1+\sin \phi)}{\sqrt{2b_N^2}}} e^{-t^2} dt = \frac{\sqrt{2b_N^2}}{\sqrt{\pi}} \cdot \frac{\sqrt{\pi}}{2} \left[\int_0^{t_1} e^{-t^2} dt - \int_0^{t_2} e^{-t^2} dt \right]$$

$$U = \frac{\sqrt{2\pi b_N^2}}{2} \left[\Phi \left[\frac{A(1+\sin \phi)}{\sqrt{2b_N^2}} \right] - \Phi \left[\frac{A \sin \phi}{\sqrt{2b_N^2}} \right] \right]$$

$$\rho_\phi = \mu \cdot U = \int \sigma \delta M \quad \left[\int e^{-x^2} dx = \frac{\sqrt{\pi}}{2} \Phi(x) \right. \\ \left. \int \Phi(x) dx = x \cdot \Phi(x) + \frac{e^{-x^2}}{\sqrt{\pi}} \right]$$

$$U = \int e^{-\frac{(r+A \sin \phi)^2}{2b_N^2}} dr = \sqrt{2b_N^2} \int e^{-\frac{(r+A \sin \phi)^2}{2b_N^2}} d \left(\frac{r+A \sin \phi}{\sqrt{2b_N^2}} \right) =$$

$$= \sqrt{2b_N^2} \cdot \frac{\sqrt{\pi}}{2} \Phi \left[\frac{r+A \sin \phi}{\sqrt{2b_N^2}} \right] = \frac{\sqrt{2\pi b_N^2}}{2} \Phi \left[\frac{r+A \sin \phi}{\sqrt{2b_N^2}} \right]$$

$$\rho_\phi = k \sqrt{\frac{2\pi b_N^2}{2}} \Phi \left[\frac{r+A \sin \phi}{\sqrt{2b_N^2}} \right] \Big|_0^A - \int_0^A \frac{\sqrt{2\pi b_N^2}}{2} \Phi \left[\frac{r+A \sin \phi}{\sqrt{2b_N^2}} \right] dr =$$

$$= \frac{A k \sqrt{2\pi b_N^2}}{2} \Phi \left(\frac{A+A \sin \phi}{\sqrt{2b_N^2}} \right) - \frac{\sqrt{2\pi b_N^2}}{2} k \sqrt{2\pi b_N^2} \int_0^A \Phi \left[\frac{r+A \sin \phi}{\sqrt{2b_N^2}} \right] d \left(\frac{r+A \sin \phi}{\sqrt{2b_N^2}} \right)$$

$$= \frac{A k \sqrt{2\pi b_N^2}}{2} \Phi \left(\frac{A+A \sin \phi}{\sqrt{2b_N^2}} \right) - k \cdot b_N^2 \sqrt{\pi} \left[\frac{r+A \sin \phi}{\sqrt{2b_N^2}} \cdot \Phi \left[\frac{r+A \sin \phi}{\sqrt{2b_N^2}} \right] \right] \Big|_0^A - \frac{k b_N^2 \sqrt{\pi}}{\sqrt{\pi}} \frac{e^{-\frac{(r+A \sin \phi)^2}{2b_N^2}}}{\sqrt{\pi}} \Big|_0^A$$

$$= \frac{A k \sqrt{2\pi b_N^2}}{2} \Phi \left(\frac{A+A \sin \phi}{\sqrt{2b_N^2}} \right) - \frac{k \cdot \sqrt{2\pi b_N^2} \sqrt{\pi}}{2} \left[(A+A \sin \phi) \Phi \left(\frac{A+A \sin \phi}{\sqrt{2b_N^2}} \right) - A \sin \phi \Phi \left(\frac{A \sin \phi}{\sqrt{2b_N^2}} \right) \right] - k_1$$

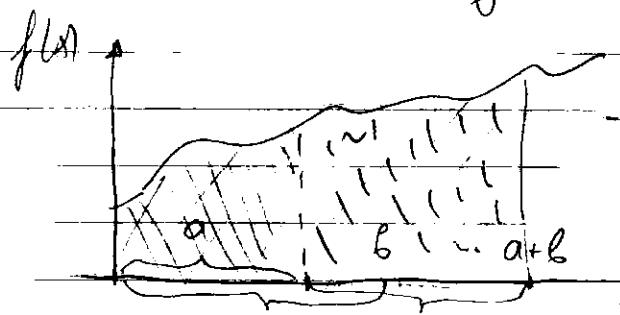
$$= \frac{A k \sqrt{2\pi b_N^2}}{2} A \sin \phi \Phi \left(\frac{A \sin \phi}{\sqrt{2b_N^2}} \right) - \frac{A k \cdot \sqrt{2\pi b_N^2} \sqrt{\pi}}{2} A \sin \phi \Phi \left(\frac{A+A \sin \phi}{\sqrt{2b_N^2}} \right) - k_1$$

$$P_y = \frac{A^2 k \sqrt{2\pi b_N^2}}{2} \sin \varphi \left[\Phi \left(\frac{A \sin \varphi}{\sqrt{2\pi b_N^2}} \right) - \Phi \left(\frac{A + A \sin \varphi}{\sqrt{2\pi b_N^2}} \right) \right] - K_1$$

$$K = e^{-\frac{A^2 \sin^2 \varphi}{2b_N^2}} e^{-\frac{A^2}{2b_N^2}} \frac{1}{2\pi b_N^2}$$

$$P_y = \frac{A^2 e^{-\frac{A^2 \sin^2 \varphi}{2b_N^2}} e^{-\frac{A^2}{2b_N^2}} \sin \varphi}{2 \sqrt{2\pi b_N^2}} \left[\Phi \left(\frac{A \sin \varphi}{\sqrt{2\pi b_N^2}} \right) - \Phi \left(\frac{A + A \sin \varphi}{\sqrt{2\pi b_N^2}} \right) \right] - K_1$$

$$\int_0^{a+b} e^{-x^2} dx = \int_0^b e^{+x^2} dx - \int_0^a e^{-x^2} dx + \int_0^a e^{-x^2} dx$$



$$\textcircled{\#} = \int_0^a f(x) dx - \int_0^b f(x) dx = - \int_b^a f(x) dx$$

$$\textcircled{\#} = - \left[\int_0^b f(x) dx - \int_0^a f(x) dx \right] = \int_0^a f(x) dx - \int_0^b f(x) dx$$

$$P_y = \frac{1}{2\sqrt{2\pi b_N^2}} A^2 e^{-\frac{A^2 \sin^2 \varphi}{2b_N^2}} e^{-\frac{A^2}{2b_N^2}} \sin \varphi \left[\Phi \left(\frac{A \sin \varphi}{\sqrt{2\pi b_N^2}} \right) - \Phi \left(\frac{A}{\sqrt{2\pi b_N^2}} \right) \right] - K_1$$

$$K_1 = K b_N^2 \left[e^{-\frac{(A + A \sin \varphi)^2}{2b_N^2}} - e^{-\frac{A^2 \sin^2 \varphi}{2b_N^2}} \right]$$

~~$$= \frac{1}{2\pi} e^{-\frac{A^2 \sin^2 \varphi}{2b_N^2}} e^{-\frac{A^2}{2b_N^2}} \frac{1}{2\pi b_N^2} \left[e^{-\frac{(A + A \sin \varphi)^2}{2b_N^2}} - e^{-\frac{A^2 \sin^2 \varphi}{2b_N^2}} \right]$$~~

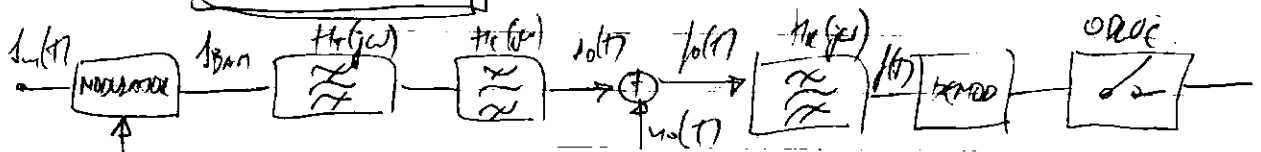
$$K_1 = e^{-\frac{A^2 \sin^2 \varphi}{2b_N^2}} e^{-\frac{A^2}{2b_N^2}} \frac{1}{2\pi b_N^2} \left[e^{-\frac{A^2 + 2A \sin \varphi + A^2 \sin^2 \varphi}{2b_N^2}} - e^{-\frac{A^2 \sin^2 \varphi}{2b_N^2}} \right]$$

$$= e^{-\frac{A^2}{2b_N^2}} \frac{1}{2\pi} \left[e^{-\frac{A^2 + 2A \sin \varphi}{2b_N^2}} - 1 \right] = \frac{1}{2\pi} \left[e^{-\frac{A^2 + 2A \sin \varphi}{2b_N^2}} - e^{-\frac{A^2}{2b_N^2}} \right]$$

$$P_y = \frac{1}{2\sqrt{2\pi b_N^2}} A^2 e^{-\frac{A^2 \sin^2 \varphi}{2b_N^2}} \sin \varphi \left[\Phi \left(\frac{A \sin \varphi}{\sqrt{2\pi b_N^2}} \right) - \Phi \left(\frac{A}{\sqrt{2\pi b_N^2}} \right) \right] - \frac{1}{2\pi} \left(e^{-\frac{A^2 + 2A \sin \varphi}{2b_N^2}} - e^{-\frac{A^2}{2b_N^2}} \right)$$

• DIGITALNA AMPLITUĐNA MODULACIJA (DAM)

GIZORGI: 070410610



$$s_q(t) = s_q(t) = \sum_{n=-\infty}^{\infty} a_n g_p(t - nT_d)$$

$$g_p = \begin{cases} A_p & 0 \leq t \leq T_d \\ 0 & \text{narvan} \end{cases}$$

DAM $a_n \in \{1, 0\}$

$$s_{DM}(t) = s_q(t) \cdot \cos(\omega_0 t) = \begin{cases} A_p \cos \omega_0 t & a_n = 1 \text{ } t \in T_d \\ 0 & a_n = 0 \text{ } t \notin T_d \end{cases}$$

$$f_0(t) = s_0(t) + y_0(t)$$

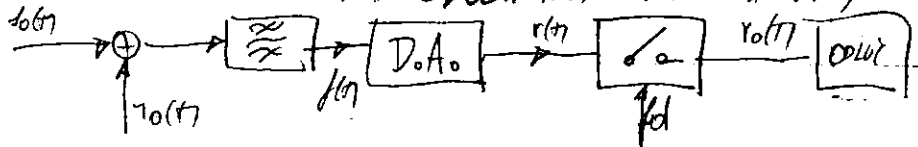
$$f(t) = s(t) + y(t)$$

$$s(t) = \begin{cases} g(t) \cos(\omega_0 t) & a_n = 1 \\ 0 & a_n = 0 \end{cases}$$

$f_s = \frac{f_0}{2}$

$f_g = 2f_s = 2 \frac{f_0}{T_d}$

• NEKODIRANA DEMODULACIJA NA DAM



$$f(t) = \begin{cases} s(t) + y(t) & a_n = 1 \\ y(t) & a_n = 0 \end{cases}$$

$$y(t) = \begin{cases} [g(t) \cos \omega_0 t + y(t)] \cos \omega_0 t & a_n = 1 \\ y(t) \cos \omega_0 t & a_n = 0 \end{cases}$$

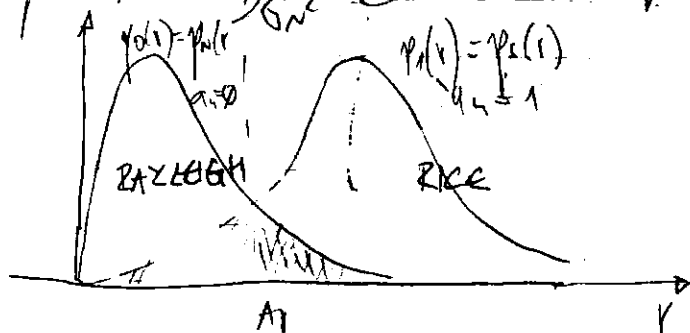
$$r(t) = \begin{cases} \sqrt{[g(t) \cos \omega_0 t + y(t)]^2 + y^2(t)} & a_n = 1 \\ \sqrt{y^2(t) + y^2(t)} & a_n = 0 \end{cases}$$

$$g(t_0) = A \quad f(t_0) = [A + x(t)] \cos \omega_0 t - y(t) \sin \omega_0 t \quad a_n = 1$$

• PRAKTIČNA IZVEDBA

$$p_s(r) = \frac{r}{\sqrt{2\pi} \sigma^2} e^{-\frac{(r-A)^2}{2\sigma^2}} I_0\left(\frac{Ar}{\sigma^2}\right) \Rightarrow \text{sigmal}$$

$$p_n(r) = -\frac{r}{\sqrt{2\pi} \sigma^2} e^{-\frac{r^2}{2\sigma^2}} \Rightarrow \text{sum}$$



$$p(e) = p(0) \cdot p(1/0) + p(1) \cdot p(0/1)$$

$$p(0/1) = \int_{-\infty}^{\infty} p_s(r) dr$$

$$p(1/0) = \int_{A_1}^{\infty} p_0(r) dr$$

$$r'(e) = \frac{1}{2} \int_0^{A_1} r_1(r) dr = \frac{1}{2} \int_0^{A_1} r_0(r) b r^2$$

$$\frac{\partial r'(e)}{\partial A_1} = \frac{1}{2} [r_1(A_1) - r_0(A_1)] = 0$$

$$I_0\left(\frac{A_1 r}{\sigma_N^2}\right) = e^{-\frac{A_1^2 + r^2}{2\sigma_N^2}} I_0\left(\frac{A_1 r}{\sigma_N^2}\right) = \frac{A_1 r}{\sigma_N^2} e^{-\frac{A_1^2}{2\sigma_N^2}}$$

$$I_0\left(\frac{A_1 r}{\sigma_N^2}\right) = e^{-\frac{A_1^2}{2\sigma_N^2} + \frac{A_1^2 + r^2}{2\sigma_N^2}} = e^{\frac{r^2}{2\sigma_N^2}}$$

MINIMIZOVATI $r'(e)$
 I.E. DERIVATA ZA
 AT VO PROJEKTOVATI

$$I_0\left(\frac{A_1 r}{\sigma_N^2}\right) = \frac{1}{2\pi} \int_0^{2\pi} e^{\frac{A_1 r}{\sigma_N^2} \cos \varphi} d\varphi$$

$$A_{opt} = f\left(\frac{A^2}{\sigma_N^2}\right) = f(\hat{\rho}^2)$$

$\hat{\rho}^2 = \frac{A^2}{\sigma_N^2}$

$b_0 = \frac{A}{\sigma_N}$

$$P_s = P(0) \cdot 0^2 + P(A) \cdot A^2 = \frac{A^2}{2}$$

$$\hat{\rho}^2 = \frac{A^2}{2\sigma_N^2}$$

$$\hat{\rho}^2 = \frac{\rho^2}{2}$$

$$b_{opt} = \sqrt{2 + \frac{\hat{\rho}^2}{4}}$$

$$P(1|0) = \int_{A_1}^{\infty} \frac{r}{\sigma_N^2} e^{-\frac{r^2}{2\sigma_N^2}} dr = - \int_{A_1}^{\infty} e^{-\frac{r^2}{2\sigma_N^2}} d\left(\frac{r^2}{2\sigma_N^2}\right) = -e^{-\frac{r^2}{2\sigma_N^2}} \Big|_{A_1}^{\infty}$$

$$P(1|0) = -\left(0 - e^{-\frac{A_1^2}{2\sigma_N^2}}\right) = e^{-\frac{A_1^2}{2\sigma_N^2}} = e^{-\frac{b_0^2}{2}}$$

$$P(0|1) = \int_0^{\infty} \frac{r}{\sigma_N^2} e^{-\frac{r^2 + A^2}{2\sigma_N^2}} I_0\left(\frac{A \cdot r}{\sigma_N^2}\right) dr = 1 - P(1|1)$$

$$P(0|1) = 1 - \int_{A_1}^{\infty} \frac{r}{\sigma_N^2} e^{-\frac{r^2 + A^2}{2\sigma_N^2}} I_0\left(\frac{A \cdot r}{\sigma_N^2}\right) dr = 1 - \int_{b_0}^{\infty} r_0 e^{-\frac{(r_0^2 + \hat{\rho}^2)}{2}} I_0(r_0 \hat{\rho}) dr_0$$

$r_0 = \frac{r}{\sigma_N}$

$b_0 = \frac{A}{\sigma_N}$

DEFINICIJA NA Θ FUNKCIJA

$$Q(a, b) = \int_a^{\infty} x e^{-\frac{x^2 + a^2}{2}} I_0(a \cdot x) dx$$

$$P(0|1) = 1 - Q\left(\frac{A}{\sigma_N}, \frac{A}{\sigma_N}\right) = 1 - Q(\hat{\rho}, b_0)$$

$$P(e) = P(1) [1 - Q(\hat{\rho}, b_0)] + P(0) \cdot e^{-\frac{b_0^2}{2}}$$

$$P(e) = P(1) [1 - Q(\hat{\rho}, \sqrt{2 + \frac{\hat{\rho}^2}{4}})] + P(0) \cdot e^{-\frac{1}{2}(2 + \frac{\hat{\rho}^2}{4})}$$

• Ako $\hat{\sigma} \gg 1$ тогад $Q(\hat{\sigma}, \sqrt{2 + \frac{\hat{\sigma}^2}{2}}) = Q(\hat{\sigma}, \frac{\hat{\sigma}}{\sqrt{2}})$

$Q(\hat{\sigma}, \frac{\hat{\sigma}}{\sqrt{2}}) = \frac{1}{2} \left[1 + \Phi\left(\frac{\hat{\sigma} - \hat{\sigma}_0}{\frac{\hat{\sigma}}{\sqrt{2}}}\right) \right] = \text{erf}\left(\frac{\hat{\sigma} - \hat{\sigma}_0}{\sqrt{2}}\right)$

$\frac{1}{2} \left[\frac{2}{\sqrt{\pi}} \int_{-\infty}^x e^{-t^2} dt + \frac{2}{\sqrt{\pi}} \int_0^x e^{-t^2} dt \right] = \frac{1}{\sqrt{\pi}} \int_0^x e^{-t^2} dt = \text{erf}(x)$

$\text{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-t^2} dt$ тако $\text{erf}(x) = \frac{1}{\sqrt{\pi}} e^{-x^2}$

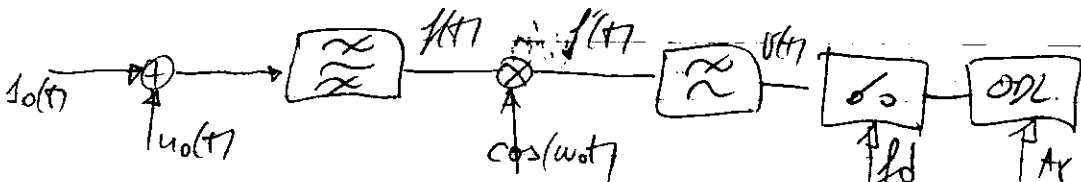
$Q(\hat{\sigma}, \frac{\hat{\sigma}}{\sqrt{2}}) = \text{erf}\left(\frac{\hat{\sigma}}{\sqrt{2}}\right) = 1 - \frac{\sqrt{2}}{\sqrt{\pi}} e^{-\frac{\hat{\sigma}^2}{2}} = 1 - \frac{1}{\sqrt{\pi}} e^{-\frac{\hat{\sigma}^2}{2}}$

• Ako $P(0) = P(1) = \frac{1}{2}$

$P(\varepsilon) = \frac{1}{2} \frac{1}{\sqrt{\pi}} \left[\frac{2}{\sqrt{\pi}} e^{-\frac{\varepsilon^2}{8}} + \frac{1}{2} e^{-\frac{\varepsilon^2}{8}} \right]$

Ako: $\hat{\sigma} \gg 1$ $\text{erf} \rightarrow 1$ $P(\varepsilon) = \frac{1}{2} e^{-\frac{\varepsilon^2}{8}}$

• KOHERENTNA DEMODULACIJA NA DAM



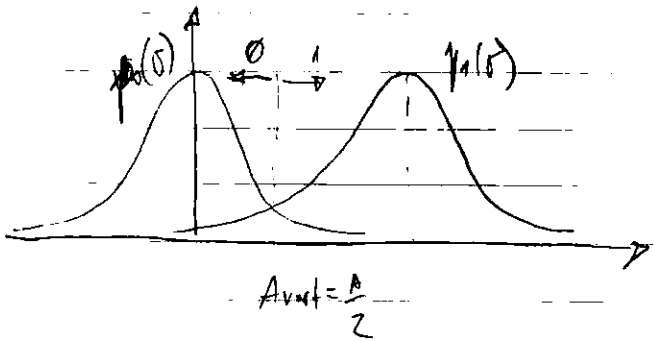
$$f(t) = \begin{cases} [g(t) + x(t)] \cos(\omega_0 t) - \gamma(t) \sin(\omega_0 t) & a_4 = 1 \\ x(t) \cos(\omega_0 t) - \gamma(t) \sin(\omega_0 t) & a_4 = 0 \end{cases}$$

$$\begin{aligned} \cos \omega_0 t \cdot \cos \omega_0 t &= \frac{1}{2} [\cos(\omega_0 t + \omega_0 t) + \cos(\omega_0 t - \omega_0 t)] = \frac{1}{2} [1 + \cos(2\omega_0 t)] \\ \sin \omega_0 t \cdot \sin \omega_0 t &= \frac{1}{2} [\cos(\omega_0 t - \omega_0 t) - \cos(\omega_0 t + \omega_0 t)] = \frac{1}{2} [1 - \cos(2\omega_0 t)] \\ \sin \omega_0 t \cdot \cos \omega_0 t &= \frac{1}{2} [\sin(\omega_0 t + \omega_0 t) + \sin(\omega_0 t - \omega_0 t)] = \frac{1}{2} \sin(2\omega_0 t) \end{aligned}$$

$$f'(t) = \begin{cases} \frac{1}{2} [g(t) + x(t)] (1 + \cos(2\omega_0 t)) - \frac{1}{2} \gamma(t) \sin(2\omega_0 t) & a_4 = 1 \\ \frac{1}{2} x(t) \cos(\omega_0 t) - \frac{1}{2} \gamma(t) \sin(2\omega_0 t) & a_4 = 0 \end{cases}$$

$v(t) = \begin{cases} k_D [g(t) + x(t)] & k_D - \text{konstanta od filtera} \\ k_D \cdot x(t) & k_D = \frac{k_F}{2} - \text{konstanta od demod. filtera} \end{cases}$

$v(t_0) = \begin{cases} k_D [A + x(t_0)] & a_4 = 1 \\ k_D x(t_0) & a_4 = 0 \end{cases}$ $v(t) \Rightarrow$ GARDOVA DEMODULACIJA !!!



$$P(E) = P(0) \cdot P(1/0) + P(1) \cdot P(0/1)$$

$$Avant = \frac{A}{2}$$

$$P(1/0) = \text{erfc} \frac{Av}{\sqrt{2\sigma_n^2}} = \text{erfc} \frac{A}{2\sqrt{2}\sigma_n}$$

$$P(0/1) = \text{erfc} \frac{A \cdot Av}{\sqrt{2\sigma_n^2}} = \text{erfc} \frac{A}{2\sqrt{2}\sigma_n}$$

$$P(1/0) = \text{erfc} \frac{\sigma^2}{2\sqrt{2}} = P(0/1) = \text{erfc} \frac{\sigma^2}{2\sqrt{2}}$$

$$\underline{\underline{P(E) = \frac{1}{2} \cdot 2 \cdot \text{erfc} \frac{\sigma^2}{2\sqrt{2}} = \text{erfc} \frac{\sigma^2}{2\sqrt{2}} = \left| \sigma^2 \gg 1 \right| = \frac{1}{\sigma^2} \left[\frac{2}{\pi} \right] e^{-\frac{\sigma^2}{2}}}}$$

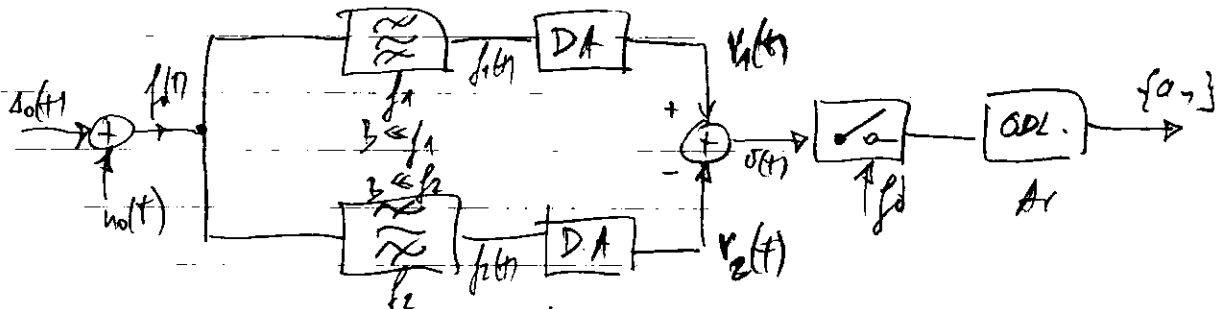
• DIGITALNA FREQ. MODULACIJA

$$s_n(t) = \sum_{n=-\infty}^{\infty} a_n g_T(t - nT_b) \quad g_T(t) = \begin{cases} A_T & 0 \leq t \leq T_b \\ 0 & \text{inačije} \end{cases}$$

$$a_n = \{-1, 1\} \quad \text{BFM}$$

$$s_{\text{BFM}} = \begin{cases} s_n(t) \cdot \cos \omega_c t, & a_n = 1 \\ s_n(t) \cdot \cos \omega_c t, & a_n = -1 \end{cases} = \begin{cases} A_T \cos \omega_c t & "1" \\ A_T \cos \omega_c t & "0" \end{cases}$$

• BFM PRUČIK SA NEKOHERENTNA DEMODULACIJA



$$f_1(t) = \begin{cases} [g(t) + x_1(t)] \cdot \cos \omega_c t - \gamma_1(t) \sin \omega_c t & a_n = 1 \\ x_1(t) \cos \omega_c t - \gamma_1(t) \sin \omega_c t & a_n = -1 \end{cases}$$

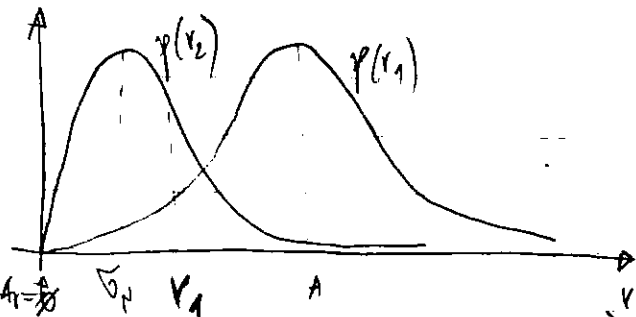
$$f_2(t) = \begin{cases} x_2(t) \cos \omega_c t - \gamma_2(t) \sin \omega_c t & a_n = 1 \\ [g(t) + x_2(t)] \cdot \cos \omega_c t - \gamma_2(t) \sin \omega_c t & a_n = -1 \end{cases}$$

$$v_1(t) = \begin{cases} \sqrt{[g(t) + x_1(t)]^2 + \gamma_1^2(t)} & a_n = 1 \quad \text{RADOVA (RICE)} \\ \sqrt{x_1^2(t) + \gamma_1^2(t)} & a_n = -1 \quad \text{RIZIČEVA (REZICIKIJA)} \end{cases}$$

$$v_2(t) = \begin{cases} \sqrt{x_2^2(t) + \gamma_2^2(t)} & a_n = 1 \\ \sqrt{[g(t) + x_2(t)]^2 + \gamma_2^2(t)} & a_n = -1 \end{cases}$$

$$v(t) = v_1(t) - v_2(t) \quad ; \quad g(t_0) = A$$

$$\boxed{\begin{matrix} v_1(t) > v_2(t) & a_n = 1 \\ v_1(t) < v_2(t) & a_n = -1 \end{matrix}}$$



$$v_1(t_0) - v_2(t_0) \leq 0 \quad \begin{matrix} > "1" \\ < "0" \end{matrix} \quad (*)$$

$$P(r_2 > r_1) = ? \quad a_1 = 1$$

$$P(r_1 > r_2) = ? \quad a_1 = -1$$

$$P(e) = P(A) \cdot P(A|A) + P(O) \cdot P(A|O)$$

$$v(t_0) = v_1 \quad P(r_2 > r_1) = P(O|A) = \int_{v_1}^{\infty} p(r_2) dr_2$$

MMV

$$P(O|A) = P(O|A)_{v_1} = \int_{v_1}^{\infty} p(O|A)_{v_1} \cdot p(r_2) dr_2$$

$$p(O|A)_{v_1} = \frac{1}{\sigma_n^2} \int_{v_1}^{\infty} r_2 e^{-\frac{r_2^2}{2\sigma_n^2}} dr_2$$

$$P(O|A) = -e^{-\frac{r_2^2}{2\sigma_n^2}} \Big|_{v_1}^{\infty} = e^{-\frac{v_1^2}{2\sigma_n^2}}$$

$$P(A|A) = \int_0^{\infty} e^{-\frac{r_1^2}{2\sigma_n^2}} \cdot \frac{r_1}{\sigma_n^2} \cdot e^{-\frac{v_1^2 - r_1^2}{2\sigma_n^2}} \cdot I_0\left(\frac{A r_1}{\sigma_n^2}\right) dr_1$$

$$v_1 \sqrt{2} = \gamma \quad \frac{A}{\sqrt{2}} = A'; \quad P(O|A) = \int_0^{\infty} \frac{r_1}{\sigma_n^2} e^{-\frac{(2r_1^2 - A^2)}{2\sigma_n^2}} I_0\left(\frac{A r_1}{\sigma_n^2}\right) dr_1 =$$

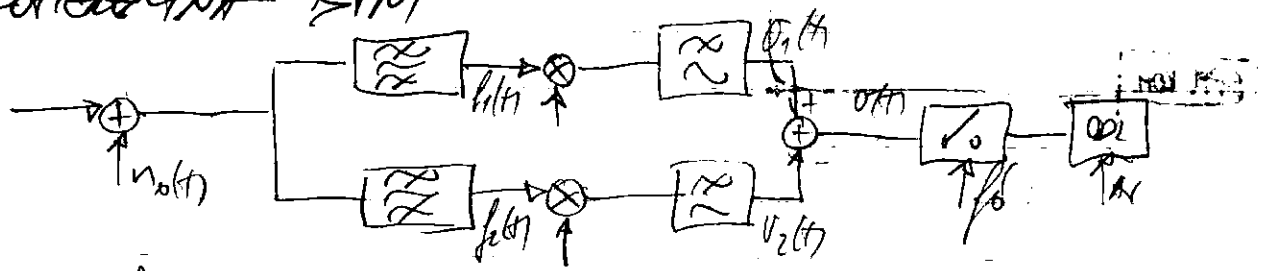
$$= \int_0^{\infty} \frac{r}{\sigma_n^2} e^{-\frac{r^2 - 2A^2}{2\sigma_n^2}} I_0\left(\frac{A' \cdot r}{\sigma_n^2}\right) \frac{dr}{\sqrt{2}} =$$

$$= \frac{1}{\sqrt{2} \cdot \sqrt{2}} e^{-\frac{A^2}{2\sigma_n^2}} \int_0^{\infty} \frac{r}{\sigma_n^2} e^{-\frac{r^2 - A^2}{2\sigma_n^2}} I_0\left(\frac{A \cdot r}{\sigma_n^2}\right) dr = \frac{1}{2} e^{-\frac{A^2}{4\sigma_n^2}}$$

$$P(A|O) = \int_0^{\infty} p(r_1) dr_1 = P(r_1 > v_2) = \frac{1}{2} e^{-\frac{A^2}{4\sigma_n^2}}$$

$$P(e) = P(O|A) = P(A|O) = \frac{1}{2} e^{-\frac{A^2}{4\sigma_n^2}} = \frac{1}{2} e^{-\frac{\rho^2}{4}} \quad \text{RFM}$$

Konvention BFM



$$f_{\text{eff}} = \begin{cases} [g(t) \cos(\omega t)] \cdot \cos \omega t - \gamma(t) \cdot \sin \omega t & a_1 = 1 \\ x(t) \cdot \cos \omega t - \gamma(t) \cdot \sin \omega t & a_1 = -1 \end{cases}$$

$$= \begin{cases} x_2(t) \cdot \cos \omega_0 t - y_2(t) \cdot \sin \omega_0 t & a_n = 1 \\ [g(t) + x_2(t)] \cdot \cos \omega_0 t - y_2(t) \cdot \sin \omega_0 t & a_n = -1 \end{cases}$$

$$U_1(t) = \begin{cases} k_D [g(t) + x_1(t)] & a_n = 1 \\ k_D \cdot x_1(t) & a_n = -1 \end{cases} \quad U_2(t) = \begin{cases} k_D x_2(t) & a_n = 1 \\ k_D [g(t) + x_2(t)] & a_n = -1 \end{cases}$$

$$U(t) = U_1 - U_2 = \begin{cases} k_D [x_1(t) + g(t)] & a_n = 1 \\ k_D [x_1(t) - g(t)] & a_n = -1 \end{cases} \quad x(t) = x_1 - x_2$$

$$g(t_0) = A \quad \sigma(t) = \begin{cases} k_D [x(t) + A] & a_n = 1 \\ k_D [x(t) - A] & a_n = -1 \end{cases}$$

$$U(t_0) = \sigma_1(t) - \sigma_2(t) \geq 0 \quad \begin{matrix} \geq 1/4 \\ < 1/16 \end{matrix}$$

$$p_g(t) = \frac{1}{\sqrt{4\pi\sigma_n^2}} e^{-\frac{t^2}{4\sigma_n^2}} \quad \sigma_g^2 = \sigma_{x_1}^2 + \sigma_{x_2}^2 = 2\sigma_{x_1}^2 = 2\sigma_n^2$$

$$p(0) = p(1) = \frac{1}{2} \quad x_1 = 0$$

$$P(e) = 2 \cdot \frac{1}{2} p(1/0) = \int_0^\infty p_1(u) du = \int_0^\infty \frac{1}{\sqrt{4\pi\sigma_n^2}} e^{-\frac{(u+A)^2}{4\sigma_n^2}} du$$

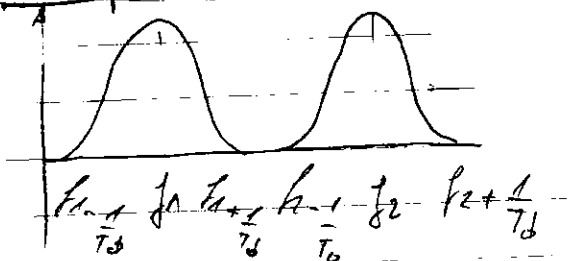
$$\frac{u+A}{2\sigma_n} = t \quad du = 2\sigma_n dt \quad \begin{matrix} u=0 & t = \frac{A}{2\sigma_n} \\ u=\infty & t = \infty \end{matrix}$$

$$P(e) = \frac{2\sigma_n}{\sqrt{\pi} 2\sigma_n} \int_{A/2\sigma_n}^\infty e^{-t^2} dt = \frac{1}{\sqrt{\pi}} \left[\int_{A/2\sigma_n}^\infty e^{-t^2} dt - \frac{2}{2} \int_0^{A/2\sigma_n} e^{-t^2} dt \right]$$

$$P(e) = \frac{1}{2} \left[1 - \Phi\left(\frac{A}{2\sigma_n}\right) \right] = \left[\Phi(x) = 1 - 2\text{erfc}(x) \right] = \text{erfc}\left(\frac{A}{2\sigma_n}\right)$$

$$P(e) = \text{erfc}\left(\frac{\hat{\sigma}}{2}\right) \quad \hat{\sigma} \gg 1 \quad \text{erfc}(x) = \frac{1}{2x\sqrt{\pi}} e^{-x^2}$$

$$P(e) = \frac{1}{\hat{\sigma}} \frac{1}{\sqrt{\pi}} e^{-\frac{\hat{\sigma}^2}{4}}$$



$$\text{BAM } P(e) \approx \frac{1}{\hat{\sigma}} \frac{1}{\sqrt{\pi}} e^{-\frac{\hat{\sigma}^2}{4}}$$

$$f_2 + \frac{1}{T_D} \leq f_2 - \frac{1}{T_D}$$

$$f_2 - f_1 \geq \frac{2}{T_D}$$

$$B_{VK} = \frac{4}{T_D}$$

• DIGITALNA PRAZNA MODULACIJA

$$s_{DM} = f_c \left\{ \sum_{n=-\infty}^{\infty} g_p(t-nT_d) e^{j(\omega_c t + \psi_n)} \right\}$$

$$s_{DM} = \cos \omega_c t \sum_{n=-\infty}^{\infty} \cos \psi_n g_p(t-nT_d) + \sin \omega_c t \sum_{n=-\infty}^{\infty} \sin \psi_n g_p(t-nT_d)$$

$$a_n = \cos \psi_n$$

$$b_n = \sin \psi_n$$

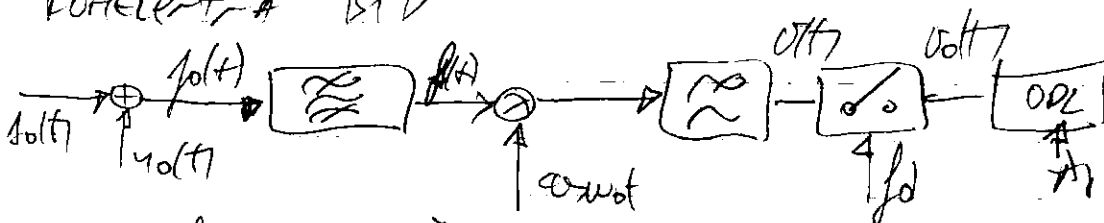
• BPM $\psi_n \in (0, \pi)$ $a_n \in \{-1, 1\}$, $b_n \in \{0, 0\}$

$$s_{BPM}(t) = \cos \omega_c t \sum_{n=-\infty}^{\infty} a_n g_p(t-nT_d) \quad a_n \in \{-1, 1\}$$

$$g_p = \begin{cases} A_p & 0 \leq t \leq T_d \\ 0 & \text{inače} \end{cases}$$

$$s_{BPM}(t) = \begin{cases} A_p \cos \omega_c t & , \quad a_n = 1 \quad \text{za } 0 \leq t \leq T_d \\ -A_p \cos \omega_c t & , \quad a_n = -1 \quad \text{---} \end{cases}$$

• Koherentna BPD



$$f(t) = \begin{cases} [g(t) + x(t)] \cos \omega_c t - y(t) \sin \omega_c t & a_n = 1 \\ [-g(t) + x(t)] \cos \omega_c t - y(t) \sin \omega_c t & a_n = -1 \end{cases}$$

$$g(t) = A \quad v(t) = \begin{cases} k_D [g(t) + x(t)] & a_n = 1 \\ k_D [-g(t) + x(t)] & a_n = -1 \end{cases}$$

$$v(t_0) = \begin{cases} k_D [A + x(t)] & a_n = 1 \\ k_D [-A + x(t)] & a_n = -1 \end{cases} \quad \sigma^2 = \sigma_x^2 = 2\sigma_N^2$$

$$P(\epsilon) = P(v < 0) = \int_0^{\infty} p_0(v) dv = \frac{1}{\sqrt{2\sigma_N^2}} \int_0^{\infty} e^{-\frac{(v+A)^2}{2\sigma_N^2}} dv = \text{erfc}\left(\frac{A}{\sqrt{2}\sigma_N}\right)$$

$$P_{BPSK}(\epsilon) = \text{erfc}\left(\frac{A}{\sqrt{2}\sigma_N}\right) = \left| \begin{matrix} \sigma_N^2 = \frac{\sigma_L^2}{2} \\ \sigma_N = \frac{\sigma_L}{\sqrt{2}} \end{matrix} \right| = \text{erfc}\left(\frac{A}{\sqrt{2}\sigma}\right)$$

$$P(\epsilon) = \text{erfc}\left(\frac{Q}{\sqrt{2}}\right) \quad \text{erfc}(x) = \frac{1}{\sqrt{\pi}} \int_x^{\infty} e^{-t^2} dt \quad P(\epsilon) = \frac{1}{\sqrt{\pi}} \int_{\frac{A}{\sqrt{2}}}^{\infty} e^{-t^2} dt$$

$$|y_{RMS}| < |y(\varepsilon)|_{RMS} < |y(\varepsilon)|_{MAX}$$

CONCEPT NA PULSATION FILTRA KA DISTORTION SO REDUCE

$$y(t) = k \cdot S^*(f\omega) \cdot e^{-j\omega t_0}$$

$$s(t) = g_0(t) \cos(\omega_0 t)$$

$$H_{RC}(j\omega) = \frac{k}{2} \left[G_0[j(\omega - \omega_0)] + G_0[j(\omega + \omega_0)] \right] e^{-j\omega t_0}$$

$$g_0(t) = A \quad -\frac{T_d}{2} \leq t \leq \frac{T_d}{2} \quad G(j\omega) = A T_d \frac{\sin \frac{\omega T_d}{2}}{\omega T_d}$$

$$H_{RL}(j\omega) = \frac{k}{2} \left[A T_d \frac{\sin \frac{(\omega - \omega_0) T_d}{2}}{(\omega - \omega_0) T_d} + A T_d \frac{\sin \frac{(\omega + \omega_0) T_d}{2}}{(\omega + \omega_0) T_d} \right] e^{-j\omega t_0}$$

• ERROR S/N NA IZEE OD FILTERING

$$\frac{S}{N} = \frac{A^2}{G_r} = \frac{\varepsilon}{\omega_0} \quad \boxed{\varepsilon = \sqrt{\frac{\varepsilon}{\omega_0}}}$$

$$\varepsilon = \int_{-T_d/2}^{T_d/2} A^2 \cos^2(\omega_0 t) dt = \frac{A^2}{\omega_0} \left(\frac{\omega_0 t}{2} + \frac{1}{4} \sin(2\omega_0 t) \right) \Big|_{-T_d/2}^{T_d/2}$$

$$\int \cos^2 x dx = \int \cos(x) \sin(x) dx = \int \sqrt{1 - \sin^2(x)} \sin(x) dx =$$

$$= \int \sqrt{1 - u^2} du = \left| \begin{array}{l} 1 - u^2 = t^2 \quad u = \sqrt{t^2 + 1} \\ -2u du = 2t dt \\ du = \frac{2t dt}{1+t^2} \end{array} \right| =$$

$$= \int \frac{2t^2 dt}{1+t^2} \quad ?$$

$$\cos^2 x = \cos x \cdot \cos x = \frac{1}{2} [\cos(x+x) + \cos(x-x)] = \frac{1}{2} [1 + \cos(2x)]$$

$$\int \frac{1}{2} [1 + \cos(2x)] dx = \frac{x}{2} + \frac{1}{4} \int \cos(2x) d(2x) = \frac{x}{2} + \frac{1}{4} \sin(2x)$$

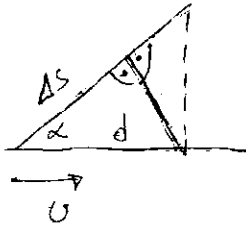
$$\varepsilon = \frac{A^2}{\omega_0} \left[\frac{\omega_0 T_d}{4} + \frac{1}{4} \sin(\omega_0 T_d) \right] - \left[\frac{\omega_0 T_d}{4} - \frac{1}{4} \sin \frac{\omega_0 T_d}{2} \right]$$

$$= \frac{A^2}{\omega_0} \left[\frac{\omega_0 T_d}{2} + \frac{1}{2} \sin(\omega_0 T_d) \right] \quad \begin{array}{l} T_d = k \cdot T_0 \\ \omega_0 = \frac{2\pi k}{T_0} = \frac{2\pi k}{T_d} \end{array}$$

$$E = \frac{A^2}{\omega} \left[\frac{\omega_0^2 d}{2} + \frac{1}{2} \sin\left(\frac{2\pi k \cdot \pi d}{\lambda}\right) \right] = \frac{A^2 T d}{2}$$

• SIMULATION OF FEED FORWARD USING MATHEMATICS FOR CLASSROOM INSTRUCTIONS;

$$s(t) = \sum_{i=1}^N a_i \cos(\omega_i t + \phi_i)$$



$$\phi_d = \frac{2\pi AS}{\lambda} = \frac{2\pi}{\lambda} d \cos \alpha$$

$$\omega_d = \frac{\phi_d}{\Delta t} = \frac{\phi_d}{d/v}$$

$$\omega_d = \frac{v}{\lambda} \cdot \frac{2\pi}{\lambda} \cdot d \cos \alpha = \frac{2\pi v}{\lambda} \cos \alpha$$

$$f_d = \frac{\omega_d}{2\pi} = \frac{v}{\lambda} \cos \alpha \quad f_d = f_{max} \cos \alpha \quad f_{max} = \frac{v}{\lambda}$$

$$\omega_{d_i} = \frac{2\pi v}{\lambda} \cos \psi_i = \frac{\omega_c \cdot v}{c} \cos \psi_i$$

$$s(t) = \sum_{i=1}^N a_i \cos(\omega_c t + \omega_{d_i} t + \phi_i)$$

$$s(t) = \cos \omega_c t \underbrace{\sum_{i=1}^N a_i \cos(\omega_{d_i} t + \phi_i)}_{I(t)} - \sin \omega_c t \underbrace{\sum_{i=1}^N a_i \sin(\omega_{d_i} t + \phi_i)}_{Q(t)}$$

$$s(t) = I(t) \cos \omega_c t - Q(t) \sin \omega_c t$$

$$r(t) = \sqrt{I(t)^2 + Q(t)^2}$$

$$I(t) = r(t) \cos \varphi$$

$$Q(t) = r(t) \sin \varphi$$

$$\varphi = \arctan \frac{Q(t)}{I(t)}$$

PDF $f(r) = \frac{r}{\sigma^2} e^{-\frac{r^2}{2\sigma^2}} \quad r \geq 0$

$$\chi^2\text{-square}(x) = \sqrt{\frac{(x - \text{expect}(x))^2}{\text{expect}(x)}}$$

DEGREE OF FREEDOM !!

Chi-square distribution depends on the DOF

• Marketing Response

- CHALLENGE OFFER 300,000 customers

- CHALLENGER 11 100.00 -11-

- 50,000 FROM ORIGINAL POPULATION WOULD HAVE

RESPONDED TO CHALLENGER IF THEY RECEIVED IT.

- 5,000 ARE EXPECTED TO RESPOND 10% OF THE POPULATION

(THAT RECEIVED CHALLENGER OFFER

→ SAMPLE RESPOND RATE 5%

→ POPULATION RESPONSE RATE 5%

$$\frac{50,000}{1,000,000} = 0.05 = 5\%$$

$$\frac{50}{1,000,000} = \frac{5}{10^5} = 0.005 = 0.5\% \quad \text{ALL PERIODS}$$

$$\frac{995,000}{1,000,000} = 99.5\%$$

$$\frac{45,000}{50,000} = 90\%$$

$$\frac{95,000}{100,000} = 95\%$$

$$P(X=k) = \binom{n}{k} p^k q^{n-k}$$

$$q = 1 - p$$

Binomial

CHALLENGE

- STANDARD ERROR OF PROPORTION (APPROXIMATIVE ESTIMATION)

$$SEP = \sqrt{\frac{p \times (1-p)}{N}}$$

p - RISK (IN %)

N - SIZE OF POPULATION

$$SEP = \sqrt{\frac{5 \times 95}{100,000}} = 0.07\%$$

p = 5%
68% CONFIDENT INTERVAL IS
4.93% ÷ 5.07%

95% CONFIDENT INTERVAL (2σ)

$$4.85\% \div 5.14\%$$

- CHAMION

FOR 4.9, 5.0, 5.1 CONFIDENCE BOUNDS OVERLAP ⇒
RESPONSES FOR CHAMION & CHALLENGER ARE SAME

- DIFFERENCE OF PROPORTIONS

STANDARD ERROR OF A DIFFERENCE OF PROPORTIONS

$$SEDP = \sqrt{\frac{p_1 \times (1-p_1)}{N_1} + \frac{p_2 \times (1-p_2)}{N_2}}$$

$$\phi(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^x e^{-\frac{t^2}{2}} dt = \frac{1}{\sqrt{2\pi}} \left[\int_0^x e^{-\frac{t^2}{2}} dt + \int_0^{\infty} e^{-\frac{t^2}{2}} dt \right] =$$

$$= \frac{1}{\sqrt{2}} \left[\frac{1}{\sqrt{\pi}} \int_0^x e^{-t^2} dt + \frac{1}{\sqrt{\pi}} \int_0^{\infty} e^{-t^2} dt \right] =$$

$$= \left[\frac{1}{2} + \frac{1}{2} \frac{1}{\sqrt{\pi}} \int_0^x e^{-t^2} dt \right] = \frac{1}{2} \left[1 + \operatorname{erf}\left(\frac{x}{\sqrt{2}}\right) \right]$$

$$\Phi_{MC} = \frac{1}{2} \left[1 + \operatorname{erf}\left(\frac{x-y}{\sqrt{2} \sqrt{u}}\right) \right]$$

$$\text{NORMALIST}(z) = \int_{-\infty}^z \frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} dx \quad \text{EACELL}$$

$$I = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^z e^{-\frac{x^2}{2}} dx$$

$$y = \frac{x}{\sqrt{2}} \quad x = z \quad t = \frac{z}{\sqrt{2}}$$

$$dx = \sqrt{2} dt \quad x = -z \quad t = -\frac{z}{\sqrt{2}}$$

$$\frac{1}{\sqrt{2\pi}} \left[\sqrt{2} \int_{-\frac{z}{\sqrt{2}}}^0 e^{-t^2} dt + \sqrt{2} \int_0^{\frac{z}{\sqrt{2}}} e^{-t^2} dt \right] = \frac{1}{\sqrt{2\pi}} \sqrt{2} \int_0^{\frac{z}{\sqrt{2}}} e^{-t^2} dt$$

$$I = \frac{1}{\sqrt{\pi}} \int_0^{\frac{z}{\sqrt{2}}} e^{-t^2} dt = \text{erf}\left(\frac{z}{\sqrt{2}}\right)$$

$$\text{Chi-square}(x) = \sqrt{\frac{(x - \text{expected}(t))^2}{\text{expected}(t)}}$$

• RAYLEIGH FADING SIMULATION; $f_c = 900 \text{ MHz}$

N - NUMBER OF MULTIPATHS $N = 4:40$

- FOR EACH N SIMULATION TIME INTERVAL 1250 WAVELENGTHS

$$T_0 = \frac{1}{f_0} = \frac{1}{9 \cdot 10^8} = 1.11 \text{ nsec} \quad T_{\text{sim}} = 1.3875 \cdot 10^{-6} \text{ sec} = 1.4 \mu\text{sec}$$

SIMULATION IS REPEATED 50 TIMES AND AVERAGED

$$s(t) = \sum_{i=1}^N a_i \cos(\omega_i t + \phi_i) \quad (1)$$

$$s(t) = \sum_{i=1}^N a_i \cos(\omega_i t + \omega_i t + \phi_i) \quad (2)$$

• a_i - WEIBULL DISTRIBUTED (weibull)

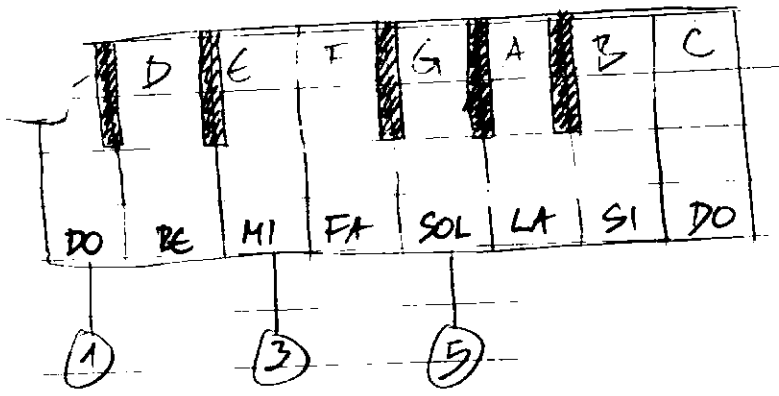
• ϕ_i - UNIFORMLY DISTRIBUTED $[0, 2\pi]$ (uniform)

• DEMODULATE WITH "demod" TO GET $I(t)$ & $Q(t)$

ENVELOPE: $\sqrt{I(t)^2 + Q(t)^2} = r(t)$

- TEST $r(t)$ AGAINST RAYLEIGH DISTRIBUTION USING CHI-SQUARE TEST (APPENDIX I)

• SO MENUVADE NA "N" NOVE DA SE VIDI POKI $r(t)$ E VO SOZLATIOTT SO RAYLEIGH PDF ZA $N \geq 6$

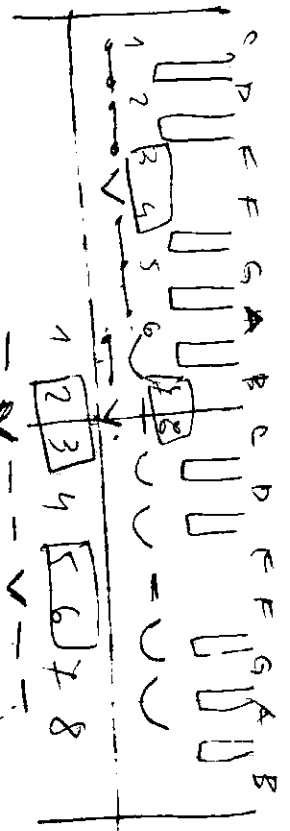


MDL - MINOR (NORO-TURO)
 DUR - MAJOR (AGREVADO)

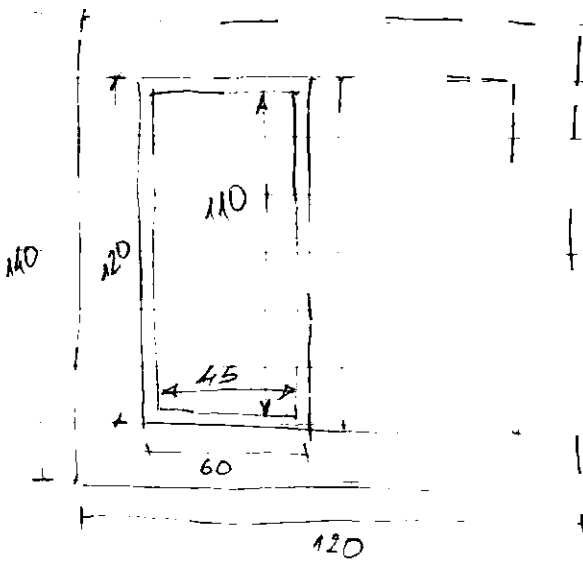
www.andromeda.net.com/totover-general.html#

(9-10, 11)

- FANOURA ERICSSON
- ~~DISCO~~ PRINCO DVDs (start 27.07.08)



C dur ~ A mol
 G dur ~ E mol



16 x 10 16
 100 800

$$\begin{aligned}
 16 \times 4 &= 64 \\
 14 \times 4 &= 56 \\
 14 \times 2 &= 28 \\
 \hline
 &148 \\
 1 \times 7 &= 7 \approx 1 \\
 2 \times 25 &= 50
 \end{aligned}$$

TERMOIAN STAZO SO
 1250

1 81070K TERMOIAN STAZO $0,45 \cdot 1,10 = 0,495 \approx 0,5 \text{ m}^2$
 RAMKA: $2 \times 120 + 2 \times 140 + 2 \times 120 + 2 \times 60 =$
 $= 240 + 280 + 240 + 120 = 480 + 400 = 880$
 $8,8 \text{ m} \times 10 \text{ €} = 88 \text{ €}$
 + TERMOIAN 12,5 €
 100 €

070200127
 080012345

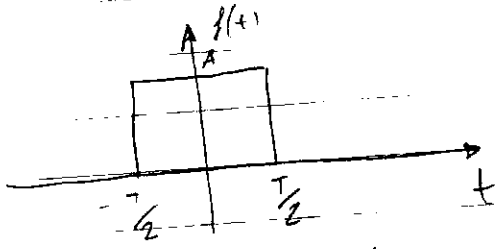
160R
 046251500
 storik
 istorik
 1116022

90 → 30 > 5%
 90 → 60 > 7%
 90 → 8 > 10%

12% → 2
 7% → 10
 8% → 15

TUKAN

$$\frac{\sin(\omega \frac{T}{2})}{\omega \frac{T}{2}} = \left| T=2\tau \right| = \frac{\sin(\omega \frac{2\tau}{2} \cdot \frac{\tau}{2})}{\omega \frac{2\tau}{2} \cdot \frac{\tau}{2}} = \frac{\sin(\frac{\omega\tau}{2})}{\frac{\omega\tau}{2}}$$



$$F(j\omega) = \int_{-T/2}^{T/2} f(t) e^{-j\omega t} dt$$

$$F(j\omega) = \int_{-T/2}^{T/2} A e^{-j\omega t} dt = \left. \frac{A e^{-j\omega t}}{-j\omega} \right|_{-T/2}^{T/2} = \frac{2AT}{j\omega} \left(\frac{e^{j\omega T/2} - e^{-j\omega T/2}}{2} \right) = \frac{2AT}{j\omega} \sin\left(\frac{\omega T}{2}\right)$$

$$F(j\omega) = \frac{AT}{j\omega T} e^{j\omega T/2} - \frac{AT}{j\omega T} e^{-j\omega T/2} = \frac{2AT}{j\omega T} \sin\left(\frac{\omega T}{2}\right) = AT \frac{\sin\left(\frac{\omega T}{2}\right)}{\frac{\omega T}{2}} = AT \text{sinc}\left(\frac{\omega T}{2}\right)$$

$$2 \times 5800 = 11600$$

$$\frac{11600}{2600} = 4.46$$

$$33 \times 21 = 693$$

$$30.5 \times 22.5 = 686$$

MOBI HC 2.157

BLADES OF GLOW

M. ORAUT FARMER 2.149

Ancurman 2.147

NEAT 2.141

$$\bar{xy} = \iint_{-\infty}^{\infty} x \cdot y \cdot p(x, y) dx dy$$

$$p_{xy}(x, y) = p_x(x) \cdot p_y(y)$$

$$\bar{xy} = \int_{-\infty}^{\infty} x \cdot p_x(x) dx \int_{-\infty}^{\infty} y \cdot p_y(y) dy = \bar{x} \cdot \bar{y}$$

$$p_{xy}(x, y) = p(x) \cdot p(y/x) = p(y) \cdot p(x/y) = \left| \int_{-\infty}^{\infty} p(x) p(y/x) dx \right|$$

$$\Rightarrow p_{xy}(x, y) = g(x) \cdot p(y)$$

108, 109, 155